

TWO-SAMPLE FUNCTIONAL LINEAR MODELS

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Abstract: In this study, we examine two-sample functional linear regressions with a scaling transformation of the regression functions. We estimate the intercept, slope function, and scalar parameter using a functional principal component analysis. We also establish the rate of convergence of the estimator of the slope function, which is shown to be optimal in a minimax sense under certain smoothness assumptions. In addition, we investigate the semiparametric efficiency of the estimation of the scalar parameter and the hypothesis tests. Then, we extend the proposed method to include sparsely and irregularly sampled functional data and establish the consistency of the estimators of the scalar parameter and the slope function. We evaluate the numerical performance of the proposed methods through simulation studies and illustrate their utility via an analysis of an AIDS data set.

Key words and phrases: Functional linear regression, functional principal component analysis, hypothesis testing, minimax rate of convergence, semiparametric comparison, semiparametric efficiency.

1. Introduction

Functional data analyses (FDAs) have become increasingly important over the past two decades. For example, see the monographs of Ramsay and Silverman (2005), Ferraty and Vieu (2006), Horváth and Kokoszka (2012), and Hsing and Eubank (2015), as well as the articles by Yao, Müller and Wang (2005a,b), Müller (2005), Hall, Müller and Wang (2006), Li and Hsing (2010), Li, Wang and Carroll (2013), Cuevas (2014), Chen et al. (2017), and Wang, Chiou and Müller (2016), and the references therein.

This study provides a semiparametric comparison of FDA regression models. Specifically, we consider

$$Y = (1 - U)r(X) + U\theta r(X) + \varepsilon = (1 - U + U\theta)r(X) + \varepsilon, \quad (1.1)$$

where U is a Bernoulli random variable with $\pi = E(U) = P(U = 1)$, $\theta \in (0, \infty)$ is an unknown parameter, $X(t)$ is a random function in the class $L_2(\mathcal{I})$ of square-integrable functions on a compact interval \mathcal{I} of \mathbb{R}^1 , $r(\cdot)$ is a function from $L_2(\mathcal{I})$

to \mathbb{R}^1 , and ε is a random error, independent of (U, X) , with mean zero and finite variance σ^2 . Furthermore, we assume that U and X are independent.

Model (1.1) refers to a two-sample problem. In the first sample ($U = 0$), the relationship between Y and $X(t)$ is described by $r(X)$. In the second sample ($U = 1$), this relationship changes to $\theta r(X)$. For independent data, Schick (1993) treated $r(\cdot)$ as a nonparametric function and established semiparametric efficiency of estimating θ .

There are many possible choices for $r(\cdot)$, including the fully nonparametric form (Ferraty and Vieu (2006)) and the single-index functional form (Chen, Hall and Müller (2011)). In this study, we examine the following linear relationship between r and $X(t)$:

$$r(X) = a + \int_{\mathcal{I}} X(t)b(t) dt,$$

with an unknown intercept a and a square integrable slope function $b(t)$. As a result, we formulate our two-sample functional linear regression as

$$E\{Y|X(t), U\} = (1 - U + U\theta) \left\{ a + \int_{\mathcal{I}} X(t)b(t) dt \right\}. \quad (1.2)$$

Let $\{(Y_i, X_i, U_i), i = 1, \dots, n\}$ be independent and identically distributed (i.i.d.) data from model (1.1). Our goal is to estimate θ, a , and $b(t)$ based on the sample. Model (1.2) is also related to the functional mixture regression (FMR) of Yao, Fu and Lee (2011), which is an extension of the classical finite-mixture regression models (DeSarbo and Cron (1988)). However, FMRs are different because the group label for each observation is unknown, whereas it is known in (1.2). If $\theta \equiv 1$, (1.2) reduces to a functional linear model: $Y = a + \int_{\mathcal{I}} X(t)b(t) dt + \varepsilon$. This model has been investigated extensively in the literature, in general, focusing is on estimates of a and $b(t)$. See, for example, Cardot, Ferraty and Sarda (2003), Ramsay and Silverman (2005), Cai and Hall (2006), Hall and Horowitz (2007), Li and Hsing (2007), Crambes, Kneip and Sarda (2009), Yuan and Cai (2010), and Cai and Yuan (2012). The most frequently used approaches for estimating $b(t)$ are based on functional principal component analyses (FPCAs) or on reproducing kernel Hilbert space (RKHS) methods. Cai and Hall (2006) and Hall and Horowitz (2007) predicted and estimated the slope function $b(t)$ based on the FPCA method. Yuan and Cai (2010) and Cai and Yuan (2012) estimated the slope function and investigated adaptive predictions using the RKHS method. Cardot, Ferraty and Sarda (2003) and Li and Hsing (2007) approximated $b(t)$ and $X(t)$ using a B-spline and a Fourier approximation, respectively, and they established the rates of convergence for the resulting estimators or predictions

under various assumptions. More recently, Lei (2014) proposed a global test for $b(t)$ based on the FPCA approach, and Shang and Cheng (2015) provided a statistical inference for (generalized) functional linear models under the RKHS framework.

In this study, we adopt the FPCA method to estimate the unknown slope function $b(t)$. An FPCA is essentially a dimension–reduction procedure; it has been well examined in the literature. See, for example, James, Hastie and Sugar (2000), Yao, Müller and Wang (2005a), Hall, Müller and Wang (2006), and Li and Hsing (2010). We modify the method proposed by He, Müller and Wang (2000) and Yao, Müller and Wang (2005b) to fit our setting. First, we use the population least squares to obtain basis representations for θ , a , and $b(t)$. Then, we replace the unknown quantities by their empirical versions with finite terms, and we derive the optimal rate of convergence for the FPCA-based estimator of the slope function $b(t)$ under certain smoothness assumptions. Next, we establish the consistency and asymptotic normality of the estimator of θ and show that this naive FPCA-based estimator is not efficient in the case of Bickel et al. (1998). We then construct an asymptotically efficient estimator for θ and propose a test statistic for θ . In practice values of X_i may be sparsely observed at a set of discrete points with noise (Yao, Müller and Wang (2005a); Yao, Müller and Wang (2005b); Li and Hsing (2010); Zhang and Wang (2016)). Lastly, we extend the FPCA-based estimation method to include sparsely and irregularly sampled functional data and establish the asymptotic consistency properties of the resulting estimators.

The rest of the paper is organized as follows. Section 2 discusses identifiability, derives the estimators for θ , a , and $b(t)$, and investigates the asymptotic properties of the proposed estimators. These properties include the consistency and asymptotic normality of the estimator of the primary parameter θ and the rate of convergence and optimality of the estimator of the slope function $b(t)$. Section 3 derives an efficient influence function for estimating θ and constructs an efficient estimator. We propose a testing procedure for θ in Section 4. Section 5 extends the proposed estimator to sparsely and irregularly sampled functional data. Section 6 presents simulation studies for evaluating the finite-sample performance of the proposed procedures. Section 7 analyzes a data set from an AIDS study. All proofs are relegated to the Supplementary Material.

2. Identifiability and Estimation

In this section, we first explore the identifiability issue for model (1.2). Then, we use the population least squares to obtain basis representations of θ , a , and $b(t)$ (He, Müller and Wang (2000), Yao, Müller and Wang (2005b)). The proposed estimators are obtained by replacing the unknown quantities in the representations with their empirical versions. Henceforth, we write $\int pq$ for $\int_{\mathcal{I}} p(t)q(t) dt$.

2.1. Model identifiability

First, we show that the functional model (1.1) is identifiable under mild conditions on the distribution of X . Let the covariance function of $X(\cdot)$ be $K(s, t) = \text{Cov}\{X(s), X(t)\}$. Its corresponding covariance operator, $K : L_2(\mathcal{I}) \rightarrow L_2(\mathcal{I})$, is defined by the mapping $(Kf)(s) = \int_{\mathcal{I}} K(s, t)f(t) dt$ for any $f \in L_2(\mathcal{I})$. If K is continuous and square integrable, we have the spectral decomposition from Mercer's theorem (Hsing and Eubank (2015, p. 120)): $K(s, t) = \sum_{j=1}^{\infty} \lambda_j \phi_j(s)\phi_j(t)$, where $\lambda_1 \geq \lambda_2 \geq \dots \geq 0$ are the eigenvalues, and ϕ_1, ϕ_2, \dots are the orthonormal eigenfunctions of the operator K . The eigenfunctions ϕ_j are also known as the functional principal components. The operator K is of full rank in $L_2(\mathcal{I})$ (Hall and Hooker (2016)), i.e., $\lambda_j \neq 0$, for all j , and ϕ_1, ϕ_2, \dots are complete in $L_2(\mathcal{I})$.

Proposition 1. *Suppose $a \neq 0$ or $b(t) \neq 0$ almost everywhere on \mathcal{I} . If an alternative model intercept a_1 , a slope function $b_1(t)$, and a scalar parameter θ_1 exist, such that*

$$P \left\{ (1 - U + U\theta) \left(a + \int Xb \right) = (1 - U + U\theta_1) \left(a_1 + \int Xb_1 \right) \right\} = 1, \quad (2.1)$$

then $a = a_1$, $\theta = \theta_1$, and $b(t) = b_1(t)$ for almost all $t \in \mathcal{I}$.

Throughout this paper, we assume that K is of full rank, and $a \neq 0$ or $b(t) \neq 0$ almost everywhere on \mathcal{I} .

2.2. Population least squares

Let $\Xi = (0, +\infty) \times \mathbb{R} \times L_2(\mathcal{I})$ and

$$S(\vartheta, \nu, \xi) = E \left\{ Y - (1 - U + U\vartheta) \left(\nu + \int_{\mathcal{I}} X(t)\xi(t) dt \right) \right\}^2.$$

It follows from the proof of Proposition 1 that θ , a and, $b(t)$ are the unique minimum of $S(\vartheta, \nu, \xi)$ over $(\vartheta, \nu, \xi) \in \Xi$; that is

$$(\theta, a, b) = \arg \min_{(\vartheta, \nu, \xi) \in \Xi} S(\vartheta, \nu, \xi).$$

Recall that U and X are independent. It is clear that

$$a = \frac{(1 - \pi)\mu_0 + \pi\theta\mu_1}{1 - \pi + \pi\theta^2} - \int_{\mathcal{I}} \mu_X(t)b(t) dt, \tag{2.2}$$

where $\mu_j = E(Y|U = j)$, for $j = 0, 1$, and $\mu_X(t) = E\{X(t)\}$. It is easy to verify that $\mu_1 = \theta\mu_0$. Consequently, finding ϑ, ν , and $\xi(\cdot)$ to minimize $S(\vartheta, \nu, \xi)$ is equivalent to finding ϑ and $\xi(\cdot)$ to minimize

$$E \left[Y - \frac{1-U+U\vartheta}{1-\pi+\pi\vartheta^2} \{ (1-\pi)\mu_0 + \pi\vartheta\mu_1 \} - (1-U+U\vartheta) \int_{\mathcal{I}} \{ X(t) - \mu_X(t) \} \xi(t) dt \right]^2. \tag{2.3}$$

Define two cross-covariance functions:

$$\begin{aligned} g(t) &= E\{(Y - \mu_Y)(X(t) - \mu_X(t))|U = 1\}, \\ h(t) &= E\{(Y - \mu_Y)(X(t) - \mu_X(t))|U = 0\}, \end{aligned}$$

where $\mu_Y = E(Y)$. Then, $g(t) = \theta h(t)$ for all $t \in \mathcal{I}$.

Moreover, if we expand $b(t) = \sum_{j=1}^{\infty} b_j \phi_j(t)$, $g(t) = \sum_{j=1}^{\infty} g_j \phi_j(t)$, and $h(t) = \sum_{j=1}^{\infty} h_j \phi_j(t)$ using $b_j = \int b \phi_j$, $g_j = \int g \phi_j$, and $h_j = \int h \phi_j$, then, by minimizing the objective function (2.3) subject to ϑ and $\xi(\cdot)$, we obtain

$$b_j = \lambda_j^{-1} \frac{(1 - \pi)h_j + \pi\theta g_j}{1 - \pi + \pi\theta^2} \tag{2.4}$$

and

$$\theta = \frac{\sum_{j=1}^{\infty} \lambda_j^{-1} g_j^2 + \mu_1^2}{\sum_{j=1}^{\infty} \lambda_j^{-1} g_j h_j + \mu_0 \mu_1}. \tag{2.5}$$

Furthermore, $\sum_{j=1}^{\infty} \lambda_j^{-1} h_j^2 = E\{\int (X - \mu_X)b\}^2 \leq \int E(X - \mu_X)^2 \int b^2$ from the Cauchy-Schwarz inequality. Recall that $\int E(X^2) < \infty$ and $g_j = \theta h_j$, and that we assume that $b(t)$ is square integrable. Then, $\sum_{j=1}^{\infty} \lambda_j^{-1} g_j^2$, $\sum_{j=1}^{\infty} \lambda_j^{-1} g_j h_j$, and $\sum_{j=1}^{\infty} \lambda_j^{-1} h_j^2$ are all convergent. Hence, the right-hand side of (2.5) is well defined.

2.3. Estimation

Next, we describe the empirical versions of the basis representations of θ, a , and $b(t)$. The conventional estimator \widehat{K} of K is defined as

$$\widehat{K}(s, t) = \frac{1}{n} \sum_{i=1}^n \{X_i(s) - \bar{X}(s)\} \{X_i(t) - \bar{X}(t)\},$$

where $\bar{X} = n^{-1} \sum_{i=1}^n X_i$. Mercer's theorem provides the spectral decomposition of the covariance function \widehat{K} as $\widehat{K}(s, t) = \sum_{j=1}^{\infty} \widehat{\lambda}_j \widehat{\phi}_j(s) \widehat{\phi}_j(t)$, where $\widehat{\lambda}_1 \geq \widehat{\lambda}_2 \geq \dots \geq 0$ are eigenvalues, and $\widehat{\phi}_1, \widehat{\phi}_2, \dots$ are the corresponding orthonormal eigenfunctions. Note that $\widehat{\lambda}_j$ vanish for $j \geq n + 1$. Thus, the functions $\widehat{\phi}_{n+1}, \widehat{\phi}_{n+2}, \dots$ may be chosen arbitrarily.

Define

$$\hat{g}(t) = \frac{1}{n\hat{\pi}} \sum_{i=1}^n Y_i U_i \{X_i(t) - \bar{X}(t)\},$$

$$\hat{h}(t) = \frac{1}{n(1-\hat{\pi})} \sum_{i=1}^n Y_i (1 - U_i) \{X_i(t) - \bar{X}(t)\},$$

where $\hat{\pi} = n^{-1} \sum_{i=1}^n U_i$. Note that $E[YU\{X(t) - \mu_X(t)\}] = \pi g(t)$. Therefore, we can treat $\hat{g}(t)$ as an estimator of $g(t)$. Similarly, $\hat{h}(t)$ is an estimator of $h(t)$. Note that we can represent $\hat{g}(t) = \sum_{j=1}^{\infty} \hat{g}_j \hat{\phi}_j(t)$ and $\hat{h}(t) = \sum_{j=1}^{\infty} \hat{h}_j \hat{\phi}_j(t)$ using $\hat{g}_j = \int \hat{g} \hat{\phi}_j$ and $\hat{h}_j = \int \hat{h} \hat{\phi}_j$, respectively.

Equation (2.5) suggests the following estimator for θ :

$$\hat{\theta} = \frac{\sum_{j=1}^{m_n} \hat{\lambda}_j^{-1} \hat{g}_j^2 + \hat{\mu}_1^2}{\sum_{j=1}^{m_n} \hat{\lambda}_j^{-1} \hat{g}_j \hat{h}_j + \hat{\mu}_0 \hat{\mu}_1}, \quad (2.6)$$

where $\hat{\mu}_0 = \{n(1-\hat{\pi})\}^{-1} \sum_{j=1}^n Y_j (1 - U_j)$ and $\hat{\mu}_1 = (n\hat{\pi})^{-1} \sum_{j=1}^n Y_j U_j$ are the sample averages of μ_0 and μ_1 , respectively, and m_n is a positive integer less than n . Assumptions on m_n will be imposed later. In practice, m_n can be chosen using cross-validation.

Equation (2.4) suggests the following estimator for $b(t)$:

$$\hat{b}(t) = \sum_{j=1}^{m_n} \hat{b}_j \hat{\phi}_j(t), \quad \text{where} \quad \hat{b}_j = \frac{(1-\hat{\pi})\hat{h}_j + \hat{\pi}\hat{\theta}\hat{g}_j}{\hat{\lambda}_j(1-\hat{\pi} + \hat{\pi}\hat{\theta}^2)}. \quad (2.7)$$

Finally, equation (2.2) suggests the following estimator for a :

$$\hat{a} = \frac{(1-\hat{\pi})\hat{\mu}_0 + \hat{\pi}\hat{\theta}\hat{\mu}_1}{1-\hat{\pi} + \hat{\pi}\hat{\theta}^2} - \int_{\mathcal{I}} \bar{X}(t) \hat{b}(t) dt. \quad (2.8)$$

2.4. Asymptotic properties

We now derive the asymptotic normality for the estimator $\hat{\theta}$ and the rate of convergence for the estimator $\hat{b}(t)$ under the L_2 -norm. Then, we show that the rate of convergence is optimal in the minimax sense.

The Karhunen–Loève expansion of the random function $X(t)$ is given by $X(t) = \mu_X(t) + \sum_{j=1}^{\infty} \xi_j \phi_j(t)$, where $\xi_j = \int (X - \mu_X) \phi_j$ are uncorrelated random variables with mean zero and variance $E(\xi_j^2) = \lambda_j$, known as functional principal component scores. Let $C > 1$ be a sufficiently large constant. We make the assumptions.

- (A1) $X(t)$ has a finite fourth moment, i.e., $\int_{\mathcal{I}} E\{X^4(t)\} dt < \infty$; $E(\xi_j^4) \leq C\lambda_j^2$ for all $j \geq 1$.
- (A2) $C^{-1}j^{-\alpha} \leq \lambda_j \leq Cj^{-\alpha}$ and $\lambda_j - \lambda_{j+1} \geq C^{-1}j^{-\alpha-1}$ for some $\alpha > 1$ and all

$$j \geq 1.$$

(A3) $|b_j| \leq Cj^{-\beta}$ for some $\beta > \alpha/2 + 1$ and all $j \geq 1$.

(A4) $m_n \rightarrow \infty$ and $m_n^{2\alpha+2}/n \rightarrow 0$ as $n \rightarrow \infty$.

Assumptions (A1)–(A3) are standard in the literature on functional linear regressions when the FPCA approach is used. See, for example, Cai and Hall (2006) and Hall and Horowitz (2007). In Assumption (A2), α measures the smoothness of the covariance function K , and it also affects the rate of convergence when estimating the slope function $b(t)$ (Theorem 2 below). The second part of Assumption (A2) requires that the spaces between λ_j are not too small, which ensures that each individual ϕ_j is identifiable. Assumption (A3) implies that $b(t)$ is sufficiently smooth, given $\beta > \alpha/2 + 1$. See Hall and Horowitz (2007) for a detailed discussion of these assumptions. Assumption (A4) is a technical condition used in the proofs of the theorems below. The same assumption was made by Imaizumi and Kato (2018) for functional linear regressions with functional responses. Note that if $m_n \asymp n^{1/(\alpha+2\beta)}$, it is easy to verify that Assumption (A4) holds, where, for two positive sequences r_n and s_n , $r_n \asymp s_n$ means that r_n/s_n is bounded away from zero and ∞ as $n \rightarrow \infty$.

Theorem 1. *Under Assumptions (A1)–(A4), $\hat{\theta}$ is a consistent estimator of θ . Furthermore, we have*

$$\begin{aligned} \sqrt{n}(\hat{\theta} - \theta) &= n^{-1/2} \sum_{i=1}^n \psi(\theta; Y_i, X_i, U_i) + o_p(1) \\ &\xrightarrow{d} N\left(0, \frac{u_4\theta^2 + \sigma^2 u_2(1 - \pi + \pi\theta^2)}{\pi(1 - \pi)u_2^2}\right), \end{aligned}$$

where

$$\psi(\theta; Y, X, U) = \left(\frac{U}{\pi} - \frac{1-U}{1-\pi}\right) \left(\frac{r^2(X)}{u_2} - 1\right) \theta + \left(\frac{U}{\pi} - \theta \frac{1-U}{1-\pi}\right) \frac{r(X)}{u_2} \varepsilon$$

is the influence function of θ , $u_2 = E\{r(X)\}^2 = E(a + \int Xb)^2$, and $u_4 = \text{Var}\{r^2(X)\} = \text{Var}\{(a + \int Xb)^2\}$.

Remark 1. Assumption (A1) ensures that u_2 and u_4 are finite. Theorem 1 implies that when π gets close to zero or one, the asymptotic variance of $\hat{\theta}$ can be very large. Therefore, the performance of the estimator $\hat{\theta}$ may be poor when the sample size of one group is too small compared to that of the other group.

Next, we establish the asymptotic property for $\hat{b}(t)$. Let $\mathcal{F} = \mathcal{F}(C, \alpha, \beta)$ denote the set of all distributions F of (Y, X, U) that are compatible with As-

sumptions (A1)–(A3), for given values of C, α , and β . Then, following Theorem 1 of Hall and Horowitz (2007), we obtain the same rate of convergence of $\widehat{b}(t)$ as Hall and Horowitz (2007) do.

Theorem 2. *Suppose Assumptions (A1)–(A3) are satisfied. Take $m_n \asymp n^{1/(\alpha+2\beta)}$. Then, we have*

$$\lim_{M \rightarrow \infty} \limsup_{n \rightarrow \infty} \sup_{F \in \mathcal{F}} P_F \left[\int_{\mathcal{I}} \{\widehat{b}(t) - b(t)\}^2 dt > Mn^{-(2\beta-1)/(\alpha+2\beta)} \right] = 0. \quad (2.9)$$

Furthermore,

$$\liminf_{n \rightarrow \infty} n^{(2\beta-1)/(\alpha+2\beta)} \inf_{\bar{b}} \sup_{F \in \mathcal{F}} E_F \int_{\mathcal{I}} \{\bar{b}(t) - b(t)\}^2 dt > 0, \quad (2.10)$$

where $\inf_{\bar{b}}$ is taken over all possible estimators, \bar{b} .

The limit in (2.10) shows that the minimax lower bound of the convergence rate for estimating $b(t)$ is $n^{-(2\beta-1)/(\alpha+2\beta)}$, and (2.9) indicates that this rate is achieved with $m_n \asymp n^{1/(\alpha+2\beta)}$. Therefore, $\widehat{b}(t)$ with $m_n \asymp n^{1/(\alpha+2\beta)}$ is a rate-optimal estimator. Furthermore, $n^{-(2\beta-1)/(\alpha+2\beta)}$ is the minimax optimal rate of convergence under the L_2 -risk, which is determined by the smoothness of the slope function and the decay rate of the eigenvalues of the covariance function.

3. Semiparametric Efficiency

The estimator $\widehat{\theta}$ of the parameter θ proposed in Section 2 is derived from $g_j = \theta h_j$ and $\mu_1 = \theta \mu_0$. This suggests that there are many potential estimators of θ , for example, $\widehat{g}_1/\widehat{h}_1$ or $(\widehat{g}_1 + 2\widehat{g}_2)/(\widehat{h}_1 + 2\widehat{h}_2)$. Thus, a natural question is whether $\widehat{\theta}$ is optimal among all regular estimators of θ . We now investigate the semiparametric efficiency of the semiparametric model (1.1). We demonstrate that $\widehat{\theta}$ is not semiparametrically efficient, even when ε is normally distributed. Then, we derive the efficient score and propose an efficient estimator based on $\widehat{\theta}$ when ε is normally distributed.

To achieve this goal, we first derive the efficient score and information bound. Similar derivations for general semiparametric models for independent data are proposed in Severini and Wong (1992), Bickel et al. (1998), and Brown and Newey (1998).

Suppose $\varepsilon \sim N(0, \sigma^2)$. In Section S5 of the Supplementary Material, we show that for model (1.2), the efficient score for θ is

$$i_{\theta}^* = \frac{U(1-\pi) - (1-U)\pi\theta}{(1-\pi + \pi\theta^2)\sigma^2} r(X)\varepsilon. \quad (3.1)$$

Then, the semiparametric information bound for θ is

$$I(\theta) = E(i_{\theta}^{*2}) = \frac{\pi(1-\pi)}{(1-\pi + \pi\theta^2)\sigma^2} u_2. \quad (3.2)$$

Therefore, the lower bound of the asymptotic variance of the regular estimators of θ is $(1-\pi + \pi\theta^2)\sigma^2/\{\pi(1-\pi)u_2\}$. Theorem 1 indicates that $\widehat{\theta}$ cannot achieve this bound, and that $\widehat{\theta}$ is not semiparametrically efficient, even if ε is normally distributed.

Next, we construct a more efficient estimator for θ than $\widehat{\theta}$, using $\widehat{\theta}$ as a preliminary estimator. Then, we demonstrate that the resultant estimator is semiparametrically efficient when ε follows a normal distribution. From Bickel et al. (1998), the efficient influence function for θ is given by

$$\psi^*(\theta; Y, X, U) = I^{-1}(\theta)i_{\theta}^* = \left(\frac{U}{\pi} - \theta \frac{1-U}{1-\pi} \right) \frac{r(X)}{u_2} \varepsilon.$$

Thus, we construct the following estimator for θ :

$$\widehat{\theta}^* = \widehat{\theta} + \frac{1}{n} \sum_{i=1}^n \left(\frac{U_i}{\widehat{\pi}} - \widehat{\theta} \frac{1-U_i}{1-\widehat{\pi}} \right) \frac{\widehat{r}(X_i)}{\widehat{u}_2} \widehat{\varepsilon}_i, \quad (3.3)$$

where $\widehat{r}(X_i) = \widehat{a} + \int_{\mathcal{I}} X_i(t) \widehat{b}(t) dt$, $\widehat{u}_2 = n^{-1} \sum_{i=1}^n \widehat{r}^2(X_i)$, and $\widehat{\varepsilon}_i = Y_i - (1-U_i + U_i \widehat{\theta}) \widehat{r}(X_i)$. Here, $\widehat{\theta}^*$ is derived as a one-step Newton–Raphson approximation.

Theorem 3. *Under the assumptions of Theorem 2, the estimator $\widehat{\theta}^*$ is asymptotically normal, i.e.,*

$$\sqrt{n}(\widehat{\theta}^* - \theta) = n^{-1/2} \sum_{i=1}^n \psi^*(\theta; Y_i, X_i, U_i) + o_p(1) \xrightarrow{d} N(0, I^{-1}(\theta)).$$

Furthermore, when ε follows a normal distribution, $\widehat{\theta}^*$ is semiparametrically efficient.

Remark 2. Note that when the density function of ε is known, but not normal, or is unknown, $\widehat{\theta}^*$ is not semiparametrically efficient. Schick (1993) constructed an efficient estimator for θ in model (1.1) using a discretized root- n preliminary estimator when the error density function is unknown. It is also worth deriving such an efficient estimator for θ in model (1.2) if the error density function is unknown. We leave this as a topic for future research.

Once the more efficient estimator $\widehat{\theta}^*$ is available, we can update the estimators of a and $b(t)$, as follows:

$$\widehat{b}^*(t) = \sum_{j=1}^{m_n} \widehat{b}_j^* \widehat{\phi}_j(t) \quad \text{with} \quad \widehat{b}_j^* = \widehat{\lambda}_j^{-1} \frac{(1 - \widehat{\pi})\widehat{h}_j + \widehat{\pi}\widehat{\theta}^*\widehat{g}_j}{1 - \widehat{\pi} + \widehat{\pi}\widehat{\theta}^{*2}},$$

$$\widehat{a}^* = \frac{(1 - \widehat{\pi})\widehat{\mu}_0 + \widehat{\pi}\widehat{\theta}^*\widehat{\mu}_1}{1 - \widehat{\pi} + \widehat{\pi}\widehat{\theta}^{*2}} - \int_{\mathcal{I}} \bar{X}(t)\widehat{b}^*(t) dt.$$

From the proof of Theorem 2 in the Supplementary Material, $\widehat{b}^*(t)$ with $m_n \asymp n^{1/(\alpha+2\beta)}$ is also a rate-optimal estimator. Theoretically, $\widehat{b}(t)$ and \widehat{b}^* have the same rate of convergence. However, in Section 6, we show that \widehat{b}^* has better finite-sample performance.

4. Hypothesis Testing

The scalar parameter θ is sometimes of primary interest. For example, $\theta = 1$ means the curves of two groups are identical, indicating that the corresponding treatments have similar effects. Thus, we may need to test whether $\theta = 1$. In general, we can test

$$H_0 : \theta = \theta_0 \quad \text{versus} \quad H_1 : \theta \neq \theta_0.$$

Theorem 2 implies that $\{nI(\theta)\}^{1/2}(\widehat{\theta}^* - \theta) \rightarrow N(0, 1)$ in distribution. We can use this result to derive a test statistic after we estimate the information bound $I(\theta)$ by substituting all unknown quantities by their estimates. We estimate $I(\theta)$ by $\widehat{I}(\theta)$, as follows

$$\widehat{I}(\theta) = \frac{\widehat{\pi}(1 - \widehat{\pi})}{(1 - \widehat{\pi} + \widehat{\pi}\widehat{\theta}^{*2})\widehat{\sigma}^{*2}} \widehat{u}_2^*,$$

where

$$\widehat{u}_2^* = \frac{1}{n} \sum_{i=1}^n \left\{ \widehat{a}^* + \int_{\mathcal{I}} X_i(t)\widehat{b}^*(t) dt \right\}^2 \quad \text{and} \quad \widehat{\sigma}^{*2} = \frac{1}{n} \sum_{i=1}^n Y_i^2 - (1 - \widehat{\pi} + \widehat{\pi}\widehat{\theta}^{*2})\widehat{u}_2^*.$$

From the proof of Lemma 5 in Section S6 of the Supplementary Material, we can also prove that \widehat{u}_2^* converges to u_2 , in probability. From Theorem 3, it is easy to verify that $\widehat{I}(\theta)$ is a consistent estimator of $I(\theta)$. Consequently, we propose the following test statistic:

$$T_n^* = \{n\widehat{I}(\theta)\}^{1/2}(\widehat{\theta}^* - \theta_0).$$

This statistic is asymptotically normal under H_0 from the Slutsky theorem. This suggests rejecting H_0 when $|T_n^*|$ is larger than $z_{1-\tau/2}$, where z_τ is the τ -th quantile of the standard normal distribution. The procedure is equivalent to that of the Wald-type test.

5. Extension to Sparse and Irregular Data

The methodological and theoretical development in the previous sections is based on the assumption that the predictor trajectory $X(t)$ is fully observed without noise, which may not be true in practice. In this section, we assume that $X_i(t)$ can only be realized for some discrete set of sampling points with additional measurement errors; that is, we observe data

$$W_{ij} = X_i(T_{ij}) + \epsilon_{ij}, \quad j = 1, \dots, N_i, \quad (5.1)$$

where ϵ_{ij} are i.i.d. measurement errors with mean zero and finite variance σ_ϵ^2 , and each $N_i \geq 2$. Assume that X_i , T_{ij} , and ϵ_{ij} are all independent.

Most existing studies classify functional data as sparse or dense, depending on the number of observations within each curve; see Li and Hsing (2010). For dense functional data, we can smooth each individual curve first to construct the curve \widehat{X}_i from the data $\mathcal{D}_i = \{(T_{ij}, W_{ij}) : 1 \leq j \leq N_i\}$ (Ramsay and Silverman (2005)). It has been shown by Hall, Müller and Wang (2006) that when the observations are sufficiently dense, the smoothing errors are asymptotically negligible. Therefore, the methodology developed in the previous sections are carried out as if \widehat{X}_i is the true curve. However, for sparse functional data, this pre-smoothing method is inadequate.

The proposed estimation procedure in Section 2 can be extended to the case of sparse and irregular designs. A key step is to estimate $\mu_X(t)$, $K(s, t)$, $g(t)$, and $h(t)$ based on sparsely observed longitudinal data $\mathcal{D} = \{(T_{ij}, W_{ij}) : 1 \leq i \leq n, 1 \leq j \leq N_i\}$. We adapt the idea of pooling sparse longitudinal data across subjects and apply the local linear smoother to the resulting scatter plots (Yao, Müller and Wang (2005a,b); Hall, Müller and Wang (2006); Li and Hsing (2010); Zhang and Wang (2016)). Let $\kappa(\cdot)$ be a univariate kernel function. Then, the mean function μ_X , covariance function K , and cross-covariance functions f and g are estimated as follows. By an abuse of notation, we use c_0 and c_1 to denote local linear regressions when estimating these functions in this section.

Step 1 The local linear estimator of the mean function $\mu_X(t)$ is $\tilde{\mu}_X(t) = \widehat{c}_0$, where

$$(\widehat{c}_0, \widehat{c}_1) = \arg \min_{c_0, c_1} \sum_{i=1}^n \sum_{j=1}^{N_i} \kappa\left(\frac{T_{ij} - t}{d_\mu}\right) \{W_{ij} - c_0 - c_1(T_{ij} - t)\}^2,$$

with bandwidth d_μ .

Step 2 Let $G_i(T_{ij}, T_{il}) = \{W_{ij} - \tilde{\mu}_X(T_{ij})\}\{W_{il} - \tilde{\mu}_X(T_{il})\}$ for $1 \leq j, l \leq N_i$. The local linear estimator of the covariance function $K(s, t)$ is $\widetilde{K}(s, t) = \widehat{c}_0$,

where

$$(\widehat{c}_0, \widehat{c}_1, \widehat{c}_2) = \arg \min_{c_0, c_1, c_2} \sum_{i=1}^n \sum_{1 \leq j \neq l \leq N_i} \kappa\left(\frac{T_{ij} - s}{d_K}\right) \kappa\left(\frac{T_{il} - t}{d_K}\right) \\ \times \{G_i(T_{ij}, T_{il}) - c_0 - c_1(T_{ij} - s) - c_2(T_{il} - t)\}^2,$$

with bandwidth d_K .

Step 3 Let $C_i(T_{ij}) = Y_i\{W_{ij} - \widetilde{\mu}_X(T_{ij})\}$ for $1 \leq j \leq N_i$. The local linear estimators of the cross-covariance functions $g(t)$ and $h(t)$ are $\widetilde{g}(t) = \widehat{c}_0/\widehat{\pi}$ and $\widetilde{h}(t) = \widetilde{c}_0/(1 - \widehat{\pi})$, respectively, where

$$(\widehat{c}_0, \widehat{c}_1) = \arg \min_{c_0, c_1} \sum_{i=1}^n \sum_{j=1}^{N_i} \kappa\left(\frac{T_{ij} - t}{d_g}\right) \{C_i(T_{ij})U_i - c_0 - c_1(T_{ij} - t)\}^2, \\ (\widetilde{c}_0, \widetilde{c}_1) = \arg \min_{c_0, c_1} \sum_{i=1}^n \sum_{j=1}^{N_i} \kappa\left(\frac{T_{ij} - t}{d_h}\right) \{C_i(T_{ij})(1 - U_i) - c_0 - c_1(T_{ij} - t)\}^2,$$

with bandwidths d_g and d_h .

Bandwidths d_μ, d_K, d_g , and d_h for the above smoothing steps are selected by leave-one-curve-out cross-validation or generalized cross-validation. We denote the estimators of λ_j and $\phi_j(t)$ by $\widetilde{\lambda}_j$ and $\widetilde{\phi}_j(t)$, respectively. These can be calculated from an eigenvalue decomposition of $\widetilde{K}(\cdot, \cdot)$ using discretization and a matrix spectral decomposition (Yao, Müller and Wang (2005a)). Therefore, motivated by the population representations in Section 2, θ , a , and $b(t)$ are estimated as follows:

$$\widetilde{\theta} = \frac{\sum_{j=1}^{m_n} \widetilde{\lambda}_j^{-1} \widetilde{g}_j^2 + \widehat{\mu}_1^2}{\sum_{j=1}^{m_n} \widetilde{\lambda}_j^{-1} \widetilde{g}_j \widetilde{h}_j + \widehat{\mu}_0 \widehat{\mu}_1}, \quad \text{and} \quad \widetilde{b}(t) = \sum_{j=1}^{m_n} \widetilde{b}_j \widetilde{\phi}_j(t),$$

with

$$\widetilde{b}_j = \widetilde{\lambda}_j^{-1} \frac{(1 - \widehat{\pi})\widetilde{h}_j + \widehat{\pi}\widetilde{\theta}\widetilde{g}_j}{1 - \widehat{\pi} + \widehat{\pi}\widetilde{\theta}^2}, \quad \text{and} \quad \widetilde{a} = \frac{(1 - \widehat{\pi})\widehat{\mu}_0 + \widehat{\pi}\widetilde{\theta}\widehat{\mu}_1}{1 - \widehat{\pi} + \widehat{\pi}\widetilde{\theta}^2} - \int_{\mathcal{I}} \widetilde{\mu}_X(t) \widetilde{b}(t) dt,$$

where $\widetilde{f}_j = \int_{\mathcal{I}} \widetilde{f}(t) \widetilde{\phi}_j(t) dt$ and $\widetilde{g}_j = \int_{\mathcal{I}} \widetilde{g}(t) \widetilde{\phi}_j(t) dt$.

Next, we establish the consistency of the proposed estimators for sparse and irregular functional data. Let $\rho_{n1} = d_g^2 + (nd_g)^{-1/2}$, $\rho_{n2} = d_h^2 + (nd_h)^{-1/2}$, and $\rho_{n3} = d_K^2 + (nd_K)^{-1/2}$. We make the following assumptions for Theorem 4.

(B1) $\kappa(\cdot)$ is a symmetric probability density function on $[-1, 1]$ and is Lipschitz continuous: There exists $0 < L < \infty$, such that $|\kappa(s) - \kappa(t)| \leq L|s - t|$ for any $s, t \in [0, 1]$.

- (B2) T_{ij} are i.i.d. copies of a random variable T defined on \mathcal{I} with density function $\varphi_T(\cdot)$, and there exist constants $m_T > 0$ and $M_T < \infty$ such that $m_T \leq \varphi_T(t) \leq M_T$ for all $t \in \mathcal{I}$. Furthermore, the second derivative of $\varphi_T(\cdot)$ is bounded on \mathcal{I} .
- (B3) The second derivatives of $\mu_X(\cdot)$, $g(\cdot)$, and $h(\cdot)$ are bounded on \mathcal{I} . All second-order partial derivatives of $K(s, t)$ are bounded on \mathcal{I}^2 .
- (B4) $d_\mu \rightarrow 0$ and $\log(n)/(nd_\mu) \rightarrow 0$.
- (B5) $d_K \rightarrow 0$ and $\log(n)/(nd_K^2) \rightarrow 0$; $\sup_{t \in \mathcal{I}} E|X(t) - \mu_X(t)|^4 < \infty$ and $E|\epsilon_{ij}|^4 < \infty$.
- (B6) $d_g \rightarrow 0$ and $\log(n)/(nd_g) \rightarrow 0$; $d_h \rightarrow 0$ and $\log(n)/(nd_h) \rightarrow 0$.
- (B7) $m_n \rightarrow \infty$, $m_n^{\alpha+1/2} \rho_{n1} \rightarrow 0$, $m_n^{\alpha+1/2} \rho_{n2} \rightarrow 0$, and $m_n^{2\alpha+3/2} \rho_{n3} \rightarrow 0$ as $n \rightarrow \infty$.

Assumptions (B1)–(B5) are adopted from Zhang and Wang (2016). Assumptions (B4) and (B5) are special cases of (C1b)–(C3b) and (D1b)–(D3b), respectively, in Zhang and Wang (2016) for sparse functional data. Assumption (B6) is similar to (B4) and is used to establish the L_2 rates of convergence of $\tilde{g}(t)$ and $\tilde{h}(t)$. Assumption (B7) is a technique condition used in the proof of Theorem 4.

Theorem 4. *Suppose that Assumptions (A2)–(A3) and (B1)–(B7) hold. For sparse data: $\max_{1 \leq i \leq n} N_i \leq N_0 < \infty$, $\tilde{\theta}$ is consistent and*

$$\int_{\mathcal{I}} \{\tilde{b}(t) - b(t)\}^2 dt \xrightarrow{P} 0.$$

Remark 3. It is not clear whether $\tilde{\theta}$ maintains root- n consistency for sparse data. The rate of convergence for $\tilde{b}(t)$ is also not defined. In addition, the impact of N_i on the asymptotic properties of $\tilde{\theta}$ and $\tilde{b}(t)$ is unknown. These topics warrant future research.

6. Simulation Studies

We conduct three Monte Carlo simulation studies to evaluate the numerical performance of the proposed estimation and test procedures. In Section 6.1, we examine the finite sample performance of $\hat{\theta}$ and $\hat{\theta}^*$ and $\hat{b}(\cdot)$ and $\hat{b}^*(\cdot)$ for different sample sizes, variances of the error, and smoothness of the covariance function K . In Section 6.2, we assess the type I error rate and the power of the statistic

T_n^* . In Section S1 of the Supplementary Material, we examine the finite sample performance of $\tilde{\theta}$ and $\tilde{b}(\cdot)$.

6.1. Estimation

For $r(X) = a + \int_{\mathcal{I}} X(t)b(t) dt$, we adopt a design similar to that of Hall and Horowitz (2007) and Yuan and Cai (2010); that is, $\mathcal{I} = [0, 1]$, $a = 0$, and $b(t)$ is given by

$$b(t) = 0.3\phi_1(t) + \sum_{k=2}^{50} 4(-1)^{k+1}k^{-2}\phi_k(t),$$

where $\phi_1(t) = 1$ and $\phi_{k+1}(t) = 2^{1/2} \cos(k\pi t)$ for $k \geq 1$. The random function $X(t)$ is generated as $X(t) = \sum_{k=1}^{50} \gamma_k Z_k \phi_k(t)$, where Z_k are independently sampled from a uniform distribution on $[-3^{1/2}, 3^{1/2}]$. It is clear that the eigenvalues of the covariance function of $X(t)$ are γ_k^2 . There are two sets of γ_k , the “well-spaced” and “closely spaced” eigenvalues, used in Hall and Horowitz (2007) and Yuan and Cai (2010). However, we only consider the “well-spaced” eigenvalues, where $\gamma_k = (-1)^{k+1}k^{-\alpha/2}$ with $\alpha = 1.1, 1.5, 2, 2.5$.

Let $\theta = 1.5$, and let U follow a binomial distribution with a success probability of $\pi = 0.6$. The error ε follows a normal distribution $N(0, \sigma^2)$, where $\sigma = 0.5$ or 1.0 . In addition, $X(t), U$, and ε are sampled independently. We consider $n = 200, 350, 500$, and 800 .

We repeat each configuration $Q = 1,000$ times, and choose m_n using 10-fold cross-validation. Table 1 presents the averages and standard deviations of the estimated $\hat{\theta}$ and $\hat{\theta}^*$. For each combination of α and σ , the average value of $\hat{\theta}$ gets closer to the true value, and the standard deviation decreases as increases n . Comparing the results for $\hat{\theta}$ and $\hat{\theta}^*$, $\hat{\theta}^*$ has a smaller standard deviation than that of $\hat{\theta}$. This observation confirms that $\hat{\theta}^*$ is more efficient than $\hat{\theta}$.

We use the mean integrated squared error (MISE) to evaluate the performance of the estimator $\hat{b}(t)$:

$$\text{MISE}(\hat{b}(t)) = Q^{-1} \sum_{q=1}^Q \int_0^1 \{\hat{b}(t)^{[q]} - b(t)\}^2 dt,$$

where $\{\hat{b}(t)^{[q]}, q = 1, \dots, Q\}$ are estimators of $b(t)$ obtained from the $Q = 1,000$ data sets. $\text{MISE}(\hat{b}^*)$ is defined analogously. The MISE and the associated standard deviations of the estimates $\hat{b}(t)$ and $\hat{b}^*(t)$ are displayed in Table 2. For each combination of α and σ , the MISE and the standard deviation decrease as n increases. The MISE of $\hat{b}^*(t)$ is consistently smaller than that of $\hat{b}(t)$, and the

Table 1. The results of the simulation study (estimation). The average and standard deviation (shown in parentheses) of the estimators (Est) $\hat{\theta}$ and $\hat{\theta}^*$ for $\theta = 1.5$.

Est	σ	n	$\alpha = 1.1$	$\alpha = 1.5$	$\alpha = 2.0$	$\alpha = 2.5$
$\hat{\theta}$	0.5	200	1.582(0.306)	1.582(0.317)	1.557(0.321)	1.555(0.326)
		350	1.546(0.221)	1.554(0.228)	1.557(0.238)	1.558(0.254)
		500	1.526(0.178)	1.531(0.186)	1.531(0.197)	1.533(0.202)
		800	1.517(0.147)	1.522(0.153)	1.524(0.159)	1.527(0.162)
	1.0	200	1.633(0.399)	1.649(0.464)	1.621(0.504)	1.653(0.610)
		350	1.573(0.289)	1.572(0.298)	1.581(0.330)	1.600(0.393)
		500	1.548(0.236)	1.561(0.264)	1.567(0.282)	1.562(0.291)
		800	1.525(0.175)	1.530(0.195)	1.548(0.212)	1.542(0.229)
$\hat{\theta}^*$	0.5	200	1.474(0.131)	1.471(0.140)	1.471(0.162)	1.493(0.192)
		350	1.482(0.095)	1.487(0.102)	1.486(0.121)	1.485(0.135)
		500	1.486(0.079)	1.490(0.085)	1.497(0.104)	1.499(0.115)
		800	1.492(0.064)	1.495(0.071)	1.496(0.081)	1.498(0.090)
	1.0	200	1.498(0.265)	1.499(0.305)	1.543(0.397)	1.518(0.442)
		350	1.508(0.196)	1.505(0.216)	1.510(0.256)	1.523(0.300)
		500	1.499(0.162)	1.509(0.192)	1.510(0.207)	1.513(0.224)
		800	1.496(0.117)	1.496(0.137)	1.511(0.161)	1.501(0.182)

MISE increases with σ for given n and α . The MISEs of $\hat{b}^*(t)$ and $\hat{b}(t)$ also increase with α , for given n and σ . Given σ , the standard deviations of the MISEs of $\hat{b}^*(t)$ and $\hat{b}(t)$ seem stable with α when $n = 800$, but increase with α when n is less than 800. It is interesting that the standard deviation of the MISE of $\hat{b}^*(t)$ is consistently larger than that of $\hat{b}(t)$.

We also compare the proposed method with the FMR method (Yao, Fu and Lee (2011)) under the current simulation setting, where the number of groups is two for the FMR. Because the FMR is a nonparametric model, we can only compare the performance of the estimators of $b(t)$. Let $\hat{b}^{\text{FMR}}(t)$ be the FMR estimator of $b(t)$ proposed by Yao, Fu and Lee (2011). The MISE and associated standard deviation of $\hat{b}^{\text{FMR}}(t)$ are displayed in Table 2. For each configuration, the MISE and the standard deviation of $\hat{b}^{\text{FMR}}(t)$ are consistently larger than those of $\hat{b}(t)$ and $\hat{b}^*(t)$. This may indicate that the proposed estimators outperform the competitor, $\hat{b}^{\text{FMR}}(t)$.

6.2. Testing

We examine the finite sample performance of the statistic T_n^* given in Section 4. We use the same setting for $r(X)$ and U as that in Subsection 6.1, but let $\theta = 1$ and $\alpha = 1.1$. Consider the following hypothesis:

Table 2. The results of the simulation study (estimation). The MISE of the estimated slope functions $\widehat{b}(t)$, \widehat{b}^* , and \widehat{b}^{FMR} . The corresponding standard deviations are given in parentheses.

	σ	n	$\alpha = 1.1$	$\alpha = 1.5$	$\alpha = 2.0$	$\alpha = 2.5$
$\widehat{b}(t)$	0.5	200	0.126(0.078)	0.103(0.061)	0.161(0.059)	0.345(0.074)
		350	0.095(0.058)	0.080(0.044)	0.078(0.038)	0.085(0.042)
		500	0.076(0.045)	0.067(0.034)	0.136(0.034)	0.136(0.027)
		800	0.065(0.035)	0.060(0.026)	0.058(0.022)	0.061(0.021)
	1.0	200	0.164(0.105)	0.155(0.099)	0.221(0.111)	0.247(0.134)
		350	0.184(0.084)	0.214(0.098)	0.177(0.063)	0.195(0.078)
		500	0.093(0.052)	0.089(0.050)	0.099(0.053)	0.167(0.051)
		800	0.074(0.039)	0.071(0.033)	0.078(0.035)	0.095(0.048)
\widehat{b}^*	0.5	200	0.115(0.076)	0.092(0.058)	0.151(0.053)	0.337(0.069)
		350	0.088(0.056)	0.073(0.042)	0.071(0.035)	0.077(0.039)
		500	0.072(0.044)	0.062(0.032)	0.131(0.031)	0.132(0.025)
		800	0.062(0.035)	0.057(0.025)	0.055(0.020)	0.058(0.020)
	1.0	200	0.157(0.103)	0.145(0.094)	0.215(0.145)	0.242(0.135)
		350	0.178(0.084)	0.166(0.066)	0.173(0.062)	0.189(0.074)
		500	0.088(0.049)	0.084(0.046)	0.093(0.050)	0.164(0.049)
		800	0.071(0.038)	0.068(0.030)	0.076(0.032)	0.092(0.048)
\widehat{b}^{FMR}	0.5	200	0.479(0.353)	0.531(0.424)	0.696(0.706)	0.907(0.887)
		350	0.359(0.298)	0.464(0.396)	0.597(0.563)	0.760(0.821)
		500	0.299(0.274)	0.399(0.377)	0.535(0.550)	0.734(0.846)
		800	0.241(0.257)	0.350(0.348)	0.467(0.530)	0.608(0.648)
	1.0	200	1.106(1.097)	1.369(1.415)	1.961(2.552)	2.400(3.091)
		350	0.955(0.873)	1.220(1.342)	1.640(2.051)	2.117(2.728)
		500	0.911(0.883)	1.068(1.087)	1.596(2.175)	2.261(3.768)
		800	0.756(0.737)	1.024(1.164)	1.326(1.640)	1.852(2.726)

$$H_0 : \theta = 1 \quad \text{versus} \quad H_1 : \theta = c,$$

where c ranges from 1 to 1.6, with an increment of 0.01. To show the effects of estimating $I(\theta)$ using $\widehat{I}(\theta)$, we proceed with $T_n = \{nI(\theta)\}^{1/2}(\widehat{\theta}^* - \theta)$ as though $I(\theta)$ were known, and then compare it with $T_n^* = \{n\widehat{I}(\theta)\}^{1/2}(\widehat{\theta}^* - \theta)$. The exact value of $I(\theta)$ is calculated using (3.2), with $\pi = 0.6$, $\theta = 1$, and $\sigma = 0.5$ or 1.0, and u_2 is calculated as $u_2 = E\left(\int_0^1 Xb\right)^2 = 0.3^2 + 16 \sum_{j=2}^{50} j^{-(4+\alpha)}$.

We set 0.05 as the nominal level, and generate 1,000 data sets. Each consists of $n = 500$ or 800 random samples in order to calculate the type I errors and the power of T_n and T_n^* . Figure 1 displays the power against c for four different settings: $(\sigma, n) = (0.5, 500)$, $(1.0, 500)$, $(0.5, 800)$, and $(1.0, 800)$. In each plot, the solid and dashed lines denote the power functions of T_n and T_n^* , respectively. These two curves are close to each other. This indicates good performance of

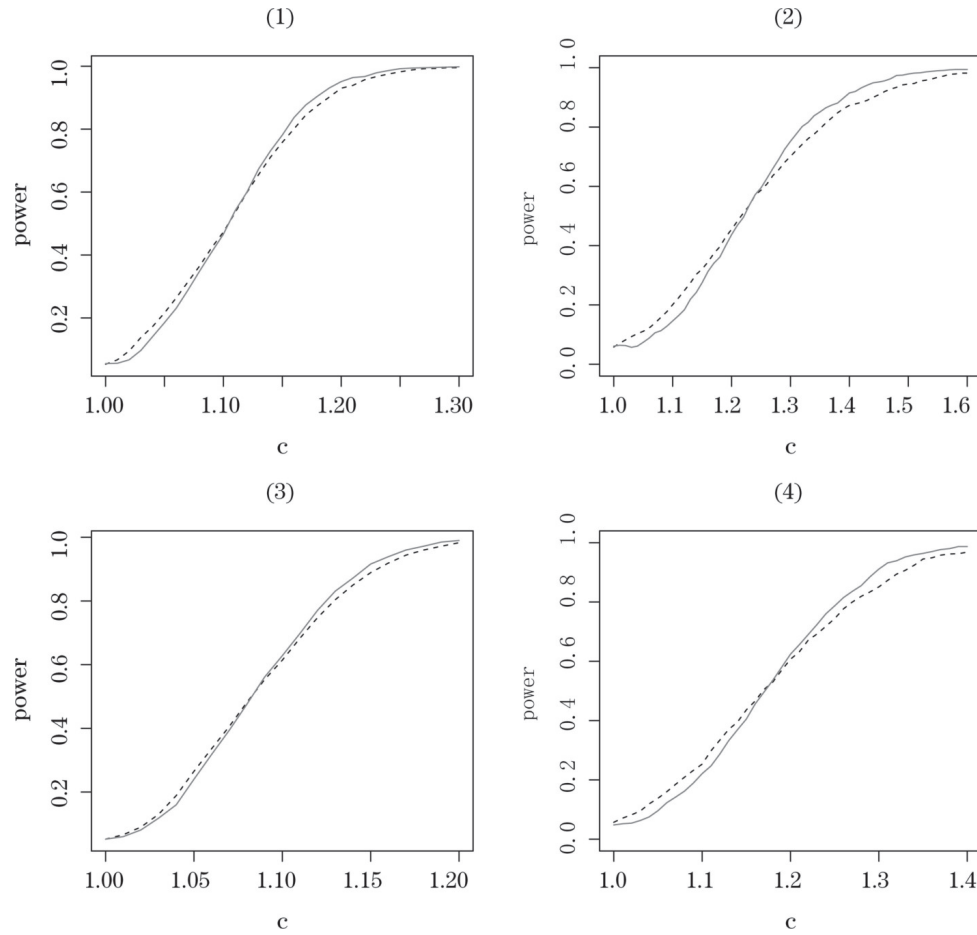


Figure 1. The results of the simulation study (testing). The power functions of the test statistic T_n^* (dashed line) and T_n (solid line) for the four settings (1)–(4), corresponding to $(\sigma, n) = (0.5, 500)$, $(1.0, 500)$, $(0.5, 800)$, and $(1.0, 800)$ for (1)–(4), respectively.

$\widehat{I}(\theta)$ as an estimator of $I(\theta)$ and that T_n^* performs well. The type I errors (the power at $c = 1$) for the four settings are displayed in Table 3. They are close to the nominal level of 0.05. Moreover, we observe that the empirical size of the power increases to one as c increases. The results show that the proposed T_n^* is a useful test.

7. Application to an AIDS Data Set

In this section, we illustrate the proposed procedures by analyzing a data set from an AIDS study. Here, CD4+ cells are targets of HIV and decrease

Table 3. The results of the simulation study (testing). Type I error rates of T_n^* and T_n for the four settings with respect to the nominal level 0.05.

(σ, n)	(0.5, 500)	(1.0, 500)	(0.5, 800)	(1.0, 800)
T_n^*	0.053	0.058	0.052	0.057
T_n	0.055	0.061	0.052	0.048

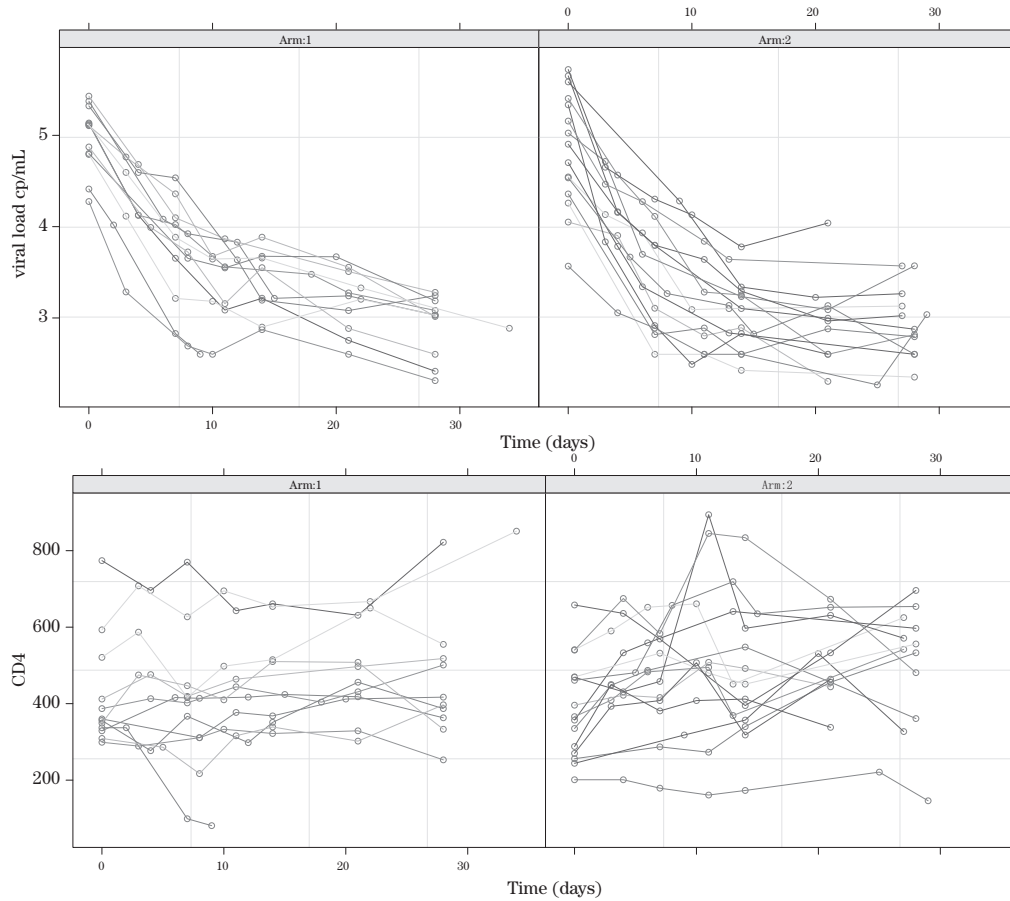


Figure 2. Scatter plots of the viral load (upper panel) and the CD4+ cell count (lower panel) against the treatment times for two arms.

in number after HIV infection. Thus, when antiviral therapies suppress the viral load, the CD4+ cell count may recover to a higher level (Lederman et al. (1998)). It is believed that the virologic response (measured by the viral load) and the immunologic response (measured by the CD4+ cell count) are negatively correlated during antiviral treatments. However, this relationship may not be

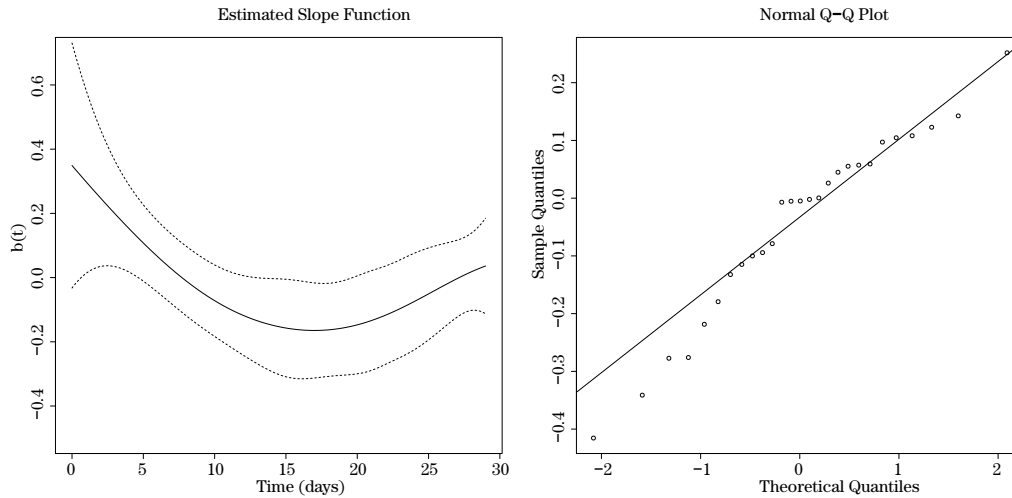


Figure 3. The results for the CD4+ data set: The estimated slope function $\hat{b}(t)$ and the 95% bootstrap pointwise confidence interval (left panel), and the Q–Q plot of the residuals (right panel).

constant throughout the treatment period. In fact, discordance between the virologic and immunologic responses has been observed in several clinical studies (Mellors et al. (1996); Wu, Ding and DeGruttola (1998)).

Motivated by an ACTG study (Lederman et al. (1998)), we use model (1.2) and apply the proposed procedures to analyze a data set from this study. Here, 53 HIV-1 infected patients were divided into two arms (arms 1 and 2) and were treated with potent antiviral drugs. In all, 361 observations of viral loads and CD4+ cell counts were obtained on days 0, 2, 7, 10, 14, 21, and 28.

The CD4+ and viral load patterns of the two arms show similarities (See Figure 2), and a combination of these two arms may be beneficial to evaluating the treatment and increasing its power. Here, θ reflects how close the effects of the viral load on the CD4+ cell count are in the two arms. In our initial analysis, the observations from the two arms were combined for the preliminary report. We now rigorously evaluate the difference by estimating θ , and then investigate whether such a combination is appropriate. We average the CD4+ count over time and divide it by 1,000. We treated this as the response variable Y , and used the viral load as the functional predictor $X(t)$, $t \in \mathcal{I}$, where $\mathcal{I} = [0, 29]$.

The smoothing parameter $m_n = 2$ is obtained using leave-one-out cross-validation. The estimated $\hat{\theta}^* = 0.9591$. The estimated slope function, and the associated pointwise confidence interval are depicted in the left panel of Figure 3.

The pattern shows that the CD4+ cell count increases as the viral load decreases in the primary treatment period. This negative relationship lasts until day 15, and then changes to a slight positive trend. The right panel of Figure 3 plots the normal Q-Q plot of residuals, and suggests a reasonable fit of the data. Then, we consider whether the two treatment arms are significantly different; i.e., we test $H_0 : \theta = 1$. The statistic $|T_n^*| = 0.1392 < 1.96$. This indicates that the difference in the two treatments between the two arms may be statistically insignificant.

8. Discussions

In this study, we developed estimation and testing procedures for two-sample functional linear models that combine two functional curves with similar patterns. The proposed methods have the following properties: (i) the estimators of the scalar parameter are asymptotically normal, and the estimators of the nonparametric functions have optimal rates of convergence; (ii) the proposed methods show promising performance in finite-sample situations; and (iii) the implemented algorithm is computationally efficient.

Our two-sample FLM can be extended as follows. In general, our model implies that the two curves differ by a constant θ , which may not be true; i.e., θ could also be a function of time. Thus, it would be interesting to estimate this function and a and $b(t)$, identify the limiting distributions, and then discuss the efficiency of the estimates. However, there are considerable issues related to identifiability and efficiency when estimating $\theta(t)$.

Furthermore, we have focused on modeling the linear relationship between $r(X)$ and $X(t)$. Therefore, it would be of interest to extend the methods to nonparametric and semiparametric relationships. However, the theory and implementation of such extensions are much more complicated and warrant further research. For example, the semiparametric asymptotic efficiency of estimating θ when ε is unknown is a far more complex problem, both technically and practically.

Supplementary Materials

The Supplementary Material presents a simulation example continued from Section 6, the proofs of Proposition 1 and Theorems 1 to 4, and the derivation of the efficient score given in (3.1).

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