

SPARSE COMPOSITE QUANTILE REGRESSION WITH ULTRAHIGH-DIMENSIONAL HETEROGENEOUS DATA

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Abstract: Although quantile regressions are widely employed for heterogeneous data, simultaneously selecting covariates that globally affect the response and estimating the coefficients is very challenging. We introduce a novel sparse composite quantile regression screening method for the analysis of ultrahigh-dimensional heterogeneous data. The proposed method enjoys the sure screening property, provides a consistent selection path, and yields consistent estimates of the coefficients simultaneously across a continuous range of quantile levels. An extended Bayesian information criterion is employed to select the “best” candidate from the path. Extensive simulation studies demonstrate the effectiveness of the proposed method, and an application to a gene expression data set is provided.

Key words and phrases: Quantile regression, sparsity, ultrahigh-dimensional data, variable screening.

1. Introduction

Ultrahigh-dimensional data are common in a variety of scientific fields, including genomics, biomedical imaging, signal processing, and finance, among others. For such data, the number of covariates p greatly exceeds the sample size n , and even grows at an exponential rate of n . A major feature of these data sets is their heterogeneity, which poses both challenges and opportunities for statistical analysis.

Quantile regression, as an important alternative to linear regression, is a technique used to investigate heterogeneity across quantiles (Koenker and Bassett (1978)). For high-dimensional data, many penalized quantile regression methods have been developed to examine the covariate effects at a single or at multiple prespecified quantile levels (Zou and Yuan (2008); Wang, Wu and Li (2012); Fan, Fan and Barut (2014)). However, these models are sensitive to the choices of quantile levels and may overlook important covariates, which is undesirable from

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the viewpoint of interpretation. To resolve this issue, Belloni and Chernozhukov (2011) and Zheng, Peng and He (2015, 2018) extended the quantile regression methods to examine regression quantiles over a continuous set of quantile levels. These kinds of quantile regression methods enjoy two advantages: (1) they use all useful information across quantiles and draw robust conclusions; and (2) they grasp global sparsity more concisely. These models offer a useful complement to the regularized quantile regression, and are more flexible in terms of variable selection, robust estimation, and heteroscedasticity detection. However, a regularized quantile regression may not perform well under ultrahigh-dimensional scenarios, especially in terms of computational expediency, statistical accuracy, and algorithmic stability (Fan and Lv (2010)). This inspired the development of screening methods.

The sure independence screening (SIS) method was proposed for sparse recovery in ultrahigh-dimensional linear regression models (Fan and Lv (2008)). Here, the idea is to rank all covariates using the marginal correlation between each covariate and the response. This method enjoys the sure screening property and is widely applied in various models (Fan, Samworth and Wu (2009); Fan and Song (2010); Zhu et al. (2011); Fan, Feng and Song (2011); Liu, Li and Wu (2014); Song et al. (2014); Fan et al. (2017); Kong et al. (2017); Pan et al. (2019)). To derive robust statistics, He, Wang and Hong (2013) considered a quantile-adaptive model-free variable screening method. Wu and Yin (2015) developed a conditional quantile screening method using a goodness-of-fit-like marginal utility. Ma, Li and Tsai (2017) employed the quantile partial correlation and proposed three variable screening algorithms. For other related works, refer to Zhang and Zhou (2018), Li, Ma and Zhang (2018), and the references therein. Note that these screening methods only consider model sparsity at a single or at multiple quantile levels. Recently, Ma and Zhang (2016) and Xu (2017) proposed composite quantile correlations in which they integrate quantile levels from zero to one. This enjoys the sure screening property and grasps global sparsity. However, these two works did not study the estimation of the coefficients, nor did they consider an interval of quantile levels that well captures part or all of the conditional distributions.

Against this background, we aim to develop a variable screening method that simultaneously globally captures important features and estimates their coefficients. Motivated by the work of Zheng, Peng and He (2015), we adopt a quantile regression model with an interval of quantile levels, denoted as $\Theta \subset (0, 1)$, and propose an approach called the sparse composite quantile regression (SCQR) for variable screening. The SCQR naturally embeds the sparsity information about

the regression functions in the composite quantile regression, and identifies active covariates using the estimates of the regression functions over a continuum of quantile levels. It uses the joint effects rather than the marginal effects of candidate covariates, following Xu and Chen (2014) and Yang et al. (2018). However, compared with these works, our method is robust in terms of model selection. Furthermore, the development of the theory and an algorithm is not a trivial extension of existing methods, owing to the nonsmooth objective function.

This study contributes to the literature in two ways. First, we establish the consistency properties of our method in terms of model selection and parameter estimation. Specifically, the SCQR method creates a solution path that includes the true model with probability approaching one, and yields a consistent estimate across a continuous range of quantile levels. To the best of our knowledge, this is new in the screening literature. An extended Bayesian information criterion (EBIC) (Lee, Noh and Park (2014)) is employed to identify the ideal model. Second, we employ a smoothing technique to develop an iterative groupwise-hard-thresholding method to approximate our proposed solution, establish the convergence of the proposed algorithm, and show the sure screening property of the approximation solution. The proposed algorithm overcomes two kinds of computational challenges. The first is that the objective function is not differentiable at the zero point. The other comes from the ℓ_0 constraint, which results in a heavy computational burden for the existing programming for quantile regression.

The rest of the paper is organized as follows. Section 2 provides some preliminaries about high-dimensional sparse quantile regression models and describes the SCQR method. Section 3 presents a highly efficient algorithm for the SCQR procedure. Section 4 establishes the theoretical properties of the SCQR procedure and the proposed algorithm. An application to a gene expression data set is provided in Section 5, and Section 6 concludes the paper. Simulation studies and all proofs are given in the online Supplementary Material.

2. Methodology

2.1. Some preliminaries

Let $\mathbf{X} = (1, x_1, \dots, x_p)^\top$ be a $(p + 1)$ -dimensional vector of covariates, and let $Q_Y(\tau|\mathbf{X}) = \inf\{y|P(Y \leq y|\mathbf{X}) \geq \tau\}$ denote the τ th conditional quantile of a response variable Y given \mathbf{X} . For the analysis, the following quantile regression

model (Zheng, Peng and He (2015)) is considered:

$$Q_Y(\tau|\mathbf{X}) = \mathbf{X}^\top \boldsymbol{\beta}_\tau^*, \quad \text{for } \tau \in \Theta, \quad (2.1)$$

where $\boldsymbol{\beta}_\tau^* = (\beta_{\tau,0}^*, \beta_{\tau,1}^*, \dots, \beta_{\tau,p}^*)^\top$ is a $(p+1)$ -dimensional vector with unknown coefficient functions of τ , $\Theta \subset (0, 1)$ is a prespecified continuous quantile index set of interest, which can be taken, in general, as the union of multiple disjoint intervals. In what follows, let $|A|$ denote the cardinality of a set A , $M^*(\tau) = \{1 \leq j \leq p : \beta_{\tau,j}^* \neq 0\}$, and $M^* = \cup_{\tau \in \Theta} M^*(\tau)$.

We consider ultrahigh-dimensional data, namely $\log(p) = o(n^{\xi_0})$, with $\xi_0 > 0$, in which a large number of predictors are irrelevant to the response. Examples of such data include gene expression microarray data, single nucleotide polymorphism data, and high-frequency financial data (Ma, Li and Tsai (2017)). Two common sparsity assumptions for $\tilde{\boldsymbol{\beta}}_\tau^* \equiv (\beta_{\tau,1}^*, \dots, \beta_{\tau,p}^*)^\top \in \mathbb{R}^p$ arise to ensure the model interpretability and identifiability: the local sparsity (LS) condition (Belloni and Chernozhukov (2011)), and the global sparsity (GS) condition (Zheng, Peng and He (2015)). The LS condition assumes that $|M^*(\tau)| = o(n)$, which tends to cause over-fitting by simply taking the union of active covariate sets selected separately for each $\tau \in \Theta$. The GS condition assumes $|M^*| = o(n)$, which is indispensable to derive a parsimonious model. Thus, we employ the GS assumption for variable screening to identify all significant covariates related to the interesting segment of the conditional distribution of the response.

2.2. Sparse composite quantile regression

We approximate $\boldsymbol{\beta}_\tau$ by a piecewise constant function with respect to $\tau \in \Theta$. Specifically, denote τ_0 and τ_K as the infimum and supremum, respectively, of Θ . Let $\tau_0 < \dots < \tau_K$ be a partition of Θ , and define the approximate function as $\bar{\boldsymbol{\beta}}_\tau = \sum_{k=1}^K \boldsymbol{\beta}_{\tau_k} I(\tau_{k-1} < \tau \leq \tau_k) \equiv (\bar{\beta}_{\tau,0}, \bar{\beta}_{\tau,1}, \dots, \bar{\beta}_{\tau,p})^\top$, for $\tau \in \Theta$, where $\boldsymbol{\beta}_{\tau_k} = (\beta_{\tau_k,0}, \beta_{\tau_k,1}, \dots, \beta_{\tau_k,p})^\top \in \mathbb{R}^{p+1}$, and $I(\cdot)$ denotes an indicator function. Define $D = (\boldsymbol{\beta}_{\tau_1}, \dots, \boldsymbol{\beta}_{\tau_K}) \equiv (\mathbf{d}_0, \dots, \mathbf{d}_p)^\top \in \mathbb{R}^{(p+1) \times K}$. Thus, determining whether $\beta_{\tau,j} \equiv 0$ over Θ reduces to identifying whether or not \mathbf{d}_j is a zero vector ($1 \leq j \leq p$). The latter is a row-wise sparsity problem for the coefficient matrix D ; hence, we can use the group learning method.

Suppose that the observed data consist of n independent and identically distributed (i.i.d) replicates of $(Y, \mathbf{X}^\top)^\top$, denoted by $\{(Y_i, \mathbf{X}_i^\top)^\top, i = 1, \dots, n\}$. We employ the composite quantile regression (CQR) in Zou and Yuan (2008) to estimate D . Let $\mathcal{U}_n(D) = (nK)^{-1} \sum_{k=1}^K \sum_{i=1}^n \rho_{\tau_k}(Y_i - \mathbf{X}_i^\top \boldsymbol{\beta}_{\tau_k})$ be the objective function, where $\rho_\tau(u) = u\{\tau - I(u < 0)\}$ is the check function (Koenker (2005)).

Based on the GS condition, we consider the following problem:

$$\min_D \mathcal{U}_n(D), \quad \text{subject to} \quad \sum_{j=1}^p I(\|\mathbf{d}_j\|_2 \neq 0) \leq t, \quad (2.2)$$

where t is a positive integer. Note that t controls the sparse level in problem (2.2). If we take $t < n$, then there are at least $(p - t)$ covariates screened out from model (2.1). Let $\hat{D} = (\hat{\beta}_{\tau_1}, \dots, \hat{\beta}_{\tau_K})$ be a minimizer of problem (2.2). An efficient algorithm is proposed to solve problem (2.2) in Section 3. Denote $\hat{\beta}_\tau = \sum_{k=1}^K \hat{\beta}_{\tau_k} I(\tau_{k-1} < \tau \leq \tau_k) \equiv (\hat{\beta}_{\tau,0}, \hat{\beta}_{\tau,1}, \dots, \hat{\beta}_{\tau,p})^\top$ as the estimate of β_τ , which is the approximation of β_τ^* , and define \hat{M}_t as the selected model index using $\hat{\beta}_\tau$; that is, $\hat{M}_t = \cup_{\tau \in \Theta} \{1 \leq j \leq p : \hat{\beta}_{\tau,j} \neq 0\}$.

Because our method is a group learning method with a sparsity constraint for composite quantile regression, we call it the sparse composite quantile regression (SCQR). The main difference between the CQR and the SCQR is that the coefficients $\beta_{\tau,j}$ are deemed to be constants over $\tau \in \Theta$ in the CQR, but are a group of functions in the SCQR. In addition, the proposed procedure employs the joint effects of candidate variables, which makes it distinct from marginal screening methods.

Let $s = |M^*|$ be the true mode size. As guaranteed by Theorem 3 in Section 4, one has that $\hat{M}_s = M^*$ holds with probability tending to one under certain regularity conditions. However, in practice, s is unknown and needs to be estimated. Motivated by Wang (2009), we derive a solution path using problem (2.2), and adopt an EBIC to estimate s . Specifically, let $\tilde{t} < n$ be a prespecified positive integer. We solve problem (2.2) for given $t \in \{1, \dots, \tilde{t}\}$, obtaining a solution path of candidate models: $\{\hat{M}_1, \dots, \hat{M}_{\tilde{t}}\}$. Theorem 3 implies that when choosing $\hat{t} \geq s$, one can always guarantee that M^* is contained in one of the candidate models $\{\hat{M}_1, \dots, \hat{M}_{\hat{t}}\}$, with an overwhelming probability. For $\mathbf{X}_i = (1, x_{i1}, \dots, x_{ip})^\top$ and an arbitrary subset $M \subset \{1, \dots, p\}$, let $\mathbf{X}_{i,M}$ be the subvector of \mathbf{X}_i consisting of all x_{ij} , with $j \in M$. Here, $\hat{\beta}_{\tau_k,M}$ is defined similarly for $1 \leq k \leq K$. The EBIC is defined as

$$\text{EBIC}(\hat{M}_t) = \log \left\{ \frac{1}{nK} \sum_{k=1}^K \sum_{i=1}^n \rho_{\tau_k} \left(Y_i - \mathbf{X}_{i,\hat{M}_t}^\top \hat{\beta}_{\tau_k,\hat{M}_t} \right) \right\} + C_n \frac{t \log(n)}{n},$$

where C_n is a positive constant that diverges along with the sample size n . We determine a hard-thresholding parameter \hat{t} as $\hat{t} = \operatorname{argmin}_{1 \leq t \leq \tilde{t}} \text{EBIC}(\hat{M}_t)$. Then, the final selected model is defined as $\hat{M} = \hat{M}_{\hat{t}}$.

Remark 1. Because there is a tradeoff between computation and model selection

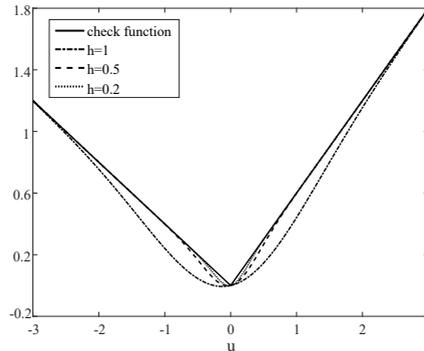


Figure 1. $\psi_{\tau,h}(u)$ is a smoothed approximation of $\rho_{\tau}(u)$.

accuracy when choosing \tilde{t} , we set $\tilde{t} = \lceil n^{1/5} \log(n) \rceil$, where $\lceil a \rceil$ denotes the largest integer part of a . This empirical choice is analogous to the recommended \tilde{t} values in Xu and Chen (2014), and works well in both our simulation studies and our real-data analysis.

3. Computational Algorithm

Koenker and D'Orey (1987) developed parametric linear programming to compute a quantile regression function for all $\tau \in (0, 1)$. Many algorithms have been introduced for high-dimensional sparse penalized quantile regression approaches; see Gu et al. (2018) for an overview. For problem (2.2), there are C_p^t candidate submodels to fit the data for a given t , where C_p^t denotes the number of t -combinations from a given set of p elements. This increases the computational burden of the existing algorithm. In addition, the check function $\rho_{\tau}(u)$ is not differentiable at point $u = 0$. To overcome these issues, we develop an efficient algorithm to solve problem (2.2) that combines a smoothing technique and an iterative hard-thresholding algorithm.

First, we approximate the indicator function $I(u < 0)$ in $\rho_{\tau}(u)$ using a local distribution function $\Phi(-u/h)$, where $\Phi(\cdot)$ is the standard normal cumulative distribution function, and h is a bandwidth that converges to zero as $n \rightarrow \infty$. This method was originally devised by Heller (2007) for a rank regression. Define $\psi_{\tau,h}(u) = u\{\tau - \Phi(-u/h)\}$, which is smooth and differentiable at point $u = 0$. Note that if $u \geq 0$, $\psi_{\tau,h}(u) \rightarrow u\tau$ as $n \rightarrow \infty$, whereas if $u < 0$, $\psi_{\tau,h}(u) \rightarrow u(\tau - 1)$. Figure 1 illustrates that $\rho_{\tau}(u)$ can be approximated well by $\psi_{\tau,h}(u)$ using an appropriate h . Thus, a smoothed version of problem (2.2) is given as follows:

$$\min_D \tilde{U}_n(D), \quad \text{subject to} \quad \sum_{j=1}^p I(\|\mathbf{d}_j\|_2 \neq 0) \leq t, \quad (3.1)$$

where $\tilde{U}_n(D) = (nK)^{-1} \sum_{k=1}^K \sum_{i=1}^n \psi_{\tau_k, h}(Y_i - \mathbf{X}_i^\top \boldsymbol{\beta}_{\tau_k})$. If the bandwidth h satisfies $nh \rightarrow \infty$ and $nh^4 \rightarrow 0$ as $n \rightarrow \infty$, then Lemma 1 in the online Supplementary Material indicates that the check function is equivalent to the smoothed version, with probability tending to one. Thus, we can focus on solving problem (3.1). For the bandwidth, we use the rule of thumb bandwidth, and choose $h = O(n^{-1/3})$. Let $\ell_\tau(\boldsymbol{\beta}) = n^{-1} \sum_{i=1}^n \psi_{\tau, h}(Y_i - \mathbf{X}_i^\top \boldsymbol{\beta})$, and denote $\dot{f}(\cdot)$ and $\ddot{f}(\cdot)$ as the first and second derivatives, respectively, of any function $f(\cdot)$. Consider the following quadratic approximation to $\ell_\tau(\mathbf{v})$:

$$\varphi_\tau(\mathbf{u}|\mathbf{v}) = \ell_\tau(\mathbf{v}) + \langle \mathbf{u} - \mathbf{v}, \dot{\ell}_\tau(\mathbf{v}) \rangle + \frac{\lambda}{2} \|\mathbf{u} - \mathbf{v}\|_2^2, \quad (3.2)$$

where $\langle \cdot, \cdot \rangle$ denotes the inner product in the Euclidean space, and λ is a pre-specified positive constant. It can be seen that $\varphi_\tau(\mathbf{v}|\mathbf{v}) = \ell_\tau(\mathbf{v})$, and thus $\varphi_\tau(\mathbf{u}|\mathbf{v})$ nicely approximates $\ell_\tau(\mathbf{v})$ for \mathbf{u} close to \mathbf{v} . Let $B = (\check{\boldsymbol{\beta}}_{\tau_1}, \dots, \check{\boldsymbol{\beta}}_{\tau_K}) \equiv (\mathbf{b}_0, \dots, \mathbf{b}_p)^\top \in \mathbb{R}^{(p+1) \times K}$. Given equation (3.2), the smoothed composite quantile function $\tilde{U}(\cdot)$ can be approximated by

$$\begin{aligned} \mathcal{Q}_\lambda(B|D) &\equiv \frac{1}{K} \sum_{k=1}^K \varphi_{\tau_k}(\check{\boldsymbol{\beta}}_{\tau_k} | \boldsymbol{\beta}_{\tau_k}) \\ &= \tilde{U}(D) + \frac{1}{K} \sum_{k=1}^K \langle \check{\boldsymbol{\beta}}_{\tau_k} - \boldsymbol{\beta}_{\tau_k}, \dot{\ell}_{\tau_k}(\boldsymbol{\beta}_{\tau_k}) \rangle + \frac{\lambda}{2K} \|B - D\|_F^2, \end{aligned}$$

where $\|A\|_F$ is the Frobenius norm of an arbitrary matrix A . Using $\mathcal{Q}_\lambda(B|D)$, we obtain an iterative solution to problem (3.1). Specifically, let $D^{[l]}$ be the estimate of D at the l th iteration. We update $D^{[l]}$ by $D^{[l+1]}$, where

$$D^{[l+1]} = \underset{B}{\operatorname{argmin}} \mathcal{Q}_\lambda(B|D^{[l]}), \quad \text{subject to} \quad \sum_{j=1}^p I(\|\mathbf{b}_j\|_2 \neq 0) \leq t.$$

This is also equivalent to

$$D^{[l+1]} = \underset{B}{\operatorname{argmin}} \left\| B - \left[D^{[l]} - \frac{1}{\lambda} \dot{\Psi}(D^{[l]}) \right] \right\|_F^2, \quad \text{subject to} \quad \sum_{j=1}^p I(\|\mathbf{b}_j\|_2 \neq 0) \leq t, \quad (3.3)$$

where $\dot{\Psi}(D) = (\dot{\ell}_{\tau_1}(\boldsymbol{\beta}_{\tau_1}), \dots, \dot{\ell}_{\tau_K}(\boldsymbol{\beta}_{\tau_K})) \in \mathbb{R}^{(p+1) \times K}$.

Algorithm 1

Let L be a prespecified positive integer.

Step 1. Choose an initial value for $D^{[0]}$, such as $D^{[0]} = 0$;

Step 2. For each $l \in \{0, 1, \dots, L\}$,

Step 2.1. Compute $D^{[l+1]}$ using equation (3.5);

Step 2.2. Stop Step 2 if the linear search criterion (3.6) is satisfied; otherwise, take the step-size to be $2\lambda^{[l]}$, and return to *Step 2.1*;

Step 3. Stop the algorithm if $l > L$ or $\|D^{[l+1]} - D^{[l]}\|_F < \delta\|D^{[l]}\|_F$, where $\delta > 0$ is a prespecified tolerance parameter. Otherwise, increase l , and return to *Step 2.1*.

In our simulation studies and real-data analysis, we take $L = 1,000$ and set $\delta = \rho = 10^{-5}$.

Proposition 1. *Let $D = (\mathbf{d}_0, \dots, \mathbf{d}_p)^\top \in \mathbb{R}^{(p+1) \times K}$ be an arbitrary matrix. If $\hat{B} = (\hat{\mathbf{b}}_0, \dots, \hat{\mathbf{b}}_p)^\top$ is an optimal solution to the problem*

$$\min_{B \in \mathbb{R}^{(p+1) \times K}} \|B - D\|_F^2, \quad \text{subject to} \quad \sum_{j=1}^p I(\|\mathbf{b}_j\|_2 \neq 0) \leq t,$$

then \hat{B} has a closed form, with the j th row defined as

$$\hat{\mathbf{b}}_0 = \mathbf{d}_0 \quad \text{and} \quad \hat{\mathbf{b}}_j = \mathbf{d}_j I(d_j^* \geq d_{(t)}^*), \quad \text{for } 1 \leq j \leq p, \tag{3.4}$$

where $d_j^ = \|\mathbf{d}_j\|_2$, and $d_{(t)}^*$ is the t -th largest value of d_1^*, \dots, d_p^* .*

The proof is given in the online Supplementary Material. Proposition 1 indicates that equation (3.4) is indeed a hard-thresholding rule. It first ranks the importance of the covariates according to the estimates of $\|\mathbf{d}_j\|_2$ in decreasing order, and then filters out those with small effects over Θ .

Based on Proposition 1, we obtain that $D^{[l+1]}$ defined in (3.3) has the following form:

$$\mathbf{d}_j^{[l+1]} = \check{\mathbf{d}}_j^{[l]} I(\|\check{\mathbf{d}}_j^{[l]}\|_2 \geq \check{d}_{(t)}), \quad \text{for } 1 \leq j \leq p, \tag{3.5}$$

where $\check{\mathbf{d}}_j^{[l]}$ is the transposition of the j th row of $[D^{[l]} - \lambda^{-1}\dot{\Psi}(D^{[l]})]$, and $\check{d}_{(t)}$ is the t th largest value of $\|\check{\mathbf{d}}_1^{[l]}\|_2, \dots, \|\check{\mathbf{d}}_p^{[l]}\|_2$.

However, there still exists a step-size λ in updating rule (3.5), which plays an important role in the convergence of the algorithm. Our empirical studies indicate that a large value of λ often leads to a slow convergence rate, while a small value of λ results in failing to identify active covariates. In what follows, a backtracking method is employed to find λ , such that the objective function decreases monotonically after each iteration. Specifically, we choose the step-size

$\lambda^{[l]}$ at the l th iteration as the minimum value, such that

$$\tilde{\mathcal{U}}_n(D^{[l+1]}) \leq \tilde{\mathcal{U}}_n(D^{[l]}) - \frac{\varrho\lambda^{[l]}}{2K} \|D^{[l+1]} - D^{[l]}\|_F^2, \tag{3.6}$$

where $\varrho \in (0, 1)$ is a fixed small constant. The proposed algorithm is presented in the following Algorithm 1.

4. Theoretical Properties

4.1. Convergence analysis of algorithm

To show the convergence property of the proposed algorithm, we need the following Lipschitz condition:

$$\|\dot{\ell}_\tau(\beta_1) - \dot{\ell}_\tau(\beta_2)\|_2 \leq \phi \|\beta_1 - \beta_2\|_2,$$

where ϕ is a positive constant independent of τ . The Lipschitz condition is satisfied if the largest eigenvalue of $\ddot{\ell}_\tau(\beta)$ is uniformly bounded in β and τ . A more serious concern is whether, for each $l \geq 0$, the step size $\lambda^{[l]}$ is bounded. Following similar arguments to those in Gong et al. (2013), the Lipschitz condition, together with criterion (3.6), guarantees the boundedness of the step size $\lambda^{[l]}$ in Step 2.2. The following theorem summarizes the convergence property of Algorithm 1.

Theorem 1. *Let $\{D^{[l]}\}$ be the sequence generated by Algorithm 1. If $\lambda^{[l]} > \phi/(1 - \varrho)$, then as $l \rightarrow \infty$, there exists at least one subsequence such that $\{D^{[l]}\}$ is convergent. In addition, if the stopping criterion is $K^{-1/2} \|D^{[l+1]} - D^{[l]}\|_F \leq \varepsilon$, we have that Algorithm 1 stops in a finite number of steps, where $\varepsilon > 0$ is a prespecified small constant.*

The proof can be found in the online Supplementary Material, and indicates that the proposed algorithm yields an approximate solution. The next theorem presents an upper bound for the estimation error of $D^{[l]}$. Let $\tilde{\phi} = \min_{0 < \|x\|_0 \leq 3t} \{x^\top \ddot{\ell}_\tau(\beta)x\} / (x^\top x) > 0$ be the restricted eigenvalue, where $\|a\|_0 = \sum_{j=1}^p I(a_j \neq 0)$ for a vector $a = (a_1, \dots, a_p)^\top \in \mathbb{R}^p$. The restricted eigenvalue condition is frequently used in the literature on high-dimensional data analysis (Candes and Tao (2007); Belloni and Chernozhukov (2011)). Let D^* denote the true value of D .

Theorem 2. *(Upper Bound of Algorithm 1). If $s \leq t$ and $\phi < \lambda^{[l]} < \tilde{\phi}/\{1 - 1/(4\sqrt{2})\}$, then*

$$\|D^{[l]} - D^*\|_F \leq 2^{-l} \|D^{[0]} - D^*\|_F + \sqrt{\frac{8}{\phi}} \|\dot{\Psi}(D^*)\|_F.$$

Theorem 2, combined with the convergence property of Algorithm 1, implies that there exists at least one subsequence such that the difference between the limiting point and the true value D^* can be bounded by $\|\dot{\Psi}(D^*)\|_F$. Moreover, if we take the initial value $D^{[0]} = 0$, after at most $l = \lceil \log_2(\|D^*\|_F / \|\dot{\Psi}(D^*)\|_F) \rceil + 1$ iterations, the sequence $\{D^{[l]}\}$ satisfies $\|D^{[l]} - D^*\|_F \leq (1 + \sqrt{8/\phi}) \|\dot{\Psi}(D^*)\|_F$. Thus, in a finite number of steps, the estimation error can be controlled using $\|\dot{\Psi}(D^*)\|_F$.

4.2. Sure screening property

Let M be an arbitrary subset of $\{1, \dots, p\}$ and $M_t = \{M : |M| \leq t\}$. Define the collection of over-fitted models with model size t as $M_+^t = \{M : M^* \subset M_t\}$. To study the asymptotic properties of the proposed SCQR, we need the following regularity conditions:

(C1) $\log(p) = o(n^{\xi_0})$, for $0 < \xi_0 < 1$.

(C2) There exist some positive constants $\omega_1, \omega_2, \xi_1$, and ξ_2 , such that for a given hard-thresholding parameter t in (2.2), the true model size $s \leq t < \omega_1 n^{\xi_1}$, and

$$\min_{j \in M^*} \left[\int_{\Theta} (\beta_{\tau,j}^*)^2 d\tau \right]^{1/2} \geq \omega_2 n^{-\xi_2}.$$

Condition (C2) suggests that the minimum signal of the active set is bounded away from zero, but it is allowed to converge to zero in $O(n^{-\xi_2})$. This encompasses what is considered by Xu and Chen (2014) for the generalized linear model.

(C3) Let $\epsilon = Y - \mathbf{X}^\top \beta_\tau^*$, and let $F(\cdot|\mathbf{x})$ and $f(\cdot|\mathbf{x})$ be the cumulative distribution function and density function, respectively, of ϵ given $\mathbf{X} = \mathbf{x}$. There exist positive constants ν and δ^* free of τ such that, for sufficiently large n and each vector $\mathbf{u} \in \{\mathbf{v} : \|\mathbf{v}_M\|_2 < \delta^*, M \in M_+^{2t}\}$,

$$\frac{1}{n^{1-\xi_2}} \sum_{i=1}^n \int_0^{\mathbf{X}_i^\top \mathbf{u}} \left[F\left(\frac{s}{n^{\xi_2}} | \mathbf{X}_i\right) - F(0 | \mathbf{X}_i) \right] ds \geq \nu \|\mathbf{u}\|_2^2.$$

Condition (C3) is similar to condition (2) of Zou and Yuan (2008), which is used to establish the asymptotic properties of a composite quantile regression. Indeed, condition (C3) can be replaced by sufficient conditions that are commonly used

in quantile regression. Some examples are given in the online Supplementary Material.

(C4) For $\mathbf{X}_i = (1, x_{i1}, \dots, x_{ip})^\top$, there exists a positive constant m such that $\sup_{i,j} |x_{ij}| \leq m$.

Condition (C4) is commonly used in the context of high-dimensional data analysis (Wang, Wu and Li (2012); Lee, Noh and Park (2014)). This assumption can be relaxed to a tail probability inequality that there exist some positive constants m_0 , m_1 , and α such that, for sufficiently large η , $P\{|x_{ij}| > \eta\} \leq m_0 \exp\{-m_1 \eta^\alpha\}$. In this case, the theoretical results still hold with slight modifications in the proofs.

Theorem 3. (*Sure Screening Property*). *Suppose that conditions (C1)–(C4) hold with $\max\{\xi_1 + \xi_2, \xi_1/2 + 2\xi_2\} < (1 - \xi_0)/2$. Then, for sufficiently large K ,*

$$P\{M^* \subset \hat{M}_t\} \rightarrow 1 \text{ as } n \rightarrow \infty.$$

Theorem 3 states that with probability tending to one, all relevant variables can be identified by carrying out the SCQR at most $O(n^{\xi_1})$ times, which is much smaller than n under condition $\max\{\xi_1 + \xi_2, \xi_1/2 + 2\xi_2\} < (1 - \xi_0)/2$. Based on Theorem 3, the strong screening consistency (Huang, Li and Wang (2014)) is further provided in the following corollary.

Corollary 1. *Under the conditions of Theorem 3, we have*

$$P\{M^* = \hat{M}_s\} \rightarrow 1 \text{ as } n \rightarrow \infty.$$

Corollary 1 suggests that if one has prior knowledge on the model size s , the selected model \hat{M}_s is exactly the true model M^* with probability approaching one. This corollary is important, because it guarantees that the true model is one of our candidate models $\{\hat{M}_1, \dots, \hat{M}_{\tilde{t}}\}$, as long as $\tilde{t} \geq s$. The consistency property for the EBIC procedure is established in the following theorem.

Theorem 4. *Suppose that conditions (C1)–(C4) hold with $\max\{\xi_1 + \xi_2, \xi_1/2 + 2\xi_2\} < (1 - \xi_0)/2$. If $E(|\epsilon|) < \infty$, $C_n^{-1} = o(1)$, and $C_n \log(n)/(n^{1-\xi_1}) = o(1)$. Then, $P\{M^* = \hat{M}\} \rightarrow 1$ as $n \rightarrow \infty$.*

Theorem 4 suggests that with probability approaching one, the true model index can be correctly identified by the SCQR when the EBIC is employed as the stopping criterion.

Theorem 5. *Under conditions (C1)–(C4) with $\max\{\xi_1 + \xi_2, \xi_1/2 + 2\xi_2\} < (1 -$*

$\xi_0)/2$, we have that there exists a constant $c_0 > 0$, such that

$$P\left\{\left[\int_{\Theta}\|\hat{\beta}_{\tau}-\beta_{\tau}^*\|_2^2d\tau\right]^{1/2}\geq c_0n^{-\xi_2}\right\}\rightarrow 0 \text{ as } n\rightarrow\infty.$$

Theorem 5 indicates that the integral squared error of the proposed estimate can be bounded by $O_p(n^{-\xi_2})$. This, combined with Theorem 3, implies that the SCQR procedure can perform variable screening and parameter estimation simultaneously. The consistency property of Algorithm 1 is guaranteed by the following theorem.

Theorem 6. *Suppose that conditions (C1)–(C4) hold with $\max\{\xi_1+\xi_2, \xi_1/2+2\xi_2\} < (1-\xi_0)/2$. If $E(|\epsilon|) < \infty$ and $\phi < \lambda^{[l]} < \tilde{\phi}/\{1-1/(4\sqrt{2})\}$. Then, there exists a constant $c_1 > 0$ such that, after $l = \lceil \log_2(\|D^*\|_F/\|\dot{\Psi}(D^*)\|_F) \rceil + 1$ iterations,*

$$P\left\{\left[\int_{\Theta}\|\hat{\beta}_{\tau}^{[l]}-\beta_{\tau}^*\|_2^2d\tau\right]^{1/2}\geq c_1n^{-\xi_2}\right\}\rightarrow 0 \text{ as } n\rightarrow\infty.$$

Theorems 5 and 6 indicate that the estimates generated by Algorithm 1 and problems (2.2) and (3.1) have the same consistency rate, $O_p(n^{-\xi_2})$. Theorem 6 also implies the following result, which indicates the sure screening property of Algorithm 1.

Corollary 2. *(Sure Screening of Algorithm 1). Under the conditions of Theorem 6, we have that, after $l = \lceil \log_2(\|D^*\|_F/\|\dot{\Psi}(D^*)\|_F) \rceil + 1$ iterations,*

$$P\{M^*\subset\hat{M}_t^{[l]}\}\rightarrow 1 \text{ as } n\rightarrow\infty.$$

Remark 2. To guarantee the sure screening property, Xu and Chen (2014) proposed using an appropriate Lasso-type initial value in their algorithm. However, the Lasso-type estimate may be unstable and time consuming under ultrahigh-dimensional settings. Corollary 2 generalizes their results, stating that zero is a reasonable initial value for Algorithm 1. This finding further enriches the SCQR method from a practical perspective.

5. Real-Data Analysis

In this section, the proposed method is applied to a gene expression data set to investigate gene regulation in the mammalian eye and to identify genetic variations relevant to human eye disease (Scheetz et al. (2006)). This data set has 31,042 gene expression probe sets on 120 rats, and the gene expression levels

are analyzed on a log scale with base 2. The response variable of interest is the expression of gene TRIM32 (probe 1389163_at), which is known to cause hereditary diseases of the human retina. As in Huang, Ma and Zhang (2008), Wang, Wu and Li (2012), and Zheng, Peng and He (2015), the main aim of this analysis is to study how the response variable depends on the gene expression of other probes. The data set is available in the **R** package “*flare*,” which has been processed to exclude probes that are not expressed or that lack variation. There are 200 probes left as covariates.

As in Zheng, Peng and He (2015), two reasonable choices for Θ are considered: (0.2, 0.8) and (0.25, 0.75). The bandwidth is chosen as $h = 1.9n^{-1/3}$ and $C_n = \log(p)/2$ in the EBIC. For comparison, two other methods are also considered: our proposed method, with Θ degenerating to one point τ , denoted by SQR(τ), with $\tau \in \{0.25 + 0.05k, \text{ for } k = 0, 1, \dots, 10\}$; and the method of simply taking the union of the active covariate sets identified by SQR(τ) at each τ , denoted by USQR. To evaluate each method, we consider 400 random partitions. For each partition, the data are divided randomly into two equal data sets: a training data set and a testing data set. Based on the training data set, we implement the screening methods and obtain the estimate of β_τ . Subsequently, we compute the prediction error

$$\text{PE}(\Theta) = \frac{1}{|\mathcal{T}|} \sum_{i \in \mathcal{T}} \int_{\Theta} \rho_\tau(Y_i - \mathbf{X}_i^\top \hat{\beta}_\tau) d\tau,$$

where $\mathcal{T} = \{i : \text{the } i\text{th subject in the testing data set}\}$ is the testing set index. For SQR(τ), we treat the coefficient functions as constants over $\tau \in \Theta$, and calculate $\text{PE}(\Theta)$. A smaller value of the prediction error indicates a better performance.

The results averaged over 400 random partitions are reported in Table 1. The table indicates that the SCQR procedure selects four of the same genes that are significantly related to the response variable for two different choices of Θ . This suggests that the SCQR method is robust to the selection of Θ , which is a desirable feature from the perspective of model selection. For the SQR(τ) method, the chosen set of probes varies with τ . For instance, the genes 1370551_a_at and 1398389_at are selected by SQR(τ), with τ from 0.4 to 0.6, but they are overlooked at lower and higher τ . These may suggest a heterogeneous relationship across different quantile levels. Further, the results indicate that three probes are selected by SQR(0.4), but that no probe is selected by SQR(0.35). This implies that the SQR(τ) method may be sensitive to the choice of τ . For the USQR procedure,

Table 1. Probe sets identified by various methods.

Θ	Method	Probes	PE(Θ)	
			[0.25, 0.75]	[0.2, 0.8]
[0.25, 0.75]	SCQR	“1370551_a.at, 1374106_at, 1384862_at, 1389457_at”	0.020(0.002)	-
[0.2, 0.8]	SCQR	“1370551_a.at, 1374106_at, 1384862_at, 1389457_at”	-	0.028(0.003)
[0.25, 0.75]	USQR	5 probes	0.034(0.002)	-
[0.2, 0.8]	USQR	5 probes	-	0.042(0.002)
0.25	SQR	0 probes	0.040(0.003)	0.047(0.003)
0.30	SQR	0 probes	0.038(0.003)	0.046(0.004)
0.35	SQR	0 probes	0.035(0.003)	0.042(0.004)
0.40	SQR	“1370551_a.at, 1384886_at, 1398389_at”	0.029(0.004)	0.035(0.005)
0.45	SQR	“1370429_at, 1370551_a.at, 1398389_at”	0.022(0.002)	0.027(0.003)
0.50	SQR	“1370551_a.at, 1398389_at”	0.021(0.003)	0.025(0.003)
0.55	SQR	“1370551_a.at, 1374106_at, 1398389_at”	0.022(0.002)	0.027(0.003)
0.60	SQR	“1370429_at, 1370551_a.at, 1398389_at”	0.028(0.004)	0.034(0.004)
0.65	SQR	0 probes	0.032(0.004)	0.039(0.005)
0.70	SQR	0 probes	0.034(0.004)	0.043(0.004)
0.75	SQR	0 probes	0.037(0.003)	0.045(0.004)

five probes are selected both for $\Theta = (0.25, 0.75)$ and $\Theta = (0.2, 0.8)$. Compared with the selection results of the USQR, the SCQR yields slightly smaller predictor errors.

6. Conclusion

We have considered a sparse composite quantile regression method for analyzing ultrahigh-dimensional heterogeneous data across a continuous range of quantile levels. An efficient iterative algorithm was developed to implement our proposed method. The properties of the proposed procedure were provided. Specifically, the theoretical results suggest that the SCQR method with ultrahigh-dimensional covariates can successfully identify active covariates with probability approaching one. At the same time, the SCQR method yields consistent estimates of coefficients. Furthermore, the proposed algorithm enjoys consistent properties in terms of variable screening and parameter estimation.

Supplementary Material

The online Supplementary Material includes simulation studies, some sufficient conditions for (C3), and the proofs of Proposition 1 and Theorems 1–6.

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