

SEMIPARAMETRIC INFERENCE PROCEDURES FOR COMPARING MULTIVARIATE ROC CURVES WITH INTERACTION TERMS

Liansheng Tang¹ and Xiao-Hua Zhou^{2,3}

¹*George Mason University*, ²*VA Puget Sound Health Care System*
and ³*University of Washington*

Abstract: Multivariate ROC curve models that include an interaction term between biomarker type and false positive rate are important in comparative biomarker studies, because such interaction allows ROC curves of different biomarkers to cross each other. However, there has been limited work in drawing inference for comparing multivariate ROC curves, especially when interaction terms are present. In this article we derive the asymptotic covariance of three estimators for multivariate ROC models. These covariance estimates have not been readily available in the literature, and bootstrap methods have been used to obtain them. With the readily available variance estimates, we can easily perform hypothesis testing among ROC curves, while bootstrap tests are not so easily performed. The asymptotic results are applied to compare ROC curves and their areas under ROC curves. Moreover, we derive simultaneous confidence bands for multivariate ROC curves. We evaluate and compare the finite sample performance of our asymptotic covariance estimators. We also discuss the advantage of using our asymptotic results over bootstrap procedures. Finally, we illustrate our approach through a well-known pancreatic cancer study.

Key words and phrases: Bootstrap, diagnostic accuracy, simultaneous confidence band.

1. Introduction

Research in early cancer detection involves developing diagnostic tools, such as a biomarker, to distinguish diseased patients from non-diseased patients. Biomarkers often yield continuous measurements. A popular tool to evaluate and compare the accuracy of biomarkers is a receiver operating characteristic (ROC) curve (Zhou, McClish and Obuchowski (2002)), which is a plot of true positive rates vs false positive rates across all thresholds. Estimating a single binormal ROC curve of a continuous-scale biomarker has been well studied in the literature (Metz, Herman and Shen (1998) and Cai and Moskowitz (2004)). However, inferential procedures for comparing multivariate ROC curve models

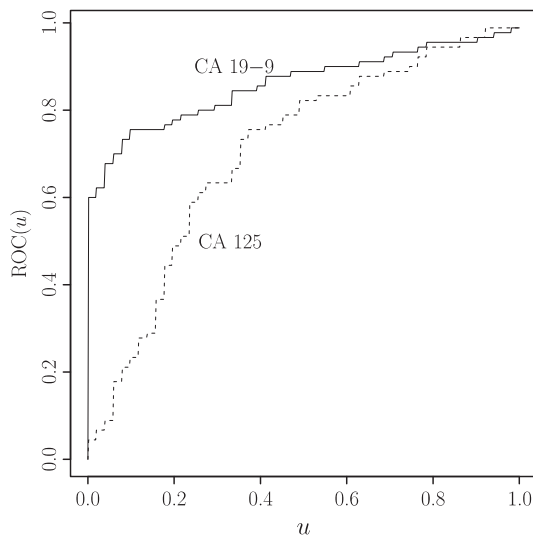


Figure 1. Empirical ROC curves for CA 19–9 and CA 125: solid line, CA 19–9; dashed line, CA 125.

with interaction terms between biomarker type and false positive rates (FPRs) have not been well studied, mainly because it is sometimes difficult to draw inferences the presence of these interaction terms. However, such interactions are important because they allow ROC curves to cross each other. For example, Wieand, Gail, James and James (1989) studied pancreatic cancer biomarkers, CA 19–9 and CA 125, which were measured on 51 pancreatitis patients and 90 pancreatic cancer patients. The empirical ROC curves were generated from this data set and their plots are shown in Figure 1. It is clear that two ROC curves cross each other when FPR gets close to 1. This shows the existence of interaction terms between biomarker type and FPRs.

Metz, Wang and Kronman (1984) proposed a maximum likelihood estimator (MLE) for estimating bivariate binormal models from ordinal data, but their method requires estimating correlation parameters, besides the location and scale parameters in marginal normal distributions. It would be difficult to extend their MLE method to more than two ROC curves when many more correlation parameters are to be estimated. As the number of biomarkers gets large, the MLE method becomes inapplicable. For multiple independent ROC curves, Zhang (2004) and Zhang and Pepe (2005) proposed an intuitive least squares (LS) method, and Pepe (2000) presented an elegant generalized linear model (GLM) approach. Since it is complicated to derive asymptotic results, the authors did not consider large sample inference for the LS and GLM estimators with clustered data. Cai and Pepe (2002) considered an interesting semiparametric

generalized estimating equation (GEE) method to allow an unknown baseline function when estimating ROC curves from correlated biomarker data. They derived asymptotic results for their estimators, but they did not consider how to compare multiple ROC curves from clustered data with the presence of interactions between biomarker type and FPRs.

In this article we consider the LS method for clustered ROC curve data with the presence of interactions between biomarker type and FPRs. We derive explicit covariance structures between empirical ROC curves and use our results to derive the asymptotic covariances of the LS estimator. We also adapt the GLM and GEE methods to this type of biomarker data and derive their asymptotic sandwich covariance estimators. These covariances have not been readily available in the literature, and bootstrap methods have been used to obtain them. With readily available variance estimates we can easily perform hypothesis testing among ROC curves, while bootstrap tests are not so easily performed. For example, if we want to test whether two ROC curves vary by a certain amount δ at a specified FPR u_0 , i.e., $H_0 : ROC_1(u_0) - ROC_2(u_0) = \delta$, it is not clear how to bootstrap from the null distribution, while it is straightforward to perform such hypothesis tests using our asymptotic results and the delta method that is introduced in Section 4. We derive inferential procedures for comparing multivariate ROC curves that include interaction terms, which have multivariate binormal ROC curves as a special case. In particular, we develop methods for comparing ROC curves and the areas under these ROC curves. We derive asymptotic simultaneous confidence bands for ROC curves. Such asymptotic results of simultaneous confidence bands of ROC curves are rarely studied. Instead, computer intensive methods are often employed to construct confidence bands (Cai and Pepe (2002)). Our confidence bands provide an easy-to-use tool to illustrate the sampling variability of the ROC curve estimates. In addition, we develop a method for comparing multiple ROC curves at some specified FPR.

This article is organized as follows. In Section 2 we consider LS, GEE and GLM methods for multivariate ROC curves. In Section 3 we derive the asymptotic results for the LS method when estimating multivariate ROC models; the asymptotic results are also derived for GLM and GEE methods. In Section 4 we apply the results to compare ROC curves and the areas under them. In addition, asymptotic simultaneous confidence bands are derived for multivariate ROC curves. We carry out large scale simulation studies to evaluate and compare the finite sample performance of our covariance estimators from the LS, GLM and GEE methods. We also carry out simulation studies to evaluate the advantages of using asymptotic results over using bootstrap procedures. The simulation results are summarized in Section 5. A comparative pancreatic cancer diagnostic trial serves as an illustrative example in Section 6, and some discussion is presented in Section 7.

2. Three Estimators of Multivariate ROC Curves

In this section, we adapt the LS and GLM methods to clustered ROC data and give a simplified version of the GEE method for estimating multivariate ROC curves. Let $X_\ell = (X_{\ell,1}, \dots, X_{\ell,m})$ denote measurements of the ℓ th biomarker on m diseased subjects, and $Y_{\tilde{\ell}} = (Y_{\tilde{\ell},1}, \dots, Y_{\tilde{\ell},n})$ denote measurements of the $\tilde{\ell}$ th biomarker on n healthy subjects, where $\ell, \tilde{\ell} = 1, \dots, K$. For the ℓ th and $\tilde{\ell}$ th different biomarkers measured on the i th diseased subject, $i = 1, \dots, m$, the measurements $X_{\ell,i}$ and $X_{\tilde{\ell},i}$ follow a bivariate survival function $\bar{F}_{\ell,\tilde{\ell}}$ with the marginal distributions \bar{F}_ℓ and $\bar{F}_{\tilde{\ell}}$, respectively, and the measurements of the j th healthy subject, $Y_{\ell,j}$ and $Y_{\tilde{\ell},j}$ with $j = 1, \dots, n$, follow a bivariate survival function $\bar{G}_{\ell,\tilde{\ell}}$ with the marginal distributions \bar{G}_ℓ and $\bar{G}_{\tilde{\ell}}$, respectively. The ROC curve of the ℓ th biomarker is then given by $Q_\ell(u) = \bar{F}_\ell(\bar{G}_\ell^{-1}(u))$, and its empirical form is $\tilde{Q}_\ell(u) = \hat{F}_\ell(\hat{G}_\ell^{-1}(u))$, where \hat{F}_ℓ and \hat{G}_ℓ are empirical functions of \bar{F}_ℓ and \bar{G}_ℓ , respectively.

Let Z_k be a dummy variable for the k th biomarker, $k = 2, \dots, K$. The multivariate ROC curves are given by

$$Q_1(u) = g\{\theta_{10} + \theta_{11}h(u)\},$$

$$\text{and } Q_k(u) = g\left[\theta_{10} + \theta_{11}h(u) + \sum_{k=2}^K \{\theta_{k0}Z_k + \theta_{k1}Z_k h(u)\}\right], \quad (2.1)$$

for $0 < a \leq u \leq b < 1$, where g is some specified link function and h is some specified baseline function. In the regression ROC modeling, $\theta_{10} + \theta_{11}h(u)$ is the baseline function, usually denoted as $h_0(u)$. In this article we take this baseline function to be a known function, up to two unknown parameters θ_{10} and θ_{11} , as in Pepe (2000), Zhang (2004) and Zhang and Pepe (2005). The important components of the model (2.1) are the $\theta_{k1}Z_k h(u)$, which are the interaction terms between FPRs and dummy variables indicating biomarker types. Such interaction terms play an important role in estimating ROC curves, especially when estimating the multivariate binormal ROC curves. With these terms, the (2.1) includes the multivariate binormal ROC model as the special case that is commonly seen in the literature (Metz, Wang and Kronman (1984)). Specifically, let g be Φ , let h be Φ^{-1} , and let Z_k be an indicator variable for the k th biomarker, so (2.1) can be written as

$$Q_1(u) = \Phi\{\theta_{10} + \theta_{11}\Phi^{-1}(u)\}$$

$$\text{and } Q_k(u) = \Phi\{\theta_{10} + \theta_{11}\Phi^{-1}(u) + \theta_{k0} + \theta_{k1}\Phi^{-1}(u)\}, \quad (2.2)$$

for $k = 2, \dots, K$. When there is only one biomarker, (2.2) reduces to the commonly used binormal model (Zhou, McClish and Obuchowski (2002)).

Let $u_\ell = (u_{\ell,1}, \dots, u_{\ell,P_\ell})^T$ be some fixed partition points in $[a, b]$ on the ℓ th empirical ROC curve. Here P_ℓ is arbitrarily chosen for the ℓ th ROC curve where $0 < a = u_{\ell,1} < \dots < u_{\ell,P_\ell} = b < 1$. For example, if we choose 50 jump points for the 1st ROC curve, we can choose $u_1 = (1/51, \dots, 50/51)$. Also, for simplicity, we write $L(u_\ell) = (L(u_{\ell,1}), \dots, L(u_{\ell,P_\ell}))^T$, where $\ell = 1, \dots, K$, for any process or function L .

Zhang (2004) and Zhang and Pepe (2005) proposed a least squares (LS) approach to estimate multiple ROC curves. They let Z_k be the indicator variables for the k th biomarker. In the LS estimating procedure, the ROC curve corresponding to a reference biomarker is chosen as the reference ROC curve. For the ℓ th empirical ROC curve, the partition points, $u_\ell = (u_{\ell,1}, \dots, u_{\ell,P_\ell})^T$, are chosen within interval boundaries $[a, b]$. When we are interested in the entire ROC curve, a and b can be chosen to be close to 0 and 1, respectively. If a partial ROC curve is of interest, a and b can be chosen accordingly. By plugging in the empirical functions \hat{F}_ℓ and \hat{G}_ℓ^{-1} , the ℓ th empirical ROC curve is $\tilde{Q}_\ell(u_\ell) = \hat{F}_\ell(\hat{G}_\ell^{-1}(u_\ell))$. Let $\tilde{Y}_\ell = g^{-1}(\tilde{Q}_\ell(u_\ell))$. We combine $\tilde{Y}_1, \dots, \tilde{Y}_K$ to get the linear regression equation

$$\tilde{Y} = M\theta + \epsilon, \tag{2.3}$$

where $\tilde{Y} = (\tilde{Y}_1^T, \dots, \tilde{Y}_K^T)^T$ is a $(\sum_\ell P_\ell) \times 1$ vector with elements $\tilde{Y}_\ell = g^{-1}(\tilde{Q}_\ell(u_\ell))$. The $(\sum_\ell P_\ell) \times (2K)$ design matrix M is

$$M = \begin{pmatrix} M_1 & 0 & 0 & \dots & 0 \\ M_2 & M_2^* & 0 & \dots & 0 \\ M_3 & 0 & M_3^* & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ M_K & 0 & 0 & \dots & M_K^* \end{pmatrix},$$

with its $P_\ell \times 2$ submatrices

$$M_\ell = \begin{pmatrix} 1 & \dots & 1 \\ h(u_{\ell,1}) & \dots & h(u_{\ell,P_\ell}) \end{pmatrix}^T, \text{ and } M_k^* = \begin{pmatrix} Z_k & \dots & Z_k \\ Z_k h(u_{\ell,1}) & \dots & Z_k h(u_{\ell,P_\ell}) \end{pmatrix}^T.$$

Also, the error term ϵ has a multivariate normal distribution given by $\epsilon \sim N(0, \Sigma_\epsilon)$. The detailed proof of its multivariate normality is given in the online version of the paper at <http://www.stat.sinica.edu.tw/statistica>. Based on the regression equations in (2.3), the LS estimator $\hat{\theta}^{LS}$ of θ is given by $\hat{\theta}^{LS} = (M^T M)^{-1} M^T \tilde{Y}$.

There are several other estimating equation methods for estimating ROC parameters. Pepe (2000) observed that the expected value of indicator variables

$I\{X_{\ell,i} \geq \widehat{G}_\ell^{-1}(u_{\ell,p})\}$ converges to the true ROC curve of the ℓ th biomarker and proposed a GLM method to estimate the ROC curve model (2.1). If partial ROC curves on $[a, b]$ are of interest, the $u_{\ell,p}$ are chosen within this range. The GLM approach estimates parameters in the model (2.1) by the estimating equations

$$\sum_{\ell=1}^K \sum_{p=1}^{P_\ell} \sum_{i=1}^m \frac{g'(\widetilde{M}_{\ell,p}^T \theta)}{g(\widetilde{M}_{\ell,p}^T \theta)(1 - g(\widetilde{M}_{\ell,p}^T \theta))} \widetilde{M}_{\ell,p} \left\{ I\{X_{\ell,i} \geq \widehat{G}_\ell^{-1}(u_{\ell,p})\} - g(\widetilde{M}_{\ell,p}^T \theta) \right\} = 0,$$

or

$$\sum_{\ell=1}^K \sum_{p=1}^{P_\ell} w_\ell(u_{\ell,p}) \widetilde{M}_{\ell,p} \left\{ \widetilde{Q}_\ell(u_{\ell,p}) - g(\widetilde{M}_{\ell,p}^T \theta) \right\} = 0,$$

for $\ell = 1, \dots, K$ and $p = 1, \dots, P_\ell$, with $\theta = (\theta_{10}, \theta_{11}, \theta_{20}, \theta_{21}, \dots, \theta_{K0}, \theta_{K1})^T$ and a weight function $w_\ell(u_{\ell,p}) = \{g'(\widetilde{M}_{\ell,p}^T \theta)\} / \{g(\widetilde{M}_{\ell,p}^T \theta)(1 - g(\widetilde{M}_{\ell,p}^T \theta))\}$. Here $\widetilde{M}_{1,p}$ is a $1 \times 2K$ vector with the first two elements being 1 and $h(u_{1,p})$, respectively, and the rest of the elements zero. The $\widetilde{M}_{k,p}$ have the first two elements being 1 and $h(u_{k,p})$, respectively, the $(2k + 1)$ th and $(2k + 2)$ th elements being Z_k and $Z_k h(u_{k,p})$, respectively, and the rest of the elements being zero. The asymptotic results of the parameter estimator not provided in Pepe (2000) are given in Section 3.

The GEE method of Cai and Pepe (2002) also used the indicator variables $I\{X_{\ell,i} \geq \widehat{G}_\ell^{-1}(u_{\ell,p})\}$, and relied on the fact that points on ROC curves can be interpreted as conditional expectations of these indicator variables. Their method is flexible enough to allow an unknown baseline function h_0 in the model (2.1). When the baseline function has the form of $h_0(u) = \theta_{10} + \theta_{11}h(u)$, the GEE method is similar to the GLM method. Specifically, the GEE method solves the estimating equations

$$\sum_{\ell=1}^K \sum_{p=1}^{P_\ell} \widetilde{M}_{\ell,p} \left\{ \widetilde{Q}_\ell(u_{\ell,p}) - g(\widetilde{M}_{\ell,p}^T \theta) \right\} = 0.$$

It is observed that if the baseline function has a known form, the GLM method differs from the GEE method by including the weight function w_ℓ .

3. Large Sample Theory of ROC Estimators

We derive the asymptotic covariance structure of multiple empirical ROC curves for clustered data. The result is then applied to derive asymptotic covariances of the LS estimator. We also derive asymptotic sandwich covariances of GLM and GEE estimators. Asymptotic results of the LS and GLM estimators for clustered data have not been provided in the literature (Pepe (2000),

Zhang (2004) and Zhang and Pepe (2005)). Although Cai and Pepe (2002) have studied the large sample theory of the GEE estimator, their covariance estimator has a complicated form. For the multivariate ROC models we consider here, the covariance estimator of resulting estimator has a simplified covariance estimator that is easy to apply. These covariance results are essential for drawing inference on comparing ROC curves and constructing simultaneous confidence ROC bands, as discussed in Section 4. We derive the covariance structure between empirical ROC curves, and summarize the results in Theorem 1. The proof of Theorem 1 is given in the online version of the paper at <http://www.stat.sinica.edu.tw/statistica>. Theorem 1 provides a basis for deriving asymptotic covariances of the LS estimator.

Theorem 1. *If 1) \bar{F}_ℓ and \bar{G}_ℓ have continuous densities \bar{F}'_ℓ and \bar{G}'_ℓ , respectively, and 2) the first derivative Q'_ℓ of Q_ℓ is bounded in (a, b) , when $m/n \rightarrow \lambda$ as $m, n \rightarrow \infty$, $cov[\sqrt{m}\{\tilde{Q}_\ell(s) - Q_\ell(s)\}, \sqrt{m}\{\tilde{Q}_{\tilde{\ell}}(t) - Q_{\tilde{\ell}}(t)\}]$ converges in distribution to*

$$\left[\bar{F}_{\ell, \tilde{\ell}} \left\{ \bar{G}_\ell^{-1}(s), \bar{G}_{\tilde{\ell}}^{-1}(t) \right\} - Q_\ell(s)Q_{\tilde{\ell}}(t) \right] + \lambda \left[Q'_\ell(s)Q'_{\tilde{\ell}}(t) \left\{ \bar{G}_{\ell, \tilde{\ell}} \left\{ \bar{G}_\ell^{-1}(s), \bar{G}_{\tilde{\ell}}^{-1}(t) \right\} - st \right\} \right],$$

for s, t in (a, b) .

3.1. Asymptotic covariance of the LS estimator

Let $\tilde{\theta}_{\ell 1} = \theta_{11}$ when $\ell = 1$, and $\tilde{\theta}_{\ell 1} = \theta_{11} + \theta_{\ell 1}$ when $\ell \geq 2$. Consider the $2K \times 2K$ square matrix

$$J = \begin{pmatrix} KD & Z_2D & \cdots & Z_KD \\ Z_2D & Z_2^2D & \cdots & O \\ \vdots & \vdots & \ddots & \vdots \\ Z_KD & O & \cdots & Z_K^2D \end{pmatrix}^{-1} \begin{pmatrix} I_2 & I_2 & \cdots & I_2 \\ O & I_2 & \cdots & O \\ & & \ddots & \\ O & O & \cdots & I_2 \end{pmatrix},$$

where

$$D = \begin{pmatrix} b - a & \int_a^b h(u)du, \\ \int_a^b h(u)du & \int_a^b h^2(u)du \end{pmatrix}$$

for $0 < a < b < 1$, and I_2 is a 2×2 identity matrix. Let

$$V_\ell(s, t) = \frac{Q_\ell(s \wedge t) - Q_\ell(s)Q_\ell(t)}{g'(g^{-1}(Q_\ell(s)))g'(g^{-1}(Q_\ell(t)))} + \lambda \tilde{\theta}_{\ell 1}^2 h'(s)h'(t)(s \wedge t - st),$$

where $\ell = 1, \dots, K$, and

$$\tilde{V}_{\ell, \tilde{\ell}}(s, t) = \frac{\bar{F}_{\ell, \tilde{\ell}}(\bar{G}_\ell^{-1}(s), \bar{G}_{\tilde{\ell}}^{-1}(t)) - Q_\ell(s)Q_{\tilde{\ell}}(t)}{g'[g^{-1}\{Q_\ell(s)\}]g'(g^{-1}(Q_{\tilde{\ell}}(t)))}$$

$$+\lambda\tilde{\theta}_{\ell_1}\tilde{\theta}_{\tilde{\ell}_1}h'(s)h'(t)\{\tilde{G}_{\ell,\tilde{\ell}}(\tilde{G}_\ell^{-1}(s),\tilde{G}_{\tilde{\ell}}^{-1}(t))-st\},$$

for $\ell, \tilde{\ell} = 1, \dots, K$, and $\ell \neq \tilde{\ell}$, where $\lambda = \lim_{m,n \rightarrow \infty} m/n$. Theorem 2 gives results for the LS estimator. The proof of Theorem 2 is given in the online version of the paper at <http://www.stat.sinica.edu.tw/statistica>.

Theorem 2. *Under the regularity conditions of Theorem 1, when $m/n \rightarrow \lambda$ as $m, n \rightarrow \infty$, and $P_\ell \rightarrow \infty$, the regression parameter estimator $\hat{\theta}^{LS}$ satisfies*

$$\sqrt{m}(\hat{\theta}^{LS} - \theta) \xrightarrow{D} N(0, \Sigma^{LS} = J\Sigma^y J^T).$$

Here Σ^y is the matrix

$$\Sigma^y = \begin{pmatrix} \Sigma_{11}^y & \Sigma_{12}^y & \cdots & \Sigma_{1K}^y \\ \Sigma_{21}^y & \Sigma_{22}^y & \cdots & \Sigma_{2K}^y \\ & & \ddots & \\ \Sigma_{K1}^y & \Sigma_{K2}^y & \cdots & \Sigma_{KK}^y \end{pmatrix}$$

whose 2×2 diagonal symmetric submatrices, $\Sigma_{\ell\ell}^y$ have elements

$$\begin{aligned} \sigma_{\ell\ell}^{(1,1)} &= \int_a^b \int_a^b V_\ell(s,t) ds dt, & \sigma_{\ell\ell}^{(2,2)} &= \int_a^b \int_a^b h(s)h(t)V_\ell(s,t) ds dt, \\ \sigma_{\ell\ell}^{(1,2)} &= \sigma_{\ell\ell}^{(2,1)} = \int_a^b \int_a^b h(s)V_\ell(s,t) ds dt, \end{aligned}$$

and whose 2×2 off-diagonal symmetric submatrices, $\Sigma_{\ell,\tilde{\ell}}^y$, have elements

$$\begin{aligned} \sigma_{\ell,\tilde{\ell}}^{(1,1)} &= \int_a^b \int_a^b \tilde{V}_{\ell,\tilde{\ell}}(s,t) ds dt, & \sigma_{\ell,\tilde{\ell}}^{(2,2)} &= \int_a^b \int_a^b h(s)h(t)\tilde{V}_{\ell,\tilde{\ell}}(s,t) ds dt \\ \sigma_{\ell,\tilde{\ell}}^{(1,2)} &= \sigma_{\ell,\tilde{\ell}}^{(2,1)} = \int_a^b \int_a^b h(s)\tilde{V}_{\ell,\tilde{\ell}}(s,t) ds dt. \end{aligned}$$

In practice, $\tilde{F}_{\ell,\tilde{\ell}}, \tilde{G}_{\ell,\tilde{\ell}}, \tilde{F}_\ell$, and \tilde{G}_ℓ are unknown, and are estimated by their respective empirical functions. If the ROC data are unclustered, the off-diagonal submatrices, $\Sigma_{\ell,\tilde{\ell}}^y$'s, are zero matrices. If we further let $h = g^{-1}$ and Z_k be indicator variables in the model (1), we get the same asymptotic result as in Zhang (2004).

3.2. Asymptotic covariances of the GLM and GEE estimators

The GLM estimator, $\hat{\theta}^L$, is obtained by solving the estimating equations

$$U(\theta) = \sum_{\ell=1}^K \sum_{p=1}^{P_\ell} w_\ell(u_{\ell,p}) \tilde{M}_{\ell,p} \left\{ \tilde{Q}_\ell(u_{\ell,p}) - g(\tilde{M}_{\ell,p}^T \theta) \right\} = 0,$$

where $\widetilde{M}_{\ell,p}$ is defined in Section 2.1. To solve these equations for $\hat{\theta}^L$, we need the Newton-Raphson method. Then

$$\begin{aligned} cov(\hat{\theta}^L) &= \left(-\frac{\partial U(\theta)}{\partial \theta} \right)^{-1} var \left(\sum_{\ell=1}^K \sum_{p=1}^P w_{\ell}(u_{\ell,p}) \widetilde{M}_{\ell,p} \{ \widetilde{Q}_{\ell}(u_{\ell,p}) - g(\widetilde{M}_{\ell,p}^T \theta) \} \right) \\ &\quad \times \left(-\frac{\partial U(\theta)}{\partial \theta} \right)^{-1}, \end{aligned}$$

where $\partial U(\theta)/\partial \theta$ is the partial derivative of $U(\theta)$ with regard to θ . Let

$$\begin{aligned} U_{1i} &= \sum_{\ell=1}^K \sum_{p=1}^{P_{\ell}} w_{\ell}(u_{\ell,p}) \widetilde{M}_{\ell,p} \left\{ I(X_{\ell i} \geq \bar{G}_{\ell}^{-1}(u_{\ell,p})) - g(\widetilde{M}_{\ell,p}^T \theta) \right\}, \\ \text{and } U_{2j} &= \sum_{\ell=1}^K \sum_{p=1}^P w_{\ell}(u_{\ell,p}) \widetilde{M}_{\ell,p} Q'_{\ell}(u_{\ell,p}) \left\{ I(Y_{\ell j} \geq \bar{G}_{\ell}^{-1}(u_{\ell,p})) - u_{\ell,p} \right\}. \end{aligned}$$

The result of Theorem 1 gives us that, under mild regularity conditions, when $m/n \rightarrow \lambda$ as $m, n \rightarrow \infty$, the GLM estimator $\hat{\theta}^L$ satisfies

$$\sqrt{m}(\hat{\theta}^L - \theta) \xrightarrow{D} N(0, \Sigma^L),$$

where

$$\begin{aligned} \Sigma^L &= \left(\sum_{\ell=1}^K \sum_{p=1}^{P_{\ell}} w_{\ell}(u_{\ell,p}) \widetilde{M}_{\ell,p} g'(\widetilde{M}_{\ell,p}^T \theta) \right)^{-1} \lim_{m,n \rightarrow \infty} \left\{ \sum_{i=1}^m U_{1i} U_{1i}^T + \lambda \sum_{v=1}^n U_{2j} U_{2j}^T \right\} \\ &\quad \times \left(\sum_{\ell=1}^K \sum_{p=1}^{P_{\ell}} w_{\ell}(u_{\ell,p}) \widetilde{M}_{\ell,p} g'(\widetilde{M}_{\ell,p}^T \theta) \right)^{-1}. \end{aligned}$$

The asymptotic property of the modified GEE estimator, $\hat{\theta}^E$, can be similarly derived. Let

$$\begin{aligned} U_{1i}^* &= \sum_{\ell=1}^K \sum_{p=1}^{P_{\ell}} \widetilde{M}_{\ell,p} \left\{ I(Y_{\ell i} \geq \bar{G}_{\ell}^{-1}(u_{\ell,p})) - g(\widetilde{M}_{\ell,p}^T \theta) \right\}, \\ \text{and } U_{2j}^* &= \sum_{\ell=1}^K \sum_{p=1}^{P_{\ell}} \widetilde{M}_{\ell,p} Q'_{\ell}(u_{\ell,p}) \left\{ I(Y_{\ell j} \geq \bar{G}_{\ell}^{-1}(u_{\ell,p})) - u_{\ell,p} \right\}. \end{aligned}$$

When $m/n \rightarrow \lambda$ as $m, n \rightarrow \infty$, the GEE estimator $\hat{\theta}^E$ satisfies

$$\sqrt{m}(\hat{\theta}^E - \theta) \xrightarrow{D} N(0, \Sigma^E),$$

where

$$\Sigma^E = \left(\sum_{\ell=1}^K \sum_{p=1}^{P_\ell} \widetilde{M}_{\ell,p} g'(\widetilde{M}_{\ell,p}^T \theta) \right)^{-1} \lim_{m,n \rightarrow \infty} \left\{ \sum_{r=1}^m U_{1i}^* U_{1i}^{*T} + \lambda \sum_{v=1}^n U_{2j}^* U_{2j}^{*T} \right\} \\ \times \left(\sum_{\ell=1}^K \sum_{p=1}^{P_\ell} \widetilde{M}_{\ell,p} g'(\widetilde{M}_{\ell,p}^T \theta) \right)^{-1} .$$

These covariance estimators are sandwich estimators. We will evaluate their finite sample performance in our simulation studies.

4. Multivariate ROC Analysis

Estimated ROC curves, denoted by \widehat{Q}_ℓ , are obtained by replacing θ with the estimator $\hat{\theta}$ in the model (2.1). $\hat{\theta}$ is estimated via either of three aforementioned methods. Here $\hat{\theta}$ is a general notation and can be found via other methods as well. But, since asymptotic results are derived for the three methods, it is convenient to utilize these results. Our asymptotic results give the corresponding covariance matrix estimator $\hat{\Sigma}$ of Σ for $\hat{\theta}$. For further notational convenience, let $\Sigma_{\ell, \tilde{\ell}}$ be the 2×2 submatrices of

$$\Sigma = \begin{pmatrix} \Sigma_{11} & \Sigma_{12} & \cdots & \Sigma_{1K} \\ \Sigma_{21} & \Sigma_{22} & \cdots & \Sigma_{2K} \\ & & \ddots & \\ \Sigma_{K1} & \Sigma_{K2} & \cdots & \Sigma_{KK} \end{pmatrix}_{2K \times 2K} .$$

The estimator $\hat{\Sigma}_{\ell, \tilde{\ell}}$ of $\Sigma_{\ell, \tilde{\ell}}$ is the corresponding submatrix of $\hat{\Sigma}$. In this section we derive methods for pairwise comparison of ROC curves. We also develop methods for comparing more than two areas under ROC curves under multivariate binormal assumptions. In addition, we derive inferential procedures for simultaneous confidence ROC bands, and for comparing multiple ROC curves at some specified FPR.

4.1. Pairwise comparison of ROC curves

It is often of interest to compare ROC curves to investigate the accuracy of biomarkers. The reference ROC curve, $Q_1(u)$, and the k th ROC curve, $Q_k(u)$, in $[a, b]$ only differ by a parameter vector $\theta_k = (\theta_{k0}, \theta_{k1})^T$. Consequently, testing the equality of these two ROC curves is equivalent to testing $H_0 : \theta_k = (0, 0)^T$. It follows from Section 3 that the asymptotic distribution of the test statistic, $\kappa_k = (\hat{\theta}_k - \theta_k)^T \Sigma_{kk}^{-1} (\hat{\theta}_k - \theta_k)$ is χ_2^2 . Similarly, testing the equality of two ROC curves of the ω th and ν th different biomarkers in $[a, b]$, $\omega, \nu = 2, \dots, K$, also

reduces to a χ^2 test. The null hypothesis becomes $H_0 : (\theta_{\omega 0} - \theta_{\nu 0}, \theta_{\omega 1} - \theta_{\nu 1}) = 0$. Let $\theta_{\omega, \nu} = (\theta_{\omega 0}, \theta_{\omega 1}, \theta_{\nu 0}, \theta_{\nu 1})^T$. The resulting chi-square statistic is

$$\kappa_{\omega, \nu} = \begin{pmatrix} (\hat{\theta}_{\omega 0} - \hat{\theta}_{\nu 0}) - (\theta_{\omega 0} - \theta_{\nu 0}) \\ (\hat{\theta}_{\omega 1} - \hat{\theta}_{\nu 1}) - (\theta_{\omega 1} - \theta_{\nu 1}) \end{pmatrix}^T (A \Sigma_{\omega, \nu} A^T)^{-1} \begin{pmatrix} (\hat{\theta}_{\omega 0} - \hat{\theta}_{\nu 0}) - (\theta_{\omega 0} - \theta_{\nu 0}) \\ (\hat{\theta}_{\omega 1} - \hat{\theta}_{\nu 1}) - (\theta_{\omega 1} - \theta_{\nu 1}) \end{pmatrix},$$

where $A = (I_2, -I_2)$ with 2×2 identity matrix I_2 , and $\Sigma_{\omega, \nu}$ is the covariance matrix of $\theta_{\omega, \nu}$.

4.2. Comparing the areas under multivariate binormal ROC curves

Our asymptotic results in Section 3 can be used to compare areas under multivariate ROC curves, especially multivariate binormal ROC curves. Let $A = (A_1, \dots, A_K)$, where A_ℓ is the area under the ℓ th ROC curve. It is well known that under the binormal assumption,

$$A_1(\theta_{10}, \theta_{11}) = \Phi \left\{ \frac{\theta_{10}}{\sqrt{1 + \theta_{11}^2}} \right\},$$

and $A_k(\theta_{10}, \theta_{11}, \theta_{k0}, \theta_{k1}) = \Phi \left\{ \frac{\theta_{10} + \theta_{k0}}{\sqrt{1 + (\theta_{11} + \theta_{k1})^2}} \right\}.$ (4.1)

Let q be a second-order differentiable and real-valued function of A . It follows that when $m/n \rightarrow \lambda$ as $m, n \rightarrow \infty$,

$$\sqrt{m} \{q(\hat{A}) - q(A)\} \xrightarrow{D} N(0, \sigma_q^2),$$

where

$$\sigma_q^2 = \lim_{m, n \rightarrow \infty} m \left\{ \frac{\partial q}{\partial A_1} \frac{\partial q}{\partial A_1} \text{var}(A_1) + 2 \sum_{k=2}^K \frac{\partial q}{\partial A_1} \frac{\partial q}{\partial A_k} \text{cov}(A_1, A_k) + \sum_{k=2}^K \sum_{\tilde{k}=2}^K \frac{\partial q}{\partial A_k} \frac{\partial q}{\partial A_{\tilde{k}}} \text{cov}(A_k, A_{\tilde{k}}) \right\}.$$

By Taylor expansions on A_ℓ and our asymptotic results, we find

$$\begin{aligned} \text{var}(A_1) &= B_1^T \Sigma_{11} B_1, \\ \text{cov}(A_1, A_k) &= B_1^T (\Sigma_{11} + \Sigma_{k1}) B_k, \\ \text{and } \text{cov}(A_k, A_{\tilde{k}}) &= B_k^T (\Sigma_{11} + \Sigma_{k\tilde{k}}) B_{\tilde{k}}, \end{aligned}$$

where

$$B_1 = \left\{ \phi \left(\frac{\theta_{10}}{\sqrt{1 + \theta_{11}^2}} \right) \frac{1}{\sqrt{1 + \theta_{11}^2}}, -\phi \left(\frac{\theta_{10}}{\sqrt{1 + \theta_{11}^2}} \right) \frac{\theta_{11}}{(\sqrt{1 + \theta_{11}^2})^{3/2}} \right\}^T,$$

$$B_k = \left[\phi \left\{ \frac{\theta_{10} + \theta_{k0}}{\sqrt{1 + (\theta_{11} + \theta_{k1})^2}} \right\} \frac{1}{\sqrt{1 + (\theta_{11} + \theta_{k1})^2}}, \right. \\ \left. - \phi \left\{ \frac{\theta_{10} + \theta_{k0}}{\sqrt{1 + (\theta_{11} + \theta_{k1})^2}} \right\} \frac{\theta_{11} + \theta_{k1}}{\{\sqrt{1 + (\theta_{11} + \theta_{k1})^2}\}^{3/2}} \right]^T,$$

and $\Sigma_{\ell\tilde{\ell}}$, for $\ell, \tilde{\ell} = 1, \dots, K$, is estimated from asymptotic results. DeLong, DeLong and Clarke-Pearson (1988) gave a similar formula for comparing the areas under nonparametric ROC curves. Although their approach is robust, semiparametric approaches may be more appealing for deriving smooth ROC curves for continuous biomarker data. If q is some linear function, the theoretical result is simplified to a similar formula in their paper. A simple example has E as a vector with the ℓ th element 1, $\tilde{\ell}$ th element -1 and other elements zero. Then $q(\hat{A}) = E\hat{A}$ corresponds to $\hat{A}_\ell - \hat{A}_{\tilde{\ell}}$, whose variance estimator follows from the variance result. Inference is then easily drawn for testing $H_0 : A_\ell = A_{\tilde{\ell}}$, and for constructing a confidence interval.

4.3. Simultaneous confidence ROC bands

The variance of estimated ROC curves at each FPR can be derived from the parameter estimator $\hat{\theta}$ and its covariance matrix estimator $\hat{\Sigma}$. Let $H = (1, h(u))$, $\tilde{H} = (H, H)$.

Corollary 2. *The variance of estimated ROC curves at u are*

$$\sigma_1^2(u) = g'[g^{-1}\{Q_1(u)\}]^2 H \Sigma_{11} H^T \\ \text{and } \sigma_k^2(u) = g'[g^{-1}\{Q_k(u)\}]^2 \tilde{H} \begin{pmatrix} \Sigma_{11} & \Sigma_{1k} \\ \Sigma_{k1} & \Sigma_{kk} \end{pmatrix} \tilde{H}^T,$$

respectively, for $k = 2, \dots, K$.

The $(1 - \alpha)100\%$ pointwise confidence interval of $Q_\ell(u)$ is then given by

$$\hat{Q}_\ell(u) \pm z_{\alpha/2} \hat{\sigma}_\ell(u), \quad 0 \leq u \leq 1.$$

In Theorem 3 below, we give explicit expressions for simultaneous bands for multivariate ROC curves. The proof of Theorem 3 is given in the online version of the paper at <http://www.stat.sinica.edu.tw/statistica>.

Theorem 3. *Under the regularity conditions of Theorem 1, the $(1 - \alpha)100\%$ simultaneous confidence bands for multivariate ROC curves in $[a, b]$ are*

$$g \left\{ H\hat{\theta}_1 \pm \sqrt{\chi_{2,\alpha}^2 H \Sigma_{11} H^T} \right\},$$

and

$$g \left\{ \tilde{H}(\hat{\theta}_1^T, \hat{\theta}_k^T)^T \pm \sqrt{\chi_{4,\alpha}^2 \tilde{H} \begin{pmatrix} \Sigma_{11} & \Sigma_{1k} \\ \Sigma_{k1} & \Sigma_{kk} \end{pmatrix} \tilde{H}^T} \right\},$$

respectively, for $k = 2, \dots, K$.

Note the reason why simultaneous confidence bands for ROC curves have such simple expressions is that we assume that g and h are known. The estimated ROC curves are fully determined by two parameters for the reference biomarker and four parameters for other biomarkers. Therefore, χ_2^2 and χ_4^2 distributions arise, and the derivation of simultaneous bands is naturally simplified.

4.4. Comparing multiple ROC curves at some specified FPR

Let $\hat{Q}(u) = (\hat{Q}_1(u), \dots, \hat{Q}_K(u))^T$. Similar to Section 4.2, suppose that q is a real-valued and second-order differentiable function of the vector \hat{Q} . We have that $q(\hat{Q}(u_0))$, at a specified FPR u_0 , converges to a normal distribution with mean zero and variance

$$\begin{aligned} \tilde{\sigma}_q^2(u_0) = & \lim_{m,n \rightarrow \infty} m \left[\frac{\partial q}{\partial Q_1} \frac{\partial q}{\partial Q_1} var\{Q_1(u_0)\} + 2 \sum_{k=2}^K \frac{\partial q}{\partial Q_1} \frac{\partial q}{\partial Q_k} cov\{Q_1(u_0), Q_k(u_0)\} \right. \\ & \left. + \sum_{k=2}^K \sum_{\tilde{k}=2}^K \frac{\partial q}{\partial Q_k} \frac{\partial q}{\partial Q_{\tilde{k}}} cov\{Q_k(u_0), Q_{\tilde{k}}(u_0)\} \right]. \end{aligned}$$

Here we have $var\{Q_1(u_0)\} = C_1(u_0)^T \Sigma_{11} C_1(u_0)$, $cov\{Q_1(u_0), Q_k(u_0)\} = C_1(u_0)^T (\Sigma_{11} + \Sigma_{k1}) C_k(u_0)$, $cov\{Q_k(u_0), Q_{\tilde{k}}(u_0)\} = C_k(u_0)^T (\Sigma_{11} + \Sigma_{k\tilde{k}}) C_{\tilde{k}}(u_0)$, where $C_1(u) = (g'\{\theta_{10} + \theta_{11}h(u)\}, \theta_{11}g'\{\theta_{10} + \theta_{11}h(u)\})^T$, $C_k(u) = [g'\{\theta_{10} + \theta_{11}h(u) + \theta_{k0} + \theta_{k1}h(u)\}, (\theta_{11} + \theta_{k1})g'\{\theta_{10} + \theta_{11}h(u) + \theta_{k0} + \theta_{k1}h(u)\}]^T$. If q is a linear function, the result can be greatly simplified.

5. Simulation Studies

5.1. Finite sample performance of hypothesis testing

We ran a large set of simulation studies to evaluate and compare the finite sample performance of our asymptotic covariance estimators for the LS, GLM and GEE methods. The bivariate normal data were $N((1, 1), \Sigma_0)$ for the diseased and $N((0, 0), \Sigma_0)$ for the healthy, where Σ_0 has the variances 1 and 2 with a correlation parameter ρ . True ROC curves of tests 1 and 2 have the same form given by $Q_1(u) = Q_2(u) = \Phi\{1/\sqrt{2} + 1/\sqrt{2}\Phi^{-1}(u)\}$, for $0 \leq u \leq 1$. Thus, the true value of the parameter vector is $\theta = (1/\sqrt{2}, 1/\sqrt{2}, 0, 0)$. We fit a bivariate binormal model to the data; that is, we let $K = 2$ in the model (2.2). The null hypothesis of equal ROC curves, $H_0 : (\theta_{20}, \theta_{21}) = (0, 0)$, can be tested

by the χ^2 test statistic $\kappa = (\hat{\theta}_{20}, \hat{\theta}_{21}) \hat{\Sigma}_{22}^{-1} (\hat{\theta}_{20}, \hat{\theta}_{21})^T$ with 2 degrees of freedom, where $(\hat{\theta}_{20}, \hat{\theta}_{21})$'s covariance matrix estimate, $\hat{\Sigma}_{22}$, is calculated using asymptotic results in Theorem 2. We simulated 1,000 data sets under the null hypothesis with $m = (50, 100, 200)$ and $n = (50, 100, 200)$ under $\rho = (0, 0.25, 0.5, 0.75)$. The nominal rejection rate was set at 5%. In the simulation, the variances of LS estimators were estimated using asymptotic results developed in Theorem 2. The variances of GLM and GEE's estimators were obtained using asymptotic results in Section 3. For a small sample size such as 50, the GEE method sometimes did not converge and we had to run more than 1,000 simulations in order to obtain 1,000 valid estimates. Since the LS method does not require iterations, the computation time is greatly reduced compared to that of GLM or GEE. Under the same circumstances, the computing time of LS is less than half that of GLM or GEE. In particular, we conducted our simulation study on the same Unix machine. It took 30 seconds for LS to estimate parameters from 1,000 simulated data sets when $m = n = 200$, while the computational times of GLM and GEE were 870 and 348 seconds, respectively. When $m = n = 50$, the computation time of LS was 24 seconds, while times of GLM and GEE were 210 and 98 seconds, respectively.

Table 1 presents rejection rates from the three approaches. As shown in Table 1, the asymptotic results for LS work well for all combinations of sample sizes as the rejection rates are close to the nominal level of 5%. Even for a small sample size 50 for both diseased and healthy groups, rejection rates do vary much from the nominal level. Moreover, rejection rates of LS are not affected by values of the correlation parameter ρ . From Table 1, GEE and GLM have much in common. Both have over-rejection rates when sample sizes are small. This is mainly due to the variability of their sandwich variance estimators. Readers are referred to Kauermann and Carroll (2001) for more details. It is also noticeable in Table 1 that as sample sizes for the healthy get larger, rejection rates of GEE and GLM get closer to the nominal level even when sample sizes for the diseased are small. However, rejection rates for the diseased, given small sample sizes for the healthy, are not improved with large sample sizes. We tried bootstrap methods in these situations. The bootstrap method performed similarly to the LS method on the rejection rates regardless of sample sizes. The bootstrap performed better than GLM and GEE when sample sizes were small, and similarly to GLM and GEE when sample sizes were large.

5.2. Finite sample performance of point and interval estimates

We used the same setting as in the previous section to evaluate and compare estimation precision of the methods in the simulation study. We again simulated 1,000 data sets under sample sizes $m = n = (50, 200, 400)$ with $\rho = 0.5$. The nominal coverage probability of confidence intervals was 95%. We applied LS,

Table 1. Rejection rates (in %) with the nominal level $\alpha = 0.05$, from asymptotic results.

<i>m</i>	<i>n</i>	LS				GEE				GLM			
		$\rho = 0$	0.25	0.5	0.75	$\rho = 0$	0.25	0.5	0.75	$\rho = 0$	0.25	0.5	0.75
50	50	3.7	6.0	3.6	6.9	13.1	11.8	14.2	11.8	15.2	16.2	14.9	10.3
50	100	4.8	4.5	3.6	7.2	6.9	7.8	7.7	6.9	9.3	8.8	10.0	8.3
50	200	4.1	6.5	4.9	5.8	5.6	5.1	5.6	4.5	5.4	5.9	4.5	5.8
100	50	5.3	5.3	5.0	6.7	16.0	14.7	12.9	13.6	15.3	14.1	11.9	11.3
100	100	5.7	5.2	6.4	6.8	8.2	8.3	9.1	8.8	11.2	9.8	10.1	9.5
100	200	4.9	5.5	4.6	5.2	4.4	4.3	4.2	5.0	4.7	5.0	5.6	5.6
200	50	5.1	6.2	4.7	4.7	16.8	14.5	16.3	13.6	18.6	15.7	14.4	13.2
200	100	4.7	5.2	4.9	5.4	9.2	9.4	8.1	10.5	11.0	11.9	9.8	11.4
200	200	4.7	4.7	5.3	5.6	5.5	4.9	4.5	4.6	5.5	4.8	5.1	6.0

The rejection rate with 1,000 realizations of normal model. The 95% prediction interval of the rejection rate is $(5.0\% \pm 1.4\%)$.

GEE and GLM to get estimates of the ROC parameter vector $(\theta_{10}, \theta_{11}, \theta_{20}, \theta_{21})$. Confidence intervals for the parameters were calculated based on asymptotic results. We then compared these methods based on bias, square root of MSE (RMSE), and the coverage probabilities of confidence intervals. The results are shown in Table 2. All three methods have good accuracy for estimating the parameters, while coverage probabilities differ among them. Our simulation results show that LS has the nice finite sample property that the coverage probabilities of all parameters are close to the nominal level for small sample sizes. When sample sizes are small, confidence intervals computed from sandwich covariance estimators for GLM and GEE cover the intercept parameters properly, but these confidence intervals over-cover slope parameters. As sample sizes approach 400, the coverages of GLM and GEE estimators get closer to the nominal level for slope parameters.

5.3. The advantage of our asymptotic results over bootstrap procedures

Many authors have applied bootstrap methods to estimate covariance matrices for the LS and GLM estimators when the asymptotic results were not available (Pepe (2000) and Zhang and Pepe (2005)). However, it can take much more computation time to do bootstrapping than to use the asymptotic results. In this simulation study, we compared coverage percentages of bootstrap covariance estimates with those of asymptotic covariance estimates for the LS approach. We used the same setting in Section 5.1 with $m = n = (50, 200, 400)$. Under each combination of sample sizes, we simulated 1,000 data sets with $\rho = 0.5$. For each data set we applied bootstrap procedures to get covariance estimates of the LS

Table 2. Bias, RMSE, coverage probability (CP) of parameter estimators.

m (n)		LS				GEE			GLM		
		Bias (in %)	RMSE	CP (in %)	BT (in %)	Bias (in %)	RMSE	CP (in %)	Bias (in %)	RMSE	CP (in %)
50	θ_{10}	-2.36	0.19	94.8	95.2	0.66	0.19	97.2	0.60	0.19	98.7
	θ_{11}	0.80	0.12	95.2	95.0	-7.88	0.15	99.9	-8.71	0.15	100.0
	θ_{20}	-0.55	0.20	93.8	95.7	-0.92	0.20	99.4	-0.69	0.21	99.1
	θ_{21}	0.28	0.16	96.2	95.8	0.49	0.16	100.0	0.24	0.15	99.9
200	θ_{10}	0.07	0.09	95.2	94.2	0.02	0.10	94.7	0.81	0.10	94.4
	θ_{11}	0.52	0.06	94.6	94.5	-1.76	0.07	99.6	-1.63	0.06	99.7
	θ_{20}	-0.28	0.10	93.9	93.9	-0.09	0.10	94.3	-0.21	0.10	95.0
	θ_{21}	0.01	0.08	94.7	95.2	0.19	0.08	99.0	-0.08	0.08	99.6
400	θ_{10}	-0.03	0.07	95.4	94.4	-0.07	0.07	94.7	0.02	0.06	96.5
	θ_{11}	0.37	0.04	94.8	95.0	-0.72	0.04	96.4	-0.86	0.04	97.1
	θ_{20}	-0.42	0.07	95.9	94.9	0.02	0.07	95.0	0.06	0.07	96.0
	θ_{21}	-0.08	0.05	95.3	95.9	-0.08	0.05	97.7	0.01	0.05	97.6

CP is the coverage percentage for 95% confidence intervals using asymptotic standard errors with a normal quantile. BT is the coverage percentage for 95% confidence intervals using the bootstrap. Results are based on 1,000 realizations of the bivariate normal model.

approach. The number of bootstrap was 1,000. We then used covariance estimates to get confidence intervals and their coverage percentages. The coverage percentages of bootstrap methods were shown in Table 2. As can be seen there, our asymptotic results were as good as bootstrap results in that coverage percentages were very close. More importantly, computation time was much shorter. For example, when using the LS method with $m = n = 400$, it took 30 seconds to obtain a bootstrap covariance estimate for one data set on a PC, it took only 5 seconds to obtain an asymptotic covariance estimate for the same data set on the same PC.

6. Application to Pancreatic Cancer Biomarkers

The main interest in the aforementioned biomarker example is to determine whether ROC curves generated by two biomarkers are equal. If not, one would wish to say which biomarker can better distinguish the diseased from the healthy. We applied the LS estimation procedure to this data set. With the probit link, $g = \Phi$, and $h = \Phi^{-1}$, ROC curves of these biomarkers have the same structure as those in (2.2) when $K = 2$. We got the estimate of the parameter vector as $(\hat{\theta}_{10}^{LS}, \hat{\theta}_{11}^{LS}, \hat{\theta}_{20}^{LS}, \hat{\theta}_{21}^{LS}) = (1.18, 0.47, -0.49, 0.55)$. Its covariance matrix estimate was calculated based on the asymptotic result in Theorem 2. The GLM and GEE parameter estimates were very close to the LS estimate, and thus were not listed. The χ^2 was then calculated to be 18.16 with the p -value 0.0001, indicating significant difference in diagnostic accuracy between two biomarkers. We also

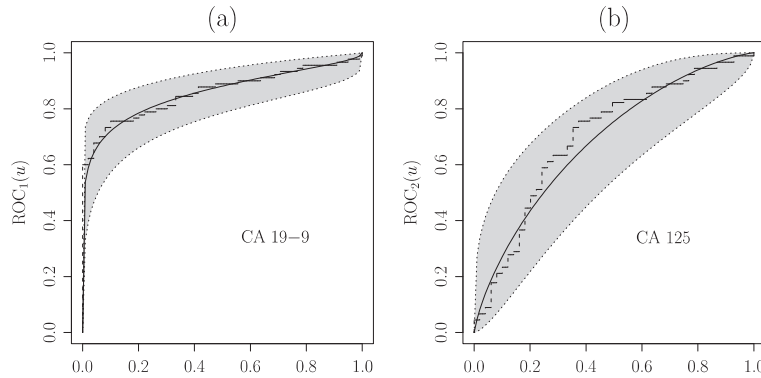


Figure 2. Estimated ROC curves and their 95% confidence bands for CA 19-9 and CA 125: dashed lines, empirical ROC; solid lines, estimated ROC; shaded regions, 95% confidence band; dotted lines, confidence band boundaries.

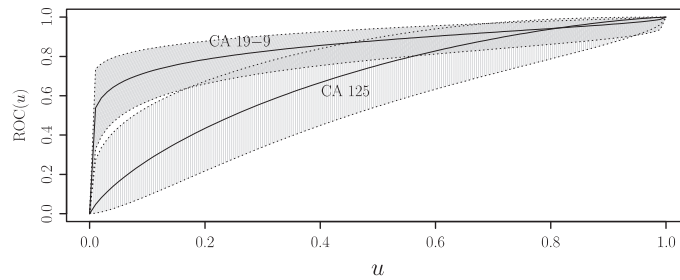


Figure 3. Overlapping 95% confidence bands for CA 19-9 and CA 125: solid lines, estimated ROC; shaded regions, 95% confidence band; dotted lines, confidence band boundaries.

calculated the difference between the two areas under estimated ROC curves using the procedure in Section 4.2, and found a significant difference between them, p -value 0.02. To visualize the sampling variability of estimated ROC curves, simultaneous ROC bands were constructed using the result in Theorem 3. Figure 2 shows the estimated ROC curves and their simultaneous bands. These ROC curves were very close to the empirical curves. Although our results on ROC curves and their areas show that the two biomarkers are different, it is clear in Figure 3 that two ROC curves intersect. The simultaneous bands can help us determine the region of FPRs where two ROC curves are different; Figure 3 shows overlapping confidence bands. It is obvious that the ROC curve for CA 19-9 is significantly better than that for CA 125 when the false positive rate is less than around 0.17, and that the two ROC curves do not differ much elsewhere.

7. Discussion

The interaction terms in our multivariate ROC model are completely different from the interactions of the K diagnostic tests on the measurement level. In fact, the interactions we refer to are between test types and FPRs. Multivariate ROC models such as the multivariate binormal play an important role in ROC analysis of clustered biomarkers. This article derived asymptotic covariances of the LS, GLM and GEE estimators for the multivariate ROC models with the presence of interaction terms between biomarker type and FPRs. To our knowledge, such asymptotic properties with correlated data have not been addressed in empirical process theory.

Our new contributions include procedures to compare AUCs and ROC curves, especially when the interaction terms between FPR's and biomarker type are present. We drew inference for pairwise comparison between ROC curves, multiple comparisons of areas under ROC curves under binormal assumptions. The inferential procedures in Section 4 for comparing ROC curves are very general for multivariate ROC models. Besides the three estimators discussed, if other estimators and their covariances were available, they can also be used in these procedures.

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Department of Statistics, The Volgenau School of Information Technology and Engineering, George Mason University, Science & Tech II, Room 155, 4400 University Drive, MS 4A7, Fairfax, VA 22030-4444, U.S.A.

E-mail: ltang1@gmu.edu

Department of Biostatistics, School of Public Health and Community Medicine, University of Washington, U.S.A.

E-mail: azhou@u.washington.edu

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