# Non-stationary variance estimation and kriging prediction Proof of Theorems

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### Supplementary Material

Proof of Theorem 1.

Proof of Theorem 2.

Proof of Theorem 3.

Proof of Theorem 4.

Figures from the Simulation Study.

# S1 Proof of Theorem 1

To prove Theorem 1, we need the following lemma to simplify the calculation.

$$\textbf{Lemma1:} \ \, \text{If} \, (X,Y) \sim N\left( \left( \begin{array}{cc} 0 \\ 0 \end{array} \right), \left( \begin{array}{cc} \sigma_1^2 & \rho \sigma_1 \sigma_2 \\ \rho \sigma_1 \sigma_2 & \sigma_2^2 \end{array} \right) \right), \\ \text{then} \, Cov[X^2,Y^2] = 2 \left( Cov[X,Y] \right)^2.$$

Proof: Since 
$$X|Y \sim N(\frac{\rho\sigma_1}{\sigma_2}Y,(1-\rho^2)), E[X^2|Y] = (1-\rho^2)\sigma_1^2 + (\frac{\rho\sigma_1}{\sigma_2}Y)^2$$

$$\begin{split} Cov[X^2,Y^2] &= E[X^2Y^2] - E[X^2]E[Y^2] \\ &= E\{E[X^2Y^2|Y]\} - \sigma_1^2\sigma_2^2 \\ &= E[Y^2\{(1-\rho^2)\sigma_1^2 + (\frac{\rho\sigma_1}{\sigma_2}Y)^2\}] - \sigma_1^2\sigma_2^2 \\ &= (1-\rho^2)\sigma_1^2\sigma_2^2 + (\frac{\rho\sigma_1}{\sigma_2})^23\sigma_2^4 - \sigma_1^2\sigma_2^2 \\ &= 2\rho^2\sigma_1^2\sigma_2^2 \\ &= 2(Cov[X,Y])^2. \end{split}$$

To establish the asymptotic results for the local polynomial regression estimator, which will be in Section 3, we rely on the following analytical properties of  $K_n(\frac{x-x_i}{\lambda})$ ,

1. 
$$\sum_{i=1}^{n-1} K_n(\frac{x-x_i}{\lambda}) = 1$$
,

2. 
$$\sum_{i=1}^{n-1} (x - x_i)^j K_n(\frac{x - x_i}{\lambda}) = 0$$
, for any  $j = 1, \dots, p$ ,

3. 
$$K_n(\cdot) = 0$$
 for all  $|x - x_i| > \lambda$ ,

4. 
$$K_n(\frac{x-x_i}{\lambda}) = O((n\lambda)^{-1})$$
 uniformly for all  $x \in [0,1]$ ,

5. 
$$\sum_{i=1}^{n-1} \left( K_n(\frac{x-x_i}{\lambda}) \right)^2 = O((n\lambda)^{-1}).$$

Property 5 can be derived from property 4 and the Cauchy-Schwartz inequality.

Proof of Theorem 1, recall  $\Delta_i=h^{-1}(D_{h,i}^2-2\sigma_\epsilon^2)$ , where  $D_{h,i}=Z(x_i)-Z(x_i+h)$ . So

$$E[D_{h,i}^2] = \sigma_i^2 h + \{\sigma_i^{(1)2} x_i + \sigma_i^{2(1)}\} h^2 + 2\sigma_\epsilon^2 + o(h^2),$$

Thus

$$\begin{split} E[\Delta_i] &= E[h^{-1}(D_{h,i}^2 - 2\sigma_{\epsilon}^2)] \\ &= h^{-1}[\sigma_i^2 h + \{\sigma_i^{(1)2} x_i + \sigma_i^{2(1)}\} h^2 + o(h^2)] \\ &= \sigma_i^2 + \{\sigma_i^{(1)2} x_i + \sigma_i^{2(1)}\} h + o(h). \end{split}$$

The bias of  $\hat{\sigma}_{\lambda}^2(x; \sigma_{\epsilon}^2) = \sum_{i=1}^{n-1} K_n(\frac{x-x_i}{\lambda}) \Delta_i$  can be calculated as

$$\begin{split} E[\hat{\sigma}_{\lambda}^{2}(x;\sigma_{\epsilon}^{2}) - \sigma^{2}(x)] &= \sum_{i=1}^{n-1} K_{n}(\frac{x - x_{i}}{\lambda}) \{ E[\Delta_{i}] - \sigma^{2}(x) \} \\ &= \sum_{i=1}^{n-1} K_{n}(\frac{x - x_{i}}{\lambda}) \{ \sigma_{i}^{2} - \sigma^{2}(x) + (\sigma_{i}^{(1)2}x_{i} + \sigma_{i}^{2(1)})h + O(h^{2}) \} \\ &= \sum_{i=1}^{n-1} K_{n}(\frac{x - x_{i}}{\lambda}) \{ \sum_{j=1}^{\lfloor \beta \rfloor} \frac{\sigma^{2(j)}(x)}{j!} (x_{i} - x)^{j} + O(|x_{i} - x|^{\beta}) \\ &+ (\sigma_{i}^{(1)2}x_{i} + \sigma_{i}^{2(1)})h + O(h^{2}) \} \\ &= \sum_{i=1}^{n-1} K_{n}(\frac{x - x_{i}}{\lambda}) \{ O(|x_{i} - x|^{\beta}) + (\sigma_{i}^{(1)2}x_{i} + \sigma_{i}^{2(1)})h + O(h^{2}) \}, \end{split}$$

where the third equality is obtained by Taylor expansion of  $\sigma_i^2 = \sigma^2(x_i)$  at x and the assumption that  $\sigma^2 \in C_{\beta}^+$ , and the last equality follows by Property 2 of  $K_n(\frac{x-x_i}{\lambda})$ . Note that

$$\left| \sum_{i=1}^{n-1} K_n(\frac{x - x_i}{\lambda}) |x_i - x|^{\beta} \right| \leq \sum_{i=1}^{n-1} |K_n(\frac{x - x_i}{\lambda})| |x_i - x|^{\beta}$$

$$\leq \sum_{i;|x - x_i| < \lambda} |K_n(\frac{x - x_i}{\lambda})| \lambda^{\beta}$$

$$= O(\lambda^{\beta})$$

where the second inequality comes from Property 3 of  $K_n(\frac{x-x_i}{\lambda})$ . So Bias term is  $O(\max(h, \lambda^{\beta}))$ .

To simplify the notation, let  $\sigma_{i,h} = \sigma(x_i + h)$ ,  $\sigma_{i,2h} = \sigma(x_i + 2h)$ ,

$$Var[D_{h,i}^{2}] = Var[(Z(x_{i} + h) - Z(x_{i}))^{2}]$$

$$= 2\{\sigma_{i}^{2}x_{i} + \sigma_{i,h}^{2}(x_{i} + h) - 2\sigma_{i}\sigma_{i,h}x_{i} + 2\sigma_{\epsilon}^{2}\}^{2}$$

$$= 2\{\sigma_{i}^{2}h + (\sigma_{i}^{(1)2}x_{i} + \sigma_{i}^{2(1)})h^{2} + O(h^{3}) + 2\sigma_{\epsilon}^{2}\}^{2},$$

where the second equality follows from Lemma 1. For j = i + 1,

$$Cov[\Delta_{i}, \Delta_{j}] = h^{-2}Cov[D_{h,i}^{2}, D_{h,j}^{2}]$$

$$= 2h^{-2}[Cov\{D_{h,i}, D_{h,j}\}]^{2}$$

$$= 2h^{-2}\sigma_{\epsilon}^{4},$$

For  $j \geq i + 2$ ,  $Cov[\Delta_i, \Delta_j] = 0$ . Thus

$$Var[\hat{\sigma}_{\lambda}^{2}(x;\sigma_{\epsilon}^{2})] = \sum_{i=1}^{n-1} \sum_{j=1}^{n-1} K_{n}(\frac{x-x_{i}}{\lambda}) K_{n}(\frac{x-x_{j}}{\lambda}) Cov[\Delta_{i}, \Delta_{j}]$$

$$= \sum_{i=1}^{n-1} K_{n}(\frac{x-x_{i}}{\lambda})^{2} Var[\Delta_{i}]$$

$$+ 2 \sum_{i=1}^{n-1} \sum_{j>i}^{n-1} K_{n}(\frac{x-x_{i}}{\lambda}) K_{n}(\frac{x-x_{j}}{\lambda}) Cov[\Delta_{i}, \Delta_{j}]$$

$$= \sum_{i=1}^{n-1} K_{n}(\frac{x-x_{i}}{\lambda})^{2} h^{-2} 2\{\sigma_{i}^{2} h + (\sigma_{i}^{(1)2} x_{i} + \sigma_{i}^{2(1)}) h^{2} + O(h^{3}) + 2\sigma_{\epsilon}^{2}\}^{2}$$

$$+ 2 \sum_{i=1}^{n-2} K_{n}(\frac{x-x_{i}}{\lambda}) K_{n}(\frac{x-x_{i+1}}{\lambda}) 2h^{-2} \sigma_{\epsilon}^{4}$$

$$= O\left((n\lambda)^{-1} \cdot \max\{1, n^{2-2\alpha}\}\right),$$

where the last equality is obtained by Property 5 of  $K_n(\frac{x-x_i}{\lambda})$ . If  $\alpha \geq 1$ , the bias term is  $O(\max(h, \lambda^{\beta}))$  and the variance term is  $O((n\lambda)^{-1})$ , the optimal bandwidth is  $\lambda = O(n^{-1/(1+2\beta)})$ , under which the mean squared error is  $O(n^{-\beta/(1+2\beta)})$ .

If  $\frac{1}{2} < \alpha < 1$ , the bias term is  $O(\max(h, \lambda^{\beta}))$  and the variance term is  $O((n\lambda)^{-1}n^{2-2\alpha})$ , the optimal bandwidth is  $\lambda = O(n^{-(2\alpha-1)/(1+2\beta)})$ , under which the mean squared error is  $O(n^{-2(1+\beta-\alpha)/(1+2\beta)})$ . Theorem 1 follows.

### S2 Proof of Theorem 2

Proof: Let  $a_{ni} = K_n(\frac{x - x_i}{\lambda})$  and  $\xi_i = \Delta_i$ . Check the following conditions as in Theorem 2.2 in Peligrad and Utev (1997).

1.  $\max_{1 \le i \le n} |a_{ni}| \to 0$  as  $n \to \infty$  and this condition holds since

$$K_n(\frac{x-x_i}{\lambda}) = O((n\lambda)^{-1}),$$

2.  $\sup_{n} \sum_{i=1}^{n} a_{ni}^{2} < \infty$  and this condition holds since

$$\sum_{i=1}^{n-1} \left( K_n\left(\frac{x-x_i}{\lambda}\right) \right)^2 = O((n\lambda)^{-1}),$$

3. For a certain  $\delta > 0$ ,  $\{|\xi_i|^{2+\delta}\}$  is uniformly integrable and this condition can be easily verified by the fact that

$$\Delta_i = h^{-1}(D_{h,i}^2 - 2\sigma_{\epsilon}^2)$$

and

$$D_{h,i} = Z_i - Z_{i+1} \sim N(0, u_i),$$

where  $u_i = \sigma_i^2 h + (\sigma_i^{(1)2} x_i + \sigma_i^{2(1)}) h^2 + O(h^3) + 2\sigma_\epsilon^2$ . So  $E\{D_{h,i}^6\} = 15u_i^3$ , then it is easy to check that

$$\sup_{1 \le i \le n} E\{|\xi_i|^3\} < \infty,$$

which guarantees that  $\{|\xi_i|^{2+\delta}\}$  is uniformly integrable.

The CLT in Theorem 2 follows.

# S3 Proof of Theorem 3

To prove Theorem 3, we can write

$$\hat{U}(\sigma_{\epsilon}^{2}) = \frac{\partial}{\partial \sigma_{\epsilon}^{2}} \left(-\frac{1}{2} \log |\hat{\Sigma}| - \frac{1}{2} \mathbf{d}^{T} \hat{\Sigma}^{-1} \mathbf{d}\right) 
= -\frac{1}{2} tr(\hat{\Sigma}^{-1} B) + \frac{1}{2} \mathbf{d}^{T} \hat{\Sigma}^{-1} B \hat{\Sigma}^{-1} \mathbf{d}, \qquad (S3.1)$$
where  $B = \begin{pmatrix} 0 & -1 & \cdots & 0 & 0 \\ -1 & 0 & \cdots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & 0 & -1 \\ 0 & 0 & \cdots & -1 & 0 \end{pmatrix}$ , and
$$\hat{\Sigma} = \begin{pmatrix} \hat{D}_{h,\lambda}(x_{1}) & -\sigma_{\epsilon}^{2} & \cdots & 0 & 0 \\ -\sigma_{\epsilon}^{2} & \hat{D}_{h,\lambda}(x_{2}) & \cdots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & \hat{D}_{h,\lambda}(x_{n-2}) & -\sigma_{\epsilon}^{2} \\ 0 & 0 & \cdots & \hat{D}_{h,\lambda}(x_{n-2}) & -\sigma_{\epsilon}^{2} \end{pmatrix}.$$

Since  $\hat{\sigma}_{\epsilon}^2$  satisfies  $\hat{U}(\hat{\sigma}_{\epsilon}^2) = 0$ , by the mean value theorem, we have

$$0 = \hat{U}(\hat{\sigma}_{\epsilon}^{2})$$
  
=  $\hat{U}(\sigma_{\epsilon,0}^{2}) + \dot{U}(\sigma_{\epsilon}^{2*})(\hat{\sigma}_{\epsilon}^{2} - \sigma_{\epsilon,0}^{2}),$ 

where  $\sigma_{\epsilon}^{2*}$  is the value between  $\sigma_{\epsilon,0}^2$  and  $\hat{\sigma}_{\epsilon}^2$ , and

$$\dot{U}(\sigma_{\epsilon}^{2}) = \partial \hat{U}(\sigma_{\epsilon}^{2})/\partial \sigma_{\epsilon}^{2} 
= \frac{1}{2} tr\{(\hat{\Sigma}^{-1}B)^{2}\} - \mathbf{d}^{T}\hat{\Sigma}^{-1}B\hat{\Sigma}^{-1}B\hat{\Sigma}^{-1}\mathbf{d}.$$
(S3.2)

So

$$\hat{\sigma}_{\epsilon}^2 - \sigma_{\epsilon,0}^2 = -\{\dot{U}(\sigma_{\epsilon}^{2*})\}^{-1} \hat{U}(\sigma_{\epsilon,0}^2). \tag{S3.3}$$

Follow the same argument in proof of Theorem 1, we can establish

$$\hat{D}_{h,\lambda}(x) = D_{h,\lambda}(x) + O_p\left(n^{-1-\beta/(1+2\beta)}\right).$$

So we have

$$\hat{\Sigma} = \Sigma + O_p \left( n^{-1 - \beta/(1 + 2\beta)} \right) D,$$

where D is some constant diagonal matrix. Using the property of matrix inverse, if  $\epsilon$  is a small number then

$$(V + \epsilon F)^{-1} = V^{-1} - \epsilon V^{-1} F V^{-1} + O(\epsilon^2).$$

We have

$$\hat{\Sigma}^{-1} = \Sigma^{-1} + O_p(n^{-1-\beta/(1+2\beta)})\Sigma^{-1}D\Sigma^{-1}.$$

Replacing  $\hat{\Sigma}^{-1}$  by the above expression in terms of  $\Sigma^{-1}$  in (S3.1) and (S3.2), we obtain

$$\begin{split} \hat{U}(\sigma_{\epsilon}^2) &= -\frac{1}{2}tr\left(\{\Sigma^{-1} + O_p(n^{-1-\beta/(1+2\beta)})\Sigma^{-1}D\Sigma^{-1}\}B\right) \\ &+ \frac{1}{2}\mathbf{d}^T\{\Sigma^{-1} + O_p(n^{-1-\beta/(1+2\beta)})\Sigma^{-1}D\Sigma^{-1}\}B\{\Sigma^{-1} + O_p(n^{-1-\beta/(1+2\beta)})\Sigma^{-1}D\Sigma^{-1}\}\mathbf{d}, \end{split}$$

and

$$\begin{split} \dot{U}(\sigma_{\epsilon}^2) &= \frac{1}{2} tr \left( [\Sigma^{-1} + O_p(n^{-1-\beta/(1+2\beta)}) \Sigma^{-1} D \Sigma^{-1} \} B]^2 \right) \\ &- \mathbf{d}^T \{ \Sigma^{-1} + O_p(n^{-1-\beta/(1+2\beta)}) \Sigma^{-1} D \Sigma^{-1} \} B \{ \Sigma^{-1} + O_p(n^{-1-\beta/(1+2\beta)}) \Sigma^{-1} D \Sigma^{-1} \} \\ &\cdot B \{ \Sigma^{-1} + O_p(n^{-1-\beta/(1+2\beta)}) \Sigma^{-1} D \Sigma^{-1} \} \mathbf{d}. \end{split}$$

Now we will discuss the order of (S3.3) case by case.

1. 
$$\alpha > 1$$
:  $\Sigma^{-1} = O(n)$  and  $O_p(n^{-1-\beta/(1+2\beta)})\Sigma^{-1}D\Sigma^{-1} = O_p(n^{1-\beta/(1+2\beta)})$ , thus  $\hat{U}(\sigma_{\epsilon}^2) \cong -\frac{1}{2}tr(\Sigma^{-1}B) + \frac{1}{2}\mathbf{d}^T\Sigma^{-1}B\Sigma^{-1}\mathbf{d}$ , and  $\hat{U}(\sigma_{\epsilon}^2) \cong \frac{1}{2}tr(\Sigma^{-1}B)^2 - \mathbf{d}^T\Sigma^{-1}B\Sigma^{-1}\mathbf{d}$ . So

$$\hat{\sigma}_{\epsilon}^{2} - \sigma_{\epsilon,0}^{2} \cong -E\left\{\dot{U}(\sigma_{\epsilon}^{2})\right\}^{-1} \left\{-\frac{1}{2}tr\left(\Sigma^{-1}B\right) + \frac{1}{2}\mathbf{d}^{T}\Sigma^{-1}B\Sigma^{-1}\mathbf{d}\right\}$$
$$= \left\{\frac{1}{2}tr\left\{(\Sigma^{-1}B)^{2}\right\}\right\}^{-1} \left\{-\frac{1}{2}tr\left(\Sigma^{-1}B\right) + \frac{1}{2}\mathbf{d}^{T}\Sigma^{-1}B\Sigma^{-1}\mathbf{d}\right\}.$$

We claim that

$$[tr\{(\Sigma^{-1}B)^2\}]^{-1}\{tr(\Sigma^{-1}B) - \mathbf{d}^T \Sigma^{-1}B\Sigma^{-1}\mathbf{d}\} = O_p(n^{-3/2})$$

in probability as  $n \to \infty$ . Since

$$E\left(\left[tr\{(\Sigma^{-1}B)^2\}\right]^{-1}\left\{tr(\Sigma^{-1}B) - \mathbf{d}^T\Sigma^{-1}B\Sigma^{-1}\mathbf{d}\right\}\right) = 0$$

and

$$\begin{split} &Var\left([tr\{(\Sigma^{-1}B)^2\}]^{-1}\{tr(\Sigma^{-1}B)-\mathbf{d}^T\Sigma^{-1}B\Sigma^{-1}\mathbf{d}\}\right)\\ =&[tr\{(\Sigma^{-1}B)^2\}]^{-2}Var\left(\mathbf{d}\Sigma^{-1}B\Sigma^{-1}\mathbf{d}\right)\\ =&[tr\{(\Sigma^{-1}B)^2\}]^{-2}tr\left\{(\Sigma^{-1}B)^2\right\}\\ =&[tr\{(\Sigma^{-1}B)^2\}]^{-1}\\ =&O(n^{-3}) \end{split}$$

2.  $\alpha < 1$ :  $\Sigma^{-1} = O(n^{\alpha})$  and  $O_p(n^{-1-\beta/(1+2\beta)})\Sigma^{-1}D\Sigma^{-1} = O_p(n^{2\alpha-1-\beta/(1+2\beta)})$ . The inequality  $2\alpha - 1 - \beta/(1+2\beta) < \alpha$  always holds in case of  $\alpha < 1$ , regardless of  $\beta > 0$ . So

$$\begin{split} \hat{\sigma}_{\epsilon}^2 - \sigma_{\epsilon,0}^2 &\;\cong\;\; -E\left\{\dot{U}(\sigma_{\epsilon}^2)\right\}^{-1} \left\{ -\frac{1}{2}tr\left(\Sigma^{-1}B\right) + \frac{1}{2}\mathbf{d}^T\Sigma^{-1}B\Sigma^{-1}\mathbf{d} \right\} \\ &=\;\; \left\{ \frac{1}{2}tr\{(\Sigma^{-1}B)^2\} \right\}^{-1} \left\{ -\frac{1}{2}tr\left(\Sigma^{-1}B\right) + \frac{1}{2}\mathbf{d}^T\Sigma^{-1}B\Sigma^{-1}\mathbf{d} \right\}. \end{split}$$

We claim that

$$[tr\{(\Sigma^{-1}B)^2\}]^{-1}\{tr(\Sigma^{-1}B) - \mathbf{d}^T\Sigma^{-1}B\Sigma^{-1}\mathbf{d}\} = O_p(n^{-(1+2\alpha)/2})$$

in probability as  $n \to \infty$ . Since

$$E\left([tr\{(\Sigma^{-1}B)^2\}]^{-1}\{tr(\Sigma^{-1}B)-\mathbf{d}^T\Sigma^{-1}B\Sigma^{-1}\mathbf{d}\}\right)=0$$

and

$$\begin{split} &Var\left([tr\{(\Sigma^{-1}B)^2\}]^{-1}\{tr(\Sigma^{-1}B)-\mathbf{d}^T\Sigma^{-1}B\Sigma^{-1}\mathbf{d}\}\right)\\ =&[tr\{(\Sigma^{-1}B)^2\}]^{-2}Var\left(\mathbf{d}\Sigma^{-1}B\Sigma^{-1}\mathbf{d}\right)\\ =&[tr\{(\Sigma^{-1}B)^2\}]^{-2}tr\left\{(\Sigma^{-1}B)^2\right\}\\ =&[tr\{(\Sigma^{-1}B)^2\}]^{-1}\\ =&O(n^{-(1+2\alpha)}). \end{split}$$

Thus

$$\hat{\sigma}_{\epsilon}^2 - \sigma_{\epsilon,0}^2 = O_p(n^{-(1+2\alpha)/2}).$$

## S4 Proof of Theorem 4

Recall

$$p(x_0) = C(\sigma)^T \{V(\sigma)\}^{-1} \mathbf{z},$$

where  $\sigma = (\sigma_1, \dots, \sigma_n, \sigma_0, \sigma_\epsilon), \ \sigma_0 = \sigma(x_0),$ 

$$C(\sigma) = \begin{pmatrix} \sigma_1 \sigma_0 \min(x_1, x_0) \\ \sigma_2 \sigma_0 \min(x_2, x_0) \\ \vdots \\ \sigma_n \sigma_0 \min(x_n, x_0) \end{pmatrix}, \ \mathbf{z} = \begin{pmatrix} z_1 \\ z_2 \\ \vdots \\ z_n \end{pmatrix},$$

and

$$V(\sigma) = \begin{pmatrix} \sigma_1^2 x_1 + \sigma_{\epsilon}^2 & \sigma_1 \sigma_2 x_1 & \cdots & \sigma_1 \sigma_n x_1 \\ \sigma_1 \sigma_2 x_1 & \sigma_2^2 x_2 + \sigma_{\epsilon}^2 & \cdots & \sigma_2 \sigma_n x_2 \\ \vdots & \vdots & \ddots & \vdots \\ \sigma_1 \sigma_n x_1 & \sigma_2 \sigma_n x_2 & \cdots & \sigma_n^2 x_n + \sigma_{\epsilon}^2 \end{pmatrix}.$$

The plug-in kriging predictor is given by

$$\hat{p}(x_0) = C(\hat{\sigma})^T \{V(\hat{\sigma})\}^{-1} \mathbf{z},$$

where  $\hat{\sigma} = (\hat{\sigma}_1, \dots, \hat{\sigma}_n, \hat{\sigma}_0, \hat{\sigma}_\epsilon)$ . Using Taylor expansion technique, we have

$$C(\hat{\sigma}) \cong C(\sigma) + \sigma_0 \begin{pmatrix} \min(x_1, x_0)(\hat{\sigma}_1 - \sigma_1) \\ \min(x_2, x_0)(\hat{\sigma}_2 - \sigma_2) \\ \vdots \\ \min(x_n, x_0)(\hat{\sigma}_n - \sigma_n) \end{pmatrix} + \begin{pmatrix} \sigma_1 \min(x_1, x_0) \\ \sigma_2 \min(x_2, x_0) \\ \vdots \\ \sigma_n \min(x_n, x_0) \end{pmatrix} (\hat{\sigma}_0 - \sigma_0)$$

$$= C(\sigma) + O(n^{-p})E,$$

Similarly, we can have

$$V(\hat{\sigma}) \cong V(\sigma) + O(n^{-q})F,$$

where p is the convergent rate of  $\hat{\sigma}$ , in the case when  $\alpha \geqslant 1$ ,  $p = \beta/(1+2\beta)$ , and in the case when  $1/2 < \alpha < 1$ ,  $p = (2\alpha - 1)/(1+2\beta)$ , q is the minimum convergent rate of  $\hat{\sigma}$  and  $\hat{\sigma}_{\epsilon}$ , i.e.  $q = \min\{p, 2\alpha\} = p$  considering  $2\alpha \geqslant p$  always holds, E and F are constant matrices. Using the property of matrix inverse, if  $\epsilon$  is a small number then

$$(V + \epsilon F)^{-1} = V^{-1} - \epsilon V^{-1} F V^{-1} + O(\epsilon^2),$$

We have

$$(V(\hat{\sigma}))^{-1} = V(\sigma)^{-1} + O(n^{-q})V(\sigma)^{-1}FV(\sigma)^{-1}.$$

So

$$\hat{p}(x_0) = \{C(\sigma) + O(n^{-p})E\}^{-T} \{V(\sigma) + O(n^{-q})F\}^{-1}\mathbf{z} 
= C(\sigma)^T V(\sigma)^{-1}\mathbf{z} + O(\max(n^{-p}, n^{-q})) 
= p(x_0) + O(n^{-p}).$$

Furthermore, we know the simply kriging predictor  $p(x_0)$  is consistent to  $\sigma(x_0)W(x_0)$  with convergence rate  $O(n^{-1/2})$ . Combine the above two facts, we have

$$\hat{p}(x_0) = \sigma(x_0)W(x_0) + O(\max\{n^{-p}, n^{-1/2}\}).$$

In our consideration, p < 1/2 always holds. So the convergence rate is  $O(n^{-p})$ . Theorem 4 follows.

# S5 Figures from the Simulation Study

# Kriging vs Nonp kernel prediction with variable bandwidth, n=200 True Kriging Madaptive smoothing Smoothing On Smoothing

Figure 1: Plot of prediction and smoothing with  $\sigma_{\epsilon}^2 = 0.1/n$ ; grey= true process  $\sigma(x)W(x)$ , red=kriging, blue=ALPRE, and green=LPRE.

### Kriging vs Nonp kernel prediction with variable bandwidth, n=200

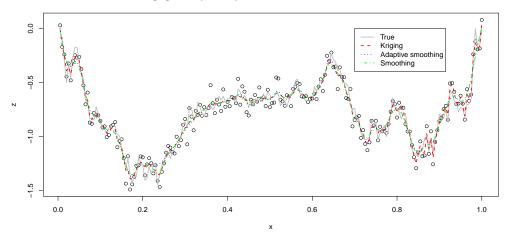


Figure 2: Plot of prediction and smoothing with  $\sigma_{\epsilon}^2=1/n$ , grey=true process  $\sigma(x)W(x)$ , red=kriging, blue=ALPRE, and green=LPRE.

### Kriging vs Nonp kernel prediction with variable bandwidth, n=200

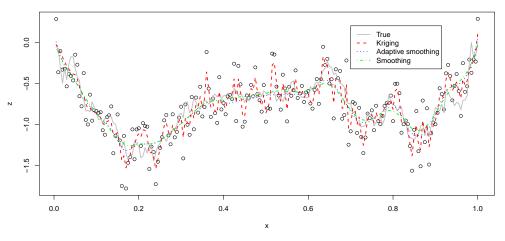


Figure 3: Plot of prediction and smoothing with  $\sigma_{\epsilon}^2=10/n$ , grey= true process  $\sigma(x)W(x)$ , red=kriging, blue=ALPRE, and green=LPRE.