# REGULARIZED PROJECTION SCORE ESTIMATION OF TREATMENT EFFECTS IN HIGH-DIMENSIONAL QUANTILE REGRESSION

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Abstract: We propose a regularized projection score method for estimating the treatment effects in a quantile regression in the presence of high-dimensional confounding covariates. We show that the proposed estimator of the treatment effects is consistent and asymptotically normal, with a root-*n* rate of convergence. We also provide an efficient algorithm for the proposed estimator. This algorithm can be implemented easily using existing software. Furthermore, we propose and validate a refitted wild bootstrapping approach for variance estimation. This enables us to construct confidence intervals for the treatment effects in high-dimensional settings. Simulation studies are carried out to evaluate the finite-sample performance of the proposed estimator. A GDP growth rate data set is used to demonstrate an application of the method.

*Key words and phrases:* Efficiency score, high dimension, quantile regression, wild bootstrap.

# 1. Introduction

A quantile regression (Koenker and Bassett (1978)) is an important tool for analyzing the relationship between a response variable and a set of covariates. It has a wide range of applications in the analysis of non-Gaussian data, which arise frequently in applied economic research. Unlike a least squares regression, which models the conditional mean of a response given the covariates, a quantile regression focuses on the conditional quantiles. Thus, it is able to describe the conditional distribution of the response, given the covariates. There is an extensive body of literature on the theoretical properties and computational algorithms for a quantile regression when the number of regressors is fixed or increases at a lower rate than the sample size; see, for example, Koenker (2005) and the references therein. In this study, we estimate low-dimensional treatment effects in the presence of a high-dimensional nuisance parameter vector.

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There is now a substantial body of work on penalized methods for variable selection in high-dimensional models. Several important penalty functions have been introduced, including the least absolute shrinkage and selection operator (Lasso) or  $\ell_1$  penalty (Tibshirani (1996)), smoothly clipped absolute deviation (SCAD) penalty (Fan and Li (2001)), and minimax concave penalty (MCP) (Zhang (2010)). A common feature of these penalties is that they are capable of producing exact zero solutions, which automatically leads to variable selection. The penalized methods also have many attractive theoretical properties related to selection, estimation, and prediction in a sparse setting  $(p \gg n)$ , including the asymptotic oracle property under certain conditions. However, these methods provide no computable error assessment of the selection results in finite-sample situations. The literature on this topic has grown too vast to be adequately summarized here. Therefore, for results on convex selection, see Bühlmann and van de Geer (2011), and the references therein, and for concave selection, see Fan and Li (2001), Zhang (2010), and Zhang and Zhang (2012).

Recently, many authors have studied the problem of statistical inference for low-dimensional parameters in high-dimensional regression models. Zhang and Zhang (2014) proposed a semiparametric efficient score approach for constructing confidence intervals of low-dimensional coefficients in high-dimensional linear models. Van de Geer et al. (2014) considered the same problem using an approach that inverts the optimization conditions for the Lasso solution, extending the work of Zhang and Zhang (2014) to include generalized linear models and problems with convex loss functions. Javanmard and Montanari (2014) considered the problem of hypothesis testing in a high-dimensional regression using a method similar to that of Zhang and Zhang (2014). Fang, Ning and Liu (2016) studied hypothesis testing and confidence intervals in high-dimensional proportional hazards models. Nevkov et al. (2018) proposed a unified theory of confidence regions and testing for high-dimensional estimating equations. Ning and Liu (2017) proposed a decorrelated score approach for hypothesis tests and confidence regions in sparse high-dimensional models. Zhu and Bradic (2018) proposed an approach for testing linear hypotheses in high-dimensional linear models without assumptions on the model sparsity or the loading vector representing the hypothesis. For other related works that use the regularized score method, refer to Belloni, Chernozhukov and Wei (2013), Dezeure et al. (2015), Lockhart et al. (2014), Meinshausen (2014), Meinshausen, Meier and Bühlmann (2009), Ning and Liu (2017), Stucky and van de Geer (2018), and Yang (2017).

Belloni et al. (2012) proposed a two-stage selection procedure with postdouble selection to estimate a single treatment effect parameter in a high-dimensional linear model. Tibshirani et al. (2016) considered the statistical inference for a forward stepwise and least angle regression in high-dimensional models after selection. Recently, various researchers have considered post-selection in the presence of high-dimensional parameters, including Berk, Brown and Zhao (2009); Berk et al. (2013), Lee et al. (2016), Lee and Taylor (2014), Rügamer and Greven (2018), and Tibshirani et al. (2016).

Belloni and Chernozhukov (2011) studied the  $\ell_1$ -penalized quantile regression under a high-dimensional setting and established a near-oracle property of the estimator. Wang, Wu and Li (2012) showed that the oracle property still holds when SCAD and MCP penalties are used. Zhao, Kolar and Liu (2014) provided a globally penalized framework for high-dimensional quantile regression models by employing adaptive  $\ell_1$  penalties; this approach achieved consistent shrinkage of the regression quantile estimates across a continuous range of quantile levels. Belloni, Chernozhukov and Kato (2018) considered the robust inference of the regression coefficients of high-dimensional quantile regression models using an optimal instrument that is a residual from a density-weighted projection of the regressor of interest on other regressors. Zheng, Peng and He (2015) proposed a robust and uniformly honest inference in a high-dimensional quantile regression using a debiased composite quantile estimator.

Inspired by the work of Zhang and Zhang (2014) and Ning and Liu (2017), we consider the estimation of a preconceived low-dimensional parameter based on a projected score approach, and study its statistical inference under linear quantile regression models. In particular, our proposed approach is similar to the decorrelated score method of Ning and Liu (2017). In essence, these approaches extend the efficient score method for dealing with infinite-dimensional nuisance parameters in semiparametric models (Bickel et al. (1998)) to high-dimensional settings. However, the decorrelated score method assumes a smooth loss function with second derivatives, which is not satisfied in the context of a quantile regression.

The rest of the paper is organized as follows. Section 2 describes the estimation method based on regularized projection scores. The asymptotic properties of the estimates of the preconceived parameters are obtained in Section 3. We then propose a resampling approach based on cross-validation and confirm its validity in Section 4. An efficient computation algorithm is given in Section 5. Based on this algorithm, we propose a one-step estimator in Section 6. Numerical studies are used to assess the finite-sample performance of the proposed method in Section 7. All proofs are given in the online Supplementary Material. An R package implementing the proposed method is available at https://github.com/xliusufe/pqr.

## 2. Regularized Projection Score Estimation

Suppose we have observations  $\{(y_i, x_i, z_i), i = 1, ..., n\}$  that are independent and identically distributed as (y, x, z), where  $y \in \mathbb{R}$  is a response variable,  $x \in \mathbb{R}^d$ is a *d*-dimensional vector containing the covariates of main interest, and  $z \in \mathbb{R}^q$ is a *q*-dimensional covariate with possibly confounding variables. Consider the linear quantile regression model

$$Q_{\tau}(y_i|x_i, z_i) = x_i'\beta_0 + z_i'\eta_0, \qquad (2.1)$$

where  $Q_{\tau}(\cdot|x_i, z_i)$  refers to the conditional  $\tau$ th quantile, given the covariate  $(x_i, z_i)$ . Here, for notional simplicity, we assume that an intercept term is included in  $\beta_0$ . We would like to estimate the effect of the covariate vector x, represented by  $\beta_0$ , on the response variable, while taking into account the effect of the covariate z, represented by  $\eta_0$ . We are interested in the case where d is small (fixed), but qis large, and may be far larger than the sample size n.

In the standard linear quantile regression, the parameters of model (2.1) are estimated by minimizing

$$M_n(\beta, \eta) = n^{-1} \sum_{i=1}^n \rho_\tau(y_i - x'_i \beta - z'_i \eta)$$

with respect to  $\beta$  and  $\eta$ , where  $\rho_{\tau}(u) = u\{\tau - I(u < 0)\}$ . This approach works well in low-dimensional cases where both d and q are fixed and smaller than n. However, in the case where  $q \gg n$ , it no longer works, owing to the singularity of the design matrix. There has been much work on penalized methods for estimating the parameter vector  $(\beta_0, \eta_0)$ . An important method is the Lasso estimator (Tibshirani (1996)),

$$(\hat{\beta}_{lasso}, \hat{\eta}_{lasso}) = \operatorname*{argmin}_{\beta, \eta} M_n(\beta, \eta) + \lambda(\|\beta\|_1 + \|\eta\|_1).$$

This provides a point estimate of  $(\beta_0, \eta_0)$ , denoted by  $(\hat{\beta}, \hat{\eta})$ . Owing to the shrinkage effect of the  $\ell_1$  penalty,  $\hat{\beta}_{lasso}$  does not converge at the usual root-*n* rate, and its asymptotic distributional property is unknown. The penalized estimate  $\hat{\beta}_{lasso}$ cannot be used directly to make statistical inferences about  $\beta_0$ , the main parameter of interest.

To reduce the shrinkage effect of the penalization of the estimation of  $\beta_0$ , we

consider the semi-penalized estimator,

$$(\tilde{\beta}, \tilde{\eta}) = \operatorname*{argmin}_{\beta, \eta} \frac{1}{n} \sum_{i=1}^{n} \rho_{\tau} (y_i - x'_i \beta - z'_i \eta) + \lambda_1 \|\eta\|_1.$$
(2.2)

Note that here  $\beta$  is not penalized. Intuitively, the estimator  $\tilde{\beta}$  should be less biased than  $\hat{\beta}_{lasso}$ , because it is not subject to penalization. However, because  $x_i$  and  $z_i$  are correlated, the bias in  $\tilde{\eta}$  will still lead to bias in  $\tilde{\beta}$ . This can be observed more clearly by considering the score equations corresponding to (2.2):

$$\frac{1}{n}\sum_{i=1}^{n}\psi_{\tau}(y_{i}-x_{i}^{\prime}\beta-z_{i}^{\prime}\eta)x_{i}=0,$$
(2.3)

$$\frac{1}{n}\sum_{i=1}^{n}\psi_{\tau}(y_{i}-x_{i}'\beta-z_{i}'\eta)z_{i} = \lambda_{1}\partial(\|\eta\|_{1}), \qquad (2.4)$$

where  $\psi_{\tau}(u) = \tau - I(u < 0)$  is the directional derivative of  $\rho_{\tau}(u)$ , and  $\partial(||\eta||_1) = (\partial(|\eta_1|), \ldots, \partial(|\eta_q|))'$ . Here,  $\partial(|\eta_j|)$  is the subdifferential of  $|\eta_j|$ ; that is,  $\partial(|\eta_j|) = 1$  if  $\eta_j > 0$ ,  $\partial(|\eta_j|) = -1$  if  $\eta_j < 0$ , and  $\partial(|\eta_j|) \in [-1, 1]$  if  $\eta_j = 0$ . The estimator  $(\tilde{\beta}', \tilde{\eta}')'$  approximately satisfies (2.3) and (2.4). Therefore,  $\tilde{\beta}$  is a solution to

$$\frac{1}{n}\sum_{i=1}^{n}\psi_{\tau}(y_i-x_i'\beta-z_i'\tilde{\eta})x_i=0.$$

However, owing to the bias in the estimator  $\tilde{\eta}$  and the correlation between  $x_i$  and  $z_i$ , the estimator  $\tilde{\beta}$  does not have a root-*n* rate of convergence.

To obtain an estimator of  $\beta_0$  with a root-*n* rate of convergence and an asymptotically normal distribution, we propose a regularized projection score approach. To describe this approach, we first consider the projection score function for  $\beta$  based on the loss function  $\rho_{\tau}$  at the population level. The projection score is defined as the residual of the projection of the score function  $\psi_{\tau}(y - x'\beta - z'\eta)x$  for  $\beta$  onto the closure of the linear span of the score function  $\psi_{\tau}(y - x'\beta - z'\eta)z$  for the nuisance parameter  $\eta$  in the Hilbert space  $L_2(P)$ , where P is the distribution of (y, x, z) under model (2.1). That is, we need to find a matrix  $H_0 \in \mathbb{R}^{d \times q}$  that minimizes

$$\mathbb{E}\|\psi_{\tau}(y - x'\beta_0 - z'\eta_0)x - \psi_{\tau}(y - x'\beta_0 - z'\eta_0)Hz\|^2 = \mathbb{E}\{\psi_{\tau}^2(\varepsilon)\|x - Hz\|^2\}$$
(2.5)

with respect to  $H \in \mathbb{R}^{d \times q}$ , where  $\varepsilon = y - x'\beta_0 - z'\eta_0$ . Here,  $\|\cdot\|$  denotes the

Euclidean norm. Then, the projection score function for  $\beta$  in the direction  $H_0$  is

$$\psi_{\tau}(y - x'\beta - z'\eta)x - \psi_{\tau}(y - x'\beta - z'\eta)H_0z = \psi_{\tau}(y - x'\beta - z'\eta)(x - H_0z).$$
(2.6)

In general, (2.5) is a weighted least squares function. Under the quantile regression model given in (2.1), it can be simplified considerably. By the law of iterated expectations, we have

$$E\{\psi_{\tau}^{2}(\varepsilon)\|x - Hz\|^{2}\} = E\{E[\psi_{\tau}^{2}(\varepsilon)|x, z]\|x - Hz\|^{2}\}$$
  
=  $\tau(1 - \tau)E\|x - Hz\|^{2},$  (2.7)

where the last equation follows from (2.1). Thus, minimizing (2.5) is equivalent to minimizing (2.7). Because  $\tau$  is independent of H, we have

$$H_0 = \operatorname*{argmin}_{H \in \mathbb{R}^{d \times q}} \mathbb{E} \|x - Hz\|^2.$$

This is a least squares problem that can be solved explicitly. In particular,  $H_0$  satisfies the normal equation  $E\{(x - Hz)z'\} = 0$ , which yields

$$H_0 = \mathrm{E}(xz') \{ \mathrm{E}(zz') \}^{-1}.$$

However, the sample version of E(zz'), which is given by  $n^{-1} \sum_{i=1}^{n} z_i z'_i$ , is not invertible if q > n. Therefore, we cannot estimate  $H_0$  by simply using the sample versions of E(xz') and E(zz'). We need to regularize the projection calculation. We can use either the standard Lasso or the group Lasso for the multi-response linear regression (Obozinski, Wainwright and Jordan (2011); Wang, Liang and Xing (2013)) estimation of the matrix  $H_0$ . For any  $H \in \mathbb{R}^{d \times q}$ , denote its *j*th column by  $h_j$ . We estimate  $H_0$  by

$$\tilde{H} = \underset{H \in \mathbb{R}^{d \times q}}{\operatorname{argmin}} \frac{1}{2n} \sum_{i=1}^{n} \|x_i - Hz_i\|^2 + \lambda_2 \sum_{j=1}^{d} \sum_{k=1}^{q} |h_{jk}|$$
(2.8)

or

$$\tilde{H} = \operatorname*{argmin}_{H \in \mathbb{R}^{d \times q}} \frac{1}{2n} \sum_{i=1}^{n} \|x_i - Hz_i\|^2 + \lambda_2 \sum_{j=1}^{q} \|h_j\|.$$
(2.9)

Note that Zhang and Zhang (2014) and van de Geer et al. (2014) use the standard Lasso to calculate the approximate projection.

By the KKT conditions, we obtain

$$\left\|\frac{1}{n}\sum_{i=1}^{n}(x_i-\tilde{H}z_i)z_{ij}\right\| \le \lambda_2, 1\le j\le q.$$

This implies that the vectors  $z_i$  and  $x_i - Hz_i$  are nearly orthogonal for a small  $\lambda_2$ . Furthermore, Lemma 1 of the Supplementary Material states that we need a sparsity assumption on  $H_0$  in the sense that  $\lambda_2 \sum_{j=1}^{q} ||h_{0j}||$  is small, where  $h_{0j}$  is the *j*th column of  $H_0$ . The orthogonality property is important in establishing the theoretical properties of the proposed estimator described below.

We are now ready to describe the proposed regularized projection score estimator. Define the score function in the direction H as

$$\Psi_n(\beta,\eta)[H] \equiv \frac{1}{n} \sum_{i=1}^n \psi_\tau(y_i - x'_i\beta - z'_i\eta)(x_i - Hz_i).$$
(2.10)

Because the parameter  $\eta$  is unknown, we replace it with the initial estimator  $\tilde{\eta}$  given in (2.2). We also estimate H by  $\tilde{H}$ . We then define the regularized projection score function for  $\beta$  as

$$\tilde{\Psi}_n(\beta) \equiv \Psi_n(\beta, \tilde{\eta})[\tilde{H}] = \frac{1}{n} \sum_{i=1}^n \psi_\tau(y_i - x_i'\beta - z_i'\tilde{\eta})(x_i - \tilde{H}z_i).$$
(2.11)

Thus, we estimate the parameter  $\beta_0$  based on the following estimating equation:

$$\tilde{\Psi}_n(\beta) = 0. \tag{2.12}$$

Owing to the nonsmoothness of  $\psi_{\tau}$ ,  $\tilde{\Psi}_n$  may not have an exact zero root. In that case, we need only to solve (2.12) within  $o_p(n^{-1/2})$  precision. In Section 5, we consider a series of minimization problems that corresponds to solving (2.12) in an iterative way.

We summarize the proposed regularized projection score approach in two steps:

- (S1) estimate the vector  $\eta_0$  and the matrix  $H_0$  by solving (2.2) and (2.9), respectively;
- (S2) estimate the parameter vector  $\beta_0$  by solving the estimation equation (2.12).

## 3. Asymptotic Properties

In this section, we establish the asymptotic results for  $\hat{\beta}$ , where  $\hat{\beta}$  is a solution of (2.12). The asymptotic results of the Lasso estimate  $\tilde{\eta}$  and the block Lasso estimate  $\tilde{H}$  are given by Belloni and Chernozhukov (2011), Obozinski, Wainwright and Jordan (2011), and Wang, Liang and Xing (2013). To simplify the presentation, we summarize their regularity conditions below; moreover, we need to make some additional assumptions.

- (A1) z follows  $N(0, \Sigma_z)$ , and the covariance  $\Sigma$  satisfies  $(x', z')' \ 0 < c_\Lambda < \Lambda_{\min}(\Sigma)$  $< \Lambda_{\max}(\Sigma) < C_\Lambda < \infty$ .  $\|\beta_0\| + \|\eta_0\| + \max_{1 \le j \le q} \|h_{0j}\| \le C_0$ , where  $C_0$  is a constant and  $h_{0j}$  is the *j*th column of  $H_0$ .
- (A2) The coefficient  $\eta_0$  is sparse with s = o(n), and  $\lambda_1 = O(\sqrt{\log(q)/n})$ , where  $S = \{j : \eta_{0j} \neq 0, j = 1, \dots, q\}$  and s = |S|.
- (A3) If the estimated coefficient matrix  $\tilde{H}$  is obtained from (2.8),  $H_0$  is sparse with  $s_{h,k} \leq s_h = o(1)$ , for  $1 \leq k \leq d$ , where  $S_{h,k} = \{j : h_{0kj} \neq 0, j = 1, \ldots, q\}$  and  $s_{h,k} = |S_{h,k}|$ . If  $\tilde{H}$  is obtained from (2.9),  $H_0$  is sparse with  $s_h = o(1)$ , where  $S_h = \{j : h_{0j} \neq 0, j = 1, \ldots, q\}$ ,  $s_h = |S_h|$ .  $s_h^2 \lor s^2 = o(\sqrt{n}/\log(q))$ , and  $\lambda_2 = O(\sqrt{\log(q)/n})$ . There exists a constant  $c_0 \in (0, 1]$ such that  $\|\Sigma_{S_h S_h}^{-1}\|_{\infty} \leq c_0$ , where  $\Sigma_{I_1 I_2}$  is the submatrix of  $\Sigma$  with row and column index sets  $I_1$  and  $I_2$ , respectively.
- (A4)  $|f(u|x,z) f(0|x,z)| \leq C|u|^{1/2}$  for some constant C uniformly on (x,z)in a neighborhood of zero. f(0|x,z) is uniformly bounded from above by  $f_{\max} < \infty$ , and from below by  $f_{\min} > 0$ , for all (x,z), where  $f(\cdot|x,z)$  is the density function of  $\varepsilon = y - x'\beta_0 - z'\eta_0$ .
- (A5)  $\max_{1 \le j \le q} \mathbb{E}\{\|(x H_0 z) z_j\|\} = O(1), \max_{1 \le j \le d} \mathbb{E}\{\|(x H_0 z) x_j\|\} = O(1),$ and  $\{E[\|z\|_{\infty}]^2\}^{1/2} \le \zeta_n$ , with  $(s \lor s_h)^{3/2} \zeta_n \lambda_2 = o(n^{1/2})$  and  $\tau_n(s \lor s_h) \log(\zeta_n s_h \lambda_2 \tau_n^{-1/2}) = o(1)$ , where  $\tau_n = (s \lor s_h)(\lambda_1 \lor \lambda_2)$ . For any  $w_i$  between  $x'_i(\hat{\beta} - \beta_0) + z'_i(\tilde{\eta} - \eta_0)$  and zero, and for any  $H \in \mathcal{U}_H$ ,

$$\max_{1 \le j \le q} \left\| n^{-1} \sum_{i=1}^{n} f(w_i | x_i, z_i) (x_i - Hz_i) z_{ij} \right\| = o_p(s^{-1} \{ \log(q) \}^{-1/2}),$$

where  $\mathcal{U}_H = \{ H \in \mathbb{R}^{d \times q} : n^{-1/2} \sum_{i=1}^n \| (H - H_0) z_i \| = O_p(s \log(q)/n) \}.$ 

(A6)  $E \{f(0|x, z)(x - H_0 z)x'\}$  is an invertible matrix.

Assumption (A1) imposes an eigenvalue restriction on the design matrix. Assumption (A2) is the mutual incoherence and self-incoherence condition that bounds the difference between the estimator  $\hat{H}$  and the true matrix  $H_0$  and the difference between the estimator  $\tilde{\eta}$  and the true parameter  $\eta_0$ . Under Assumptions (A1) and (A2), the conditions of Belloni and Chernozhukov (2011), Obozinski, Wainwright and Jordan (2011), and Wang, Liang and Xing (2013) are satisfied. Assumption (A3) limits the increasing rate of the covariate dimension relative to the sample size to ensure that the Bahadur representation of the estimator  $\hat{\beta}$  holds. Assumption (A4) is used to obtain  $\hat{\beta}$ , which is widely used in the quantile regression literature. Assumption (A5) imposes the orthogonality of  $x - \hat{H}z$  and z, where  $x - \hat{H}z$  is the projection of x to the space of z. Because  $E\{(x - H_0z)z_j\} = 0$ , from the definition of  $H_0$ , Assumption (A5) holds if  $(x - H_0z)z_j$  is weakly correlated with f(0|x, z), the conditional density around zero. Thus, it is weaker than the assumption of independence between (x, z) and  $\epsilon$ , which is imposed by Zhao, Kolar and Liu (2014) and Bradic and Kolar (2017). Similar conditions are used in Theorem 3.1 of van de Geer et al. (2014) when generalized linear models are considered.

**Theorem 1.** Under model (2.1), if Assumptions (A1)–(A4) hold,

$$\hat{\beta} \xrightarrow{p} \beta_0$$

**Theorem 2.** Under model (2.1), if Assumptions (A1)–(A6) hold,

$$n^{1/2}(\hat{\beta} - \beta_0) \xrightarrow{L} N(0, Q^{-1}DQ'^{-1}),$$

where  $Q = E\{f(0|x, z)(x - H_0z)x'\}$  and  $D = \tau(1 - \tau)E\{(x - H_0z)(x - H_0z)'\}$ .

Theorem 2 establishes that the proposed estimator is asymptotically normal. However, under the high-dimensional setting, it is challenging to estimate the asymptotic covariance matrix  $Q^{-1}DQ'^{-1}$ , in which the density of the error term is involved. In the following section, we propose a resampling method that avoids estimating the error density at zero.

#### 4. Refitted Wild Bootstrap

Adopting the ideas of the refitted cross-validation of Fan, Guo and Hao (2011) and the wild bootstrap of Feng, He and Hu (2011), we propose a refitted wild bootstrap method to estimate the asymptotic variance-covariance matrix of  $\hat{\beta}$ . This resampling method accounts for heterogeneous errors and can bypass the estimation of different densities of errors at zero. Unlike the method of Wang, Keilegom and Maidman (2018), which only considered a fixed number of covariates, the proposed refitted wild bootstrap method can deal with high-

dimensional confounding covariates with divergent dimension q.

We randomly split the original data set into two even parts and carry out the refitted wild bootstrapping using the following steps.

- (B1) Estimate the parameters using the method described in Section 2 and the first part of the data set, and denote the estimates as  $\tilde{\eta}_1$ .
- (B2) Use the second part of the data set to estimate the parameters using the regular quantile regression method based on the nonzero coefficient set determined by the vector  $\tilde{\eta}_1$ . Denote the estimate as  $(\hat{\beta}'_2, \tilde{\eta}'_2)$ , where the vector  $\tilde{\eta}_2$  includes those zero coefficients determined in Step (B1), for notation consistency.
- (B3) Independently generate weights  $\zeta_i$  satisfying the following conditions:
  - (B3.1) there are two positive constants  $c_1$  and  $c_2$  satisfying  $\sup\{\zeta \in \mathbb{G} : \zeta \leq 0\} = -c_1$  and  $\inf\{\zeta \in \mathbb{G} : \zeta \geq 0\} = c_2$ , where  $\mathbb{G}$  is the support of  $\zeta$ ;
  - (B3.2) the distribution G of  $\zeta$  satisfies  $\int_0^{+\infty} \zeta^{-1} g(\omega) d\zeta = -\int_{-\infty}^0 \zeta^{-1} g(\zeta) d\zeta$ = 1/2 and  $E_{\zeta}[|\zeta|] < \infty$ , where  $g(\zeta)$  is the density of  $\zeta$  and the expectation  $E_{\zeta}$  is taken under G;
  - (B3.3) the  $\tau$ th quantile of the weight  $\zeta$  is zero.
- (B4) Use the second part of the data set to obtain the bootstrapped samples as  $y_i^* = \hat{\beta}_2' x_i + \tilde{\eta}_2' z_i + \zeta_i |\hat{r}_i|$ , where  $\hat{r}_i = y_i \hat{\beta}_2' x_i \tilde{\eta}_2' z_i$ .
- (B5) Use the bootstrapped samples to estimate the parameters using the method of Section 2, and denote the estimate of  $\beta_0$  by  $\hat{\beta}^*$ .
- (B6) Repeat (B2)–(B5) *B* times, and denote the sample variance of *B* copies of  $\hat{\beta}^*$  as  $\hat{V}_2$ .

Similarly, we use the second part of the data set to determine those variables with nonzero coefficients, and use the first part to estimate the variance-covariance matrix using the approach described in (B1)–(B6). Denote the estimated matrix as  $\hat{V}_1$ . We use  $(\hat{V}_1 + \hat{V}_2)/2$  to estimate the variance of  $\hat{\beta}$ , and repeat the above procedure a certain number of times to reduce the randomness effects of splitting the data.

The growth rate of the dimension of  $\beta$  in condition (A3) is too fast to ensure the validity of the refitted wild bootstrap of (B1)–(B6). We need to further limit the rate to

(A3')  $s \log(q)/n^{1/3} \to 0.$ 

Let  $P^*$  denote the probability under the resampling procedure given in (B1)–(B6).

**Theorem 3.** Under Assumptions (A1)-(A2), (A4)-(A6), and (A3'), using the resampling approach described in steps (B1)-(B6), we have

$$\sup_{x \in \mathbb{R}} \left| P^*\left( \left(\frac{n}{2}\right)^{1/2} (\hat{\beta}^* - \hat{\beta}) \le x \right) - P\left(n^{1/2} (\hat{\beta} - \beta_0) \le x \right) \right| \xrightarrow{p} 0.$$

Theorem 3 provides a theoretical justification for using the refitted wild bootstrap to estimate the asymptotic variance-covariance matrix. This makes it possible to conduct statistical inferences without estimating the error densities. In the following section, we describe a computational algorithm for solving the estimating equation (2.12).

#### 5. Computation

As pointed out in Section 2, we need to determine how to solve

$$\tilde{\Psi}_n(\beta) = \frac{1}{n} \sum_{i=1}^n \psi_\tau(y_i - x'_i \beta - z'_i \tilde{\eta})(x_i - \tilde{H} z_i) = 0.$$
(5.1)

Let  $\tilde{y}_i = y_i - z'_i \tilde{\eta}$  and  $\tilde{x}_i = x_i - \tilde{H} z_i$ . Write

$$\sum_{i=1}^{n} \psi_{\tau}(y_i - x'_i \beta - z'_i \tilde{\eta})(x_i - \tilde{H}z_i) = \sum_{i=1}^{n} \psi_{\tau}\{\tilde{y}_i - (\tilde{H}z_i)'\beta - \tilde{x}'_i\beta\}\tilde{x}_i.$$

Let  $\beta^k$  be the value at the *k*th iteration, for k = 0, 1, 2, ... We take the Lasso estimator by solving (2.2) as the initial estimator  $\beta^0$ , and use the following iterative steps:

Step 1: Calculate

$$\tilde{y}_i^k = \tilde{y}_i - (\tilde{H}z_i)'\beta^k$$

Step 2: Solve

$$\beta^{k+1} = \underset{\beta}{\operatorname{argmin}} \sum_{i=1}^{n} \rho_{\tau} (\tilde{y}_{i}^{k} - \tilde{x}_{i}^{\prime} \beta).$$

Step 3: Set  $k \leftarrow k+1$ ; go to Step 1 until certain convergence criteria are satisfied.

Note that Step 2 is an optimization problem based on a low-dimensional quantile regression, so it can be solved using existing software. Refer to Koenker (2005) for details on its computation.

#### 6. One-Step Estimator

The procedure given in Section 5 inspired the following one-step estimation approach.

First, we obtain an initial estimator of  $\beta$  by solving (2.2). Recall that the projected score function is

$$\tilde{\Psi}_n(\beta) = \frac{1}{n} \sum_{i=1}^n \psi_\tau(y_i - x'_i \beta - z'_i \tilde{\eta})(x_i - \tilde{H}z_i),$$

where  $\tilde{H}$  is obtained by solving (2.9). We consider a modified projected score function

$$\tilde{\Psi}_{n}^{*}(\beta) = \frac{1}{n} \sum_{i=1}^{n} \psi \{ y_{i} - (x_{i} - \tilde{H}z_{i})'\beta - (\tilde{H}z_{i})'\tilde{\beta} - z_{i}'\tilde{\eta} \} (x_{i} - \tilde{H}z_{i}).$$

Let  $\tilde{y}_i = y_i - (\tilde{H}z_i)'\tilde{\beta} - z_i'\tilde{\eta}$ . Then, solving  $\tilde{\Psi}^*(\beta) = 0$  is equivalent to solving

$$\hat{\beta}_{one} = \underset{\beta}{\operatorname{argmin}} \frac{1}{n} \sum_{i=1}^{n} \rho_{\tau} \big( \tilde{y}_i - (x_i - \tilde{H} z_i)' \beta \big).$$

Clearly,  $\hat{\beta}_{one}$  can be considered a one-step update from the initial estimator  $\tilde{\beta}$ .

We replace Assumption (A6) with the following assumption:

(A6')  $E\{f(0|x,z)(x-H_0z)(x-H_0z)'\}$  is an invertible matrix.

We then have the following result.

**Theorem 4.** Under model (2.1), if Assumptions (A1)–(A5) and (A6') hold, then

$$n^{1/2}(\hat{\beta}_{one} - \beta_0) \stackrel{L}{\longrightarrow} N(0, \widetilde{Q}^{-1}D\widetilde{Q}^{-1}),$$

where  $\widetilde{Q} = E\{f(0|x,z)(x-H_0z)(x-H_0z)'\}$ , and D is defined as in Theorem 2.

Note that  $\tilde{Q}$  is different from Q in Theorem 2, owing to the modification of the score function. In addition, the refitted wild bootstrap method of Section 4 can be used similarly to estimate the asymptotic covariance matrix  $\tilde{Q}^{-1}D\tilde{Q}^{-1}$ . The computation of this estimator is efficient because no iterations of (Step 1)– (Step 2) are needed.

## 7. Numerical Studies

## 7.1. A simulation study

We investigate the finite-sample performance of the estimation method of Section 2 using the variance-covariance matrix estimated by the refitted wild bootstrap method described in Section 4. Two sample sizes, n = 50 and n = 100, are used, and two quantile levels,  $\tau = 0.5$  and  $\tau = 0.75$ , are considered.

We simulate data from the model

$$y_i = \mu + \sum_{j=1}^{3} x_{ij}\beta_j + \sum_{k=1}^{199} z_{ik}\eta_k + e_i, \quad i = 1, \dots, n,$$

where all the covariate variables and the model error  $e_i$  are generated independently from the standard normal distribution. We consider a sparsity structure with coefficients given as

$$(\mu, \beta_1, \beta_2, \beta_3, \eta_1, \eta_2, \eta_3, \dots, \eta_{199}) = (3, 3, 3, 3, 3, 3, 3, 0, \dots, 0).$$

We use the method of Huang, Breheny and Ma (2012) to solve (2.9), using the Bayesian information criterion for the choice of penalties. Then, we use the method of Belloni and Chernozhukov (2011) to solve (2.2) at confidence levels 0.7 and 0.8, corresponding to sample sizes n = 50 and n = 100, respectively. We repeat the bootstrap procedure 1,000 times to estimate the covariance matrix, where the random weights follow the discrete distribution

$$P(W = w) = \begin{cases} 1 - \tau, w = 2(1 - \tau) \\ \tau, & w = -2\tau \end{cases},$$

for  $0 < \tau < 1$ . The R packages *quantreg* and *grpreg* are used to solve (2.2) and (2.9), respectively. We generate 1,000 Monte Carlo samples to compare the performance of the proposed method and the oracle method, where the sparsity structure is assumed to be known.

We report the biases of the proposed and the oracle estimators, as well as the relative efficiency, which is the ratio of the mean squared errors of the two estimators. We also estimate the coverage probabilities of the proposed method at the 95% confidence level. As shown in Table 1, the bootstrap leads to overall conservative interval estimates, especially when the quantile level  $\tau = 0.75$ . When the sample size is as small as 50, the relative efficiencies vary from 70% to 82%; these efficiencies can be improved to 82% to 92% when the sample size is doubled.

Table 1. Estimated coverage probability (CP) at 95% confidence level,	and the estimated
relative efficiencies (RE) and biases (Bias) of the proposed estimator (I	EC) and the oracle
estimator (Oracle).	

n = 50	Parameter	Bias of EC $(\times 10^{-3})$	Bias of Oracle $(\times 10^{-3})$	RE	CP ( $\times 100\%$ )
	$\beta_1$	-9.608	-0.971	0.811	95.9
$\tau = 0.5$	$\beta_2$	0.945	1.993	0.701	95.8
	$\beta_3$	-3.486	-8.541	0.813	96.2
	$\beta_1$	-2.744	-6.880	0.697	99.0
$\tau = 0.75$	$\beta_2$	2.891	-0.413	0.617	97.8
	$\beta_3$	-4.957	-12.802	0.690	98.7
n = 100	Parameter	Bias of EC $(\times 10^{-3})$	Bias of Oracle $(\times 10^{-3})$	$\operatorname{RE}$	CP ( $\times 100\%)$
	$\beta_1$	-2.245	-1.684	0.992	95.6
$\tau = 0.5$	$\beta_2$	-2.913	0.455	0.919	96.5
	$\beta_3$	-7.060	-6.316	0.948	96.2
	$\beta_1$	-5.663	-0.863	0.854	97.2
$\tau = 0.75$	$\beta_2$	1.615	1.790	0.927	97.7
	$eta_3$	-8.156	-2.809	0.938	97.8

From the results shown in Table 1, the proposed method usually leads to estimates with smaller biases, probably because of the projection procedure used in our estimation.

# 7.2. Case study of GDP growth rate

In this section, we analyze the national growth rate of GDP using data collected by Barro and Lee (2013). Their results indicate that in a broad group of countries, educational attainment serves as a proxy for the stock of human capital, as well as for economic development. This data set includes 138 countries and eight broad categories comprising national income, education, population/fertility, government expenditure, PPP deflators, political variables, and trade policy, among others. A detailed description can be found at http:// www.barrolee.com/. Data are presented either quinquennially, for the period 1950-2010, or as averages of five-year sub-periods over 1950-2010.

There is a subset of data including 90 complete observations (by country) with 61 covariates, which can be downloaded in the R package hdm (Chernozhukov, Hansen and Spindler (2016)). There are 41 observations out of 90 from 1965; the rest are from 1975. In this example, we only consider the 49 observations from 1975. We choose national GDP growth rate per capita as the response  $y_i$ , and denote the 61 scaled covariates by  $\tilde{x}_i = (\tilde{x}_{i1}, \ldots, \tilde{x}_{ip})'$ , for  $i = 1, \ldots, n$ , where n = 49 and p = 61. We first take the logarithm or cubic-root

Table 2. List of *p*-values of the two variables for GDP growth rate. The numbers in parentheses are the estimated coefficients at the corresponding quantile levels. \*govsh41: Ratio of real government "consumption" expenditure to real GDP, and \*gvxdxe41: Ratio of real government "consumption" expenditure, net of spending on defense and education, to real GDP.

Variable Name	$\tau = 0.25$	$\tau = 0.5$	$\tau = 0.75$
govsh41*	0.0122 (0.8215)	0.2722 ( $0.1971$ )	0.9356 (-0.00498)
$gvxdxe41^*$	0.0043 (-0.6523)	0.0026 (-0.3530)	0.7259 (- $0.2403$ )

transformation such that each predictor's empirical distribution is more normally distributed.

There is a large body of literature on the relationship between economic development and government consumption expenditure; see Landau (1986), Barro (1990), Barro (1991), Barro (1989), Devarajan, Swaroop and Zou (1996), d'Agostino, Dunne and Pieroni (2016), and Dissou, Didic and Yakautsava (2016). Owing to the correlation between government consumption expenditure and other variables that characterize population/fertility, political instability, the economic system, and so on, we need to reduce their influence by using the proposed regularized projection procedure.

The following two variables are important to understanding the effect of a country's government consumption expenditure on its economic growth rate: the ratio of real government "consumption" expenditure to real GDP (govsh41, denoted by  $\tilde{x}_{i1}$ ), and the ratio of real government "consumption" expenditure, net of spending on defense and education, to real GDP (gvxdxe41, denoted by  $\tilde{x}_{i2}$ ). We use these two variables as treatments, denoted by  $x_i = (\tilde{x}_{i1}, \tilde{x}_{i2})'$ , and the remaining ones as confounders, denoted by  $z_i$ ,  $i = 1, \ldots, n$ . Then we consider the linear quantile regression model (2.1) on these treatments and confounders:

$$Q_{\tau}(y_i|x_i, z_i) = \beta_0 + \sum_{j=1}^2 x_{ij}\beta_j + \sum_{k=1}^{59} z_{ik}\eta_k, \ i = 1, \dots, 49.$$

We report the estimated coefficients and the corresponding p-values in Table 2.

Barro (1989, 1990, 1991) found that both variables, govsh41 and gvxdxe41, are negatively associated with the GDP growth rate. However, our results indicate that it may be a good strategy to promote GDP growth by increasing the total government consumption expenditure in slowly growing economies. At the same time, countries with relatively slow GDP growth rates should limit government expenditure on defense and education to ensure economic growth.

# 8. Conclusion

In this work, we used regularized projection scores to estimate low-dimensional preconceived parameters in high-dimensional quantile regression models. Our asymptotic results facilitate classical statistical inference in high-dimensional scenarios, which has been largely overlooked in the quantile regression literature. In addition, we proposed a refitted wild bootstrapping approach to bypass the estimation of the variance-covariance matrix of the estimator, which involves the probability densities of the errors. To the best of our knowledge, this is the first demonstration of wild bootstrapping in a high-dimensional setting in the quantile regression literature.

The proposed method can be implemented easily because its computation is based on existing algorithms, which can be accomplished using R packages. In practice, we advocate the one-step estimator owing to its computational efficiency in high-dimensional settings, especially when a resampling approach is needed.

## Supplementary Material

The proofs of Theorems 1–4 and related technical details can be found in the online Supplementary Material.

## Acknowledgments

The authors are grateful to the anonymous referees, associate editor, and editor for their helpful comments. Feng's research was supported by the National Natural Science Foundation of China (11971292 and 11690012), Program for Innovative Research Team of SUFE, and Key Laboratory for Applied Statistics of MOE (130028906), Northeast Normal University. Huang's work was supported in part by NSF grant DMS-1916199. Liu's research was supported by the National Natural Science Foundation of China (11771267).

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(Received June 2018; accepted May 2020)