# Supplement to Doubly Constrained Factor Models with Applications 

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## Proof of the identifiability of $\omega_{1}, \omega_{2}$ and $\omega_{3}$ of the proposed model

Note that $\boldsymbol{\omega}_{1}, \boldsymbol{\omega}_{2}$ and $\boldsymbol{\omega}_{3}$ cannot be fully identified without additional restrictions. To see this, first note that the covariance matrix of $\operatorname{vec}\left(\boldsymbol{Z}^{\prime}\right)$ is $\widetilde{\boldsymbol{\Sigma}}=\boldsymbol{I}_{T} \otimes \boldsymbol{A}+\boldsymbol{G} \boldsymbol{G}^{\prime} \otimes \boldsymbol{B}$, where $\boldsymbol{A}=\boldsymbol{H} \boldsymbol{\omega}_{1} \boldsymbol{\omega}_{1}^{\prime} \boldsymbol{H}^{\prime}+\boldsymbol{\Psi}$, and $\boldsymbol{B}=\boldsymbol{\omega}_{2} \boldsymbol{\omega}_{2}^{\prime}+\boldsymbol{H} \boldsymbol{\omega}_{3} \boldsymbol{\omega}_{3}^{\prime} \boldsymbol{H}^{\prime}$. Let $M_{1}, M_{2}$, and $M_{3}$ be $r \times r, p \times p$, and $q \times q$ matrix, respectively, such that $M_{1} M_{1}^{\prime}=I_{r}, M_{2} M_{2}^{\prime}=I_{p}$, and $M_{3} M_{3}^{\prime}=I_{q}$, then we have $\widetilde{\boldsymbol{\Sigma}}=$ $\boldsymbol{I}_{T} \otimes \tilde{A}+\boldsymbol{G} \boldsymbol{G}^{\prime} \otimes \tilde{B}$, where $\tilde{A}=\boldsymbol{H} \boldsymbol{\omega}_{1} M_{1} M_{1}^{\prime} \boldsymbol{\omega}_{1}^{\prime} \boldsymbol{H}^{\prime}+\boldsymbol{\Psi}$, and $\tilde{B}=\boldsymbol{\omega}_{2} M_{2} M_{2}^{\prime} \boldsymbol{\omega}_{2}^{\prime}+\boldsymbol{H} \boldsymbol{\omega}_{3} M_{3} M_{3}^{\prime} \boldsymbol{\omega}_{3}^{\prime} \boldsymbol{H}^{\prime}$. We thus have two equivalent forms for $\widetilde{\boldsymbol{\Sigma}}$. Since the number of free parameters of $M_{1}$ is $r(r-$ $1) / 2$, we need $r(r-1) / 2$ restrictions to identify $\boldsymbol{\omega}_{1}$. Similarly, we need $p(p-1) / 2$ and $q(q-1) / 2$ restrictions to identify $\boldsymbol{\omega}_{2}$ and $\boldsymbol{\omega}_{3}$, respectively. This is the reason we put the conditions that $\boldsymbol{\Gamma}_{1}, \boldsymbol{\Gamma}_{2}$, and $\boldsymbol{\Gamma}_{3}$ of Equation (2.11) are all diagonal. Second, write $\boldsymbol{\omega}_{2} \boldsymbol{\omega}_{2}^{\prime}=\sum_{i=1}^{p} \boldsymbol{\omega}_{2(i)} \boldsymbol{\omega}_{2(i)}^{\prime}$, where $\boldsymbol{\omega}_{2(i)}$ represents the $i$-th column of $\boldsymbol{\omega}_{2}$, meaning that swapping the columns of $\boldsymbol{\omega}_{2}$ would not change the values of $\boldsymbol{\omega}_{2} \boldsymbol{\omega}_{2}^{\prime}$ at all, and there are $p$ columns in total, so we add the conditions $\gamma_{11}^{2}>\gamma_{22}^{2}>\cdots>\gamma_{p p}^{2}$ for the identifiability of $\boldsymbol{\omega}_{2}$. Similar reasons apply to the conditions $\gamma_{11}^{1}>\gamma_{22}^{1}>\cdots>\gamma_{r r}^{1}$, and $\gamma_{11}^{3}>\gamma_{22}^{3}>\cdots>\gamma_{q q}^{3}$. Finally, $\boldsymbol{\omega}_{2} \boldsymbol{\omega}_{2}^{\prime}=\sum_{i=1}^{p}\left(-\boldsymbol{\omega}_{2(i)}\right)\left(-\boldsymbol{\omega}_{2(i)}^{\prime}\right)$, so we add the condition that the first non-zero element in each column of the matrix $\boldsymbol{\omega}_{2}$ is positive. Similar conditions apply to the corresponding elements of $\boldsymbol{\omega}_{1}$ and $\boldsymbol{\omega}_{3}$. This proves the identifiability of $\boldsymbol{\omega}_{1}, \boldsymbol{\omega}_{2}$ and $\boldsymbol{\omega}_{3}$.

## Proof of Lemma 1

To prove part (a), write $\boldsymbol{B}=\boldsymbol{\omega}_{B} \boldsymbol{\omega}_{B}^{\prime}$, where $\boldsymbol{\omega}_{B}=\left[\begin{array}{cc}\boldsymbol{\omega}_{2} & \boldsymbol{H} \boldsymbol{\omega}_{3}\end{array}\right]$, then we have

$$
\begin{aligned}
& |\widetilde{\boldsymbol{\Sigma}}| \\
= & \left|\boldsymbol{I}_{T} \otimes \boldsymbol{A}+\left(\boldsymbol{G} \otimes \boldsymbol{\omega}_{B}\right)\left(\boldsymbol{G}^{\prime} \otimes \boldsymbol{\omega}_{B}^{\prime}\right)\right|
\end{aligned}
$$

(by the definition of $\widetilde{\boldsymbol{\Sigma}}$ and Theorem 7.7 of Schott, 1997)
$=\left|\boldsymbol{I}_{T} \otimes \boldsymbol{A}\right|\left|\boldsymbol{I}_{m(p+q)}+\left(\boldsymbol{G}^{\prime} \otimes \boldsymbol{\omega}_{B}^{\prime}\right)\left(\boldsymbol{I}_{T} \otimes \boldsymbol{A}^{-1}\right)\left(\boldsymbol{G} \otimes \boldsymbol{\omega}_{B}\right)\right|$
(by Theorem 18.1.1 of Harville, 1997, and Theorem 7.9 (a) of Schott, 1997)
$=|\boldsymbol{A}|^{T}\left|\boldsymbol{I}_{m(p+q)}+\frac{T}{m} \boldsymbol{I}_{m} \otimes \boldsymbol{\omega}_{B}^{\prime} \boldsymbol{A}^{-1} \boldsymbol{\omega}_{B}\right|$
(by Equation (2), Theorems 7.7 and 7.11 of Schott, 1997)
$=|\boldsymbol{A}|^{T}\left|\boldsymbol{I}_{m N}+\frac{T}{m} \boldsymbol{I}_{m} \otimes \boldsymbol{A}^{-1 / 2} \boldsymbol{B} \boldsymbol{A}^{-1 / 2}\right|$
(by Theorem 7.7 of Schott, 1997, and Theorem 18.1.1 of Harville, 1997)

$$
\begin{aligned}
& =|\boldsymbol{A}|^{T}\left|\boldsymbol{I}_{m} \otimes \boldsymbol{A}^{-1 / 2}\right|^{2}\left|\left(\boldsymbol{I}_{m} \otimes \boldsymbol{A}^{1 / 2}\right)\left(\boldsymbol{I}_{m} \otimes \boldsymbol{I}_{N}+\frac{T}{m} \boldsymbol{I}_{m} \otimes \boldsymbol{A}^{-1 / 2} \boldsymbol{B} \boldsymbol{A}^{-1 / 2}\right)\left(\boldsymbol{I}_{m} \otimes \boldsymbol{A}^{1 / 2}\right)\right| \\
& =|\boldsymbol{A}|^{T-m}\left(I_{m} \otimes \boldsymbol{A}+\boldsymbol{I}_{m} \otimes \frac{T}{m} \boldsymbol{B}\right) \quad \text { (by Theorems } 7.7 \text { and } 7.11 \text { of Schott, 1997) } \\
& =|\boldsymbol{A}|^{T-m}\left|\boldsymbol{I}_{m} \otimes \boldsymbol{Q}\right| \quad \text { (by the definition of } \boldsymbol{Q} \text { and Theorem 7.6 (e) of Schott, 1997) } \\
& =|\boldsymbol{Q}|^{m}|\boldsymbol{A}|^{T-m} \quad \text { (by Theorem 7.11 of Schott, 1997). }
\end{aligned}
$$

This proves part (a).
Now, we prove part (b). We will prove part (b) by showing that $\widetilde{\boldsymbol{\Sigma}} \widetilde{\boldsymbol{\Sigma}}^{-1}=\widetilde{\boldsymbol{\Sigma}}^{-1} \widetilde{\boldsymbol{\Sigma}}=\boldsymbol{I}_{N T}$. First note that, by the definitions of $\boldsymbol{U}$ and $\boldsymbol{Q}$, we have $\boldsymbol{Q} \boldsymbol{U} \boldsymbol{A}=-\boldsymbol{B}$, and so $\boldsymbol{Q U}=-\boldsymbol{B} \boldsymbol{A}^{-1}$. Therefore,

$$
\begin{aligned}
\widetilde{\Sigma}_{\boldsymbol{\Sigma}^{-1}} & =\left(\boldsymbol{I}_{T} \otimes \boldsymbol{A}+\boldsymbol{G} \boldsymbol{G}^{\prime} \otimes B\right)\left(\boldsymbol{I}_{T} \otimes \boldsymbol{A}^{-1}+\boldsymbol{G} \boldsymbol{G}^{\prime} \otimes \boldsymbol{U}\right) \\
& =\left(\boldsymbol{I}_{T} \otimes \boldsymbol{I}_{N}\right)+\left(\boldsymbol{G} \boldsymbol{G}^{\prime} \otimes \boldsymbol{A} \boldsymbol{U}\right)+\left(\boldsymbol{G} \boldsymbol{G}^{\prime} \otimes \boldsymbol{B} \boldsymbol{A}^{-1}\right)+\left(\frac{T}{m} \boldsymbol{G} \boldsymbol{G}^{\prime} \otimes \boldsymbol{B} \boldsymbol{U}\right) \\
& =\boldsymbol{I}_{N T}+\left(\boldsymbol{G} \boldsymbol{G}^{\prime} \otimes \boldsymbol{Q} \boldsymbol{U}\right)+\left(\boldsymbol{G} \boldsymbol{G}^{\prime} \otimes \boldsymbol{B} \boldsymbol{A}^{-1}\right) \\
& =\boldsymbol{I}_{N T}
\end{aligned}
$$

Similarly, it can be shown that $\widetilde{\boldsymbol{\Sigma}}^{-1} \widetilde{\boldsymbol{\Sigma}}=\boldsymbol{I}_{N T}$. This proves (b).
Part (c) follows from part (b) and Theorem 7.17 of Schott (1997).

## References

[1] Harville, D. A. (1997). Matrix Algebra From a Statistician's Perspective. New York: Springer.
[2] Schott, James R. (1997). Matrix Analysis for Statistics. New York: Wiley.

