

FUNCTIONAL COEFFICIENT MOVING AVERAGE MODEL WITH APPLICATIONS TO FORECASTING CHINESE CPI

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Supplementary Material

Appendix: Lemmas and Proofs

Lemma 1 (Fan and Yao, 2006). Suppose that

1. $\{X_t, Y_t\}$ are strictly stationary and α -mixing with $\sum_{l \geq 1} l^\lambda [\alpha(l)]^{1-\frac{2}{\delta}} \leq \infty$ and $E\{|Y_t|^\delta | X_t = x\} < \infty$ for some $\delta > 2$ and $\lambda > 1 - 2/\delta$.
2. The conditional density $f_{X_0, X_l | Y_0, Y_l}(x_0, x_l | y_0, y_l) \leq A < \infty$ for some $A > 0$ and all $l > 0$.
3. The conditional distribution of Y_t given $X_t = u$, denoted by $G(y|u)$ is continuous at the point $u = x$.
4. As $T \rightarrow \infty$, $h \rightarrow 0$ and there exists a sequence of positive integers $s_T \rightarrow \infty$ and $s_T = o((Th)^{1/2})$ such that $(T/h)^{1/2} \alpha(s_T) \rightarrow 0$ as $T \rightarrow \infty$.
5. $K(\cdot)$ is a symmetric and bounded kernel with a bounded support $[-1, 1]$ such that $\int K(u) du = 1$.
6. $\sigma^2(\cdot) = \text{Var}(Y_t | X_t = \cdot)$ and the density function $f(\cdot)$ of X_t are continuous at the point x .

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Let $\hat{m}(x)$ be the local linear estimator of the conditional mean $m(x) = E(Y_t|X_t = x)$, then

$$\sqrt{Th}(\hat{m}(x) - m(x) - \frac{1}{2} \int u^2 K(u) du m''(x)h^2) \xrightarrow{d} N(0, \frac{\sigma^2(x)}{f(x)} \int K^2(u) du)$$

Lemma 2. Suppose $x_t \sim FMA(1)$. For $j = 0, 1$, Let

$$(\hat{a}_j^*(z), \hat{b}_j^*(z)) = \operatorname{argmin}_{(a,b)} \sum_{t=1}^T \{(x_t - \mu)(x_{t-j} - \mu) - a - b(z_t - z)\}^2 K\left(\frac{z_t - z}{h}\right),$$

then under the assumptions (A1)~(A6), it holds that

$$\sqrt{Th} \begin{pmatrix} \hat{a}_1^*(z) - (1 + \theta^2(z))\sigma^2 - \frac{1}{2}\sigma_K^2\theta''(z)\sigma^2h^2 \\ \hat{a}_0^*(z) - \theta(z)\sigma^2 - \sigma_K^2(\theta(z)\theta''(z) + \theta'^2(z))\sigma^2h^2 \end{pmatrix} \xrightarrow{d} N(0, \frac{\Gamma(z)}{p(z)}\sigma^4R(K)).$$

Proof. For any $v = (v_0, v_1)^T \in \mathbb{R}^2$, let $y_t(v) = v_0(x_t - \mu)^2 + v_1(x_t - \mu)(x_{t-1} - \mu)$. Denote $\hat{a}^*(z; v)$ by the local linear estimator of $E(y_t(v)|z_t = z) = v_0(1 + \theta^2(z))\sigma^2 + v_1\theta(z)\sigma^2$, i.e.

$$(\hat{a}^*(z; v), \hat{b}^*(z; v)) = \operatorname{argmin}_{a(z), b(z)} \sum_{t=2}^T (y_t(v) - a - b(z_t - z))^2 K\left(\frac{z_t - z}{h}\right)$$

Then it is easy to show that $\hat{a}^*(z; v) = v_0\hat{a}_0^*(z) + v_1\hat{a}_1^*(z)$. If we proved that

$$\begin{aligned} \sqrt{Th}(\hat{a}^*(z; v) - E(y_t(v)|z_t = z) - \frac{1}{2}\sigma^2h^2\sigma_K^2 v^T \begin{pmatrix} \theta''(z) \\ 2(\theta(z)\theta''(z) + \theta'^2(z)) \end{pmatrix}) \\ \xrightarrow{d} N(0, \frac{v^T\Gamma(z)v}{p(z)}\sigma^4R(K)). \end{aligned} \quad (1)$$

Then Lemma 2 will be proved by Cramér Device. Now we prove (1).

First, by Assumptions (A2) and (A3), $\{y_t(v), z_t\}$ is strictly stationary and α -mixing such that

$$E(|y_t(v)|^\delta | z_t = z) < C||v||^2 E(|\epsilon_t|^{2\delta} + |\epsilon_{t-1}|^{2\delta} + |\epsilon_{t-2}|^{2\delta} | z_t = z) < \infty$$

and $\alpha(m) \leq Am^{-\beta}$. Let $\lambda = \frac{\beta}{2} - \frac{1}{\delta}$, then $\lambda > 1$ since $\beta > (2\delta - 2)/(\delta - 2)$ and

$$\sum_{l \geq 1} l^\lambda (\alpha(l))^{1 - \frac{2}{\delta}} \leq A^{1 - \frac{2}{\delta}} \sum_{l \geq 1} l^{-(1 - \frac{2}{\delta})(\frac{\beta}{2} + \frac{1}{\delta - 2})} < \infty.$$

Thus, the condition 1 of Lemma 1 is satisfied.

By Assumption (A1), it holds that $h = O(T^{-(1-\epsilon_0)})$. Let $s_T = [(Th)^{1/2}/\log T]$, then $s_T = o((Th)^{1/2})$ and

$$(T/h)^{1/2} \alpha(s_T) = O(T^{1 - \frac{1+\beta}{2}\epsilon_0} (\log T)^{-\beta}) = o(1).$$

Thus, the condition 4 of Lemma 1 is satisfied.

Further, it follows Assumptions (A4), (A5) and (A6) that the conditions 2,3,5,6 of Lemma 1 hold. Therefore, (1) is proved by Lemma 1 and hence the lemma is proved by Cramér Device. \square

Lemma 3. Suppose that Assumptions (A1)~(A6) holds. Then

$$|\hat{a}_j(z) - \hat{a}_j^*(z)| = O_p\left(\frac{1}{\sqrt{T}}\right) \quad (2)$$

Proof. First, we show that $\bar{x} = O_p(T^{-1/2})$.

$$TVar(\bar{x}) = \sum_{|j| < T} \left(1 - \frac{|j|}{T}\right) \gamma(j) \leq \sum_{-\infty}^{\infty} \left(1 - \frac{|j|}{T}\right) \gamma(j) < \infty.$$

Thus $\lim_{T \rightarrow \infty} TVar(\bar{x}) = \sum_{-\infty}^{\infty} \gamma(h)$ and then $\bar{x} = O_p(T^{-1/2})$. Let $w_t(z) = K\left(\frac{z_t - z}{h}\right)(s_{n,2} - (z_t - z)s_{n,1})$, where $s_{n,j} = \sum_{t=1}^T K\left(\frac{z_t - z}{h}\right)(z_t - z)^j$, then

$$\hat{a}_j(z) = \frac{\sum_{t=j+1}^T w_t(z)(x_t - \bar{x})(x_{t-j} - \bar{x})}{\sum_{t=j+1}^T w_t(z)}, \quad \hat{a}_j^*(z) = \frac{\sum_{t=j+1}^T w_t(z)(x_t - \mu)(x_{t-j} - \mu)}{\sum_{t=j+1}^T w_t(z)}.$$

Notice that

$$|\hat{a}_j(z) - \hat{a}_j^*(z)| \leq |\mu^2 - \bar{x}^2| + |\mu - \bar{x}| \left| \frac{\sum_{t=j+1}^T w_t(z)(x_t + x_{t-j})}{\sum_{t=j+1}^T w_t(z)} \right|.$$

On the one hand,

$$\mu^2 - \bar{x}^2 = (\mu - \bar{x})(\mu + \bar{x}) = O_p\left(\frac{1}{\sqrt{T}}\right).$$

On the other hand, $\frac{\sum_{t=j+1}^T w_t(z)(x_t + x_{t-j})}{\sum_{t=j+1}^T w_t(z)}$ is the local linear estimator of $E(x_t + x_{t-j} | z_t = z)$. Let Then by Lemma 1, it is easy to prove that

$$\left| \frac{\sum_{t=j+1}^T w_t(z)(x_t + x_{t-j})}{\sum_{t=j+1}^T w_t(z)} \right| = O_p(1)$$

and hence

$$|\hat{a}_j(z) - \hat{a}_j^*(z)| = O_p\left(\frac{1}{\sqrt{T}}\right).$$

□

Proof of Theorem 1.

Without loss of generality, we assume $\mu = 0$. Let $M_T = T^{-1} \sum_{t=1}^T K_h(z_t - z)$,

$$\begin{aligned} \hat{g}\{\theta(z)\} - g\{\theta(z)\} &= \frac{\hat{a}_1(z)}{\hat{a}_0(z)} - \frac{\theta(z)}{1 + \theta^2(z)} = \frac{\hat{a}_1^*(z) + O_p(T^{-\frac{1}{2}})}{\hat{a}_0^*(z) + O_p(T^{-\frac{1}{2}})} - \frac{\theta(z)}{1 + \theta^2(z)} \\ &= \frac{\theta(z)\sigma^2 + \frac{1}{2}\sigma_K^2\theta''(z)\sigma^2h^2 + (Th)^{-\frac{1}{2}}A_1 + O_p(T^{-\frac{1}{2}})}{(1 + \theta^2(z))\sigma^2 + \sigma_K^2(\theta(z)\theta''(z) + \theta'^2(z))\sigma^2h^2 + (Th)^{-\frac{1}{2}}A_0 + O_p(T^{-\frac{1}{2}})} - \frac{\theta(z)}{1 + \theta^2(z)} \\ &= G(z)h^2 + (Th)^{-\frac{1}{2}} \frac{(1 + \theta^2(z))A_1 - \theta(z)A_0 + O_p(1)}{(1 + \theta^2(z))^2 + o_p(1)} \end{aligned}$$

where the second equality follows from Lemma 3, the third quality follows from Lemma 2 and

$$\begin{pmatrix} A_0 \\ A_1 \end{pmatrix} \sim N\left(0, \frac{\Gamma(z)}{p(z)}\sigma^4 R(K)\right)$$

Then it follows from Slutsky Theorem that

$$\sqrt{Th}(\hat{g}\{\theta(z)\} - g\{\theta(z)\} - G(z)h^2) \xrightarrow{d} N(0, \nu(z)).$$

□

Proof of Theorem 2. For (i), by Theorem 1, it suffices to prove

$$\sqrt{Th/\nu(z)}(\tilde{g}\{\theta(z)\} - \hat{g}\{\theta(z)\}) \xrightarrow{d} 0.$$

For arbitrary $\epsilon > 0$,

$$\begin{aligned} & P(\sqrt{Th/\nu(z)}(\tilde{g}\{\theta(z)\} - \hat{g}\{\theta(z)\}) > \epsilon) \leq P(\tilde{g}\{\theta(z)\} \neq \hat{g}\{\theta(z)\}) \\ & = P(|\hat{g}\{\theta(z)\}| > \frac{1}{2}) \leq P(|\hat{g}\{\theta(z)\} - g\{\theta(z)\}| > \frac{1}{2} - |g\{\theta(z)\}|) \rightarrow 0. \end{aligned}$$

Thus, (i) is proved. Now turn to (ii). Notice that $G = 0$ when $g\{\theta(z)\} = \frac{1}{2}$, thus by Theorem 1, we know that

$$\sqrt{Th/\nu(z)}(\hat{g}\{\theta(z)\} - \frac{1}{2}) \xrightarrow{d} Z$$

where $Z \sim N(0, 1)$. Let $f(x) = \min\{x, 0\}$, then

$$\sqrt{Th/\nu(z)}(\tilde{g}\{\theta(z)\} - \frac{1}{2}) = f[\sqrt{Th/\nu(z)}(\hat{g}\{\theta(z)\} - \frac{1}{2})].$$

Since f is continuous, by continuous mapping theorem, we have

$$\sqrt{Th/\nu(z)}(\tilde{g}\{\theta(z)\} - \frac{1}{2}) \xrightarrow{d} f(Z),$$

where $f(Z) \sim \Phi^-$. Therefore, (ii) is proved and similarly (iii) is proved. \square

Proof of Theorem 3. (i) is directly followed from Lemma 2 and Delta Method. Now we prove (ii) while (iii) can be dealt with in similar way. It follows Remark 1 that $G(z) = 0$ when $\theta(z) = 1$, by Theorem 1, we know that

$$\sqrt{Th/\nu(z)}(\hat{g}\{\theta(z)\} - \frac{1}{2}) \xrightarrow{d} N(0, 1),$$

where $Z \sim N(0, 1)$. For any positive d , we have

$$\begin{aligned} & P\left\{\sqrt[4]{\frac{Th}{\nu(z)}}(\hat{\theta}(z) - 1) \leq -r\right\} = P\left\{\hat{\theta}(z) \leq 1 - \frac{r\sqrt[4]{\nu(z)}}{\sqrt[4]{Th}}\right\} \\ & = P\left\{g(\hat{\theta}(z)) \leq g\left(1 - \frac{r\sqrt[4]{\nu(z)}}{\sqrt[4]{Th}}\right)\right\} \end{aligned}$$

$$\begin{aligned}
&= P \left\{ \sqrt{Th} \left[g(\hat{\theta}(z)) - \frac{1}{2} \right] \leq \sqrt{Th} \left[g\left(1 - \frac{r \sqrt[4]{\nu(z)}}{\sqrt[4]{Th}}\right) - g(1) \right] \right\} \\
&= P \left\{ \sqrt{Th} \left[g(\hat{\theta}(z)) - \frac{1}{2} \right] \leq \sqrt{Th} \left[-\frac{r^2 \sqrt{\nu(z)}}{4\sqrt{Th}} + o\left(\frac{1}{\sqrt{Th}}\right) \right] \right\} \\
&= P \left\{ \sqrt{Th/\nu(z)} \left(g(\hat{\theta}(z)) - \frac{1}{2} \right) \leq -\frac{r^2}{4} + o(1) \right\} \rightarrow \Phi\left(-\frac{r^2}{4}\right).
\end{aligned}$$

Also, since $\hat{\theta}(z) \leq 1$, we have

$$\sqrt[4]{Th/\nu(z)}(\hat{\theta}(z) - \theta(z)) \xrightarrow{d} H_{\Phi}^-.$$

□

Proof of Theorem 4. Write $\hat{\theta}(z) = h[g\{\hat{a}_1(z)/\hat{a}_0(z)\}] =: q\{\hat{a}_1(z), \hat{a}_0(z)\}$, say.

By Taylor expansion,

$$\hat{\theta}(z) = q\{a_1(z), a_0(z)\} + \sum_{j=0}^1 \frac{\partial q\{a_1(z), a_0(z)\}}{\partial a_j(z)} \{\hat{a}_j(z) - a_j(z)\} + O_p((Th)^{-1/2} + h^2)$$

The test statistic can be expressed as

$$\begin{aligned}
D_T &= Th^{1/2} \left[\int \{\hat{\theta}(z) - E\{\hat{\theta}(z)\}\}^2 \pi(z) dz \right. \\
&\quad + 2 \int \{\hat{\theta}(z) - E\{\hat{\theta}(z)\}\} \{E\{\hat{\theta}(z) - \hat{\theta}\} \pi(z) dz \\
&\quad \left. + \int \{E\{\hat{\theta}(z) - \hat{\theta}\}^2 \pi(z) dz \right] \\
&= D_{T1} + D_{T2} + D_{T3}, \quad \text{say.}
\end{aligned} \tag{3}$$

Let us first study D_{T1} , which can be expressed as

$$D_{T1} = Th^{1/2} \int (\hat{a}(z) - E\{\hat{a}(z)\})^T \frac{\partial q(z)}{\vec{a}} \frac{\partial^T q(z)}{\vec{a}} (\hat{a}(z) - E\{\hat{a}(z)\}) \pi(z) dz.$$

Take expectation, we have

$$E(D_{T1}) = h^{-1/2} \int \{g'\{\theta(z)\}^2 \nu(z)\} \pi(z) dz \{1 + o(1)\}. \tag{4}$$

It can be shown (Chen, Gao and Tang, 2008; Chen and Gao, 2011) that

$$\begin{aligned}
& \text{Var}(D_{T1}) \\
&= 2T^2h \int \int \text{Cov}^2\{\hat{\theta}(z_1) - E\{\hat{\theta}(z_1)\}, \hat{\theta}(z_2) - E\{\hat{\theta}(z_2)\}\} \pi(z_1)\pi(z_2) dz_1 dz_2 \\
&= 2T^2h \int \int \left[\sum_{i,j=0}^1 \frac{\partial q(z_1)}{\partial a_i} \frac{\partial q(z_2)}{\partial a_j} \text{Cov}\{\hat{a}_i(z_1) - E\{\hat{a}_i(z_1)\}, \hat{a}_j(z_2) - E\{\hat{a}_j(z_2)\}\} \right]^2 \\
&\quad \times \pi(z_1)\pi(z_2) dz_1 dz_2 \{1 + o(1)\}.
\end{aligned}$$

Standard derivations in kernel regression estimation show that, for $i, j = 0$ or 1 ,

$$\begin{aligned}
& \text{Cov}\{\hat{a}_i(z_1) - E\{\hat{a}_i(z_1)\}, \hat{a}_j(z_2) - E\{\hat{a}_j(z_2)\}\} \\
&= (Th)^{-1} f^{-1}(z_2) K^{(2)} \left(\frac{z_1 - z_2}{h} \right) m_{i,j}(z_1) \{1 + o(1)\}.
\end{aligned}$$

These lead to

$$\begin{aligned}
& \sigma^2(D_{T1}) =: \text{Var}(D_{T1}) \\
&= 2h^{-1} \int \int \left\{ K^{(2)} \left(\frac{z_1 - z_2}{h} \right) \right\}^2 f^{-2}(z_2) \left[\sum_{i,j=0}^1 \frac{\partial q(z_1)}{\partial a_i} \frac{\partial q(z_2)}{\partial a_j} m_{i,j}(z_1) \right]^2 \\
&\quad \times \pi(z_1)\pi(z_2) dz_1 dz_2 \{1 + o(1)\} \\
&= 2K^{(4)}(0) \int f^{-2}(z) \left[\sum_{i,j=0}^1 \frac{\partial q(z)}{\partial a_i} \frac{\partial q(z)}{\partial a_j} m_{i,j}(z) \right]^2 \pi^2(z) dz \{1 + o(1)\} \quad (5)
\end{aligned}$$

where $K^{(2)}(\cdot)$ is the convolution of K and $K^{(4)}(\cdot)$ is the convolution of $K^{(2)}$. Let $\sigma_{D_T}^2$ denote the leading order term of (5).

Employing the same technique used in Chen and Gao (2011) for goodness-of-test statistics for α -mixing sequences, it can be shown that the statistic D_{T1} is asymptotically normally distributed so that

$$\sigma^{-1}(D_{T1})\{D_{T1} - E(D_{T1})\} \xrightarrow{d} N(0, 1) \quad \text{as } T \rightarrow \infty. \quad (6)$$

To study the properties of D_{T2} , let θ^* be the limit of the estimator $\hat{\theta}$ such that $\hat{\theta} \xrightarrow{P} \theta^*$ at the rate of \sqrt{T} . Clearly, under H_0 , $\theta^* = \theta(z)$ for any z . Under H_1 , θ^* can be viewed as the one in Θ which minimizes a criterion function for the estimation, like a likelihood or a distance function. This is a common provision

made in testing hypothesis (White, 1982; Chen and Gao, 2007). Let

$$D_{T21} = 2Th^{1/2} \int \{\hat{\theta}(z) - E\{\hat{\theta}(z_1)\}\} \{E\{\hat{\theta}(z_1)\} - \theta^*\} \pi(z) dz.$$

Under H_0 , D_{T21} vanishes. Under H_1 , $E(D_{T21}) = 0$ and $Var(D_{T21}) = O(Th)$. Hence, D_{T21} is at most $O_p\{(Th)^{1/2}\}$. As

$$D_{T2} = Th^{1/2} \int \{\hat{\theta}(z) - E\{\hat{\theta}(z_1)\}\} \{E\{\hat{\theta}(z_1)\} - \theta^* + \theta^* - \hat{\theta}\} \pi(z) dz,$$

$D_{T2} = O_p(h^{1/2})$ under H_0 and $O_p\{(Th)^{1/2}\}$ under H_1 .

We can argue similarly that $D_{T3} = Th^{1/2} \int \{E\{\hat{\theta}(z)\} - \hat{\theta}\}^2 \pi(z) dz$ is $o_p(1)$ under H_0 , but diverges to positive infinity at the rate of $Th^{1/2}$ under H_1 , which is faster than T_{T2} . In summary,

$$D_T - E(D_T) = D_{T1} - E(D_{T1}) + o_p(1) \quad \text{under } H_0 \quad \text{and} \quad (7)$$

$$D_T - E(D_{T1}) = O_p(Th^{1/2}) \quad \text{under } H_1. \quad (8)$$

These together with (6) lead to the conclusion of Theorem 4. \square

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