ENVELOPE QUANTILE REGRESSION

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Abstract: The quantile regression method is a valuable complement to the classical mean regression, helping to ensure robust and comprehensive data analyses in a variety of applications. We propose a novel envelope quantile regression (EQR) method that adapts a nascent technique called *enveloping* to improve the efficiency of the standard quantile regression. The proposed method aims to identify the material and immaterial information in a quantile regression model, and then use only the material information for estimation. By excluding the immaterial information, the EQR method has the potential to substantially reduce estimation variability. Unlike existing envelope model approaches, which rely mainly on the likelihood framework, our proposed estimator is defined through a set of nonsmooth estimating equations. We facilitate the estimation via the generalized method of moments, and derive the asymptotic normality of the proposed estimator by applying empirical process techniques. Furthermore, we establish that the EQR is asymptotically more efficient than (or at least as asymptotically efficient as) the standard quantile regression estimators, without imposing stringent conditions. Hence, our work advances the envelope model theory to general distribution-free settings. We demonstrate the effectiveness of the proposed method via Monte Carlo simulations and real data examples.

Key words and phrases: Asymptotic efficiency, envelope model, generalized method of moments, reducing subspace, sufficient dimension reduction.

1. Introduction

Envelopes were first proposed by Cook, Li and Chiaromonte (2010) for response reduction and parsimonious estimation in multivariate linear regressions with normal errors. In this setting, the envelope approach has been proved to achieve asymptotic efficiency and reduce the estimation variability over that of the standard methods. Since then, a variety of envelope models have been developed and demonstrated promising performances in multivariate statistical problems. For example, Su and Cook (2011, 2012) and Cook and Su (2013)

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subsequently studied envelope methods for various data structures in linear regression models. Cook, Helland and Su (2013) used envelopes to study predictor reduction and established a connection between envelope models and partial least squares. Based on this connection, Zhu and Su (2019) derived the envelope-based sparse partial least squares method. Cook, Forzani and Zhang (2015) applied the envelope method to reduced rank regression. Cook and Zhang (2015) extended the applicability of the envelope model beyond linear regressions to include, for example, generalized linear regressions and the cox proportional hazards model. Su et al. (2016) proposed sparse envelope models for variable selection in a multivariate linear regression setting. Khare, Pal and Su (2017) developed Bayesian envelope approaches. Li and Zhang (2017) and Ding and Cook (2018) proposed envelopes for tensor and matrix regression problems. Envelopes for spatial and time series data have been studied by Rekabdarkolaee et al. (2017) and Wang and Ding (2018), respectively.

The existing works, however, have mainly tended to focus on mean regressions and likelihood-based models. As a result, the estimations and inferences often rely on the maximum likelihood principle. In particular, the asymptotic efficiency of the envelope estimators often requires a normality assumption. Thus, a primary objective of this study is to develop a new nonlikelihood-based framework for enveloping, and to extend the envelope theory to general distributionfree settings to potentially improve efficiency. Although developed in the context of quantile regressions (QRs), our framework can also be extended to other statistical methods and procedures.

The QR (Koenker and Bassett (1978); Koenker (2005)) is a popular regression technique, widely used in economics, health sciences, and many other fields. It does not require distributional assumptions on the error terms, and thus is a flexible distribution-free regression technique. By accommodating varying covariate effects at different quantile levels, a QR provides a more complete picture of the relationship between the response variable and the covariates. In addition, It incorporates heterogeneous covariate effects and is robust to outliers. Because of its good statistical properties and flexibility in practice, the QR has become a popular alternative to the least squares regression, and has gained considerable interest in recent years. For example, Knight (1998), He and Shao (2000), Chernozhukov (2005), He and Zhu (2011), Feng, He and Hu (2011), Yang and He (2012), and many others have studied the theoretical properties and inference tools of QRs under different settings, and Portnoy and Koenker (1997), Chen and Wei (2005), Koenker (2011), and others have investigated the computational

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perspectives of such regressions. Furthermore, the QR has been extended to longitudinal and survival data analyses (He, Zhu and Fung (2002); Portnoy (2003); Wei et al. (2006); Peng and Huang (2008); Wang and Wang (2009); Xu et al. (2017), among many others). We refer to Koenker (2005, 2017) and Koenker et al. (2017) for a comprehensive review of the QR.

In this article, we propose a new approach called the *envelope quantile regres*sion (EQR) that adapts a nascent technique called enveloping (Cook (2018)) by introducing dimension reduction into quantile modeling. In a variety of settings, it is reasonable to assume there exist linear combinations of predictors that are irrelevant to the conditional quantiles of the response and these combinations do not affect the conditional quantiles through their association with the remaining combinations. Thus, we can focus on a subspace of the full predictor space that is directly relevant to the model fitting. We refer to the relevant part of the predictors as material information, and to the remaining predictors as immaterial information. Using immaterial information in model fitting is likely to increase estimation variation. The proposed EQR approach does not change the traditional objectives of the QR. However, by fully utilizing information on both the predictors and the response, it can distinguish between material and immaterial information when modeling the conditional quantiles, and synchronously exclude immaterial information from the model estimation. This simultaneous dimension reduction and regression fitting yields an improvement in estimation efficiency that can be substantial when the immaterial variation is large.

This study makes three main contributions to the literature. First, we develop a new EQR approach that adapts the ideas of enveloping to QRs and achieves efficiency gains. We prove that the EQR estimator is \sqrt{n} -consistent and asymptotically normal. More importantly, it is asymptotically more efficient than (or at least as asymptotically efficient as) the standard QR estimators, without imposing stringent conditions. In addition, whilst we mainly focus on linear QRs here, our approach can be extended naturally to include partially linear QRs, censored QRs and other settings. Second, our formulation offers the first nonlikelihood-based envelope method with a theoretical justification on the asymptotical efficiency. Furthermore, it establishes a new framework for enveloping and advances the recent development of envelopes to general distribution-free procedures with possibly nonsmooth objective functions. Third, the theoretical development of the EQR estimator is based on rather different techniques than those used in existing envelope models and QRs. The proposed estimator is defined through a set of nonsmooth estimating equations. We facilitate the es-

timation via the generalized method of moments (GMM) that not only ensures desirable theoretical properties but further improves the asymptotic efficiency of the estimators. Empirical process techniques are employed to establish the asymptotics, which can be used to handle both nonsmooth and over-parametrized models and, potentially, can be applied to more complex enveloping problems.

Most existing envelope approaches focus on continuous variables, so does the EQR method. When categorical predictors are present, we develop a partial envelope quantile model that applies the enveloping idea to the continuous predictors only. We show that the partial envelope quantile model improves the estimation efficiency of the regression coefficients, especially those of the continuous predictors.

The rest of the article is organized as follows. In Section 2, we briefly review the linear QR and propose the EQR method. In Section 3, we establish the theoretical properties of the EQR estimators and demonstrate their efficiency. Section 4 presents the new GMM estimation procedure and discusses dimension selection procedures for the proposed EQR. Section 5 demonstrates the empirical performance of the EQR method via simulations and real examples. Section 6 is devoted to the development of partial EQR for data with categorical predictors. We conclude with a brief discussion in Section 7. Technical details, proofs, and additional simulation results are given in the online Supplementary Material.

To facilitate our discussion, we introduce the following notations that will be used throughout the article. Let $\mathbb{R}^{r \times u}$ be the set of all $r \times u$ matrices, and let $\mathbb{S}^{m \times m}$ be the set of all $m \times m$ real and symmetric matrices. For any $\mathbf{A} \in \mathbb{R}^{r \times u} (u \leq r)$, Span(\mathbf{A}) is the subspace of \mathbb{R}^r spanned by the columns of \mathbf{A} . Let $\mathbf{P}_{\mathbf{A}} = \mathbf{A} (\mathbf{A}^T \mathbf{A})^{\dagger} \mathbf{A}^T$ be the projection onto Span(\mathbf{A}), and let $\mathbf{Q}_{\mathbf{A}} = \mathbf{I}_r - \mathbf{P}_{\mathbf{A}}$ be the projection onto Span(\mathbf{A})^{\perp}, the orthogonal complement of Span(\mathbf{A}), where \dagger denotes the Moore-Penrose inverse and \mathbf{I}_r is the identity matrix of dimension r. Note that $\mathbf{P}_{\mathbf{A}}$ and $\mathbf{Q}_{\mathbf{A}}$ can be equivalently denoted by $\mathbf{P}_{\mathcal{A}}$ and $\mathbf{Q}_{\mathcal{A}}$, respectively, where $\mathcal{A} = \text{Span}(\mathbf{A})$. Let "vec" denote the vectorization operator that stacks the columns of an argument matrix. Let "vech" represent the half-vectorization operator that vectorizes only the lower triangular of a symmetric matrix. We use $|| \cdot ||$ to represent the Frobenius norm.

2. EQR

2.1. A brief review of the QR

Consider a univariate response variable Y and a p-dimensional predictor ve-

ctor $\mathbf{X} \in \mathbb{R}^p$. Let $F_Y(y|\mathbf{X} = \mathbf{x}) = P(Y \leq y|\mathbf{X} = \mathbf{x})$ be the cumulative distribution function (CDF) of Y given $\mathbf{X} = \mathbf{x}$. The τ -th conditional quantile of Y is defined as

$$Q_Y(\tau | \mathbf{X} = \mathbf{x}) = \inf\{y : F_Y(y | \mathbf{X} = \mathbf{x}) \ge \tau\}, \ 0 < \tau < 1.$$

A linear QR model assumes a linear relationship between the τ -th conditional quantile of Y and the predictors; that is,

$$Q_Y(\tau | \mathbf{X}) = \mu_\tau + \boldsymbol{\beta}_\tau^T \mathbf{X}, \qquad (2.1)$$

where μ_{τ} is the intercept, and $\beta_{\tau} \in \mathbb{R}^p$ is the slope vector of the τ -th conditional quantile of $Y|\mathbf{X}$. The primary objective of a QR is to estimate β_{τ} , for any $0 < \tau < 1$, and then to make a statistical inference about β_{τ} . The standard method used to obtain $\tilde{\beta}_{\tau}$, the estimator of β_{τ} , is to solve

$$(\tilde{\mu}_{\tau}, \tilde{\boldsymbol{\beta}}_{\tau}) = \operatorname*{argmin}_{\mu_{\tau} \in \mathbb{R}, \boldsymbol{\beta}_{\tau} \in \mathbb{R}^{p}} \sum_{i=1}^{n} \rho_{\tau} (Y_{i} - \mu_{\tau} - \boldsymbol{\beta}_{\tau}^{T} \mathbf{X}_{i}),$$
(2.2)

where (Y_i, \mathbf{X}_i) , for i = 1, ..., n, is a random sample of (Y, \mathbf{X}) , and $\rho_{\tau}(z) = z[\tau - I(z < 0)]$ is a piecewise linear loss function. This objective function can be solved efficiently using linear programming algorithms. Furthermore, the estimator $\tilde{\beta}_{\tau}$ is \sqrt{n} -consistent and asymptotically normal.

Note that the minimizer in (2.2) is also a root of the estimating equations

$$\frac{1}{n} \sum_{i=1}^{n} \mathbf{W}_{i}[I(Y_{i} < \mu_{\tau} + \boldsymbol{\beta}_{\tau}^{T} \mathbf{X}_{i}) - \tau] = o_{p}(n^{-1/2}), \qquad (2.3)$$

where $\mathbf{W}_i = (1, \mathbf{X}_i^T)^T$. For a detailed background of QRs, we refer to Koenker (2005).

2.2. EQR

We now introduce the EQR approach, which we use to distinguish between material and immaterial information in terms of modeling the conditional quantiles of the response. The EQR approach builds on the observations that in a variety of applications some portion of the predictors are irrelevant to modeling the conditional quantile of the response and do not affect the response through the rest. For example, a disease may be related to a few genetic pathways, while these pathways are uncorrelated with others that are not responsible for the

disease.

To formulate this statement mathematically, suppose that for the given quantile level of interest τ , there exists a subspace $S_{\tau} = \text{Span}(\Gamma_{\tau})$ of \mathbb{R}^p , where $\Gamma_{\tau} \in \mathbb{R}^{p \times d_{\tau}}(d_{\tau} \leq p)$ is a semi-orthogonal basis of S_{τ} , such that

i) $Q_Y(\tau | \mathbf{X}) = Q_Y(\tau | \mathbf{P}_{\mathcal{S}_\tau} \mathbf{X})$ and ii) $\operatorname{Cov}(\mathbf{P}_{\mathcal{S}_\tau} \mathbf{X}, \mathbf{Q}_{\mathcal{S}_\tau} \mathbf{X}) = 0,$ (2.4)

where $\mathbf{P}_{S_{\tau}}$ and $\mathbf{Q}_{S_{\tau}}$ are projection matrices, defined at the end of Section 1.

The first part of (2.4) means that $Q_Y(\tau|\mathbf{X})$ depends on \mathbf{X} only through $\mathbf{P}_{S_{\tau}}\mathbf{X}$. Hence $\mathbf{P}_{S_{\tau}}\mathbf{X}$ contains full information for modeling the τ -th conditional quantile of Y. The second part indicates that $\mathbf{P}_{S_{\tau}}\mathbf{X}$ is uncorrelated with $\mathbf{Q}_{S_{\tau}}\mathbf{X}$, which ensures that $\mathbf{Q}_{S_{\tau}}\mathbf{X}$ does not provide information about the τ -th conditional quantile of Y through its association with $\mathbf{P}_{S_{\tau}}\mathbf{X}$. Thus, \mathbf{X} affects the τ -th conditional quantile of Y only through $\mathbf{P}_{S_{\tau}}\mathbf{X}$. We call $\mathbf{P}_{S_{\tau}}\mathbf{X}$ the material part of \mathbf{X} , and $\mathbf{Q}_{S_{\tau}}\mathbf{X}$ the immaterial part of \mathbf{X} . Let $\Sigma_{\mathbf{X}}$ denote the covariance matrix of \mathbf{X} . By Cook, Li and Chiaromonte (2010), if a subspace S_{τ} is spanned by the eigenvectors of $\Sigma_{\mathbf{X}}$ and it contains $\boldsymbol{\beta}_{\tau}$, then S_{τ} satisfies the conditions in (2.4).

Many applications naturally satisfy (2.4). For example, suppose all coordinates of **X** are equally correlated such that $\Sigma_{\mathbf{X}} = \sigma_{\mathbf{X}}^2 \mathbf{I}_p + r \mathbf{1}_p \mathbf{1}_p^T$, where r is a constant and 1_p is a p-dimensional vector of ones, and β_{τ} has a sparse structure such as $\boldsymbol{\beta}_{\tau} = (1, 2, 0, \dots, 0)^T$. Note that the eigenvectors of $\Sigma_{\mathbf{X}}$ include $\mathbf{1}_p$ and any vector in Span $(1_p)^{\perp}$. Let $v_1 = (r-1, -1, \dots, -1)^T$ and $v_2 = (-1, r-1, -1, \dots, -1)^T$. Since $v_1^T 1_p = 0$ and $v_2^T 1_p = 0$, v_1 and v_2 are eigenvectors of $\Sigma_{\mathbf{X}}$. We can take $\mathcal{S}_{\tau} = \operatorname{Span}(v_1, v_2, 1_p)$. Because $\beta_{\tau} \in \mathcal{S}_{\tau}, \mathcal{S}_{\tau}$ satisfies i) and ii) in (2.4). This example demonstrates that if X is equally correlated and β_{τ} is sparse, we can find a subspace that satisfies the conditions in (2.4). A second example is that when $\Sigma_{\mathbf{X}}$ has a low rank decomposition. Suppose $\Sigma_{\mathbf{X}}$ has the structure $\Sigma_{\mathbf{X}} = \mathbf{A}\mathbf{A}^T + c\mathbf{I}_p$, where c is a constant, $\mathbf{A} \in \mathbb{R}^{p \times k}$, and k < p. Then $\text{Span}(\mathbf{A})$ is spanned by the eigenvectors of $\Sigma_{\mathbf{X}}$. Such low rank covariance structures occur in many applications such as factor analysis, where most of the variation of the predictor vector can be explained by a small number of common factors or principal components. If β_{τ} is contained in Span(A), we can take $\mathcal{S}_{\tau} = \text{Span}(A)$. Thus, \mathcal{S}_{τ} satisfies the conditions in (2.4). If β_{τ} is not contained in Span(A), let $\mathcal{A} = \text{Span}(\mathbf{A})$. Then any vector in the orthogonal complement of \mathcal{A} is an eigenvector of $\Sigma_{\mathbf{X}}$. We can write $\beta_{\tau} = \mathbf{P}_{\mathcal{A}}\beta_{\tau} + \mathbf{Q}_{\mathcal{A}}\beta_{\tau}$, and let $v = \mathbf{Q}_{\mathcal{A}}\beta_{\tau}$. Note that v is an eigenvector of $\Sigma_{\mathbf{X}}$. Let $\mathcal{S}_{\tau} = \text{Span}(\{\mathbf{A}, v\})$, then $\boldsymbol{\beta}_{\tau} \in \mathcal{S}_{\tau}$ and \mathcal{S}_{τ} satisfies the conditions in (2.4). Therefore, for any vector β_{τ} , and regardless of whether it has a sparsity

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structure like $\beta_{\tau} = (*, \ldots, *, 0, \ldots, 0)$, we can find a subspace S_{τ} with dimension at most k + 1 that satisfies the conditions in (2.4). Note that we use a sparse β_{τ} in some examples only for illustrative purposes and (2.4) does not require sparsity in β_{τ} .

In fact, the subspace S_{τ} in (2.4) always exists, because it can be trivially chosen as the full space \mathbb{R}^p . However, the subspace might not be unique, and what we wish to determine is the smallest subspace such that the conditions holds. To address the uniqueness of the material part, we consider the intersection of all such subspaces that satisfy (2.4), which is minimal and well defined. To see this, we first define a reducing subspace, as given in Cook, Li and Chiaromonte (2010).

Definition 1. A subspace $\mathcal{R} \subseteq \mathbb{R}^p$ is said to be a reducing subspace of $\mathbf{M} \in \mathbb{R}^{p \times p}$ if \mathcal{R} decomposes \mathbf{M} as $\mathbf{M} = \mathbf{P}_{\mathcal{R}} \mathbf{M} \mathbf{P}_{\mathcal{R}} + \mathbf{Q}_{\mathcal{R}} \mathbf{M} \mathbf{Q}_{\mathcal{R}}$.

This definition is commonly used in the literature on invariance subspaces and functional analysis (Conway (1990)). Lemma 1 connects our formulation to reducing subspaces.

Lemma 1. Under model (2.1), (i) $Q_Y(\tau | \mathbf{X}) = Q_Y(\tau | \mathbf{P}_{S_{\tau}} \mathbf{X})$ if and only if $\beta_{\tau} \in S_{\tau}$, and (ii) $\operatorname{Cov}(\mathbf{P}_{S_{\tau}}\mathbf{X}, \mathbf{Q}_{S_{\tau}}\mathbf{X}) = 0$ if and only if S_{τ} is a reducing subspace of $\Sigma_{\mathbf{X}}$.

For part (i), since $Q_Y(\tau | \mathbf{X}) = \mu_{\tau} + \boldsymbol{\beta}_{\tau}^T \mathbf{P}_{\mathcal{S}_{\tau}} \mathbf{X} + \boldsymbol{\beta}_{\tau}^T \mathbf{Q}_{\mathcal{S}_{\tau}} \mathbf{X} = Q_Y(\tau | \mathbf{P}_{\mathcal{S}_{\tau}} \mathbf{X})$, we have $\mathbf{Q}_{\mathcal{S}_{\tau}} \boldsymbol{\beta}_{\tau} = 0$, and therefore, $\boldsymbol{\beta}_{\tau} \in \mathcal{S}_{\tau}$. For the other direction, if $\boldsymbol{\beta}_{\tau} \in \mathcal{S}_{\tau}$, $Q_Y(\tau | \mathbf{X}) = \mu_{\tau} + \boldsymbol{\beta}_{\tau}^T \mathbf{P}_{\mathcal{S}_{\tau}} \mathbf{X}$, then $Q_Y(\tau | \mathbf{X}) = Q_Y(\tau | \mathbf{P}_{\mathcal{S}_{\tau}} \mathbf{X})$. Part (ii) holds as it can be shown that $\Sigma_{\mathbf{X}} = \mathbf{P}_{\mathcal{S}_{\tau}} \Sigma_{\mathbf{X}} \mathbf{P}_{\mathcal{S}_{\tau}} + \mathbf{Q}_{\mathcal{S}_{\tau}} \Sigma_{\mathbf{X}} \mathbf{Q}_{\mathcal{S}_{\tau}}$ when $\operatorname{Cov}(\mathbf{P}_{\mathcal{S}_{\tau}} \mathbf{X}, \mathbf{Q}_{\mathcal{S}_{\tau}} \mathbf{X}) = 0$.

Therefore, based on Lemma 1, (2.4) holds if and only if S_{τ} is a reducing subspace of $\Sigma_{\mathbf{X}}$ that contains $\boldsymbol{\beta}_{\tau}$. Such a reducing subspace might not be unique. However, by the properties of reducing subspaces, the intersection of all reducing subspaces that contain $\boldsymbol{\beta}_{\tau}$ is also a reducing subspace containing $\boldsymbol{\beta}_{\tau}$, and it is unique and minimal. Thus, to maximize the reduction and efficiency gains, this smallest reducing subspace that contains $\boldsymbol{\beta}_{\tau}$ is of interest. We call it the $\Sigma_{\mathbf{X}}$ envelope of $\boldsymbol{\beta}_{\tau}$, and denote it as $\mathcal{E}_{\Sigma_{\mathbf{X}}}(\boldsymbol{\beta}_{\tau})$, or \mathcal{E}_{τ} .

To establish the EQR model, let $\mathbf{\Phi}_{\tau} \in \mathbb{R}^{p \times u_{\tau}}$ $(u_{\tau} \leq p)$ be a semi-orthogonal basis of \mathcal{E}_{τ} and $\mathbf{\Phi}_{0\tau} \in \mathbb{R}^{p \times (p-u_{\tau})}$ be a semi-orthogonal basis of $\mathcal{E}_{\tau}^{\perp}$, the orthogonal subspace of \mathcal{E}_{τ} . We first assume that the envelope dimension u_{τ} is known. The determination of the envelope dimension is discussed in Section 4. Since $\beta_{\tau} \in \mathcal{E}_{\tau}$, we can write β_{τ} in a coordinate form as $\beta_{\tau} = \mathbf{\Phi}_{\tau} \boldsymbol{\eta}_{\tau}$, where $\boldsymbol{\eta}_{\tau}$ is the coordinate

of β_{τ} relative to the basis Φ_{τ} . In addition, because \mathcal{E}_{τ} is a reducing subspace of $\Sigma_{\mathbf{X}}$, $\Sigma_{\mathbf{X}}$ can be decomposed into two orthogonal parts: $\Sigma_{\mathbf{X}} = \mathbf{P}_{\mathcal{E}_{\tau}} \Sigma_{\mathbf{X}} \mathbf{P}_{\mathcal{E}_{\tau}} + \mathbf{Q}_{\mathcal{E}_{\tau}} \Sigma_{\mathbf{X}} \mathbf{Q}_{\mathcal{E}_{\tau}}$. Therefore, model (2.1) can be reparameterized as the following envelope structure:

$$Q_Y(\tau | \mathbf{X}) = \mu_\tau + \boldsymbol{\eta}_\tau^T \boldsymbol{\Phi}_\tau^T \mathbf{X}$$

$$\Sigma_{\mathbf{X}} = \boldsymbol{\Phi}_\tau \boldsymbol{\Omega}_\tau \boldsymbol{\Phi}_\tau^T + \boldsymbol{\Phi}_{0\tau} \boldsymbol{\Omega}_{0\tau} \boldsymbol{\Phi}_{0\tau}^T,$$
(2.5)

where $\Omega_{\tau} \in \mathbb{R}^{u_{\tau} \times u_{\tau}}$ and $\Omega_{0\tau} \in \mathbb{R}^{(p-u_{\tau}) \times (p-u_{\tau})}$ are positive definite matrices that serve as coordinates of $\mathbf{P}_{\mathcal{E}_{\tau}} \Sigma_{\mathbf{X}} \mathbf{P}_{\mathcal{E}_{\tau}}$ and $\mathbf{Q}_{\mathcal{E}_{\tau}} \Sigma_{\mathbf{X}} \mathbf{Q}_{\mathcal{E}_{\tau}}$ relative to the bases Φ_{τ} and $\Phi_{0\tau}$, respectively. We call this model the EQR model.

By incorporating enveloping into the formulation of the QR, the EQR model utilizes underlying information in both the predictors and the response to identify the material and immaterial information. Then it connects the parameter of interest, β_{τ} , to the material part only, leading to efficiency gains in the parameter estimation. As a simple illustration, suppose that the envelope basis Φ_{τ} is known and $E(\mathbf{X}) = 0$. Let $\tilde{\beta}_{\tau}$ be the standard estimator of β_{τ} from (2.1). Then the asymptotic variance of $\tilde{\beta}_{\tau}$, denoted as $\operatorname{avar}(\sqrt{n}\tilde{\beta}_{\tau})$, is $\omega^2 \Sigma_{\mathbf{X}}^{-1}$ under an independent and identically distributed (i.i.d.) error model (Koenker (2005)), where ω is a constant. Because Φ_{τ} is known, the envelope estimator of β_{τ} is then $\hat{\beta}_{\tau} = \Phi_{\tau}\hat{\eta}_{\tau}$, and

$$\operatorname{avar}(\sqrt{n}\widehat{\beta}_{\tau}) = \Phi_{\tau}\operatorname{avar}(\sqrt{n}\widehat{\eta}_{\tau})\Phi_{\tau} = \omega^{2}\Phi_{\tau}\left[\operatorname{Var}(\Phi_{\tau}^{T}\mathbf{X})\right]^{-1}\Phi_{\tau} = \omega^{2}\Phi_{\tau}\Omega_{\tau}^{-1}\Phi_{\tau}^{T}.$$

Thus, $\operatorname{avar}(\sqrt{n}\tilde{\boldsymbol{\beta}}_{\tau}) - \operatorname{avar}(\sqrt{n}\hat{\boldsymbol{\beta}}_{\tau}) = \omega^2 \Sigma_{\mathbf{X}}^{-1} - \omega^2 \boldsymbol{\Phi}_{\tau} \boldsymbol{\Omega}_{\tau}^{-1} \boldsymbol{\Phi}_{\tau}^T = \omega^2 \boldsymbol{\Phi}_{0\tau} \boldsymbol{\Omega}_{0\tau}^{-1} \boldsymbol{\Phi}_{0\tau}^T \geq 0$, where the last equation holds because $\Sigma_{\mathbf{X}}^{-1} = \boldsymbol{\Phi}_{\tau} \boldsymbol{\Omega}_{\tau}^{-1} \boldsymbol{\Phi}_{\tau}^T + \boldsymbol{\Phi}_{0\tau} \boldsymbol{\Omega}_{0\tau}^{-1} \boldsymbol{\Phi}_{0\tau}^T$. Therefore, the envelope estimator is asymptotically more efficient than (or at least as efficient as) the standard quantile estimator, and the efficiency gains can be quite substantial when the immaterial variation $\boldsymbol{\Phi}_{0\tau} \boldsymbol{\Omega}_{0\tau}^{-1} \boldsymbol{\Phi}_{0\tau}^T$ of $\Sigma_{\mathbf{X}}^{-1}$ is relatively large. In Section 3, we provide a rigorous justification of the asymptotic efficiency of EQR estimators under general settings, while the estimation algorithm is presented in Section 4.

In addition, the total number of free parameters in β_{τ} and $\Sigma_{\mathbf{X}}$ under the EQR model is $u_{\tau} + p(p+1)/2$, where u_{τ} for $\boldsymbol{\eta}_{\tau}$, $u_{\tau}(p-u_{\tau})$ for $\text{Span}(\boldsymbol{\Phi}_{\tau})$, $u_{\tau}(u_{\tau}+1)/2$ for $\boldsymbol{\Omega}_{\tau}$, and $(p-u_{\tau})(p-u_{\tau}+1)/2$ for $\boldsymbol{\Omega}_{0\tau}$. In contrast, without enveloping, the number of free parameters in β_{τ} and $\Sigma_{\mathbf{X}}$ is p+p(p+1)/2. Thus, the EQR model reduces the number of parameters by $p-u_{\tau}$.

3. Theoretical Results

Consider the QR model in (2.1) with an arbitrary quantile level of interest τ . Denote the conditional density function of $Y|\mathbf{X}$ as $f_{Y|\mathbf{X}}$. Denote the asymptotic variance of a general statistic \mathbf{M}_n as $\operatorname{avar}(\sqrt{n}\mathbf{M}_n)$. Let $\boldsymbol{\theta} := (\boldsymbol{\theta}_1^T, \boldsymbol{\theta}_2^T)^T \in \mathbb{R}^{2p+1+s}$, where $\boldsymbol{\theta}_1 = (\mu_{\tau}, \boldsymbol{\beta}_{\tau}^T)^T$ represents the parameters in the conditional QR, $\boldsymbol{\theta}_2 = (\operatorname{vech}(\Sigma_{\mathbf{X}})^T, \boldsymbol{\mu}_{\mathbf{X}}^T)^T$ contains parameters in the marginal distribution of \mathbf{X} , and s = p(p+1)/2 is the dimension of $\operatorname{vech}(\Sigma_{\mathbf{X}})$. Let $\boldsymbol{\theta}^* = (\boldsymbol{\theta}_1^T, \operatorname{vech}(\Sigma_{\mathbf{X}})^T)^T$ be a collection of parameters that are directly related to the envelope model in (2.5). Here $\boldsymbol{\theta}, \boldsymbol{\theta}_1$, and $\boldsymbol{\theta}^*$ are all relevant to τ but, for convenience, we omit the subscript τ for these notations.

We first consider unitizing estimating equations to estimate the unknown parameter vector $\boldsymbol{\theta}$. We employ (2.2) and the first- and second-order moment conditions of **X** as our estimation equations:

$$h_{n}(\boldsymbol{\theta}) = \begin{pmatrix} h_{1,n}(\boldsymbol{\theta}_{1}) \\ h_{2,n}(\boldsymbol{\theta}_{2}) \\ h_{3,n}(\boldsymbol{\theta}_{2}) \end{pmatrix} = \begin{pmatrix} \frac{1}{n} \sum_{i=1}^{n} \mathbf{W}_{i}[I(Y_{i} < \mu_{\tau} + \boldsymbol{\beta}_{\tau}^{T} \mathbf{X}_{i}) - \tau] \\ \operatorname{vech}(\Sigma_{\mathbf{X}}) - \operatorname{vech}(\mathbf{S}_{\mathbf{X}}) \\ \boldsymbol{\mu}_{\mathbf{X}} - \bar{\mathbf{X}} \end{pmatrix}$$
$$= \frac{1}{n} \sum_{i=1}^{n} g(\mathbf{Z}_{i}; \boldsymbol{\theta}) = o_{p}(n^{-1/2}),$$
(3.1)

where $\mathbf{S}_{\mathbf{X}} = (1/n) \sum_{i=1}^{n} (\mathbf{X}_{i} - \boldsymbol{\mu}_{\mathbf{X}}) (\mathbf{X}_{i} - \boldsymbol{\mu}_{\mathbf{X}})^{T}$ is the sample covariance matrix of \mathbf{X} given $\boldsymbol{\mu}_{\mathbf{X}}, \mathbf{Z}_{i} = (Y_{i}, \mathbf{X}_{i}^{T})^{T}$, and $g(\mathbf{Z}_{i}; \boldsymbol{\theta}) = (g_{1}^{T}(\mathbf{Z}_{i}; \boldsymbol{\theta}_{1}), g_{2}^{T}(\mathbf{Z}_{i}; \boldsymbol{\theta}_{2}), g_{3}^{T}(\mathbf{Z}_{i}; \boldsymbol{\theta}_{2}))^{T}$, with $g_{1}(\mathbf{Z}_{i}; \boldsymbol{\theta}_{1}) = \mathbf{W}_{i}[I(Y_{i} < \boldsymbol{\mu}_{\tau} + \boldsymbol{\beta}_{\tau}^{T}\mathbf{X}_{i}) - \tau], g_{2}(\mathbf{Z}_{i}; \boldsymbol{\theta}_{2}) = \operatorname{vech}(\Sigma_{\mathbf{X}}) - \operatorname{vech}\{(\mathbf{X}_{i} - \boldsymbol{\mu}_{\mathbf{X}})^{T}\}, \text{ and } g_{3}(\mathbf{Z}_{i}; \boldsymbol{\theta}_{2}) = \boldsymbol{\mu}_{\mathbf{X}} - \mathbf{X}_{i}.$

Let $\tilde{\theta}$ and $\tilde{\theta}^*$ denote the standard estimators of θ and θ^* , respectively, from solving the estimating equation in (3.1) without enveloping, and let θ_0 and θ_0^* be the true values of θ and θ^* , respectively. The main parameters of interest are β_{τ} and $\Sigma_{\mathbf{X}}$ in EQR model, and in addition the estimator of $\mu_{\mathbf{X}}$ is $\bar{\mathbf{X}}$, which remains unchanged under enveloping and has the same asymptotic distribution in both envelope and non-envelope settings. Thus, we ignore $\mu_{\mathbf{X}}$ in the following theoretical development.

To investigate the asymptotic behavior of the estimator of θ^* , we require the following regularity conditions.

(C1) For any \mathbf{x} in the support of \mathbf{X} , the conditional distribution of $\mathbf{Y}|\mathbf{X} = \mathbf{x}$ is absolutely continuous, with the continuous density $f_{\mathbf{Y}|\mathbf{X}}$ uniformly bounded away from zero and ∞ at $\xi_0(\tau|\mathbf{x})$, the τ -conditional quantile of $Y|\mathbf{X} = \mathbf{x}$ under $\boldsymbol{\theta}_0$.

- (C2) The expectation $\mathbb{E}_{\boldsymbol{\theta}_0}[g(\mathbf{Z};\boldsymbol{\theta})]$ is twice differentiable at $\boldsymbol{\theta}_0$, with $(\partial \mathbb{E}_{\boldsymbol{\theta}_0} [g(\mathbf{Z};\boldsymbol{\theta})]/\partial \boldsymbol{\theta}^T)|_{\boldsymbol{\theta}=\boldsymbol{\theta}_0}$ having full rank and a finite Frobenius norm. The matrix $\mathbb{E}_{\boldsymbol{\theta}_0}[g(\mathbf{Z};\boldsymbol{\theta}_0)g^T(\mathbf{Z};\boldsymbol{\theta}_0)]$ is positive definite and has a finite Frobenius norm, and the array $(\partial \mathbb{E}_{\boldsymbol{\theta}_0}[g(\mathbf{Z};\boldsymbol{\theta})g^T(\mathbf{Z};\boldsymbol{\theta})]/\partial \boldsymbol{\theta}^T)|_{\boldsymbol{\theta}=\boldsymbol{\theta}_0}$ has a finite Frobenius norm.
- (C3) $\mathbf{E}||\mathbf{X}||^3$ is bounded. In addition, the support $\boldsymbol{\Theta}$ of $\boldsymbol{\theta}$ is compact, and $\boldsymbol{\theta}_0$ is an interior point of $\boldsymbol{\Theta}$.

Conditions (C1) and (C3) are standard in the literature on QRs. Condition (C2) is a regular assumption for estimating equations. Theorem 1 establishes the asymptotic distribution of the standard estimator $\tilde{\theta}$ of θ^* .

Theorem 1. Under the regularity conditions (C1)–(C3), $\sqrt{n}(\tilde{\theta}^* - \theta_0^*)$ converges in distribution to a multivariate normal distribution with mean zero and covariance matrix $\operatorname{avar}(\sqrt{n}\tilde{\theta}^*) = \mathbf{U}^{-1}\mathbf{V}\mathbf{U}^{-1}$, where

$$\mathbf{U} = \begin{pmatrix} \mathbf{E}_{\boldsymbol{\theta}_0}[f_{Y|\mathbf{X}}(\xi_0(\tau|\mathbf{X}))\mathbf{W}\mathbf{W}^T] & 0\\ 0 & \mathbf{I}_s \end{pmatrix}$$

and

$$\mathbf{V} = \begin{pmatrix} \tau(1-\tau) \mathbf{E}_{\boldsymbol{\theta}_0}[\mathbf{W}\mathbf{W}^T] & 0\\ 0 & \operatorname{var}_{\boldsymbol{\theta}_0}\{\operatorname{vech}[(\mathbf{X} - \boldsymbol{\mu}_{\mathbf{X},0})(\mathbf{X} - \boldsymbol{\mu}_{\mathbf{X},0})^T]\} \end{pmatrix},$$

with $\mu_{\mathbf{X},0}$ being the true value of $\mu_{\mathbf{X}}$.

The proof for Theorem 1 is given in Section A of the Supplementary Material. Theorem 1 shows that the standard estimator $\tilde{\boldsymbol{\theta}}_1 = (\tilde{\mu}_{\tau}, \tilde{\boldsymbol{\beta}}_{\tau}^T)^T$ for the conditional QR from solving $h_n(\boldsymbol{\theta}) = 0$ is asymptotically independent of the standard estimator vech $(\tilde{\Sigma}_{\mathbf{X}})$ for the marginal distribution of \mathbf{X} . In addition, let $\tilde{\boldsymbol{\theta}}_{1,m}$ denote the estimator of $\boldsymbol{\theta}_1$ obtained directly by minimizing (2.1). It follows from the results in Knight (1998) and Koenker (2005) that $\tilde{\boldsymbol{\theta}}_1$ is asymptotically equivalent to $\tilde{\boldsymbol{\theta}}_{1,m}$.

Under the envelope setting, we denote the parameters in the coordinate representation of the EQR model (2.5) as the following vector:

$$\boldsymbol{\zeta}_{\tau} = \left(\mu_{\tau}, \boldsymbol{\eta}_{\tau}^{T}, \operatorname{vec}(\boldsymbol{\Phi}_{\tau})^{T}, \operatorname{vech}(\Omega_{\tau})^{T}, \operatorname{vech}(\Omega_{0\tau})^{T}\right)^{T} = \left(\boldsymbol{\zeta}_{\tau,1}, \boldsymbol{\zeta}_{\tau,2}^{T}, \boldsymbol{\zeta}_{\tau,3}^{T}, \boldsymbol{\zeta}_{\tau,4}^{T}, \boldsymbol{\zeta}_{\tau,5}^{T}\right)^{T},$$

and define the parameter of interest θ^* as

$$\boldsymbol{\theta}^{*} = \begin{pmatrix} \mu_{\tau} \\ \boldsymbol{\beta}_{\tau} \\ \operatorname{vech}(\boldsymbol{\Sigma}_{\mathbf{X}}) \end{pmatrix} = \begin{pmatrix} \mu_{\tau} \\ \boldsymbol{\Phi}_{\tau} \boldsymbol{\eta}_{\tau} \\ \operatorname{vech}(\boldsymbol{\Phi}_{\tau} \boldsymbol{\Omega}_{\tau} \boldsymbol{\Phi}_{\tau}^{T} + \boldsymbol{\Phi}_{0\tau} \boldsymbol{\Omega}_{0\tau} \boldsymbol{\Phi}_{0\tau}^{T}) \end{pmatrix} := \begin{pmatrix} \psi_{1}(\boldsymbol{\zeta}_{\tau}) \\ \psi_{2}(\boldsymbol{\zeta}_{\tau}) \\ \psi_{3}(\boldsymbol{\zeta}_{\tau}) \end{pmatrix} = \psi(\boldsymbol{\zeta}_{\tau}).$$
(3.2)

Note that under enveloping, the estimating equations in (3.1) are reparameterized as

$$h_{n}(\boldsymbol{\theta}) = \begin{pmatrix} h_{1,n}(\boldsymbol{\theta}_{1}) \\ h_{2,n}(\boldsymbol{\theta}_{2}) \\ h_{3,n}(\boldsymbol{\theta}_{2}) \end{pmatrix} = \begin{pmatrix} \frac{1}{n} \sum_{i=1}^{n} \mathbf{W}_{i} [I(Y_{i} < \mu_{\tau} + \boldsymbol{\eta}_{\tau}^{T} \boldsymbol{\Phi}_{\tau}^{T} \mathbf{X}_{i}) - \tau] \\ \operatorname{vech}(\boldsymbol{\Phi}_{\tau} \Omega_{\tau} \boldsymbol{\Phi}_{\tau}^{T} + \boldsymbol{\Phi}_{0\tau} \Omega_{0\tau} \boldsymbol{\Phi}_{0\tau}^{T}) - \operatorname{vech}(\mathbf{S}_{\mathbf{X}}) \\ \boldsymbol{\mu}_{\mathbf{X}} - \bar{\mathbf{X}} \end{pmatrix}. \quad (3.3)$$

The number of equations in (3.3) is 1 + 2p + p(p+1)/2. This is greater than the number of free parameters in μ_{τ} , β_{τ} , $\mu_{\mathbf{X}}$, and $\Sigma_{\mathbf{X}}$ under the envelope parameterization, namely, $1 + u_{\tau} + p + p(p+1)/2$. Therefore, it cannot be guaranteed that all equations can be solved for zero simultaneously. Hence a solution for (3.3) may not exist. Instead, we propose estimating the parameters by utilizing the idea of generalized method of moments (GMM; Hansen (1982)) for the parsimonious envelope model. Let $\boldsymbol{\zeta}_{\tau}' = (\boldsymbol{\zeta}_{\tau}^T, \boldsymbol{\mu}_{\mathbf{X}}^T)^T$ and $\psi_0(\boldsymbol{\zeta}_{\tau}') := (\psi^T(\boldsymbol{\zeta}_{\tau}), \boldsymbol{\mu}_{\mathbf{X}}^T)^T = \boldsymbol{\theta}$. The envelope GMM estimator $\hat{\boldsymbol{\theta}}_g$ of $\boldsymbol{\theta}$ is then defined as

$$\widehat{\boldsymbol{\theta}}_{g} = \operatorname*{argmin}_{\boldsymbol{\theta}:\boldsymbol{\theta}=\psi_{0}(\boldsymbol{\zeta}_{\tau}')} h_{n}^{T}(\boldsymbol{\theta})\widehat{\boldsymbol{\Delta}}h_{n}(\boldsymbol{\theta}), \qquad (3.4)$$

where $\widehat{\Delta}$ is chosen to be any \sqrt{n} -consistent estimator of $\{ \mathbf{E}_{\boldsymbol{\theta}_0}[g(\mathbf{Z};\boldsymbol{\theta}_0)g^T(\mathbf{Z};\boldsymbol{\theta}_0)] \}^{-1}$, for example, $\widehat{\Delta} = \{ n^{-1} \sum_{i=1}^n g(\mathbf{Z}_i; \widetilde{\boldsymbol{\theta}}) g^T(\mathbf{Z}_i; \widetilde{\boldsymbol{\theta}}) \}^{-1}$. In Section 4, we propose an estimation procedure to attain the envelope GMM estimator $\widehat{\boldsymbol{\theta}}_g$.

Let $\hat{\theta}_g^*$ denote the envelope GMM estimator of θ^* , the parameter of interest. We next establish the asymptotic theory for $\hat{\theta}_g^*$ and compare it with the standard estimator $\tilde{\theta}^*$.

Theorem 2. (1) Under the regularity conditions (C1)–(C3), assume that the support of the envelope parameter vector $\boldsymbol{\zeta}_{\tau}$ is compact, then $\sqrt{n}(\hat{\boldsymbol{\theta}}_{g}^{*} - \boldsymbol{\theta}_{0}^{*})$ converges in distribution to a multivariate normal distribution with mean zero and covariance matrix

$$\operatorname{avar}(\sqrt{n}\widehat{\theta}_g^*) = \Psi(\Psi^T \mathbf{U} \mathbf{V}^{-1} \mathbf{U} \Psi)^{\dagger} \Psi^T,$$

where $\Psi = \partial \psi(\zeta_{\tau}) / \partial \zeta_{\tau}^T$ is the gradient matrix of $\psi(\zeta_{\tau})$ relative to ζ_{τ} . Its explicit

expression is given in the Supplementary Material (B.6). (2) In addition, $\operatorname{avar}(\sqrt{n}\widehat{\theta}_a^*) \leq \operatorname{avar}(\sqrt{n}\widetilde{\theta}^*)$.

The proof of Theorem 2 is given in Section B of the Supplementary Material. The main challenge of the proof lies in the fact that objective function in (3.4) is not only nonsmooth, but is also over-parameterized. We employ empirical process techniques (Van Der Vaart and Wellner (1996); Van der Vaart (1998)) and the results in Newey and McFadden (1994) and Shapiro (1986) for the derivation. The theorem shows the asymptotic normality for the envelope GMM estimator $\hat{\theta}_g^*$ of the joint parameters in the QR and the covariance matrix of **X**. More importantly, it establishes the asymptotic efficiency of $\hat{\theta}_g^*$ relative to the standard estimator $\tilde{\theta}^*$. Thus, by utilizing information on both the predictors and the response, the proposed EQR approach can lead to gains in efficiency in QR estimations.

To illustrate the efficiency gains, we consider a special case of i.i.d error models, and assume that \mathbf{X} is multivariate normal and $E(\mathbf{X}) = 0$. After some simplification of the form of the asymptotic variance given in Theorem 1 and Theorem 2 (see Section B of the Supplementary Material), we have

$$\operatorname{avar}(\sqrt{n}\tilde{\boldsymbol{\beta}}_{\tau}) = \frac{\tau(1-\tau)}{f^2(\boldsymbol{\xi}(\tau))} \boldsymbol{\Sigma}_{\mathbf{X}}^{-1},$$

and

$$\operatorname{avar}(\sqrt{n}\widehat{\boldsymbol{\beta}}_{g,\tau}) = \frac{\tau(1-\tau)}{f^2(\xi(\tau))} \boldsymbol{\Phi}_{\tau} \boldsymbol{\Omega}_{\tau}^{-1} \boldsymbol{\Phi}_{\tau}^T + (\boldsymbol{\eta}_{\tau}^T \otimes \boldsymbol{\Phi}_{0\tau}) \mathbf{T}^{-1}(\boldsymbol{\eta}_{\tau} \otimes \boldsymbol{\Phi}_{0\tau}^T),$$

where

$$\mathbf{T} = \frac{f^2(\xi(\tau))}{\tau(1-\tau)} (\boldsymbol{\eta}_{\tau} \boldsymbol{\eta}_{\tau}^T) \otimes \boldsymbol{\Omega}_{0\tau} + \boldsymbol{\Omega}_{\tau} \otimes \boldsymbol{\Omega}_{0\tau}^{-1} + \boldsymbol{\Omega}_{\tau}^{-1} \otimes \boldsymbol{\Omega}_{0\tau} - 2\mathbf{I}_{u_{\tau}} \otimes \mathbf{I}_{p-u_{\tau}}.$$

Compared with the simple example given in Section 2.2, the asymptotic variance of $\hat{\beta}_{g,\tau}$ has an additional term $(\eta_{\tau}^T \otimes \Phi_{0\tau}) \mathbf{T}^{-1} (\eta_{\tau} \otimes \Phi_{0\tau}^T)$, which can be viewed as the cost of estimating the envelope, because it is unknown in general. Theorem 2 shows that even with this estimation cost, the envelope GMM estimator $\hat{\beta}_{g,\tau}$ is still asymptotically more efficient than (or at least as asymptotically efficient as) the standard estimator $\hat{\beta}_{\tau}$.

Statistical inferences for the envelope GMM estimator can be performed based on the asymptotic distribution in Theorem 2. We can estimate the asymptotic variance using $\widehat{\operatorname{avar}}(\sqrt{n}\widehat{\theta}_q^*) = \widehat{\Psi}(\widehat{\Psi}^T \widehat{\mathbf{U}}\widehat{\mathbf{V}}^{-1}\widehat{\mathbf{U}}\widehat{\Psi})^{\dagger}\widehat{\Psi}^T$, where $\widehat{\Psi}$, $\widehat{\mathbf{U}}$, and

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 $\hat{\mathbf{V}}$ are consistent estimators of $\mathbf{\Psi}$, \mathbf{U} , and \mathbf{V} , respectively. Correspondingly, $\widehat{\operatorname{avar}}(\sqrt{n}\widehat{\boldsymbol{\theta}}_g^*) \to \operatorname{avar}(\sqrt{n}\widehat{\boldsymbol{\theta}}_g^*)$ in probability. Then statistical inferences can be made based on asymptotic normality. A consistent estimator of $\mathbf{\Psi}$ can be easily obtained using the estimated envelope parameters, and that of \mathbf{V} can be provided by moment estimation. The estimation of \mathbf{U} is not straightforward as it involves an unknown density function. This problem occurs in a standard QR inference as well. We can adopt the kernel-based estimation approach (Powell (1991); Koenker (2005)) to achieve consistent estimation of $\mathbf{U}_{(1)} =$ $\mathbf{E}_{\boldsymbol{\theta}_0}[f_{Y|\mathbf{X}}(\xi_0(\tau|\mathbf{X}))\mathbf{W}\mathbf{W}^T]$, with $\hat{\mathbf{U}}_{(1)} = (nh_n)^{-1}\sum_{i=1}^n K(\hat{\xi}_i(\tau|\mathbf{X})/h_n)\mathbf{W}_i\mathbf{W}_i^T$ under certain Lipschitz continuity conditions on f, where $\hat{\xi}_i(\tau|\mathbf{X}) = Y_i - \hat{\mu}_{g,\tau} - \hat{\boldsymbol{\beta}}_{g,\tau}^T\mathbf{X}_i$, and $K(\cdot)$ and h_n are the kernel function and bandwidth satisfying $h_n \to 0$ and $\sqrt{n}h_n \to \infty$. For example, Powell (1991) used the kernel $K(\hat{\xi}_i(\tau|\mathbf{X})) =$ $I(|\hat{\xi}_i(\tau|\mathbf{X})| < h_n)/2$. One might refer to Powell (1991) and Koenker (2005) for further discussion on the choices of $K(\cdot)$ and h_n .

On the other hand, the bootstrap method is a useful alternative for inference of an EQR estimator, and is widely used in standard QR inferences (Knight (1999); Koenker (2005); Wang and Wang (2009); Feng, He and Hu (2011), among many others). For example, one can apply a paired bootstrap or a wild bootstrap to conduct an inference for the EQR estimator under heteroscedastic errors. These methods have been shown to achieve consistency in QR inferences (Knight (1999); Feng, He and Hu (2011)). We applied the paired bootstrap in our numerical studies (see Figures 1 and 2). It performs fairly well and shows accurate estimations of the standard deviations compared with those obtained from repeated samples.

For statistical inferences, the EQR estimator might lose some efficiency compared with its theoretical asymptotic variance, owing to the estimation uncertainty of the unknown parameters. In this circumstance, the performance of the EQR estimator might fall into one of the following two scenarios. First, when the immaterial variation of the data is substantial, even if the envelope dimension is relatively large (e.g., close to the full dimension), the EQR could still outperform the standard QR. In this case, the efficiency gains from identifying and removing immaterial information could overcome the estimation uncertainty, leading to more efficient estimators and smaller mean squared errors (MSEs). On the other hand, when the immaterial variation is relatively small, while the envelope dimension is large, the efficiency gains from enveloping might be inadequate to overcome the cost of the uncertainty when estimating the envelope subspace and parameters. In this case, the estimation uncertainty (including the estimation of

both the envelope dimension and the envelope parameters) could counteract and dominate the efficiency gains, resulting in relatively close, or worse performance of the EQR estimator compared with that of the QR estimator. Simulation studies illustrating these two cases are provided in Section D.1 of the Supplementary Material.

If the parameters in (2.1) do not have the envelope structure, the EQR estimator $\hat{\beta}_{g,\tau}$ may still have a smaller MSE than that of the standard QR estimator $\tilde{\beta}_{\tau}$ based on the bias-variance trade-off. Specifically, although the EQR estimator might be biased, it could have a smaller estimation variance. Then if the reduction of the estimation variance is substantial, the EQR estimator will have a smaller MSE. A simulation is included in Section D.2 of the Supplementary Material.

4. Estimation

In the literature on envelope models, estimations are routinely performed by optimizing a standard objective function, such as the log likelihood function, under the envelope parameterization. Existing envelope estimation techniques usually require the first two derivatives of the objective function (Cook, Li and Chiaromonte (2010); Cook and Zhang (2016); Cook, Forzani and Su (2016)). However, the objective function for a QR (2.2) is nonsmooth.

We start with estimating equation (3.3). In (3.3), Φ_{τ} is not estimable as it can be any orthogonal basis of $\mathcal{E}_{\Sigma_{\mathbf{X}}}(\boldsymbol{\beta}_{\tau})$, and only $\mathcal{E}_{\Sigma_{\mathbf{X}}}(\boldsymbol{\beta}_{\tau}) = \operatorname{Span}(\Phi_{\tau})$ is estimable. To obtain an estimator of $\mathcal{E}_{\Sigma_{\mathbf{X}}}(\boldsymbol{\beta}_{\tau})$, we have to perform a Grassmann manifold optimization, which can be slow and difficult in sizable problems. Cook, Forzani and Su (2016) proposed a reparameterization of Φ_{τ} such that the Grassmann manifold optimization problem can be converted to an unconstrained matrix optimization problem. It is shown that the computing speed is greatly improved under the new parameterization. Therefore, we adopt this reparameterization for our problem and this does not affect our theoretical results. Without loss of generality, we assume that the upper $u_{\tau} \times u_{\tau}$ block is invertible. Write

$$\boldsymbol{\Phi}_{\tau} = \begin{pmatrix} \boldsymbol{\Phi}_{\tau 1} \\ \boldsymbol{\Phi}_{\tau 2} \end{pmatrix} = \begin{pmatrix} \mathbf{I}_{u_{\tau}} \\ \boldsymbol{\Phi}_{\tau 2} \boldsymbol{\Phi}_{\tau 1}^{-1} \end{pmatrix} \boldsymbol{\Phi}_{\tau 1} \equiv \begin{pmatrix} \mathbf{I}_{u_{\tau}} \\ \mathbf{A} \end{pmatrix} \boldsymbol{\Phi}_{\tau 1} \equiv \boldsymbol{\Phi}_{\tau}^{*} \boldsymbol{\Phi}_{\tau 1}.$$
(4.1)

Then $\mathcal{E}_{\Sigma_{\mathbf{x}}}(\boldsymbol{\beta}_{\tau})$ and **A** have a one-to-one correspondence. Specifically, for a u_{τ} -dimensional subspace of \mathcal{R}^p , we have a unique representing basis $\boldsymbol{\Phi}_{\tau}^*$, the first u_{τ} rows of which form an identity matrix. Thus, if we obtain an esti-

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mator of **A**, say $\widehat{\mathbf{A}}$, we can easily obtain $\widehat{\mathbf{\Phi}}_{\tau}^*$ following the structure in (4.1), and $\widehat{\mathcal{E}}_{\Sigma_{\mathbf{X}}}(\boldsymbol{\beta}_{\tau}) = \operatorname{Span}(\widehat{\mathbf{\Phi}}_{\tau}^*)$. Now let $\boldsymbol{\eta}_{\tau}^* = \boldsymbol{\Phi}_{\tau 1} \boldsymbol{\eta}_{\tau}$ and $\Omega_{\tau}^* = \boldsymbol{\Phi}_{\tau 1} \Omega_{\tau} \boldsymbol{\Phi}_{\tau 1}^T$ be the coordinates of $\boldsymbol{\beta}_{\tau}$ and $\Sigma_{\mathbf{X}}$, respectively, with respect to $\boldsymbol{\Phi}_{\tau}^*$. Let $\boldsymbol{\zeta}_{\tau}^* = \{\mu_{\tau}, \operatorname{vec}(\boldsymbol{\eta}_{\tau}^*)^T, \operatorname{vech}(\boldsymbol{\Omega}_{\tau}^*)^T, \operatorname{vech}(\Omega_{0\tau})^T, \operatorname{vec}(\boldsymbol{\mu}_{\mathbf{X}})^T\}^T$. Under this parameterization, (3.3) becomes

$$h_n^*(\boldsymbol{\zeta}_{\tau}^*) = \begin{pmatrix} \frac{1}{n} \sum_{i=1}^n \mathbf{W}_i \{ I[Y_i < \mu_{\tau} + (\boldsymbol{\Phi}_{\tau}^* \boldsymbol{\eta}_{\tau}^*)^T \mathbf{X}_i] - \tau \} \\ \frac{1}{n} \sum_{i=1}^n \{ \operatorname{vech}(\boldsymbol{\Phi}_{\tau}^* \boldsymbol{\Omega}_{\tau}^* \boldsymbol{\Phi}_{\tau}^{*T} + \boldsymbol{\Phi}_{0\tau} \boldsymbol{\Omega}_{0\tau} \boldsymbol{\Phi}_{0\tau}^T) - \operatorname{vech}[(\mathbf{X}_i - \boldsymbol{\mu}_{\mathbf{X}})(\mathbf{X}_i - \boldsymbol{\mu}_{\mathbf{X}})^T] \} \\ \frac{1}{n} \sum_{i=1}^n (\boldsymbol{\mu}_{\mathbf{X}} - \mathbf{X}_i) \end{bmatrix} \\ \equiv \frac{1}{n} \sum_{i=1}^n g^*(\mathbf{Z}_i; \boldsymbol{\zeta}_{\tau}^*).$$

$$(4.2)$$

To obtain the GMM estimator, we use the following two-step algorithm:

Step 1. Obtain the estimator of ζ_{τ}^* by minimizing $h_n^*(\zeta_{\tau}^*)^T h_n^*(\zeta_{\tau}^*)$; denote this as $\tilde{\zeta}_{\tau}^*$.

Step 2. Estimate the optimal weight matrix as

$$\widehat{\boldsymbol{\Delta}}^{-1} = \left[\frac{1}{n} \sum_{i=1}^{n} g^{*}(\mathbf{Z}_{i}; \widetilde{\boldsymbol{\zeta}_{\tau}^{*}}) g^{*}(\mathbf{Z}_{i}; \widetilde{\boldsymbol{\zeta}_{\tau}^{*}})^{T}\right]^{-1}$$

Then obtain the GMM estimator $\widehat{\zeta}_{\tau}^*$ by minimizing the following quadratic form:

$$Q_n(\boldsymbol{\zeta}_{\tau}^*) = h_n^*(\boldsymbol{\zeta}_{\tau}^*)^T \widehat{\boldsymbol{\Delta}}^{-1} h_n^*(\boldsymbol{\zeta}_{\tau}^*)$$

Now $\widehat{\mu}_{\tau}$, $\widehat{\boldsymbol{\beta}}_{\tau} = \widehat{\boldsymbol{\Phi}}_{\tau}^* \widehat{\boldsymbol{\eta}}_{\tau}^*$, and $\widehat{\boldsymbol{\Sigma}}_{\mathbf{X}} = \widehat{\boldsymbol{\Phi}}_{\tau}^* \widehat{\boldsymbol{\Omega}}_{\tau}^* (\widehat{\boldsymbol{\Phi}}_{\tau}^*)^T + \widehat{\boldsymbol{\Phi}}_{0\tau} \widehat{\boldsymbol{\Omega}}_{0\tau} \widehat{\boldsymbol{\Phi}}_{0\tau}^T$ are the envelope GMM estimators of μ_{τ} , $\boldsymbol{\beta}_{\tau}$, and $\boldsymbol{\Sigma}_{\mathbf{X}}$, respectively.

To optimize the discontinuous GMM objective function, we use the function fminsearch in the R package neldermead. This function does not require the derivative of the objective function, and is also applicable to discontinuous objective functions. It uses the Nelder-Mead method, or downhill simplex method (Nelder and Mead (1965)), to find the minima of the objective function. More information on the method can be found in Section E of the Supplementary Material. The Nelder-Mead method has also been used to fit other QR models (e.g., Koenker and Park (1996); Otsu (2003); Noufaily and Jones (2013)).

To select the dimension of the envelope $\mathcal{E}_{\Sigma_{\mathbf{X}}}(\boldsymbol{\beta}_{\tau})$, we apply the robust cross-validation approach (RCV) (Oh et al. (2004)). More specifically, we randomly

divide the data into K folds, use the kth fold for testing and the remaining K-1 folds for training. We repeat this for k = 1, ..., K, and aggregate the prediction error based on the quantile loss function. For a fixed u_{τ} , the RCV criterion is

$$\operatorname{RCV}(u_{\tau}) = \frac{1}{n} \sum_{i=1}^{n} \rho_{\tau} (Y_i - \widehat{\mu}_{\tau,-k(i)} - \widehat{\beta}_{\tau,-k(i)}^T \mathbf{X}_i),$$

where $\hat{\mu}_{\tau,-k(i)}$ and $\hat{\beta}_{\tau,-k(i)}$ are computed using the data excluding the *k*th fold, in which the *i*th observation resides. Since cross-validation often overfits, we pick u_{τ} according to the "one-standard error" rule. That is, we choose the smallest u_{τ} whose error is no more than one standard error above the minimum value of the RCV. In our numerical studies, we found that the performance of the RCV is stable, even with a small sample size.

5. Simulation and Data Analysis

In this section, we demonstrate the efficiency gains of the EQR model using a numerical experiment and a real data example. We consider the following simulation setting:

$$Y_i = \mu + \boldsymbol{\alpha}^T \mathbf{X}_i + (5 + \boldsymbol{\gamma}^T \mathbf{X}_i) \epsilon_i, \text{ for } i = 1, \dots, n,$$

where $\alpha = \Phi \eta_1$, $\gamma = \Phi \eta_2$, and the error ϵ follows the standard normal distribution with distribution function denoted by F_{ϵ} . Here $\Phi \in \mathbb{R}^{p \times u} (u < p)$ is a semiorthogonal matrix. Hence $\mu_{\tau} = \mu + 5F_{\epsilon}^{-1}(\tau), \ \boldsymbol{\beta}_{\tau} = \boldsymbol{\Phi}(\boldsymbol{\eta}_1 + \boldsymbol{\eta}_2 F_{\epsilon}^{-1}(\tau)) = \boldsymbol{\Phi}\boldsymbol{\eta}_{\tau},$ $\Phi_{\tau} = \Phi$, and $u_{\pi} = u$, for $0 < \tau < 1$. We set p = 10, u = 2 and varied the sample size n from 50 to 1,000. We set X to follow a multivariate normal distribution with mean zero and variance having the structure $\mathbf{\Phi} \mathbf{\Omega} \mathbf{\Phi}^T + \mathbf{\Phi}_0 \mathbf{\Omega}_0 \mathbf{\Phi}_0^T$, where $\mathbf{\Phi}_0$ is a completion of Φ , and Ω and Ω_0 are coordinate matrices. We generated Φ with the first p/2 rows to be $(-1/\sqrt{p/2}, 0)$ and the other rows to be $(0, -1/\sqrt{p/2})$. The matrix Ω is a diagonal matrix with diagonal elements 50 and 100, Ω_0 is an identity matrix, $\boldsymbol{\eta}_1$ is $(-5\sqrt{p/2}, -5\sqrt{p/2})^T$, $\boldsymbol{\eta}_2$ is $(0, -\sqrt{2p}/20)^T$, and μ is 5. Therefore, α is a vector of 5 and γ is a vector with the first p/2 elements to be 0 and the rest to be 0.1. For each sample size, 200 replications were generated. For each replication, we fit the standard QR model (2.1) and the EQR model with $u_{\pi} = 2$. For each element in β_{τ} , we computed the estimation standard deviation from the 200 estimators. We also generated 200 bootstrap repetitions using the paired bootstrap, and computed the bootstrap standard deviation. We



Figure 1. Comparison of the EQR estimator and the standard QR estimator with u_{τ} fixed at true value ($\tau = 0.5$). Lines — mark the standard deviations of the EQR estimator and lines – – mark the standard deviations of the standard QR estimator. The lines with "+" mark the bootstrap standard deviations for the corresponding estimators.

considered $\tau = 0.5$ and $\tau = 0.9$. The results for a randomly chosen element in β_{τ} are summarized in Figures 1 and 2. The EQR model achieves obvious efficiency gains in this example. We compared the estimation standard deviations of the standard QR estimator and the EQR estimator for each element in β_{τ} . We found that, at sample size 50, the EQR estimator reduced the estimation standard deviation by 57.1% to 65.9% for $\tau = 0.5$. Under the standard QR model, to reduce the standard deviation by 65.9%, we need to increase the sample size by approximately 8.6 times the original sample size. The efficiency gain is more pronounced for $\tau = 0.9$, where the EQR estimator reduced the estimation standard deviation by 71.0% to 75.9%. To achieve a reduction of 75.9% in the estimation standard deviation, we need to increase the sample size by 17 times the original sample size under the standard QR model. Figures 1 and 2 also show that the bootstrap standard deviation is a very good approximation to the estimation standard deviation.

We also investigated the selection performance of five-fold RCV for each sample size. For different sample sizes, the fraction of 200 replications in which the RCV selects the true dimension is summarized in Table 1. It is quite stable across all sample sizes in Table 1. With small sample sizes, when it fails to select the true u_{τ} , it tends to overestimate and pick a larger dimension than the truth. In that case, we may achieve less efficiency gains, but we do not lose any material information. Therefore, we consider the performance of RCV to be reasonable with small sample sizes.

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Figure 2. Comparison of the EQR estimator and the standard QR estimator with u_{τ} fixed at true value ($\tau = 0.9$). Lines — mark the standard deviations of the EQR estimator and lines – – mark the standard deviations of the standard QR estimator. The lines with "+" mark the bootstrap standard deviations for the corresponding estimators.

Table 1. The fraction that RCV selects the true dimension.



Figure 3. Comparison of the EQR estimators and the standard QR estimator with $\tau = 0.5$. The line — marks the standard deviations of the EQR estimator with true u_{τ} , the line — with * marks the standard deviations of the EQR estimator with selected u_{τ} , and the line – marks the standard deviations of the standard QR estimator.

Now we compute the estimation standard deviation of the EQR estimator again, but use the selected u_{τ} instead of the true u_{τ} . This estimation standard



Figure 4. Comparison of the EQR estimators and the standard QR estimator with $\tau = 0.9$. The line — marks the standard deviations of the EQR estimator with true u_{τ} , the line — with * marks the standard deviations of the EQR estimator with selected u_{τ} , and the line — marks the standard deviations of the standard QR estimator.

deviation includes the variability in model selection and the variability of the EQR estimator, given the selected u_{τ} . The results are included in Figures 3 and 4. For ease of comparison, we also include lines for the EQR estimators with u_{τ} fixed at the true value. At sample size n = 50, the EQR estimator with selected u_{τ} reduces the estimation standard deviation of the QR estimator by 51.7% to 59.3% for $\tau = 0.5$, and by 63.9% to 72.6% for $\tau = 0.9$. Compared with the results with true u_{τ} , the EQR estimator loses some efficiency gains due to the variability in the selection, but the EQR estimator is still more efficient than the standard QR estimator. We also include the MSEs for the EQR and standard QR estimators in Figures 5 and 6. With n = 50, the EQR estimator with true u_{τ} reduces the MSE by 81.2% to 88.0% for $\tau = 0.5$, and by 91.7% to 94.0% for $\tau = 0.9$. The EQR estimator with selected u_{τ} reduces the MSE by 75.9% to 83.2% for $\tau = 0.5$, and by 87.1% to 92.1% for $\tau = 0.9$. The reduction in the MSE is due mainly to the efficiency gains. In this simulation, RCV always overestimates u_{τ} , which loses some efficiency, but does not bring in bias. In fact, the squared bias of the EQR estimator is about the same as that of the QR estimator (see the results in Section D.3 of the Supplementary Material).

We further examine the EQR model using the baseball salary data (Watnik (1998)). The data contain salaries for 337 non-pitchers for the 1992 Major League Baseball season. The histogram of the salaries is right-skewed, which means that some of the players have much higher salaries than the others do. The data set also includes 12 measures of the players' performance in the previous year, including batting average, on-base percentage, number of runs, hits, doubles, triples, home runs, batted in, walks, strike-outs, stolen bases, and errors. Each

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Figure 5. Comparison of the EQR estimators and the standard QR estimator with $\tau = 0.5$. The line — marks the MSE of the EQR estimator with true u_{τ} , the line — with * marks the MSE of the EQR estimator with selected u_{τ} , and the line – marks the MSE of the standard QR estimator.



Figure 6. Comparison of the EQR estimators and the standard QR estimator with $\tau = 0.9$. The line — marks the MSE of the EQR estimator with true u_{τ} , the line — with * marks the MSE of the EQR estimator with selected u_{τ} , and the line – marks the MSE of the standard QR estimator.

predictor is scaled to have standard deviation one. We fit the EQR model to the data. RCV suggested $u_{\tau} = 4$ for $\tau = 0.5$. Across all elements in β_{τ} , the ratios of the bootstrap standard deviations of the standard QR estimator to those of the EQR estimator range from 0.99 to 6.78, with an average of 2.90. For $\tau = 0.9$, $u_{\tau} = 2$ was selected using RCV. The ratios of the bootstrap standard deviations range from 1.88 to 29.48, with an average of 8.30. To obtain an efficient estimator whose estimation standard deviation is 1/8.3 of the original standard deviation under the standard QR, we need to increase the sample to $8.30^2 \approx 70$ times the

original sample size. The efficiency gain of the EQR model is massive in this example.

6. Partial EQR Model

The partial EQR model is motived by applications in which some predictors are categorical. For example, in medical studies, gender and race are often measured as covariates, along with continuous variables, such as gene expression intensities, to study causes of a certain disease. If categorical predictors are present, the EQR model cannot be applied directly. To resolve this issue, we propose enveloping the continuous predictors, and leaving the categorical predictors intact. In this way, the coefficients of the continuous variables can be estimated more efficiently, and the coefficients of the categorical variables are estimated with about the same efficiency as that of the QR model. Specifically, let $\mathbf{X} = (\mathbf{X}_1^T, \mathbf{X}_2^T)^T$, where $\mathbf{X}_1 \in \mathbb{R}^{p_1}$ contains the continuous predictors, and $\mathbf{X}_2 \in \mathbb{R}^{p_2}$ contains the categorical predictors, $p_1 + p_2 = p$. Then the QR model (2.1) can be written as

$$Q_Y(\tau \mid \mathbf{X}) = \mu_\tau + \boldsymbol{\beta}_{1,\tau}^T \mathbf{X}_1 + \boldsymbol{\beta}_{2,\tau}^T \mathbf{X}_2, \qquad (6.1)$$

where $\beta_{1,\tau} \in \mathbb{R}^{p_1}$ is the coefficient vector of \mathbf{X}_1 , and $\beta_{2,\tau} \in \mathbb{R}^{p_2}$ is the coefficient vector of \mathbf{X}_2 . Let $\boldsymbol{\mu}_{\mathbf{X}_1}$ and $\boldsymbol{\Sigma}_{\mathbf{X}_1}$ denote the mean and covariance matrix of \mathbf{X}_1 . Given the presence of \mathbf{X}_2 , suppose \mathcal{S}_{τ} is a subspace of \mathbb{R}^{p_1} that satisfies the following two conditions:

i)
$$Q_Y(\tau \mid \mathbf{X}) = Q_Y(\tau \mid \mathbf{P}_{\mathcal{S}_{\tau}}\mathbf{X}_1, \mathbf{X}_2)$$
 and ii) $\operatorname{Cov}(\mathbf{P}_{\mathcal{S}_{\tau}}\mathbf{X}_1, \mathbf{Q}_{\mathcal{S}_{\tau}}\mathbf{X}_1) = 0.$ (6.2)

Then it can shown that S_{τ} is a reducing subspace of $\Sigma_{\mathbf{X}_1}$ that contains $\boldsymbol{\beta}_{1,\tau}$. The intersection of all such S_{τ} is called the partial $\Sigma_{\mathbf{X}_1}$ -envelope of $\boldsymbol{\beta}_{1,\tau}$, denoted by $\mathcal{E}_{\Sigma_{\mathbf{X}_1}}(\boldsymbol{\beta}_{1,\tau})$, or $\mathcal{E}_{1,\tau}$ for short. We denote the dimension of $\mathcal{E}_{\Sigma_{\mathbf{X}_1}}(\boldsymbol{\beta}_{1,\tau})$ as d_{τ} $(d_{\tau} \leq p_1)$. Since we only consider the envelope on $\boldsymbol{\beta}_{1,\tau}$, $\boldsymbol{\beta}_{2,\tau}$ remains intact. We call (6.1) a partial envelope quantile regression (PEQR) model if the conditions in (6.2) are incorporated. Let $\Psi_{\tau} \in \mathbb{R}^{p_1 \times d_{\tau}}$ be an orthonormal basis of $\mathcal{E}_{\Sigma_{\mathbf{X}_1}}(\boldsymbol{\beta}_{1,\tau})$, and $\Psi_{0,\tau} \in \mathbb{R}^{p_1 \times (p_1 - d_{\tau})}$ be a completion of Ψ_{τ} . Then the coordinate form of the PEQR model is

$$Q_Y(\tau | \mathbf{X}) = \mu_\tau + \boldsymbol{\eta}_\tau^T \boldsymbol{\Psi}_\tau^T \mathbf{X}_1 + \boldsymbol{\beta}_{2,\tau}^T \mathbf{X}_2$$

$$\Sigma_{\mathbf{X}_1} = \boldsymbol{\Psi}_\tau \Omega_\tau \boldsymbol{\Psi}_\tau^T + \boldsymbol{\Psi}_{0\tau} \Omega_{0\tau} \boldsymbol{\Psi}_{0\tau}^T, \qquad (6.3)$$

where $\beta_{1,\tau} = \Psi_{\tau} \eta_{\tau}, \eta_{\tau} \in \mathbb{R}^{d_{\tau}}$ carries the coordinates of $\beta_{1,\tau}$ with respect to Ψ_{τ} ,

and $\Omega_{\tau} \in \mathbb{R}^{d_{\tau} \times d_{\tau}}$ and $\Omega_{0,\tau} \in \mathbb{R}^{(p_1-d_{\tau}) \times (p_1-d_{\tau})}$ carry the coordinates of $\Sigma_{\mathbf{X}_1}$ with respect to Ψ_{τ} and $\Psi_{0\tau}$, respectively. Let $s_1 = p_1(p_1+1)/2$. Then the number of parameters in this model is $1 + p_2 + d_{\tau} + s_1$, reduced from $1 + p_1 + p_2 + s_1$ without enveloping, and the parameter vector is

$$\boldsymbol{\zeta}_{1,\tau} = (\mu_{\tau}, \operatorname{vec}(\boldsymbol{\eta}_{\tau})^T, \operatorname{vec}(\boldsymbol{\Psi}_{\tau})^T, \boldsymbol{\beta}_{2,\tau}^T, \operatorname{vech}(\Omega_{\tau})^T, \operatorname{vech}(\Omega_{0,\tau})^T)^T.$$

The estimation of the parameters in PEQR is similar to that in EQR. We adopt the reparametrization in (4.1). Let $\Psi_{\tau,1}$ be the matrix that contains the first d_{τ} rows in Ψ_{τ} , and let $\Psi_{\tau,2}$ be the matrix that contains the remaining rows in Ψ_{τ} . Without loss of generality, we assume that $\Psi_{\tau,1}$ is nonsingular. Let $\Psi_{\tau}^* = \Psi_{\tau}\Psi_{\tau,1}^{-1}$, $\eta_{\tau}^* = \Psi_{\tau,1}\eta_{\tau}$, and $\Omega_{\tau}^* = \Psi_{\tau,1}\Omega_{\tau}\Psi_{\tau,1}^T$. Then $\Psi_{\tau}^* = (\mathbf{I}_{d_{\tau}}, \mathbf{A}_1^T)^T$, where $\mathbf{A}_1 = \Psi_{\tau,2}\Psi_{\tau,1}^{-1}$. We write $\mathbf{X}_i = (\mathbf{X}_{1,i}^T, \mathbf{X}_{2,i}^T)^T$ and $\mathbf{W}_i = (1, \mathbf{X}_i^T)^T$, for $i = 1, \ldots, n$. Under the PEQR model, define

$$h_{n}^{*}(\boldsymbol{\zeta}_{1,\tau}^{*}) = \begin{pmatrix} \frac{1}{n} \sum_{i=1}^{n} \mathbf{W}_{i} \{ I[Y_{i} < \mu_{\tau} + (\boldsymbol{\Psi}_{\tau}^{*} \boldsymbol{\eta}_{\tau}^{*})^{T} \mathbf{X}_{1,i} + \boldsymbol{\beta}_{2,\tau}^{T} \mathbf{X}_{2,i}] - \tau \} \\ \frac{1}{n} \sum_{i=1}^{n} \{ \operatorname{vech}(\boldsymbol{\Psi}_{\tau}^{*} \Omega_{\tau}^{*} \boldsymbol{\Psi}_{\tau}^{*T} + \boldsymbol{\Psi}_{0\tau} \Omega_{0\tau} \boldsymbol{\Psi}_{0\tau}^{T}) - \operatorname{vech}[(\mathbf{X}_{1,i} - \boldsymbol{\mu}_{\mathbf{X}_{1}})(\mathbf{X}_{1,i} - \boldsymbol{\mu}_{\mathbf{X}_{1}})^{T}] \} \\ \frac{1}{n} \sum_{i=1}^{n} (\boldsymbol{\mu}_{\mathbf{X}_{1}} - \mathbf{X}_{1,i}) \end{cases}$$

$$\equiv \frac{1}{n} \sum_{i=1}^{n} g_{n}^{*}(\boldsymbol{\zeta}_{1,\tau}^{*}),$$

$$(6.4)$$

where $\boldsymbol{\zeta}_{1,\tau}^* = (\mu_{\tau}, \operatorname{vec}(\boldsymbol{\eta}_{\tau}^*)^T, \operatorname{vec}(\mathbf{A}_1)^T, \boldsymbol{\beta}_{2,\tau}^T, \operatorname{vech}(\Omega_{\tau}^*)^T, \operatorname{vech}(\Omega_{0,\tau})^T, \boldsymbol{\mu}_{\mathbf{X}_1}^T)^T$. We follow the procedures in Section 4, and use a two-step algorithm to obtain the GMM estimator of $\boldsymbol{\zeta}_{1,\tau}^*$:

Step 1. Find the estimator $\zeta_{1,\tau}^*$ by minimizing $h_n^*(\zeta_{1,\tau}^*)^T h_n^*(\zeta_{1,\tau}^*)$; denote this as $\tilde{\zeta}_{1,\tau}^*$.

Step 2. Estimate the optimal weight matrix as

$$\widehat{\boldsymbol{\Delta}}^{-1} = \left[\frac{1}{n}\sum_{i=1}^{n}g_n^*(\widetilde{\boldsymbol{\zeta}}_{1,\tau}^*)g_n^*(\widetilde{\boldsymbol{\zeta}}_{1,\tau}^*)^T\right]^{-1},$$

and obtain the GMM estimator $\widehat{\zeta}_{1,\tau}^*$ as the minimizer of the following quadratic form:

$$Q_n(\boldsymbol{\zeta}_{1,\tau}^*) = h_n^*(\boldsymbol{\zeta}_{1,\tau}^*)^T \widehat{\boldsymbol{\Delta}}^{-1} h_n^*(\boldsymbol{\zeta}_{1,\tau}^*).$$

Then the envelope GMM estimators of $\beta_{1,\tau}$ and $\Sigma_{\mathbf{X}_1}$ are $\widehat{\beta}_{1,\tau} = \widehat{\Psi}^*_{\tau} \widehat{\eta}^*_{\tau}$ and

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$$\widehat{\Sigma}_{\mathbf{X}_1} = \widehat{\boldsymbol{\Psi}}_{\tau}^* \widehat{\Omega}_{\tau}^* \widehat{\boldsymbol{\Psi}^*}_{\tau}^T + \widehat{\boldsymbol{\Psi}}_{0\tau} \widehat{\Omega}_{0\tau} \widehat{\boldsymbol{\Psi}}_{0\tau}^T, \text{ respectively.}$$

The selection of the dimension for $\mathcal{E}_{\Sigma_{\mathbf{x}_1}}(\boldsymbol{\beta}_{1,\tau})$ can be performed by RCV.

The asymptotic variance of the envelope GMM estimator can be derived similarly as in Theorem 2. As $\boldsymbol{\beta}_{\tau} = (\boldsymbol{\beta}_{1,\tau}^T, \boldsymbol{\beta}_{2,\tau}^T)^T$, $\boldsymbol{\theta}^*$ in the PEQR setting is $\boldsymbol{\theta}^* = (\mu_{\tau}, \boldsymbol{\beta}_{1,\tau}^T, \boldsymbol{\beta}_{2,\tau}^T, \operatorname{vech}(\Sigma_{\mathbf{X}_1})^T)^T$. Let $\hat{\boldsymbol{\theta}}_{pe}^*$ denote the PEQR estimator of $\boldsymbol{\theta}^*$, and let $\tilde{\boldsymbol{\theta}}^*$ denote the standard estimator of $\boldsymbol{\theta}^*$ by directly solving the estimating equations without enveloping. Let $\boldsymbol{\theta}_0^*$ be the true value of $\boldsymbol{\theta}^*$. As discussed in the EQR model, we ignore $\boldsymbol{\mu}_{\mathbf{X}_1}$, with no loss of generality.

Theorem 3. Under the same conditions as in Theorem 2, (1) $\sqrt{n}(\widehat{\theta}_{pe}^* - \theta_0^*)$ converges in distribution to a normal distribution with mean zero and covariance matrix $\operatorname{avar}(\sqrt{n}\widehat{\theta}_{pe}^*) = \mathbf{G}(\mathbf{G}^T\mathbf{U}_{pe}\mathbf{V}_{pe}^{-1}\mathbf{U}_{pe}\mathbf{G})^{\dagger}\mathbf{G}^T$, where $\mathbf{G} = \partial \theta^* / \partial \zeta_{1,\tau}^T$ is the gradient matrix of θ^* relative to $\zeta_{1,\tau}$,

$$\mathbf{U}_{pe} = \begin{pmatrix} \mathbf{E}_{\boldsymbol{\theta}_0}[f_{Y|\mathbf{X}}(\xi_0(\tau|\mathbf{X}))\mathbf{W}\mathbf{W}^T] & 0\\ 0 & \mathbf{I}_{s_1} \end{pmatrix}$$

and

$$\mathbf{V}_{pe} = \begin{pmatrix} \tau(1-\tau) \mathbf{E}_{\boldsymbol{\theta}_0}[\mathbf{W}\mathbf{W}^T] & 0\\ 0 & \operatorname{var}_{\boldsymbol{\theta}_0}\{\operatorname{vech}[(\mathbf{X}_1 - \boldsymbol{\mu}_{\mathbf{X}_1,0})(\mathbf{X}_1 - \boldsymbol{\mu}_{\mathbf{X}_1,0})^T]\} \end{pmatrix},$$

with $\mu_{\mathbf{X}_1,0}$ being the true value of $\mu_{\mathbf{X}_1}$.

(2) In addition,
$$\operatorname{avar}(\sqrt{n}\boldsymbol{\theta}_{ne}^*) \leq \operatorname{avar}(\sqrt{n}\boldsymbol{\theta}^*)$$
.

Theorem 3 suggests that the PEQR improves the estimation efficiency of $\beta_{1,\tau}$, but without sacrificing the estimation efficiency of $\beta_{2,\tau}$. The proof of Theorem 3 is briefly described in Section C of the Supplementary Material.

Next we demonstrate the performance of the PEQR using a simulation and an example. To save space, we present the simulation setting and results in Section D.4 of the Supplementary Material, where the PEQR demonstrates efficiency gains in estimating the parameters compared with that of the standard QR. We present the real data analysis below.

We applied the PEQR model to Boston housing data (Harrison and Rubinfeld (1978)). The data contain housing values and 13 attributes for 506 owneroccupied homes in suburbs of Boston. The 13 attributes include one categorical variable: the Charles River dummy variable, which takes the value one if a tract bounds the river, and zero otherwise. The 12 continuous variables include crime rate, nitric oxides concentration, pupil-teacher ratio by town, and others. Each

continuous variable was scaled to have a sample standard deviation of one. We adopted the value of the homes as the response and the 13 attributes as predictors. As the distribution of the response is right-skewed, we fit the standard QR model and the PEQR model to the data. RCV suggested $d_{\tau} = 3$ for $\tau = 0.5$, and $d_{\tau} = 2$ for $\tau = 0.9$. We computed the bootstrap standard deviation from the standard QR model and the PEQR model for each element in β_{τ} , and took the ratio. The ratios ranged from 0.88 to 3.44 with an average of 2.12 for $\tau = 0.5$, and ranged from 0.83 to 5.50 with an average of 3.57 for $\tau = 0.9$. The PEQR model demonstrates efficiency gains in this example.

7. Discussion

In this study, the EQR approach, along with its variant the PEQR, is developed to reduce estimation variation and improve the efficiency of QRs. The new EQR method utilizes information on both the predictors and the response by connecting the covariance matrix $\Sigma_{\mathbf{X}}$ of \mathbf{X} to the parameter of interest β_{τ} for identifying material and immaterial information in estimating β_{τ} , while synchronously excluding immaterial information from the estimation. As a result of this simultaneous dimension reduction and regression fitting, the proposed method can lead to gains in efficiency. It also advances the recent development of envelopes to general distribution-free procedures with possibly nonsmooth objective functions, and offers new technical tools for the justification of asymptotic efficiency. The idea of the EQR can be naturally extended to other quantile regression settings, such as censored quantile regression and partially linear quantile regression, for survival and other complex data analyses. On the other hand, since $\Sigma_{\mathbf{X}}$ is incorporated in the estimation procedure, the number of parameters in EQR can be large when the number of predictors increases. Hence a direct application of EQR to high dimensional settings is difficult. To overcome this problem, a penalized EQR model can be considered by imposing sparsity on the parameters β_{τ} , $\Sigma_{\mathbf{X}}$, and the weighted matrix $\boldsymbol{\Delta}$ in the GMM estimation, inspired by Su et al. (2016) and Qian, Ding and Cook (2018). The theoretical properties of the associated estimators require further investigation. We leave the penalized EQR model as a potentially interesting future research project.

Supplementary Material

The online Supplementary Material contains proofs, technical details, and additional simulations.

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