# Likelihood Based Inference for Skew-Normal Independent Linear Mixed Models 

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This note contains the proofs of Lemma 1, 2, proposition 1. In appendix b, we have the restricted estimation, appendix C, has the observed information matrix, and appendix D contains the additional simulation study results.

## Appendix A: Some Lemmas and Proofs

Lemma 1. Let $\mathbf{Y} \sim S N I_{p}(\boldsymbol{\mu}, \boldsymbol{\Sigma}, \boldsymbol{\lambda} ; H)$ and $\mathbf{Y}$ is partitioned as $\mathbf{Y}^{\top}=\left(\mathbf{Y}_{1}^{\top}, \mathbf{Y}_{2}^{\top}\right)^{\top}$ of dimensions $p_{1}$ and $p_{2}\left(p_{1}+p_{2}=p\right)$, respectively; let $\boldsymbol{\mu}=\left(\boldsymbol{\mu}_{1}^{\top}, \boldsymbol{\mu}_{2}^{\top}\right)^{\top}$ and

$$
\boldsymbol{\Sigma}=\left(\begin{array}{ll}
\boldsymbol{\Sigma}_{11} & \boldsymbol{\Sigma}_{12} \\
\boldsymbol{\Sigma}_{21} & \boldsymbol{\Sigma}_{22}
\end{array}\right)
$$

be the corresponding partitions of $\boldsymbol{\mu}$ and $\boldsymbol{\Sigma}$. Then, marginally $\mathbf{Y}_{1} \sim S N I_{p_{1}}\left(\boldsymbol{\mu}_{1}, \boldsymbol{\Sigma}_{11}, \boldsymbol{\Sigma}_{11}^{1 / 2} \widetilde{\boldsymbol{v}} ; H\right)$, where

$$
\widetilde{\boldsymbol{v}}=\frac{\boldsymbol{v}_{1}+\boldsymbol{\Sigma}_{11}^{-1} \boldsymbol{\Sigma}_{12} \boldsymbol{v}_{2}}{\sqrt{1+\boldsymbol{v}_{2}^{\top} \boldsymbol{\Sigma}_{22.1} \boldsymbol{v}_{2}}}
$$

with $\boldsymbol{\Sigma}_{22.1}=\boldsymbol{\Sigma}_{22}-\boldsymbol{\Sigma}_{21} \boldsymbol{\Sigma}_{11}^{-1} \boldsymbol{\Sigma}_{12}, \boldsymbol{v}=\boldsymbol{\Sigma}^{-1 / 2} \boldsymbol{\lambda}=\left(\boldsymbol{v}_{1}^{\top}, \boldsymbol{v}_{2}^{\top}\right)^{\top}$.

Proof. See Proposition 5.4 and 5.5 in Branco and Dey (2001).
Lemma 2. Let $\mathbf{Y} \in \mathbb{R}^{p}$ a random vector with the following extended skew-normal $p d f$

$$
f(\mathbf{y})=\frac{1}{\Phi\left(c / \sqrt{1+\mathbf{a}^{\top} \mathbf{\Sigma} \mathbf{a}}\right)} \phi_{p}(\mathbf{y} ; \boldsymbol{\mu}, \boldsymbol{\Sigma}) \Phi_{1}\left(c+\mathbf{a}^{\top}(\mathbf{y}-\boldsymbol{\mu})\right)
$$

where $c$ is A fixed real constant and $\mathbf{a}$ is a fixed $p$-dimensional vector. Then,

$$
E\{\mathbf{Y}\}=\boldsymbol{\mu}+\boldsymbol{\delta} W_{\Phi_{1}}(\bar{c}),
$$

where $\boldsymbol{\delta}=\boldsymbol{\Sigma} \mathbf{a} / \sqrt{1+\mathbf{a}^{\top} \boldsymbol{\Sigma} \mathbf{a}}$ and $\bar{c}=c / \sqrt{1+\mathbf{a}^{\top} \boldsymbol{\Sigma} \mathbf{a}}$.
Proof. It follows by using the well known stochastic representation $\mathbf{Y} \stackrel{d}{=} \mu+\delta Z_{(-\bar{c}, \infty)}+\mathbf{Z}$, where $Z_{(-\bar{c}, \infty)} \stackrel{d}{=}\left(Z_{0} \mid Z_{0}+\bar{c}>0\right)$, with $Z_{0} \sim N(0,1)$ and being independent of $\mathbf{Z} \sim$ $N_{p}\left(\mathbf{0}, \boldsymbol{\Sigma}-\boldsymbol{\delta} \boldsymbol{\delta}^{\top}\right)$ (see e.g. Arellano-Valle and Azzalini, 2006), and the fact that $\mathrm{E}\left\{Z_{(-\bar{c}, \infty)}\right\}=$ $W_{\Phi_{1}}(\bar{c})$ (see Johnson et al., 1994, Section 10.1).

Proof of Proposition 1: Consider the case where $U$ is (absolutely) continues. Let $h(u ; \nu)$ be the pdf of $U, h(u \mid \mathbf{y})=f(\mathbf{y} \mid u) h(u ; \nu) / f(\mathbf{y})$ be the conditional pdf of $U$ given $\mathbf{Y}=\mathbf{y}$, and $h_{0}\left(u \mid \mathbf{y}_{0}\right)$ be the conditional pdf of $U$ given $\mathbf{Y}_{0}=\mathbf{y}$, where $\mathbf{Y}_{0} \mid U=u \sim N_{p}\left(\boldsymbol{\mu}, u^{-1} \boldsymbol{\Sigma}\right)$. Since $h(u \mid \mathbf{y})=f(\mathbf{y} \mid u) h(u ; \nu) / f(\mathbf{y})$ and $h_{0}(u \mid \mathbf{y})=\phi_{p}\left(\mathbf{y} ; \boldsymbol{\mu}, u^{-1} \boldsymbol{\Sigma}\right) h(u ; \nu) / f_{0}(\mathbf{y})$, where $f_{0}$ is the pdf of $\mathbf{Y}_{0}$, we have for any integrable function $g(u)$ that

$$
\begin{aligned}
\mathrm{E}[g(U) \mid \mathbf{Y}=\mathbf{y}] & =(1 / f(\mathbf{y})) \int_{0}^{\infty} g(u) f(\mathbf{y} \mid u) h(u ; \nu) d u \\
& =(2 / f(\mathbf{y})) \int_{0}^{\infty} g(u) \phi_{p}\left(\mathbf{y} ; \boldsymbol{\mu}, u^{-1} \boldsymbol{\Sigma}\right) h(u ; \nu) \Phi\left(u^{1 / 2} \mathrm{~A}\right) d u \\
& =(2 / f(\mathbf{y})) \int_{0}^{\infty} g(u) f_{0}(\mathbf{y} \mid u) h(u ; \nu) \Phi\left(u^{1 / 2} \mathrm{~A}\right) d u \\
& =\left(2 f_{0}(\mathbf{y}) / f(\mathbf{y})\right) \int_{0}^{\infty} g(u) \Phi\left(u^{1 / 2} \mathrm{~A}\right) h_{0}\left(u \mid \mathbf{y}_{0}\right) d u .
\end{aligned}
$$

Thus, the proof follows by considering the special cases with $g(u)=u^{r}$ and $g(u)=$ $u^{r / 2} W_{\Phi}\left(u^{1 / 2} \mathrm{~A}\right)$. The proof when $U$ is discrete is analogous if we replace $\int$ by $\sum$.

## Appendix B:

## - Restricted estimation

As in Lachos et al. (2007), suppose that our interest centers in estimating the parameter vector $\boldsymbol{\beta}$ under $k$ linearly independent restrictions defined as $\mathbf{C}_{j}^{\top} \boldsymbol{\beta}-c_{j}=0$, where the $\mathbf{C}_{j}, j=1, \ldots, k$, are $p \times 1$ vectors and $c_{j}, j=1, \ldots, k$, are scalars which are assumed to be
both known. The interest is to maximize the complete $\log$-likelihood function $\ell_{c}\left(\boldsymbol{\theta} ; \mathbf{y}_{c}\right)$ subject to the linear constraints $\mathbf{C} \boldsymbol{\beta}-\mathbf{c}=\mathbf{0}$, where $\mathbf{C}=\left(\mathbf{C}_{1}, \ldots, \mathbf{C}_{k}\right)^{\top}$ and $\mathbf{c}=\left(c_{1}, \ldots, c_{k}\right)^{\top}$. Following Lachos et al. (2007), one can show that the equality restricted estimate of $\boldsymbol{\beta}$ is given by

$$
\begin{aligned}
\widetilde{\boldsymbol{\beta}}_{c}^{(k+1)}= & \widehat{\boldsymbol{\beta}}^{(k)}+\left(\sum_{i=1}^{n} \widehat{u}_{i}^{(k)} \mathbf{X}_{i}^{\top}\left[\widehat{\boldsymbol{\Sigma}}_{i}^{(k)}\right]^{-1} \mathbf{X}_{i}\right)^{-1} \\
& \times \mathbf{C}^{\top}\left[\mathbf{C}\left(\sum_{i=1}^{n} \widehat{u}_{i}^{(k)} \mathbf{X}_{i}^{\top}\left[\widehat{\boldsymbol{\Sigma}}_{i}^{(k)}\right]^{-1} \mathbf{X}_{i}\right)^{-1} \mathbf{C}^{\top}\right]^{-1}\left(\mathbf{c}-\mathbf{C} \widehat{\boldsymbol{\beta}}^{(k)}\right),
\end{aligned}
$$

for $k=0,1, \ldots$, where $\left(\widehat{u}_{i}^{(k)},\left(\widehat{u \mathbf{b}}{ }_{i}^{(k)}\right), i=1, \ldots, n\right.$, and $\widehat{\boldsymbol{\beta}}^{(k)}$ are obtained from (??) and (??), respectively. The EM-algorithm for estimating the parameters of the model (??) and (??) under the restriction $\mathbf{C} \boldsymbol{\beta}=\mathbf{d}$, denoted by $\widetilde{\boldsymbol{\theta}}_{0}$, follows the same procedures of the EM-algorithm, replacing $\widehat{\boldsymbol{\beta}}^{(k)}$ by $\widetilde{\boldsymbol{\beta}}_{c}$ in the M-step.

## - Generating of truncated gamma distribution

Suppose that $X \sim \operatorname{Gamma}(\alpha, \beta)$. To draw $X$ such that $a<X<b$

- Generate $U \sim U[0,1]$
- Let $V=F(a)+[F(b)-F(a)] U$
- return $X=F^{-1}(V)$,
where $F$ is the cdf of the $\operatorname{Gamma}(\alpha, \beta)$ distribution. In R software to generate of $0<X<$ 1 , we use the following code:

$$
X=\operatorname{qgamma}((\operatorname{pgamma}(1, \alpha, \beta)) * \operatorname{runif}(1), \alpha, \beta)
$$

- Derivation of the conditional expectation in the EM algorithm

The notation used is that of Section 3. From (??) we have that

$$
\begin{aligned}
f\left(\mathbf{y}_{i}, \mathbf{b}_{i}, t_{i}, u_{i} \mid \boldsymbol{\theta}\right) & =f\left(\mathbf{y}_{i} \mid \mathbf{b}_{i}, u_{i}, \boldsymbol{\theta}\right) f\left(\mathbf{b}_{i} \mid t_{i}, u_{i}, \boldsymbol{\theta}\right) f\left(t_{i} \mid \boldsymbol{\theta}\right) f\left(u_{i} \mid \boldsymbol{\theta}\right) \\
& =f\left(\mathbf{y}_{i} \mid \boldsymbol{\theta}\right) f\left(u_{i} \mid \mathbf{y}_{i}, \boldsymbol{\theta}\right) f\left(t_{i} \mid u_{i}, \mathbf{y}_{i}, \boldsymbol{\theta}\right) f\left(\mathbf{b}_{i} \mid t_{i}, u_{i}, \mathbf{y}_{i}, \boldsymbol{\theta}\right),
\end{aligned}
$$

by using successively Lemma 3 in Arellano-Valle et al. (2005), we can see that

$$
\begin{aligned}
& \mathbf{b}_{i} \mid T_{i}=t_{i}, U_{i}=u_{i}, \mathbf{Y}_{i}=\mathbf{y}_{i}, \boldsymbol{\theta} \sim N_{q}\left(u_{i}^{-1 / 2} \mathbf{s}_{i} t_{i}+\mathbf{B}_{i} \mathbf{Z}_{i} \boldsymbol{\Sigma}_{i}^{-1}\left(\mathbf{y}_{i}-\mathbf{X}_{i} \boldsymbol{\beta}\right), u_{i}^{-1} \mathbf{B}_{i}\right), \\
& T_{i} \mid U_{i}=u_{i}, \mathbf{Y}_{i}=\mathbf{y}_{i}, \boldsymbol{\theta} \sim N_{1}\left(u_{i}^{1 / 2} \mu_{i}, M_{i}^{2}\right) \mathbb{I}_{(0, \infty)}\left(t_{i}\right),
\end{aligned}
$$

and since $\mathbf{Y}_{i} \mid \boldsymbol{\theta} \sim S N I_{n_{i}}\left(\mathbf{X}_{i} \boldsymbol{\beta}, \boldsymbol{\Psi}_{i}, \overline{\boldsymbol{\lambda}}_{b_{i}}, H\right)$, then from Section 2 the conditional expectations of $U_{i} \mid \mathbf{Y}_{i}=\mathbf{y}_{i}, \boldsymbol{\theta}$ are known for the particular SNI distributions considered. Then, all the necessary conditional expectations can be computed by noting that for any integrable function $g$

$$
\mathrm{E}\left\{U_{i}^{r} T_{i}^{s} g\left(\mathbf{b}_{i}\right) \mid \mathbf{Y}_{i}, \boldsymbol{\theta}\right\}=\mathrm{E}\left\{U_{i}^{r} \mathrm{E}\left\{T_{i}^{s} \mathrm{E}\left\{g\left(\mathbf{b}_{i}\right) \mid T_{i}, U_{i}, \mathbf{Y}_{i}\right\} \mid U_{i}, \mathbf{Y}_{i}\right\} \mid \mathbf{Y}_{i}, \boldsymbol{\theta}\right\},
$$

$i=1, \ldots, n$.

## Appendix C: The observed information matrix

First we reparameterize $\mathbf{D}=\mathbf{F}^{2}$ for ease of computation and theoretical derivation, where $\mathbf{F}$ is the square root of $\mathbf{D}$ containing $q(q+1) / 2$ distinct elements $\boldsymbol{\alpha}_{b}=\left(\alpha_{1}, \ldots, \alpha_{q(q+1) / 2}\right)^{\top}$. Given the observed sample $\mathbf{y}=\left(\mathbf{y}_{1}^{\top}, \ldots, \mathbf{y}_{n}^{\top}\right)^{\top}$, the log-likelihood function for $\boldsymbol{\theta}=\left(\boldsymbol{\theta}_{1}^{\top}, \boldsymbol{\theta}_{2}^{\top}, \boldsymbol{\nu}^{\top}\right)^{\top}$, with $\boldsymbol{\theta}_{1}=\left(\boldsymbol{\beta}^{\top}, \boldsymbol{\gamma}^{\top}\right)^{\top}$ and $\boldsymbol{\theta}_{2}=\left(\boldsymbol{\alpha}_{b}^{\top}, \boldsymbol{\lambda}^{\top}\right)^{\top}$ is given by $\ell(\boldsymbol{\theta})=\sum_{i=1}^{n} \ell_{i}(\boldsymbol{\theta})$, where

$$
\begin{equation*}
\ell_{i}(\boldsymbol{\theta})=\log 2-\frac{n_{i}}{2} \log 2 \pi-\frac{1}{2} \log \left|\boldsymbol{\Psi}_{i}\right|+\log K_{i} \tag{1}
\end{equation*}
$$

with $K_{i}(\boldsymbol{\theta})=\int_{0}^{\infty} u_{i}^{n_{i} / 2} \exp \left\{-\frac{1}{2} u_{i} \mathrm{~d}_{\mathrm{i}}\right\} \Phi\left(\mathrm{u}_{\mathrm{i}}^{1 / 2} \mathrm{~A}_{\mathrm{i}}\right) \mathrm{dH}\left(\mathrm{u}_{\mathrm{i}} ; \boldsymbol{\nu}\right)$, where $\mathrm{d}_{\mathrm{i}}=\left(\mathbf{y}_{\mathbf{i}}-\mathbf{X}_{\mathrm{i}} \boldsymbol{\beta}\right)^{\top} \boldsymbol{\Psi}_{\mathrm{i}}^{-1}\left(\mathbf{y}_{\mathbf{i}}-\right.$ $\left.\mathbf{X}_{\mathbf{i}} \boldsymbol{\beta}\right)$ and $\mathrm{A}_{i}=\frac{\boldsymbol{\lambda}^{\top} \mathbf{F} \mathbf{Z}_{i} \boldsymbol{\Psi}_{i}^{-1}\left(\mathbf{y}_{i}-\mathbf{X}_{i} \boldsymbol{\beta}\right)}{\left(1+\boldsymbol{\lambda}^{\top} \mathbf{F}^{-1} \boldsymbol{\Lambda}_{i} \mathbf{F}^{-1} \boldsymbol{\lambda}\right)^{1 / 2}}$. Thus, we have after some algebraic manipulations that the score vector is given by

$$
\begin{equation*}
\mathbf{s}=\sum_{i=1}^{n} \frac{\partial \ell_{i}(\boldsymbol{\theta})}{\partial \boldsymbol{\theta}}=-\frac{n}{2} \frac{\partial \log \left|\boldsymbol{\Psi}_{i}\right|}{\partial \boldsymbol{\theta}}-\sum_{i=1}^{n} \frac{1}{K_{i}} \frac{\partial K_{i}}{\partial \boldsymbol{\theta}}, \tag{2}
\end{equation*}
$$

where $\frac{\partial K_{i}}{\partial \boldsymbol{\theta}}=I_{i}^{\phi}\left(\frac{n_{i}+1}{2}\right) \frac{\partial \mathrm{A}_{i}}{\partial \boldsymbol{\theta}}-\frac{1}{2} I_{i}^{\Phi}\left(\frac{n_{i}+2}{2}\right) \frac{\partial \mathrm{d}_{\mathrm{i}}}{\partial \boldsymbol{\theta}}$, with

$$
\begin{gathered}
I_{i}^{\Phi}(w)=\int_{0}^{\infty} u_{i}^{w} \exp \left\{-\frac{1}{2} u_{i} \mathrm{~d}_{\mathrm{i}}\right\} \Phi\left(\mathrm{u}_{\mathrm{i}}^{1 / 2} \mathrm{~A}_{\mathrm{i}}\right) \mathrm{dH}\left(\mathrm{u}_{\mathrm{i}} ; \boldsymbol{\nu}\right), \\
I_{i}^{\phi}(w)=\int_{0}^{\infty} u_{i}^{w} \exp \left\{-\frac{1}{2} u_{i} \mathrm{~d}_{\mathrm{i}}\right\} \phi_{1}\left(\sqrt{\mathrm{u}_{\mathrm{i}}^{1 / 2} \mathrm{~A}_{\mathrm{i}}}\right) \mathrm{dH}\left(\mathrm{u}_{\mathrm{i}} ; \boldsymbol{\nu}\right) .
\end{gathered}
$$

and $K_{i}(\boldsymbol{\theta})=I_{i}^{\Phi}\left(\frac{n_{i}}{2}\right)$. Direct substitution of $H$ in the integrals above yields immediately the following results for each distribution considered, namely

- Skew-t:

$$
\begin{aligned}
I_{i}^{\Phi}(w) & =\frac{2^{w} \nu^{\nu / 2} \Gamma(w+\nu / 2)}{\Gamma(\nu / 2)\left(\nu+\mathrm{d}_{\mathrm{i}}\right)^{/ 2+\mathrm{w}}} T\left(\sqrt{\frac{\nu+2 w}{\mathrm{~d}_{\mathrm{i}}+\nu}} \mathrm{A}_{i} ; \nu+2 w\right) \text { and } \\
I_{i}^{\phi}(w) & =\frac{2^{w} \nu^{\nu / 2} \Gamma\left(\frac{\nu+2 w}{2}\right)}{\sqrt{2 \pi} \Gamma(\nu / 2)\left(\mathrm{d}_{\mathrm{i}}+\mathrm{A}_{\mathrm{i}}^{2}+\nu\right)^{\frac{\nu+2 \mathrm{w}}{2}}}
\end{aligned}
$$

- Skew-slash:

$$
\begin{aligned}
& I_{i}^{\Phi}(w)=\frac{2^{2+w} \Gamma(\nu+w)}{\mathrm{d}_{\mathrm{i}}^{\nu+\mathrm{w}}} P_{1}\left(\nu+w, \frac{\mathrm{~d}_{\mathrm{i}}}{2}\right) E\left\{\Phi\left(S_{i}^{1 / 2} \mathrm{~A}_{i}\right)\right\} \text { and } \\
& I_{i}^{\phi}(w)=\frac{\nu 2^{\nu+w} \Gamma(\nu+w)}{\sqrt{2 \pi}\left(\mathrm{~d}_{\mathrm{i}}+\mathrm{A}_{\mathrm{i}}^{2}\right)^{\nu+\mathrm{w}}} P_{1}\left(\nu+w, \frac{\mathrm{~d}_{\mathrm{i}}+\mathrm{A}_{\mathrm{i}}^{2}}{2}\right),
\end{aligned}
$$

where $S_{i} \sim \operatorname{Gamma}\left(\nu+w, \frac{\mathrm{~d}_{\mathrm{i}}}{2}\right) \mathbb{I}_{(0,1)}$.

- Contaminated skew-normal:

$$
\begin{aligned}
I_{i}^{\Phi}(w) & =\sqrt{2 \pi}\left\{\nu_{1} \nu_{2}^{w-1 / 2} \phi_{1}\left(\mathrm{~d}_{\mathrm{i}} ; 0, \frac{1}{\nu_{2}}\right) \Phi\left(\nu_{2}^{1 / 2} \mathrm{~A}_{\mathrm{i}}\right)+\left(1-\nu_{1}\right) \phi_{1}\left(\sqrt{\mathrm{~d}_{\mathrm{i}}}\right) \Phi\left(\mathrm{A}_{\mathrm{i}}\right)\right\} \text { and } \\
I_{i}^{\phi}(w) & =\nu_{1} \nu_{2}^{w-1 / 2} \phi_{1}\left(\sqrt{\mathrm{~d}_{\mathrm{i}}+\mathrm{A}_{\mathrm{i}}^{2}} \mid 0, \nu_{2}^{-1}\right)+\left(1-\nu_{1}\right) \phi_{1}\left(\sqrt{\mathrm{~d}_{\mathrm{i}}+\mathrm{A}_{\mathrm{i}}^{2}}\right)
\end{aligned}
$$

the derivatives of $\log \boldsymbol{\Psi}_{i}, d_{i}, \mathrm{~A}_{i}$ and $K_{i}(\boldsymbol{\theta})$ involves tedious but not complicated algebraic manipulations and are given next. We consider the common situation in which $\boldsymbol{\Sigma}_{i}=\sigma_{e}^{2} \mathbf{R}_{i}$

- For $\log \boldsymbol{\Psi}_{i}$ :

$$
\begin{aligned}
& \frac{\partial \log \left|\boldsymbol{\Psi}_{i}\right|}{\partial \boldsymbol{\tau}}=\mathbf{0}, \text { for } \boldsymbol{\tau}=\boldsymbol{\beta}, \boldsymbol{\lambda} \text { and } \boldsymbol{\nu} \\
& \frac{\partial \log \left|\boldsymbol{\Psi}_{i}\right|}{\partial \sigma_{e}^{2}}=\operatorname{tr}\left(\boldsymbol{\Psi}^{-1} \mathbf{R}_{i}\right), \frac{\partial \log \left|\mathbf{\Psi}_{i}\right|}{\partial \alpha_{r}}=\operatorname{tr}\left(\boldsymbol{\Psi}^{-1} \mathbf{Z}_{i}\left(\dot{\mathbf{F}}_{r} \mathbf{F}+\mathbf{F} \dot{\mathbf{F}}_{r}\right) \mathbf{Z}_{i}^{\top}\right),
\end{aligned}
$$

## - For $A_{i}$ :

$$
\begin{aligned}
\frac{\partial A_{i}}{\partial \boldsymbol{\beta}} & =-\frac{1}{a_{i}} \mathbf{X}_{i}^{\top} \mathbf{\Psi}_{i}^{-1} \mathbf{Z}_{i} \mathbf{F} \boldsymbol{\lambda}, \\
\frac{\partial A_{i}}{\partial \boldsymbol{\lambda}} & =\frac{1}{a_{i}} \mathbf{F} \mathbf{Z}_{i}^{\top} \mathbf{\Psi}_{i}^{-1}\left(\mathbf{Y}_{i}-\mathbf{X}_{i} \boldsymbol{\beta}\right)-\frac{1}{a_{i}^{2}} A_{i} \mathbf{F}^{-1} \boldsymbol{\Lambda}_{i} \mathbf{F}^{-1} \boldsymbol{\lambda}, \\
\frac{\partial A_{i}}{\partial \sigma_{e}^{2}} & =-\frac{1}{a_{i}} \boldsymbol{\lambda}^{\top} \mathbf{F} \mathbf{Z}_{i}^{\top} \boldsymbol{\Psi}_{i}^{-1} \mathbf{R}_{i} \boldsymbol{\Psi}_{i}^{-1}\left(\mathbf{Y}_{i}-\mathbf{X}_{i} \boldsymbol{\beta}\right)-\frac{1}{2 \sigma_{e}^{4} a_{i}^{2}} A_{i} \boldsymbol{\lambda}^{\top} \mathbf{F}^{-1} \boldsymbol{\Lambda}_{i} \mathbf{Z}_{i}^{\top} \mathbf{R}_{i}^{-1} \mathbf{Z}_{i} \boldsymbol{\Lambda}_{i} \mathbf{F}^{-1} \boldsymbol{\lambda}, \\
\frac{\partial A_{i}}{\partial \alpha_{r}} & =\frac{1}{a_{i}} \boldsymbol{\lambda}^{\top} \dot{\mathbf{F}}_{r} \mathbf{Z}_{i}^{\top} \boldsymbol{\Psi}_{i}^{-1}\left(\mathbf{Y}_{i}-\mathbf{X}_{i} \boldsymbol{\beta}\right)-\frac{1}{a_{i}^{2}} \boldsymbol{\lambda}^{\top} \mathbf{F} \mathbf{Z}_{i}^{\top} \boldsymbol{\Psi}_{i}^{-1} \mathbf{Z}_{i}\left(\dot{\mathbf{F}}_{r} \mathbf{F}+\mathbf{F} \dot{\mathbf{F}}_{r}\right) \mathbf{Z}_{i}^{\top} \mathbf{\Psi}_{i}^{-1}\left(\mathbf{Y}_{i}-\mathbf{X}_{i} \boldsymbol{\beta}\right) \\
& -\frac{1}{2 a_{i}^{2}} A_{i} \boldsymbol{\lambda}^{\top} \mathbf{F}^{-1}\left(-\dot{\mathbf{F}}_{r} \mathbf{F}^{-1} \boldsymbol{\Lambda}_{i}-\boldsymbol{\Lambda}_{i} \mathbf{F}^{-1} \dot{\mathbf{F}}_{r}-\boldsymbol{\Lambda}_{i} \mathbf{F}^{-1}\left(-\dot{\mathbf{F}}_{r} \mathbf{F}^{-1}-\mathbf{F}^{-1} \dot{\mathbf{F}}_{r}\right) \mathbf{F}^{-1} \boldsymbol{\Lambda}_{i}\right) \mathbf{F}^{-1} \boldsymbol{\lambda},
\end{aligned}
$$

where $a_{i}=\left(1+\boldsymbol{\lambda}^{\top} \mathbf{F}^{-1} \boldsymbol{\Lambda}_{i} \mathbf{F}^{-1} \boldsymbol{\lambda}\right)^{1 / 2}$.

- For $d_{i}$ :

$$
\begin{aligned}
\frac{\partial d_{i}}{\partial \boldsymbol{\beta}} & =-2 \mathbf{X}_{i}^{\top} \mathbf{\Psi}_{i}^{-1}\left(\mathbf{Y}_{i}-\mathbf{X}_{i} \boldsymbol{\beta}\right), \quad \frac{\partial d_{i}}{\partial \boldsymbol{\lambda}}=\mathbf{0}, \\
\frac{\partial d_{i}}{\partial \sigma_{e}^{2}} & =-\left(\mathbf{Y}_{i}-\mathbf{X}_{i} \boldsymbol{\beta}\right)^{\top} \mathbf{\Psi}_{i}^{-1} \mathbf{R}_{i} \boldsymbol{\Psi}_{i}^{-1}\left(\mathbf{Y}_{i}-\mathbf{X}_{i} \boldsymbol{\beta}\right), \\
\frac{\partial d_{i}}{\partial \alpha_{r}} & =-\left(\mathbf{Y}_{i}-\mathbf{X}_{i} \boldsymbol{\beta}\right)^{\top} \mathbf{\Psi}_{i}^{-1} \mathbf{Z}_{i}\left(\dot{\mathbf{F}}_{r} \mathbf{F}+\mathbf{F} \dot{\mathbf{F}}_{r}\right) \mathbf{Z}_{i}^{\top} \mathbf{\Psi}_{i}^{-1}\left(\mathbf{Y}_{i}-\mathbf{X}_{i} \boldsymbol{\beta}\right),
\end{aligned}
$$

where $\dot{\mathbf{F}}_{r}=\frac{\partial \mathbf{F}}{\partial \alpha_{r}}$ and $r=1, \ldots, q(q+1) / 2$.

- For $K_{i}(\boldsymbol{\theta})$ :
- skew-t

$$
\begin{aligned}
\frac{\partial K_{i}(\boldsymbol{\theta})}{\partial \nu} & =\frac{1}{2}\left\{\log \frac{\nu}{2}+1-\Psi^{*}\left(\frac{\nu}{2}\right)\right\} I_{i}^{\Phi}\left(\frac{n_{i}}{2}\right)-\frac{1}{2} I_{i}^{\Phi}\left(\frac{n_{i}}{2}+1\right) \\
& +\frac{1}{2} \int_{0}^{\infty} u_{i}^{n_{i} / 2} \log u_{i} \exp \left\{-\frac{1}{2} u_{i} \mathrm{~d}_{\mathrm{i}}\right\} \Phi\left(\mathrm{u}_{\mathrm{i}}^{1 / 2} \mathrm{~A}_{\mathrm{i}}\right) \mathrm{h}\left(\mathrm{u}_{\mathrm{i}}, \nu\right) \mathrm{du}_{\mathrm{i}}
\end{aligned}
$$

where $\Psi^{*}=\frac{\partial \log (x)}{\partial x}$ is digamma function.

- skew-slash

$$
\frac{\partial K_{i}(\boldsymbol{\theta})}{\partial \nu}=I_{i}^{\Phi}\left(\frac{n_{i}}{2}+\nu-1\right)+\nu \int_{0}^{1} u_{i}^{n_{i} / 2+\nu-1} \log u_{i} \exp \left\{-\frac{1}{2} u_{i} \mathrm{~d}_{\mathrm{i}}\right\} \Phi\left(\mathrm{u}_{\mathrm{i}}^{1 / 2} \mathrm{~A}_{\mathrm{i}}\right) \mathrm{du}_{\mathrm{i}}
$$

- skew-contaminated normal

$$
\begin{aligned}
\frac{\partial K_{i}(\boldsymbol{\theta})}{\partial \nu_{1}} & =\nu_{2}^{n_{i} / 2} \exp \left\{-\frac{1}{2} \nu_{2} d_{i}\right\} \Phi_{1}\left(\nu_{2}^{1 / 2} A_{i}\right)-\exp \left\{-\frac{1}{2} d_{i}\right\} \Phi_{1}\left(A_{i}\right) \\
\frac{\partial K_{i}(\boldsymbol{\theta})}{\partial \nu_{2}} & =\nu_{1} \frac{n_{i}}{2} \nu_{2}^{n_{i} / 2-1} \exp \left\{-\frac{1}{2} \nu_{2} d_{i}\right\} \Phi_{1}\left(\nu_{2}^{1 / 2} A_{i}\right)-\frac{1}{2} \nu_{2}^{n_{i} / 2} d_{i} \exp \left\{-\frac{1}{2} \nu_{2} d_{i}\right\} \Phi_{1}\left(\nu_{2}^{1 / 2} A_{i}\right) \\
& +\frac{1}{2} \nu_{2}^{\left(n_{i}-1\right) / 2} A_{i} \exp \left\{-\frac{1}{2} \nu_{2} d_{i}\right\} \phi_{1}\left(\sqrt{\nu_{2}^{1 / 2} A_{i}}\right)
\end{aligned}
$$

## Appendix D: Additional simulation study results

## Simulation results for SSL-LMM

Table 1: Monte Carlo results based on 500 data sets, true $S S L_{1}(0,2,3,3)$ distribution for the random effects and $S L_{1}(0,0.25,3)$ for the random errors. MEAN and SD are average and standard deviation of the estimates, AVE SE is average of estimated standard errors. True values of parameters are in parentheses.

| Parameter | MEAN | SD | AVE SE | MEAN | SD | AVE SE | MEAN | SD | AVE SE |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | ( | SSL-LMM |  | (ii) SN-LMM |  |  | (iii) N-LMM |  |  |
| $\beta_{0}$ (1) | 1.0404 | 0.2855 | 0.2371 | 0.9651 | 0.2621 | 0.2560 | 2.2735 | 0.1728 | 0.1722 |
| $\beta_{1}(2)$ | 2.0000 | 0.0183 | 0.0191 | 2.0001 | 0.0191 | 0.0193 | 2.0001 | 0.0191 | 0.0198 |
| $\beta_{2}$ (1) | 1.0236 | 0.1995 | 0.1994 | 1.0344 | 0.2035 | 0.2082 | 1.0300 | 0.2294 | 0.2448 |
| $\sigma_{e}^{2}(0.25)$ | 0.2607 | 0.0375 | 0.0364 | 0.3715 | 0.0335 | 0.0256 | 0.3716 | 0.0334 | 0.0268 |
| $\sigma_{b}^{2}$ (2) | 2.0537 | 0.6060 | 0.5461 | 3.1105 | 0.8718 | 0.6604 | 1.3255 | 0.3248 | 0.2048 |
| $\lambda$ (3) | 4.1008 | 3.7138 | 3.3410 | 4.3293 | 2.5387 | 2.5377 | - | - | - |
| $\nu$ (4) | 4.9442 | 5.5248 | 9.3553 | - | - | - | - | - | - |

Figure 1: Simulation study based on 500 data sets of SSL-LMM. (a) box-plot of the mean absolute difference of the estimated and simulated random effects for the 100 individuals. (b) True density of the random effects (solid line) and Monte Carlo average estimated densities for 500 data set: using N-LMM (dashed-dotted), SN-LMM (dotted) and SSLLMM (dotted-line) fitted. The solid lines are the respective mean.



## Simulation results for SCN-LMM

Table 2: Monte Carlo results based on 500 data sets, true $S C N_{1}(0,2,3,0.3,0.3)$ distribution for the random effects and $C N_{1}(0,0.25,0.3,0.3)$ for the random errors. MEAN and SD are average and standard deviation of the estimates, AVE SE is average of estimated standard errors. True values of parameters are in parentheses.

|  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Parameter | MEAN | SD | AVE SE | MEAN | SD | AVE SE | MEAN | SD | AVE SE |  |  |  |  |  |  |
|  | $(\mathrm{i})$ |  | SCN-LMM | (ii) |  |  |  |  |  |  |  | SN-LMM |  | (iii) | N-LMM |
| $\beta_{0}(1)$ | 1.0375 | 0.2416 | 0.2195 | 0.8750 | 0.2126 | 0.1996 | 2.3463 | 0.1916 | 0.1878 |  |  |  |  |  |  |
| $\beta_{1}(2)$ | 1.9989 | 0.0179 | 0.0194 | 1.9990 | 0.0196 | 0.0207 | 1.9990 | 0.0196 | 0.0210 |  |  |  |  |  |  |
| $\beta_{2}(1)$ | 0.9991 | 0.1965 | 0.2034 | 1.0145 | 0.2050 | 0.2164 | 1.0199 | 0.2664 | 0.2662 |  |  |  |  |  |  |
| $\sigma_{e}^{2}(0.25)$ | 0.2438 | 0.0397 | 0.0349 | 0.4235 | 0.0438 | 0.0295 | 0.4238 | 0.0440 | 0.0304 |  |  |  |  |  |  |
| $\sigma_{b}^{2}(2)$ | 1.9514 | 0.5864 | 0.5381 | 3.8002 | 0.9099 | 0.7080 | 1.5867 | 0.3504 | 0.2430 |  |  |  |  |  |  |
| $\lambda(3)$ | 4.4608 | 4.1936 | 3.9464 | 5.4969 | 2.7730 | 3.0077 | - | - | - |  |  |  |  |  |  |
| $\nu(0.3)$ | 0.3208 | 0.1220 | 0.1079 | - | - | - | - | - | - |  |  |  |  |  |  |
| $\gamma(0.3)$ | 0.2961 | 0.0515 | 0.0536 | - | - | - | - | - | - |  |  |  |  |  |  |

Figure 2: Simulation study based on 500 data sets of SCN-LMM. (a) box-plot of the mean absolute difference of the estimated and simulated random effects for the 100 individuals. (b) True density of the random effects (solid line) and Monte Carlo average estimated densities for 500 data set: using N-LMM (dashed-dotted), SN-LMM (dotted) and SCNLMM (dotted-line) fitted. The solid lines are the respective mean.


