

**SUPPLEMENTARY MATERIAL FOR
“AN APPROXIMATE BAYESIAN APPROACH
TO MODEL-ASSISTED SURVEY ESTIMATION
WITH MANY AUXILIARY VARIABLES”**

Shonosuke Sugasawa¹ and Jae Kwang Kim²

¹*The University of Tokyo and* ²*Iowa State University*

This Supplementary Material contains a proof of (5), details of posterior computation, proofs of theorems and results of additional simulation suites.

S1 Proof of (2.5)

We assume the same conditions in the proof of Theorem 1, given in Section S3. From (2.4), we have

$$\begin{aligned} E(R_n) &= -E \left\{ (\hat{\mathbf{X}}_{\text{HT}} - \bar{\mathbf{X}}_N)^t (\hat{\boldsymbol{\beta}}_1 - \boldsymbol{\beta}_{1*}) \right\} = -\text{tr} \left\{ \text{Cov} \left(\hat{\mathbf{X}}_{\text{HT}}, \hat{\boldsymbol{\beta}}_1 \right) \right\} \\ &= -\sum_{j=1}^p \text{Cov} \left(\hat{x}_{\text{HT},j}, \hat{\beta}_j \right) = O(p/n), \end{aligned}$$

where the expectation is taken with respect to the sampling distribution. Also, we can show that $V(R_n) = O(p/n^2)$. Therefore, using Chebychev inequality, we have $R_n = O_p(p/n)$ and result (2.5) follows.

S2 Posterior computation

We provide the algorithm for generating the approximate posterior distribution of β_1 given in (4.20) with two shrinkage priors, Laplace and horseshoe (4.18) priors. Using the mixture representation of both priors, we get the following Gibbs sampling algorithm.

Laplace prior

We consider the mixture representation of Laplace distribution: $\beta_k|\tau_k \sim N(0, \tau_k^2)$ and $\tau_k^2 \sim \text{Exp}(\lambda^2/2)$, independently, for $k = 1, \dots, p$. For λ^2 , we consider the conjugate prior $\text{Ga}(a, b)$, where $\text{Ga}(a, b)$ is a gamma distribution with shape parameter a and rate parameter b . The full conditional distribution of β_1 is multivariate normal with mean $\mathbf{A}^{-1}\hat{\mathbf{V}}_{\beta_{11}}^{-1}\hat{\beta}_1$ and variance-covariance matrix \mathbf{A}^{-1} where $\mathbf{A} = \hat{\mathbf{V}}_{\beta_{11}}^{-1} + \mathbf{D}^{-1}$ with $\mathbf{D} = \text{diag}(\tau_1^2, \dots, \tau_p^2)$. The full conditional distribution of λ^2 is $\text{Ga}(a + p, b + \sum_{k=1}^p \tau_k^2/2)$, and $\tau_1^2, \dots, \tau_p^2$ are conditionally independent, with $1/\tau_j^2$ conditionally inverse-Gaussian with parameters $\mu = \sqrt{\lambda/\beta_j^2}$ in the parametrization of the inverse-Gaussian density given by

$$f(x) = \sqrt{\frac{\lambda}{2\pi}} x^{-3/2} \exp\left\{-\frac{\lambda(x-\mu)^2}{2\mu^2 x}\right\}, \quad x > 0.$$

Horseshoe prior

The prior for β_1 can be expressed as a hierarchy: $\beta_k|u_k \sim N(0, \lambda^2 u_k^2)$ and $u_k \sim \text{HC}(0, 1)$ independently for $k = 1, \dots, p$, where $\text{HC}(0, 1)$ is the standard half-Cauchy distribution. Using the hierarchical expression of the half-Cauchy distribution, we obtain the following Gibbs sampling steps. Let $\mathbf{A} = \hat{\mathbf{V}}_{\beta_{11}}^{-1} + \mathbf{B}^{-1}$, where $\mathbf{B} = \lambda^2 \text{diag}(u_1^2, \dots, u_p^2)$. The full conditional distribution of β_1 is multivariate normal with mean $\mathbf{A}^{-1}\hat{\mathbf{V}}_{\beta_{11}}^{-1}\hat{\beta}_1$ and variance-covariance matrix \mathbf{A}^{-1} . The

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full conditional distribution of u_k^2 and λ^2 are, respectively, give by

$$\text{IG}\left(1, \frac{1}{\xi_k} + \frac{\beta_k^2}{2\lambda^2}\right) \quad \text{and} \quad \text{IG}\left(\frac{p+1}{2}, \frac{1}{\gamma} + \frac{1}{2} \sum_{k=1}^p \frac{\beta_k^2}{u_k^2}\right),$$

where $\text{IG}(a, b)$ denotes an inverse-Gamma distribution with shape parameter a and rate parameter b . Here ξ_k and γ are additional latent variables, and their full conditional distributions are given by $\text{IG}(1, 1 + 1/u_k^2)$ and $\text{IG}(1, 1 + 1/\lambda^2)$, respectively.

S3 A sketched proof of Theorem 1

To discuss the asymptotic properties of the approximate Bayesian method, we first assume a sequence of finite populations and samples with finite fourth moments as in Isaki and Fuller (1982). The finite population is a random sample from an unknown superpopulation model. Let \bar{Y}_* and β_{1*} be the probability limit of \hat{Y}_{HT} and $\hat{\beta}_1$, respectively. Let $B_n = (\bar{Y}_* - r_n, \bar{Y}_* + r_n)$ and C_n be a ball with centre β_{1*} and radius $r_n \sim n^{\tau-1/2}$ for $0 < \tau < 1/2$. Furthermore, let Θ_β and Θ_Y be the supports of the prior distributions of β_1 and $\bar{Y}|\beta_1$. We make the following regularity assumptions:

(C1) Assume that the sufficient conditions for the asymptotic normality of \hat{Y}_{reg} for $\bar{Y} \in B_n$ hold for the sequence of finite populations and samples.

(C2) For fixed $\beta_1 \in \Theta_\beta$, assume that the conditional prior distribution $\pi(\bar{Y}|\beta_1)$ is positive and satisfies a Lipschitz condition over its support Θ_Y , that is, there exists $C_1(\beta_1) < \infty$ such that $|\pi(\theta_1|\beta_1) - \pi(\theta_2|\beta_1)| \leq C_1(\beta_1)|\theta_1 - \theta_2|$ for $\theta_1, \theta_2 \in \Theta_Y$ and $\beta_1 \in \Theta_\beta$.

(C3) Assume that $\hat{\mathbf{V}}_{\beta_{11}} = \mathbf{V}_{\beta_{11}}\{1 + o_P(1)\}$ and $(\hat{\beta}_1 - \beta_1)^t \hat{\mathbf{V}}_{\beta_{11}}^{-1} (\hat{\beta}_1 - \beta_1) = (\hat{\beta}_1 - \beta_1)^t \mathbf{V}_{\beta_{11}}^{-1} (\hat{\beta}_1 - \beta_1)\{1 + o_P(1)\}$ for any $\beta_1 \in C_n$ and $n \rightarrow \infty$.

(C4) Assume that $\pi(\boldsymbol{\beta}_1)$ is positive and finite over its support Θ_β .

Sufficient conditions for (C1) are discussed within various asymptotic structures (e.g. Binder, 1983; Pfeffermann and Sverchkov, 2009). Conditions (C2) and (C4) are satisfied for common priors such as (multivariate) normal distribution. Condition (C3) essentially requires that the design variance estimators be consistent and meet a certain continuity condition.

Proof. Let $g(\bar{Y}, \boldsymbol{\beta}) = \phi(\hat{Y}_{\text{reg}}(\boldsymbol{\beta}_1); \bar{Y}, \hat{V}_e(\boldsymbol{\beta}))\phi_p(\hat{\boldsymbol{\beta}}_1; \boldsymbol{\beta}_1, \hat{\mathbf{V}}_{\beta_{11}})\pi(\boldsymbol{\beta}_1)\pi(\bar{Y}|\boldsymbol{\beta}_1)$. Then, the approximated posterior distribution is given by

$$p(\bar{Y}|\hat{Y}_{\text{reg}}(\hat{\boldsymbol{\beta}}_1), \hat{\boldsymbol{\beta}}_1) = \frac{\int g(\bar{Y}, \boldsymbol{\beta}_1)d\boldsymbol{\beta}_1}{\iint g(\bar{Y}, \boldsymbol{\beta}_1)d\boldsymbol{\beta}_1 d\bar{Y}}.$$

Note that

$$\int g(\bar{Y}, \boldsymbol{\beta}_1)d\boldsymbol{\beta}_1 = \int_{C_n} g(\bar{Y}, \boldsymbol{\beta}_1)d\boldsymbol{\beta}_1 + \int_{\mathbb{R}^p \setminus C_n} g(\bar{Y}, \boldsymbol{\beta}_1)d\boldsymbol{\beta}_1 \quad (\text{S3.1})$$

By the same argument in the proof of Theorem 1 in Wang et al. (2018), we have

$$\text{plim}_{n \rightarrow \infty} \int_{C_n} \phi_p(\hat{\boldsymbol{\beta}}_1; \boldsymbol{\beta}_1, \hat{\mathbf{V}}_{\beta_{11}})d\boldsymbol{\beta}_1 = 1,$$

so the second term in (S3.1) is $o_P(1)$. On the other hand, under condition (C3), $\phi_p(\hat{\boldsymbol{\beta}}_1; \boldsymbol{\beta}_1, \hat{\mathbf{V}}_{\beta_{11}}) = \phi_p(\hat{\boldsymbol{\beta}}_1; \boldsymbol{\beta}_1, \mathbf{V}_{\beta_{11}})\{1 + o_P(1)\}$ as $n \rightarrow \infty$, for any $\boldsymbol{\beta}_1 \in C_n$, thereby under condition (C4),

$$\begin{aligned} \int_{C_n} g(\bar{Y}, \boldsymbol{\beta}_1)d\boldsymbol{\beta}_1 &= \int_{C_n} \phi(\hat{Y}_{\text{reg}}(\boldsymbol{\beta}_1); \bar{Y}, \hat{V}_e(\boldsymbol{\beta}_1))\phi_p(\hat{\boldsymbol{\beta}}_1; \boldsymbol{\beta}_1, \mathbf{V}_{\beta_{11}})\pi(\boldsymbol{\beta}_1)d\pi(\bar{Y}|\boldsymbol{\beta}_1)\boldsymbol{\beta}_1 \\ &= \phi(\hat{Y}_{\text{reg}}(\boldsymbol{\beta}_{1*}); \bar{Y}, \hat{V}_e(\boldsymbol{\beta}_{1*}))\pi(\boldsymbol{\beta}_{1*})\pi(\bar{Y}|\boldsymbol{\beta}_{1*})\{1 + o_P(1)\} \end{aligned}$$

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as $n \rightarrow \infty$ since $V \rightarrow 0$ and $\hat{\beta}_1 \rightarrow \beta_{1*}$ as $n \rightarrow \infty$. Hence, we have

$$\begin{aligned} p(\bar{Y}|\hat{Y}_{\text{reg}}(\hat{\beta}_1), \hat{\beta}_1) &= \frac{\pi(\beta_{1*})\phi(\hat{Y}_{\text{reg}}(\beta_{1*}); \bar{Y}, \hat{V}_e(\beta_{1*}))\pi(\bar{Y}|\beta_{1*})\{1 + o_P(1)\}}{\pi(\beta_{1*}) \int \phi(\hat{Y}_{\text{reg}}(\beta_{1*}); \bar{Y}, \hat{V}_e(\beta_{1*}))\pi(\bar{Y}|\beta_{1*})d\bar{Y}\{1 + o_P(1)\}} \\ &= \frac{\pi(\bar{Y}|\beta_{1*})}{\pi(\bar{Y}_*|\beta_{1*})}\phi(\hat{Y}_{\text{reg}}(\beta_{1*}); \bar{Y}, \hat{V}_e(\beta_{1*}))\{1 + o_P(1)\} \\ &= \phi(\hat{Y}_{\text{reg}}(\beta_{1*}); \bar{Y}, \hat{V}_e(\beta_{1*}))\{1 + o_P(1)\} \end{aligned} \quad (\text{S3.2})$$

$$= \phi(\hat{Y}_{\text{reg}}(\hat{\beta}_1); \bar{Y}, \hat{V}_e(\hat{\beta}_1))\{1 + o_P(1)\}, \quad (\text{S3.3})$$

for any $\bar{Y} \in B_n$ as $n \rightarrow \infty$, where (S3.2) follows from (C2), and (S3.3) follows from the properties $\hat{V}_e(\hat{\beta}_1) = \hat{V}_e(\beta_{1*})\{1 + o_P(1)\}$ and $\hat{Y}_{\text{reg}}(\hat{\beta}_1) = \hat{Y}_{\text{reg}}(\beta_{1*})\{1 + o_P(1)\}$ under (C1).

Let $R_n = \{\bar{Y} \in \Theta_Y : \hat{V}_e(\hat{\beta}_1)^{-1}(\hat{Y}_{\text{reg}}(\hat{\beta}_1) - \bar{Y})^2 \leq \chi_1^2(q)\}$, where $\chi_k^2(q)$ is the upper $100q\%$ -quantile of the chi-squared distribution with k degree of freedom. Then, $\text{plim}_{n \rightarrow \infty} P(R_n) = q$.

Since $\hat{Y}_{\text{reg}}(\hat{\beta}_1) - \bar{Y}_* = O_p(n^{-1/2})$ and $r_n = n^{\tau-1/2}$, which is slower than $n^{-1/2}$, it holds that $\lim_{n \rightarrow \infty} P(R_n \subset B_n) = 1$. Then,

$$\lim_{n \rightarrow \infty} P\left(\int_{B_n} \phi(\hat{Y}_{\text{reg}}(\hat{\beta}_1); \bar{Y}, \hat{V}_e(\hat{\beta}_1))d\bar{Y} \geq \int_{R_n} \phi(\hat{Y}_{\text{reg}}(\hat{\beta}_1); \bar{Y}, \hat{V}_e(\hat{\beta}_1))d\bar{Y}\right) = 1,$$

which means that

$$\lim_{n \rightarrow \infty} P\left(\int_{B_n} \phi(\hat{Y}_{\text{reg}}(\hat{\beta}_1); \bar{Y}, \hat{V}_e(\hat{\beta}_1))d\bar{Y} \geq q\right) = 1$$

for any $q \in (0, 1)$, implying

$$\text{plim}_{n \rightarrow \infty} \int_{B_n} \phi(\hat{Y}_{\text{reg}}(\hat{\beta}_1); \bar{Y}, \hat{V}_e(\hat{\beta}_1))d\bar{Y} = 1. \quad (\text{S3.4})$$

Then,

$$\begin{aligned} &\sup_{\bar{Y} \in \Theta_Y} \left| p(\bar{Y}|\hat{Y}_{\text{reg}}(\hat{\beta}_1), \hat{\beta}_1) - \phi(\bar{Y}; \hat{Y}_{\text{reg}}(\hat{\beta}_1), \hat{V}_e(\hat{\beta}_1)) \right| \\ &\leq \sup_{\bar{Y} \in B_n} \left| p(\bar{Y}|\hat{Y}_{\text{reg}}(\hat{\beta}_1), \hat{\beta}_1) - \phi(\bar{Y}; \hat{Y}_{\text{reg}}(\hat{\beta}_1), \hat{V}_e(\hat{\beta}_1)) \right| \\ &\quad + \sup_{\bar{Y} \in \Theta_Y \setminus B_n} \left| p(\bar{Y}|\hat{Y}_{\text{reg}}(\hat{\beta}_1), \hat{\beta}_1) - \phi(\bar{Y}; \hat{Y}_{\text{reg}}(\hat{\beta}_1), \hat{V}_e(\hat{\beta}_1)) \right|, \end{aligned}$$

which are both $o_P(1)$ from (S3.3) and (S3.4). This completes the proof. \square

S4 A sketched proof of Theorem 2

The condition (C4) given in the proof of Theorem 1 may not be satisfied for shrinkage priors.

For example, the horseshoe prior diverge at the origin $\beta_k = 0$. In what follows, let $\boldsymbol{\beta} = (\beta_0, \boldsymbol{\beta}_1^t)$

and define $\hat{\boldsymbol{\beta}}_1$ and $\hat{\boldsymbol{\beta}}_1^{(R)}$ in the same way. We use the following alternative condition for the shrinkage prior $\pi_\lambda(\boldsymbol{\beta}_1)$:

- (C5) The regularized estimator $\hat{\boldsymbol{\beta}}_1^{(R)}$ under penalty $-\log \pi_\lambda(\boldsymbol{\beta}_1)$ is asymptotically normal, that is, $\sqrt{n}(\hat{\boldsymbol{\beta}}_1^{(R)} - \boldsymbol{\beta}_{1*}) \rightarrow N(0, \mathbf{C})$, where \mathbf{C} is a positive definite matrix and λ is appropriately chosen.

Under the Laplace prior, $\hat{\boldsymbol{\beta}}_1^{(R)}$ is equivalent to the Lasso estimator, and the above property holds if $\lambda = o(\sqrt{n})$ (Knight and Fu, 2000; McConville et al., 2017). For general prior $\pi_\lambda(\boldsymbol{\beta}_1)$, this condition holds if the assumption regarding the penalty term $P_\lambda(\boldsymbol{\beta}_1)$ given in Fan and Li (2001) is satisfied.

Proof. It is noted that

$$\begin{aligned} & \phi_p(\hat{\boldsymbol{\beta}}_1; \boldsymbol{\beta}_1, \hat{\mathbf{V}}_{\beta_{11}}) \pi_\lambda(\boldsymbol{\beta}_1) \\ & \propto \exp \left\{ -\frac{1}{2} (\hat{\boldsymbol{\beta}}_1 - \boldsymbol{\beta}_1)^t \hat{\mathbf{V}}_{\beta_{11}}^{-1} (\hat{\boldsymbol{\beta}}_1 - \boldsymbol{\beta}_1) + \log \pi_\lambda(\boldsymbol{\beta}_1) \right\} \\ & = \exp \left\{ -\frac{1}{2} \max_{\beta_0} \sum_{i \in A} \frac{1}{\pi_i} (y_i - \beta_0 - x_i^t \boldsymbol{\beta}_1)^2 + \log \pi_\lambda(\boldsymbol{\beta}_1) \right\} \{1 + o_P(1)\} \\ & = \exp \left\{ -\frac{n}{2} (\hat{\boldsymbol{\beta}}_1^{(R)} - \boldsymbol{\beta}_1)^t \mathbf{C}^{-1} (\hat{\boldsymbol{\beta}}_1^{(R)} - \boldsymbol{\beta}_1) \right\} \{1 + o_P(1)\}. \end{aligned}$$

Define

$$g(\bar{Y}, \boldsymbol{\beta}_1) = \phi(\hat{Y}_{\text{reg}}(\boldsymbol{\beta}_1); \bar{Y}, \hat{V}_e(\boldsymbol{\beta}_1)) \phi(\hat{\boldsymbol{\beta}}_1; \boldsymbol{\beta}_1, \hat{\mathbf{V}}_{\beta_{11}}) \pi_\lambda(\boldsymbol{\beta}_1) \pi(\bar{Y} | \boldsymbol{\beta}_1).$$

Then, it holds that

$$\int_{S_n} g(\bar{Y}, \boldsymbol{\beta}_1) d\boldsymbol{\beta}_1 = \phi(\hat{Y}_{\text{reg}}(\boldsymbol{\beta}_{1*}); \bar{Y}, \hat{V}_e(\boldsymbol{\beta}_{1*})) \pi_\lambda(\boldsymbol{\beta}_{1*}) \pi(\bar{Y} | \boldsymbol{\beta}_{1*}) \{1 + o_P(1)\}$$

S5. ADDITIONAL SIMULATION RESULTS

as $n \rightarrow \infty$, where S_n is a ball with center β_{1*} and radius $O(n^{\tau-1/2})$ for $0 < \tau < 1/2$. Hence, the statement can be proved in the same way as the proof of Theorem 1 since $\phi(\hat{Y}_{\text{reg}}(\beta_{1*}); \bar{Y}, \hat{V}_e(\beta_{1*})) = \phi(\hat{Y}_{\text{reg}}(\hat{\beta}_1^{(R)}); \bar{Y}, \hat{V}_e(\hat{\beta}_1^{(R)}))\{1 + o_P(1)\}$. \square

S5 Additional simulation results

We here provide additional simulation results. We first considered the same scenarios in the main document with larger sample size, namely, $n = 400$. The results are reported in Tables S1-S4. We can see the almost the same tendency confirmed in Tables 2-5 in the main document.

We next adopted two additional scenarios for the data generating processes. For simplicity, we here consider only linear regression with $n = 300$. In the first scenario, we generate $x_i = (x_{i1}, \dots, x_{ip^*})$ from a p^* -dimensional multivariate normal distribution with vector $(1, \dots, 1)^t$ and variance-covariance matrix $2R(0.5)$, so the correlations among the covariates are stronger than those in the main document. We set $\beta_0 = 1$ (non-zero intercept) and set the other settings to the same ones in the main document. In the second scenario, we investigate potential effects of unobserved covariates. To this end, we first generated (w_i, x_i^t) from a $(p^* + 1)$ -dimensional multivariate normal distribution with vector $(1, \dots, 1)^t$ and variance-covariance matrix $2R(0.5)$. Then, the response variables Y_i are generated from the following linear regression model:

$$Y_i = \beta_0 + \delta w_i + \beta_1 x_{i1} + \dots + \beta_{p^*} x_{ip^*} + \varepsilon_i, \quad i = 1, \dots, N,$$

where $\varepsilon_i \sim N(0, 2)$. We set $\delta = 1$, $(\beta_0, \beta_1, \beta_4, \beta_7, \beta_{10}) = (1, 1, -0.5, 1, -0.5)$ and the other β_k 's are set to zero. Although the covariate w_i is included in the data generating process, we estimate the population mean by using only x_i . Therefore, w_i is the unobserved covariate and the working model used in the model-assisted methods is misspecified. Under the two scenarios, we applied the same methods adopted in the main document and evaluated their performance

in terms of MSE, Bias, CP and AL, where the results are shown in Tables S5-S8. We can again see the almost the same tendency confirmed in Tables 2-5 in the main document.

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Table S1: Square root of Mean squared errors (RMSE) and bias of point estimators under $p \in \{20, 30, 40, 50\}$ and $n = 400$ in scenarios (A) and (B) with linear regression. All values are multiplied by 100.

		(A)				(B)			
Method		20	30	40	50	20	30	40	50
RMSE	GREG	10.3	10.4	10.6	10.9	9.9	10.1	10.3	10.5
	GREG-L	10.2	10.2	10.2	10.3	9.6	9.6	9.6	9.6
	GREG-R	10.3	10.5	10.7	10.9	9.8	10.0	10.2	10.3
	GREG-V	10.2	10.4	10.5	10.7	9.8	9.9	10.1	10.2
	GREG-M	10.3	10.4	10.6	10.9	9.9	10.1	10.3	10.5
	AB	10.3	10.5	10.7	11.0	10.0	10.2	10.5	10.6
	ABL	10.3	10.4	10.6	10.8	9.9	10.0	10.2	10.3
	ABH	10.2	10.2	10.3	10.3	9.7	9.7	9.8	9.8
	HT	14.8	14.8	14.8	14.8	12.6	12.6	12.6	12.6
	Bias	GREG	-0.15	-0.13	-0.18	-0.22	0.43	0.93	1.39
GREG-L		-0.22	-0.22	-0.25	-0.24	0.12	0.18	0.25	0.34
GREG-R		-0.18	-0.18	-0.22	-0.26	0.44	0.94	1.39	1.87
GREG-V		-0.21	-0.22	-0.24	-0.23	0.27	0.62	0.95	1.30
GREG-M		-0.15	-0.13	-0.18	-0.22	0.43	0.93	1.39	1.86
AB		-0.17	-0.16	-0.20	-0.24	0.43	0.93	1.37	1.85
ABL		-0.19	-0.18	-0.22	-0.25	0.38	0.80	1.17	1.56
ABH		-0.20	-0.20	-0.21	-0.25	0.14	0.30	0.46	0.63
HT		-0.29	-0.29	-0.29	-0.29	-0.39	-0.39	-0.39	-0.39

Table S2: Coverage probabilities (CP) and average lengths (AL) of 95% confidence/credible intervals under $p \in \{20, 30, 40, 50\}$ and $n = 400$ in scenarios (A) and (B) with linear regression. All values are multiplied by 100.

		(A)				(B)			
Method		20	30	40	50	20	30	40	50
CP	GREG	93.8	92.4	91.1	89.4	94.0	92.6	91.5	91.4
	GREG-L	94.2	94.0	94.1	93.9	94.9	94.4	94.8	94.5
	GREG-R	93.3	92.2	91.8	90.1	94.4	93.0	91.7	91.7
	GREG-V	94.1	93.3	92.8	90.9	94.5	94.0	92.8	92.4
	GREG-M	94.0	93.0	92.8	91.6	94.9	93.7	93.5	93.5
	AB	94.2	94.2	94.5	94.4	95.6	95.5	94.3	94.7
	ABL	94.2	94.3	94.9	94.9	95.6	95.0	94.5	94.6
	ABH	94.6	94.8	94.6	94.4	95.2	95.3	95.5	95.5
	HT	94.2	94.2	94.2	94.2	94.8	94.8	94.8	94.8
	AL	GREG	37.4	36.9	36.4	35.9	37.6	37.1	36.6
GREG-L		37.9	37.8	37.7	37.7	37.7	37.6	37.5	37.4
GREG-R		37.5	37.0	36.6	36.2	37.4	36.9	36.4	35.9
GREG-V		37.6	37.2	36.8	36.4	37.8	37.5	37.2	36.8
GREG-M		38.1	38.1	38.2	38.2	38.4	38.5	38.6	38.7
AB		39.2	39.5	39.9	40.2	39.6	40.2	40.8	41.3
ABL		39.0	39.2	39.5	39.6	39.4	39.8	40.2	40.5
ABH		38.8	38.8	38.8	38.9	39.0	39.2	39.3	39.3
HT		57.5	57.5	57.5	57.5	51.1	51.1	51.1	51.1

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Table S3: Square root of Mean squared errors (RMSE) and bias of point estimators under $p \in \{20, 30, 40, 50\}$ and $n = 400$ in scenarios (A) and (B) with logistic regression. All values are multiplied by 100.

		(A)				(B)			
Method		20	30	40	50	20	30	40	50
RMSE	GREG	1.90	1.91	1.93	1.97	1.94	1.98	2.00	2.06
	GREG-L	1.86	1.87	1.87	1.87	1.90	1.91	1.91	1.92
	GREG-R	1.88	1.89	1.91	1.93	1.93	1.97	1.98	2.02
	AB	1.89	1.89	1.91	1.93	1.93	1.96	1.98	2.01
	ABL	1.88	1.88	1.89	1.90	1.91	1.91	1.89	1.88
	ABH	1.87	1.87	1.88	1.89	1.88	1.87	1.86	1.87
	HT	2.36	2.36	2.36	2.36	2.39	2.39	2.39	2.39
Bias	GREG	-0.03	-0.03	-0.03	-0.05	-0.05	0.01	0.08	0.19
	GREG-L	-0.02	-0.01	-0.01	-0.02	-0.12	-0.11	-0.10	-0.09
	GREG-R	-0.03	-0.02	-0.02	-0.04	-0.07	-0.02	0.02	0.09
	AB	-0.04	-0.03	-0.03	-0.06	-0.06	0.00	0.06	0.15
	ABL	-0.03	-0.02	-0.01	0.00	-0.07	-0.02	0.02	0.08
	ABH	-0.02	-0.02	-0.02	-0.02	-0.11	-0.11	-0.11	-0.11
	HT	0.01	0.01	0.01	0.01	-0.12	-0.12	-0.12	-0.12

Table S4: Coverage probabilities (CP) and average lengths (AL) of 95% credible/confidence intervals under $p \in \{20, 30, 40, 50\}$ and $n = 400$ in scenarios (A) and (B) with logistic regression. All values are multiplied by 100.

		(A)				(B)			
Method		20	30	40	50	20	30	40	50
	GREG	92.8	91.2	90.6	89.5	92.9	91.8	91.5	89.6
	GREG-L	93.0	92.9	92.9	93.0	94.3	94.3	94.5	94.0
	GREG-R	93.2	91.9	91.0	91.0	93.3	92.6	91.7	91.9
CP	AB	94.4	94.6	94.6	95.0	95.2	95.5	95.8	96.0
	ABL	94.5	94.4	95.3	95.3	95.2	95.8	96.7	97.4
	ABH	94.9	94.6	94.7	95.9	96.0	96.4	96.7	97.3
	HT	95.9	95.9	95.9	95.9	95.5	95.5	95.5	95.5
	GREG	7.01	6.87	6.73	6.58	7.27	7.12	6.96	6.79
	GREG-L	7.12	7.09	7.07	7.05	7.40	7.37	7.35	7.32
	GREG-R	7.09	6.98	6.88	6.81	7.36	7.24	7.14	7.05
AL	AB	7.47	7.57	7.67	7.78	7.80	7.92	8.06	8.24
	ABL	7.49	7.60	7.72	7.86	7.80	7.93	8.06	8.22
	ABH	7.45	7.54	7.65	7.78	7.75	7.83	7.94	8.06
	HT	9.60	9.60	9.60	9.60	9.53	9.53	9.53	9.53

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Table S5: RMSE and bias of point estimators under $p \in \{20, 30, 40, 50\}$ and $n = 300$ in scenarios (A) and (B), where the simulated data is generated from linear regression with non-zero intercept and higher correlations among covariates. All values are multiplied by 100.

		(A)				(B)			
Method		20	30	40	50	20	30	40	50
RMSE	GREG	11.9	12.0	12.1	12.4	11.7	11.7	11.9	12.2
	GREG-L	11.5	11.5	11.5	11.5	11.5	11.5	11.4	11.5
	GREG-R	11.7	11.7	11.8	12.1	11.7	11.9	12.1	12.3
	GREG-V	11.9	11.9	12.0	12.2	11.6	11.6	11.7	11.8
	GREG-M	11.9	12.0	12.1	12.4	11.7	11.7	11.9	12.2
	AB	11.7	11.8	12.0	12.4	11.2	11.4	11.8	12.3
	ABL	11.6	11.6	11.8	12.1	11.0	11.2	11.3	11.6
	ABH	11.5	11.5	11.6	11.7	10.8	10.9	10.9	10.9
	HT	16.2	16.2	16.2	16.2	13.6	13.6	13.6	13.6
	Bias	GREG	-1.08	-1.23	-1.26	-1.35	-0.53	0.33	1.07
GREG-L		0.02	0.02	0.03	0.06	-0.02	0.18	0.33	0.46
GREG-R		0.11	0.05	0.10	0.13	0.76	1.75	2.54	3.31
GREG-V		-0.56	-0.71	-0.73	-0.66	-0.27	0.46	0.97	1.60
GREG-M		-1.08	-1.23	-1.26	-1.35	-0.53	0.33	1.07	1.96
AB		0.16	0.12	0.22	0.21	1.07	2.17	3.11	4.08
ABL		0.13	0.09	0.15	0.15	0.86	1.74	2.45	3.09
ABH		0.10	0.04	0.05	0.07	0.28	0.62	0.90	1.17
HT		-0.08	-0.08	-0.08	-0.08	-1.61	-1.61	-1.61	-1.61

Table S6: CP and AL of 95% credible/confidence intervals under $p \in \{20, 30, 40, 50\}$ and $n = 300$ in scenarios (A) and (B), where the simulated data is generated from linear regression with non-zero intercept and higher correlations among covariates. All values are multiplied by 100.

		(A)				(B)			
	Method	20	30	40	50	20	30	40	50
CP	GREG	94.3	93.2	92.2	90.9	94.2	93.3	92.6	90.7
	GREG-L	94.3	94.5	93.9	93.8	95.6	95.5	95.3	95.3
	GREG-R	94.4	93.9	93.5	92.3	94.2	93.6	92.0	90.9
	GREG-V	94.2	94.3	93.8	93.4	94.7	94.2	93.9	93.4
	GREG-M	94.7	94.7	94.2	93.6	95.3	95.3	94.4	92.9
	AB	95.1	95.1	95.1	94.3	95.4	95.1	95.1	94.4
	ABL	95.1	95.1	95.0	94.7	95.6	95.2	95.7	95.4
	ABH	95.4	94.9	94.8	94.7	95.9	95.7	95.6	95.9
	HT	95.5	95.5	95.5	95.5	95.4	95.4	95.4	95.4
	AL	GREG	44.0	43.0	42.1	41.2	44.5	43.6	42.6
GREG-L		43.8	43.6	43.6	43.5	44.4	44.2	44.1	43.9
GREG-R		43.2	42.6	42.1	41.5	43.8	43.1	42.5	41.9
GREG-V		44.5	43.8	43.1	42.4	45.0	44.4	43.8	43.2
GREG-M		45.0	44.8	44.7	44.7	45.4	45.4	45.4	45.5
AB		45.8	46.3	46.8	47.3	44.6	45.6	46.6	47.5
ABL		45.5	45.8	46.0	46.2	44.1	44.6	45.2	45.6
ABH		45.1	45.1	45.1	45.1	43.5	43.6	43.7	43.8
HT		64.4	64.4	64.4	64.4	54.0	54.0	54.0	54.0

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Table S7: RMSE and bias of point estimators under $p \in \{20, 30, 40, 50\}$ and $n = 300$ in scenarios (A) and (B), where the simulated data is generated from linear regression with non-zero intercept and an unobserved covariate. All values are multiplied by 100.

		(A)				(B)			
Method		20	30	40	50	20	30	40	50
RMSE	GREG	12.4	12.5	12.8	13.0	11.7	11.9	12.2	12.6
	GREG-L	12.1	12.2	12.2	12.3	11.5	11.6	11.7	11.7
	GREG-R	12.2	12.5	12.7	12.9	11.8	12.2	12.7	13.1
	GREG-V	12.4	12.5	12.6	12.7	11.6	11.8	12.0	12.2
	GREG-M	12.4	12.5	12.8	13.0	11.7	11.9	12.2	12.6
	AB	12.2	12.5	12.7	13.0	11.0	11.5	12.2	12.7
	ABL	12.1	12.4	12.5	12.7	10.9	11.2	11.6	11.9
	ABH	12.1	12.1	12.2	12.3	10.7	10.8	10.8	10.9
	HT	17.7	17.7	17.7	17.7	14.1	14.1	14.1	14.1
	Bias	GREG	-1.67	-1.79	-1.88	-2.01	-0.19	0.72	1.49
GREG-L		-0.13	-0.12	-0.14	-0.09	0.74	1.06	1.17	1.35
GREG-R		-0.16	-0.04	0.00	-0.03	1.50	2.54	3.42	4.33
GREG-V		-0.97	-1.05	-1.11	-1.20	0.22	0.87	1.59	2.21
GREG-M		-1.67	-1.79	-1.88	-2.01	-0.19	0.72	1.49	2.43
AB		-0.21	-0.10	-0.07	-0.12	1.61	2.72	3.65	4.67
ABL		-0.22	-0.09	-0.08	-0.13	1.43	2.32	3.03	3.76
ABH		-0.21	-0.16	-0.15	-0.14	0.85	1.21	1.49	1.81
HT		0.66	0.66	0.66	0.66	-0.75	-0.75	-0.75	-0.75

Table S8: CP and AL of 95% credible/confidence intervals under $p \in \{20, 30, 40, 50\}$ and $n = 300$ in scenarios (A) and (B), where the simulated data is generated from linear regression with non-zero intercept and an unobserved covariate. All values are multiplied by 100.

		(A)				(B)			
	Method	20	30	40	50	20	30	40	50
CP	GREG	92.9	91.9	90.9	88.5	95.0	93.9	91.9	91.0
	GREG-L	93.0	92.4	92.4	92.5	95.8	94.7	94.6	94.6
	GREG-R	92.2	91.8	91.0	89.0	94.3	92.5	90.5	89.4
	GREG-V	93.7	92.7	91.8	91.4	95.2	94.8	93.5	92.8
	GREG-M	93.6	93.1	92.9	91.4	95.0	95.2	93.8	93.7
	AB	93.8	93.6	93.2	93.5	95.6	95.2	94.5	92.8
	ABL	93.5	93.1	93.6	92.9	96.1	95.4	94.5	94.1
	ABH	94.0	93.7	93.2	93.0	96.2	96.4	95.5	95.8
	HT	94.3	94.3	94.3	94.3	95.2	95.2	95.2	95.2
	AL	GREG	45.0	44.0	43.1	42.1	45.7	44.6	43.7
GREG-L		44.6	44.5	44.3	44.3	45.4	45.2	45.1	44.9
GREG-R		44.0	43.4	42.8	42.3	44.8	44.1	43.4	42.7
GREG-V		45.6	44.8	44.1	43.4	46.3	45.6	44.9	44.2
GREG-M		46.0	45.8	45.7	45.6	46.6	46.5	46.5	46.5
AB		46.6	47.2	47.7	48.2	45.1	46.0	47.1	48.0
ABL		46.4	46.7	46.9	47.0	44.6	45.2	45.7	46.1
ABH		46.0	46.0	46.0	46.0	43.9	44.1	44.3	44.3
HT		67.1	67.1	67.1	67.1	55.3	55.3	55.3	55.3