# A STUDY OF VARIABLE BANDWIDTH SELECTION FOR LOCAL POLYNOMIAL REGRESSION 

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#### Abstract

A decisive question in nonparametric smoothing techniques is the choice of the bandwidth or smoothing parameter. The present paper addresses this question when using local polynomial approximations for estimating the regression function and its derivatives. A fully-automatic bandwidth selection procedure has been proposed by Fan and Gijbels (1995a), and the empirical performance of it was tested in detail via a variety of examples. Those experiences supported the methodology towards a great extend. In this paper we establish asymptotic results for the proposed variable bandwidth selector. We provide the rate of convergence of the bandwidth estimate, and obtain the asymptotic distribution of its error relative to the theoretical optimal variable bandwidth. These asymptotic properties give extra support to the proposed bandwidth selection procedure. It is also demonstrated how the proposed selection method can be applied in the density estimation setup. Some examples illustrate this application.


Key words and phrases: Assessment of bias and variance, asymptotic normality, binning, density estimation, local polynomial fitting, variable bandwidth selector.

## 1. Introduction

Primary interest of this paper focuses on exploring the regression relationship between two variables $X$ and $Y$. Various nonparametric techniques can be used to detect the underlying regression structure, but each of them involves the decisive choice of a smoothing parameter or bandwidth. In this paper we discuss how to choose a bandwidth when local polynomial fitting is used. It has been shown extensively in the literature that the local polynomial approximation method has various nice features, among which, nice minimax properties, satisfactory boundary behavior, applicability for a variety of design-situations and easy interpretability. (See, for example, Stone (1977), Cleveland (1979), Fan and Gijbels (1992), Fan (1993) and Ruppert and Wand (1994), among others.)

Assume that the bivariate data $\left(X_{1}, Y_{1}\right), \ldots,\left(X_{n}, Y_{n}\right)$ form an i.i.d. sample from a certain population. The objective is to estimate the regression function $m(x)=E(Y \mid X=x)$ and its derivatives. If the $(p+1)$ th-derivative of $m(x)$ at
the point $x_{0}$ exists, we then approximate $m(x)$ locally by a polynomial of order $p$ :

$$
\begin{equation*}
m(x) \approx m\left(x_{0}\right)+m^{\prime}\left(x_{0}\right)\left(x-x_{0}\right)+\cdots+m^{(p)}\left(x_{0}\right)\left(x-x_{0}\right)^{p} / p! \tag{1.1}
\end{equation*}
$$

for $x$ in a neighborhood of $x_{0}$, and do a local polynomial regression fit

$$
\begin{equation*}
\min _{\beta} \sum_{i=1}^{n}\left(Y_{i}-\sum_{j=0}^{p} \beta_{j}\left(X_{i}-x_{0}\right)^{j}\right)^{2} K\left(\frac{X_{i}-x_{0}}{h}\right), \tag{1.2}
\end{equation*}
$$

where $\beta=\left(\beta_{0}, \ldots, \beta_{p}\right)^{T}$. Here $K(\cdot)$ denotes a nonnegative weight function and $h$ is a smoothing parameter - determining the size of the neighborhood of $x_{0}$. Let $\left\{\hat{\beta}_{\nu}\left(x_{0}\right)\right\}$ denote the solution to the weighted least squares problem (1.2). Then it is obvious from the Taylor expansion in (1.1) that $\nu!\hat{\beta}_{\nu}\left(x_{0}\right)$ estimates $m^{(\nu)}\left(x_{0}\right)$, $\nu=0, \ldots, p$.

For convenience we introduce some matrix notation. Let $\mathbf{W}$ be the diagonal matrix of weights, with entries $W_{i} \equiv K\left(\left(X_{i}-x_{0}\right) / h\right)$. Denote by $\mathbf{X}$ the design matrix whose $(l, j)$ th element is $\left(X_{l}-x_{0}\right)^{j-1}$ and put $\mathbf{y}=\left(Y_{1}, \ldots, Y_{n}\right)^{T}$. Then, the weighted least squares problem (1.2) reads as follows:

$$
\min _{\beta}(\mathbf{y}-\mathbf{X} \beta)^{T} \mathbf{W}(\mathbf{y}-\mathbf{X} \beta)
$$

The solution vector is provided via ordinary least squares and is given by

$$
\begin{equation*}
\hat{\beta}=\left(\mathbf{X}^{T} \mathbf{W} \mathbf{X}\right)^{-1} \mathbf{X}^{T} \mathbf{W} \mathbf{y} \tag{1.3}
\end{equation*}
$$

An important issue for the performance of the estimator $\hat{\beta}_{\nu}\left(x_{0}\right)$ is the choice of the smoothing parameter $h$. A constant bandwidth can be sufficient if the unknown regression function behaves quite smoothly. In other situations a local variable bandwidth (which changes with the location point $x_{0}$ ) is a necessity. The problem of choosing a smoothing parameter has received much attention in the literature. See for example, Müller, Stadtmüller and Schmitt (1987), Vieu (1991), Brockmann, Gasser and Hermann (1993), Jones, Marron and Sheather (1992) and the references therein.

Automatic procedures for selecting constant and local variable bandwidths in local polynomial regression have been developed recently by Fan and Gijbels (1995a). This operable method is different from Fan and Gijbels (1992) in that the bandwidth varies with locations. The basic idea for their procedure is to assess the conditional Mean Squared Error (MSE) of the estimators via deriving good finite sample estimates of this theoretical conditional MSE. (See also Section 2.) The performance of this selection method was investigated in detail via simulation studies. In the present paper we provide further theoretical foundations for
the proposed bandwidth selection rule. More precisely, we establish the rate of convergence of the bandwidth selector as well as the asymptotic distribution of its error relative to the theoretical optimal variable bandwidth. Furthermore, we show how to convert a density estimation problem into a regression problem. This inner connection makes it possible to apply the regression techniques for density estimation. See Wei and Chu (1994) for another way of converting a density estimation problem into a regression problem.

The organization of the paper is as follows. In the next section, we explain briefly the bandwidth selection rule and present the asymptotic results for the estimated optimal bandwidth. In Section 3 we discuss how the bandwidth selection procedure can be applied in density estimation. Some examples illustrate the application in this setup. The last section contains the proofs of the theoretical results established in Section 2.

## 2. Bandwidth Selection Method and Main Results

Let $\hat{\beta}$ be the vector of the local polynomial regression estimates, defined in (1.3). Clearly, its bias and variance, conditionally upon $\underset{\sim}{X}=\left\{X_{1}, \ldots, X_{n}\right\}$, are given by

$$
\begin{align*}
\operatorname{Bias}(\hat{\beta} \mid \underset{\sim}{X}) & =\mathrm{E}(\hat{\beta} \mid \underset{\sim}{X})-\beta=\left(\mathbf{X}^{T} \mathbf{W} \mathbf{X}\right)^{-1} \mathbf{X}^{T} \mathbf{W}(\mathbf{m}-\mathbf{X} \beta), \\
\operatorname{Var}(\hat{\beta} \mid \underset{\sim}{X}) & =\left(\mathbf{X}^{T} \mathbf{W} \mathbf{X}\right)^{-1}\left(\mathbf{X}^{T} \Sigma \mathbf{X}\right)\left(\mathbf{X}^{T} \mathbf{W} \mathbf{X}\right)^{-1}, \tag{2.1}
\end{align*}
$$

with $\mathbf{m}=\left(m\left(X_{1}\right), \ldots, m\left(X_{n}\right)\right)^{T}$, and $\Sigma=\operatorname{diag}\left(K^{2}\left(\left(X_{i}-x_{0}\right) / h\right) \sigma^{2}\left(X_{i}\right)\right)$, where $\sigma^{2}(\cdot)$ denotes the conditional variance of $Y$ given $X$.

Note that the expressions in (2.1) give the exact conditional bias and variance of the local polynomial fit. We next study asymptotic expansions of this bias vector and variance matrix. These expansions serve as a gateway to prove the asymptotic normality of the selected bandwidth. Let $f_{X}(\cdot)$ denote the marginal density of $X$. The following assumptions will be needed.

## Assumptions:

(i) The kernel $K$ is a continuous density function having bounded support;
(ii) $f_{X}\left(x_{0}\right)>0$ and $f_{X}^{\prime \prime}(x)$ is bounded in a neighborhood of $x_{0}$;
(iii) $m^{(p+3)}(\cdot)$ exists and is continuous in a neighborhood of $x_{0}$;
(iv) $\sigma^{2}(\cdot)$ has a bounded second derivative in a neighborhood of $x_{0}$;
(v) $m^{(p+1)}\left(x_{0}\right) \neq 0$ and the kernel $K$ is symmetric.

In the sequel we use the following notations. Let $\mu_{j}=\int u^{j} K(u) d u$ and $\nu_{j}=\int u^{j} K^{2}(u) d u$ and denote

$$
\begin{array}{ll}
S_{p}=\left(\mu_{i+j-2}\right)_{1 \leq i, j \leq(p+1)}, & \tilde{S}_{p}=\left(\mu_{i+j-1}\right)_{1 \leq i, j \leq(p+1)} \\
S_{p}^{*}=\left(\nu_{i+j-2}\right)_{1 \leq i, j \leq(p+1)}, & \tilde{S}_{p}^{*}=\left(\nu_{i+j-1}\right)_{1 \leq i, j \leq(p+1)}
\end{array}
$$

Further, set $c_{p}=\left(\mu_{p+1}, \ldots, \mu_{2 p+1}\right)^{T}$ and $\tilde{c}_{p}=\left(\mu_{p+2}, \ldots, \mu_{2 p+2}\right)^{T}$.
The asymptotic expansions for the conditional bias and variance are provided in the next theorem.

Theorem 1. Under Assumptions (i)-(iv), the bias vector and variance matrix of $\hat{\beta}$ have the following expansions:

$$
\begin{equation*}
\operatorname{Bias}(\hat{\beta} \mid \underset{\sim}{X})=h^{p+1} H^{-1}\left[\beta_{p+1} S_{p}^{-1} c_{p}+h b^{*}\left(x_{0}\right)+O_{P}\left(h^{2}+\frac{1}{\sqrt{n h}}\right)\right] \tag{2.2}
\end{equation*}
$$

and

$$
\begin{equation*}
\operatorname{Var}(\hat{\beta} \mid \underset{\sim}{X})=\frac{\sigma^{2}\left(x_{0}\right)}{f_{X}\left(x_{0}\right) n h} H^{-1}\left[S_{p}^{-1} S_{p}^{*} S_{p}^{-1}+h V^{*}\left(x_{0}\right)+O_{P}\left(h^{2}+\frac{1}{\sqrt{n h}}\right)\right] H^{-1} \tag{2.3}
\end{equation*}
$$

where $H=\operatorname{diag}\left(1, h, \ldots, h^{p}\right)$,

$$
b^{*}\left(x_{0}\right)=\frac{f_{X}^{\prime}\left(x_{0}\right) \beta_{p+1}+\beta_{p+2} f_{X}\left(x_{0}\right)}{f_{X}\left(x_{0}\right)} S_{p}^{-1} \tilde{c}_{p}-\frac{f_{X}^{\prime}\left(x_{0}\right)}{f_{X}\left(x_{0}\right)} \beta_{p+1} S_{p}^{-1} \tilde{S}_{p} S_{p}^{-1} c_{p}
$$

and

$$
\begin{aligned}
V^{*}\left(x_{0}\right)= & \frac{2 \sigma^{\prime}\left(x_{0}\right) f_{X}\left(x_{0}\right)+\sigma\left(x_{0}\right) f_{X}^{\prime}\left(x_{0}\right)}{\sigma\left(x_{0}\right) f_{X}\left(x_{0}\right)} S_{p}^{-1} \tilde{S}_{p}^{*} S_{p}^{-1} \\
& -\frac{f_{X}^{\prime}\left(x_{0}\right)}{f_{X}\left(x_{0}\right)}\left(S_{p}^{-1} \tilde{S}_{p} S_{p}^{-1} S_{p}^{*} S_{p}^{-1}+S_{p}^{-1} S_{p}^{*} S_{p}^{-1} \tilde{S}_{p} S_{p}^{-1}\right) .
\end{aligned}
$$

We would like to mention that the " $O_{P}$-terms" in Theorem 1 hold uniformly in $n^{-b}<h<n^{-a}$ for $0<a<b<1$, if they are replaced by $O_{P}\left(h^{2}+\log n / \sqrt{n h}\right)$. Indeed, this can be shown using the same arguments as in the proof of Theorem 1 and the fact that $\left(n h^{j+1}\right)^{-1} \sum_{i=1}^{n}\left(X_{i}-x_{0}\right)^{j} K\left(\left(X_{i}-x_{0}\right) / h\right)=f_{X}\left(x_{0}\right) \mu_{j}+$ $h f_{X}^{\prime}\left(x_{0}\right) \mu_{j+1}+O_{P}\left(h^{2}+\log n / \sqrt{n h}\right)$, uniformly in $h \in\left[n^{-b}, n^{-a}\right]$.
Remark 1. For a symmetric kernel $K$, we show in the proof of Theorem 2 that the $(\nu+1)$ th-diagonal element of $V^{*}\left(x_{0}\right)$ and the $(\nu+1)$ th-element of $b^{*}\left(x_{0}\right)$ are zero when $p-\nu$ is odd. In other words, if $p-\nu$ is odd, the second leading terms in the expansions of the bias and variance of $\hat{\beta}_{\nu}$ are zero. The requirement for odd $p-\nu$ is natural, since the odd order approximations outperform the even order ones, as demonstrated in Ruppert and Wand (1994) and Fan and Gijbels (1995b).

Based on Theorem 1, we can derive the rate of convergence for bandwidth selection. We need the following simple lemma.

Lemma 1. Suppose that a function $M(h)$ has the following asymptotic expansion:

$$
M(h)=c h^{2(p+1-\nu)}\left(1+O_{P}\left(h^{2}+\frac{\log n}{\sqrt{n h}}\right)\right)+\frac{d}{n h^{2 \nu+1}}\left(1+O_{P}\left(h^{2}+\frac{\log n}{\sqrt{n h}}\right)\right)
$$

uniformly in $h \in\left[n^{-b}, n^{-a}\right]$. Let $h_{\text {opt }}$ be the minimizer of $M(h)$. Then

$$
h_{o p t}=\left(\frac{(2 \nu+1) d}{2(p+1-\nu) c n}\right)^{\frac{1}{2 p+3}}\left(1+O_{P}\left(n^{-\frac{2}{2 p+3}} \log n\right)\right)
$$

and
$M\left(h_{o p t}\right)=c^{1-s} d^{s}(2 p+3)(2 \nu+1)^{-(1-s)}[2(p+1-\nu)]^{-s} n^{-s}\left(1+O_{P}\left(n^{-\frac{2}{2 p+3}} \log n\right)\right)$, with $s=2(p+1-\nu) /(2 p+3)$, provided that $c, d>0$. If further $p>1$, the $\log n$ factor does not have to appear in the " $O_{P}$-terms".

We now study the theoretical optimal variable bandwidth for estimating the $\nu$ th-derivative $m^{(\nu)}\left(x_{0}\right)$. Let

$$
\operatorname{MSE}_{\nu}\left(x_{0}\right)=b_{p, \nu}^{2}\left(x_{0}\right)+V_{p, \nu}\left(x_{0}\right)
$$

where $b_{p, \nu}\left(x_{0}\right)$ and $V_{p, \nu}\left(x_{0}\right)$ are respectively the $(\nu+1)$ th-element of $\operatorname{Bias}(\hat{\beta} \mid \underset{\sim}{X})$ and the $(\nu+1)$ th-diagonal element of $\operatorname{Var}(\hat{\beta} \mid \underset{\sim}{X})$. Define

$$
h_{\nu, o p t}=\arg \min _{h} \operatorname{MSE}_{\nu}\left(x_{0}\right) .
$$

The quantity $\operatorname{MSE}_{\nu}\left(x_{0}\right)$ is, in a sense, an ideal assessment of the conditional MSE of $\hat{\beta}_{\nu}$, and $h_{\nu, o p t}$ is the ideal bandwidth selector.

We have the following expression for this ideal optimal bandwidth.
Theorem 2. Under Assumptions (i)-(v),

$$
\frac{h_{\nu, o p t}-h_{\nu, o}}{h_{\nu, o}}=O_{P}\left(n^{-\frac{2}{2 p+3}} \log n\right)
$$

provided that $p-\nu$ is odd, where, with $e_{\nu+1}$ the $(p+1) \times 1$ unit vector containing 1 on the $(\nu+1)$ th-position,

$$
\begin{equation*}
h_{\nu, o}=\left(\frac{(2 \nu+1) \sigma^{2}\left(x_{0}\right) e_{\nu+1}^{T} S_{p}^{-1} S_{p}^{*} S_{p}^{-1} e_{\nu+1}}{2(p+1-\nu) f_{X}\left(x_{0}\right)\left(\beta_{p+1} e_{\nu+1}^{T} S_{p}^{-1} c_{p}\right)^{2} n}\right)^{\frac{1}{2 p+3}} \tag{2.4}
\end{equation*}
$$

Hence the ideal optimal bandwidth $h_{\nu, \text { opt }}$ behaves in first order like $h_{\nu, o}$, the asymptotical optimal bandwidth.

We next briefly motivate a natural estimator for assessing the bias and the variance in (2.1). Using a Taylor expansion around the point $x_{0}$, we have

$$
\mathbf{m}-\mathbf{X} \beta \approx\left(\beta_{p+1}\left(X_{i}-x_{0}\right)^{p+1}\right)_{1 \leq i \leq n}, \quad \text { and } \quad \sigma\left(X_{i}\right) \approx \sigma\left(x_{0}\right)
$$

Substituting this into (2.1) leads to

$$
\begin{align*}
\operatorname{Bias}(\hat{\beta} \mid \underset{\sim}{X}) & \approx \beta_{p+1} S_{n}^{-1}\left(s_{n, p+1}, \ldots, s_{n, 2 p+1}\right)^{T}, \\
\operatorname{Var}(\hat{\beta} \mid \underset{\sim}{X}) & \approx \sigma\left(x_{0}\right) S_{n}^{-1}\left(\mathbf{X} \mathbf{W}^{2} \mathbf{X}\right) S_{n}^{-1}, \tag{2.5}
\end{align*}
$$

where

$$
s_{n, j}=\sum_{i=1}^{n}\left(X_{i}-x_{0}\right)^{j} K\left(\frac{X_{i}-x_{0}}{h}\right) \text { and } S_{n}=\mathbf{X}^{T} \mathbf{W} \mathbf{X}=\left(s_{n, i+j-2}\right)_{1 \leq i, j \leq(p+1)} .
$$

A natural estimate of the bias and the variance is obtained by estimating $\beta_{p+1}$ and $\sigma^{2}\left(x_{0}\right)$ in (2.5) from another least squares problem.

Let $\beta_{p+1}$ be estimated by using a local polynomial regression of order $r$ $(r>p)$ with a bandwidth $h_{*}$. Further, estimate $\sigma^{2}\left(x_{0}\right)$ by the standardized residual sum of squares:

$$
\hat{\sigma}^{2}\left(x_{0}\right)=\frac{1}{\operatorname{tr}\left(\mathbf{W}^{*}\right)-\operatorname{tr}\left(\left(\mathbf{X}^{* T} \mathbf{W}^{*} \mathbf{X}^{*}\right)^{-1} \mathbf{X}^{*} \mathbf{W}^{* 2} \mathbf{X}^{*}\right)} \sum_{i=1}^{n}\left(Y_{i}-\hat{Y}_{i}\right)^{2} K\left(\frac{X_{i}-x_{0}}{h_{*}}\right)
$$

where $\mathbf{X}^{*}=\left(\left(X_{i}-x_{0}\right)^{j}\right)_{n \times(r+1)}$ is the design matrix, $\mathbf{W}^{*}=\operatorname{diag}\left(K\left(\left(X_{i}-\right.\right.\right.$ $\left.\left.x_{0}\right) / h_{*}\right)$ ) is the matrix of weights and $\hat{\mathbf{y}}=\mathbf{X}^{*}\left(\mathbf{X}^{* T} \mathbf{W} \mathbf{X}^{*}\right)^{-1} \mathbf{X}^{*^{T}} \mathbf{W}^{*} \mathbf{y}$ is the vector of "predicted" values after the local $r$ th-order polynomial fit. The estimated conditional MSE of $\hat{\beta}_{\nu}=\hat{\beta}_{\nu}\left(x_{0}\right)$ is naturally defined by

$$
\widehat{\operatorname{MSE}}_{\nu}\left(x_{0}\right)=\hat{b}_{p, \nu}^{2}\left(x_{0}\right)+\hat{V}_{p, \nu}\left(x_{0}\right)
$$

where $\hat{b}_{p, \nu}\left(x_{0}\right)$ and $\hat{V}_{p, \nu}\left(x_{0}\right)$ are respectively the $(\nu+1)$ th-element of the bias vector and the $(\nu+1)$ th-diagonal element of the variance matrix in (2.5), with $\beta_{p+1}$ and $\sigma\left(x_{0}\right)$ being estimated. More precisely, $\hat{b}_{p, \nu}\left(x_{0}\right)$ refers to the $(\nu+1)$ thelement of $\hat{\beta}_{p+1} S_{n}^{-1}\left(s_{n, p+1}, \ldots, s_{n, 2 p+1}\right)^{T}$ and $\hat{V}_{p, \nu}\left(x_{0}\right)$ is the $(\nu+1)$ th-diagonal element of $\hat{\sigma}^{2}\left(x_{0}\right) S_{n}^{-1}\left(\mathbf{X}^{T} \mathbf{W}^{2} \mathbf{X}\right) S_{n}^{-1}$.

Define the estimated optimal bandwidth as

$$
\hat{h}_{\nu}=\arg \min _{h} \widehat{\operatorname{MSE}}_{\nu}\left(x_{0}\right)
$$

We now study the sampling properties of $\hat{h}_{\nu}$. Using the arguments provided in Theorems 1 and 2 on the set $\left\{\left|\hat{\beta}_{p+1}\right| \leq c,\left|\hat{\sigma}\left(x_{0}\right)\right| \leq c\right\}$, where $c$ is a large constant, we find that

$$
\begin{equation*}
\frac{\hat{h}_{\nu}-\hat{h}_{\nu, o}}{\hat{h}_{\nu, o}}=O_{P}\left(n^{-\frac{2}{2 p+3}} \log n\right), \tag{2.6}
\end{equation*}
$$

where $\hat{h}_{\nu, o}$ is defined similarly as $h_{\nu, o}$ in equation (2.4), but now with $\beta_{p+1}, \sigma^{2}\left(x_{0}\right)$, replaced respectively by $\hat{\beta}_{p+1}, \hat{\sigma}^{2}\left(x_{0}\right)$.

Using equation (2.6) and Theorem 2, we obtain

$$
\frac{\hat{h}_{\nu}-h_{\nu, o p t}}{h_{\nu, o p t}}=\frac{\hat{h}_{\nu, o}-h_{\nu, o}}{h_{\nu, o}}+O_{P}\left(n^{-\frac{2}{2 p+3}} \log n\right) .
$$

If further the estimators $\hat{\beta}_{p+1}$ and $\hat{\sigma}^{2}\left(x_{0}\right)$ are stochastically bounded away from zero and infinity, then we have for the relative error

$$
\begin{equation*}
\frac{\hat{h}_{\nu}-h_{\nu, o p t}}{h_{\nu, o p t}}=\frac{\left(\hat{\sigma}^{2}\left(x_{0}\right) / \sigma^{2}\left(x_{0}\right)\right)^{\frac{1}{2 p+3}}-\left(\hat{\beta}_{p+1}^{2} / \beta_{p+1}^{2}\right)^{\frac{1}{2 p+3}}}{\left(\hat{\beta}_{p+1}^{2} / \beta_{p+1}^{2}\right)^{\frac{1}{2 p+3}}}+O_{P}\left(n^{-\frac{2}{2 p+3}} \log n\right) \tag{2.7}
\end{equation*}
$$

In order to discuss the asymptotic distribution of $\left(\hat{h}_{\nu}-h_{\nu, o p t}\right) / h_{\nu, o p t}$, we make some further assumptions.

## Assumptions:

(vi) $E\left(Y^{4} \mid X=x\right)<\infty$ for $x$ in a neighborhood of $x_{0}$.
(vii) The bandwidth $h_{*}$ satisfies $n^{-\frac{1}{2 p+3}} \ll h_{*} \ll n^{-\frac{2 p-1}{(2 p+3)^{2}}}(\log n)^{-\frac{2}{2 p+3}}$.

Note that $\hat{\sigma}^{2}(x)$ converges to $\sigma^{2}(x)$ much faster than $\hat{\beta}_{p+1}$ to $\beta_{p+1}$. (See the proof of Theorem 3.) Thus, it follows from (2.7) that the behavior of $\hat{\beta}_{p+1}$ dictates that of the relative error. For this reason, we introduce the following notation. Let $\alpha$ be the $(p+2)$ th-element of the vector $S_{r}^{-1} c_{r}$ and $\gamma$ be the $(p+2)$ th-diagonal element of the matrix $S_{r}^{-1} S_{r}^{*} S_{r}^{-1}$. Note that $\alpha$ and $\gamma$ are the constant factors in the asymptotic bias and variance expressions of $\hat{\beta}_{p+1}$ using the local $r$ th-order polynomial regression.

Theorem 3. Suppose that $p-\nu$ is odd. Then, under Assumptions (i) - (vii),

$$
\begin{equation*}
\sqrt{n h_{*}^{2 p+3}}\left(\frac{\hat{h}_{\nu}-h_{\nu, o p t}}{h_{\nu, o p t}}+\frac{2 \alpha \beta_{r+1}}{(2 p+3) \beta_{p+1}} h_{*}^{r-p}\right) \xrightarrow{D} N\left(0, \frac{4 \gamma \sigma^{2}\left(x_{0}\right)}{(2 p+3)^{2} \beta_{p+1}^{2} f_{X}\left(x_{0}\right)}\right) . \tag{2.8}
\end{equation*}
$$

Remark 2. The asymptotic distribution of the relative error is independent of $\nu$. When $r=p+2$ and $h_{*} \sim n^{-1 /(2 r+3)}$, the relative error is of order $O_{P}\left(n^{-2 /(2 r+3)}\right)$. Specifically the relative error is of order $O_{P}\left(n^{-2 / 9}\right)$ when $p=1$.

The above result informs us about the asymptotic behavior of $\hat{h}_{\nu}$ in the case that $m^{(p+1)}\left(x_{0}\right) \neq 0$ (see Assumption (v)). The asymptotic behavior of $\hat{h}_{\nu}$ when $m^{(p+1)}\left(x_{0}\right)=0$ has not been established yet. In order to derive such a result a higher order expansion of the conditional bias of the estimator is needed. Indeed in that case both leading terms in the asymptotic expression for the conditional
bias are zero for $p-\nu$ odd. We do not investigate the selection of $\hat{h}_{\nu}$ when $p-\nu$ is even since, as mentioned before, these polynomial approximations are unfavorable.

To illustrate Theorem 3 let us consider the special case of estimating the regression function ( $\nu=0$ ) using a local linear fit ( $p=1$ ). Taking for example $r=3$ we find, via straightforward calculations, that $\alpha=\left(\mu_{6}-\mu_{2} \mu_{4}\right) /\left(\mu_{4}-\mu_{2}^{2}\right)$ and $\gamma=\left(\mu_{2}^{2} \nu_{0}-2 \mu_{2} \nu_{2}+\nu_{4}\right) /\left(\mu_{4}-\mu_{2}^{2}\right)^{2}$. Then, if the bandwidth $h_{*}$ satisfies $n^{-1 / 5} \ll h_{*} \ll n^{-1 / 25}(\log n)^{-2 / 5}$, Theorem 3 provides the following asymptotic normality result for $\hat{h}_{0}$ :

$$
\sqrt{n h_{*}^{5}}\left(\frac{\hat{h}_{0}-h_{0, o p t}}{h_{0, o p t}}+\frac{\alpha m^{(4)}\left(x_{0}\right)}{30 m^{\prime \prime}\left(x_{0}\right)} h_{*}^{2}\right) \xrightarrow{D} N\left(0, \frac{16 \gamma \sigma^{2}\left(x_{0}\right)}{25\left(m^{\prime \prime}\left(x_{0}\right)\right)^{2} f_{X}\left(x_{0}\right)}\right) .
$$

A data-driven procedure for choosing $h_{*}$ is provided in Fan and Gijbels (1995a) via a RSC (Residual Sum of Squares)-criterion. See that paper for the criterion, as well as its implementation. There the reader can also find simulation studies illustrating the behavior of the relative error $\left(\hat{h}_{\nu}-h_{\nu, o p t}\right) / h_{\nu, o p t}$.

## 3. Application to Density Estimation

The bandwidth selection procedure for the regression problem can also be applied to the density estimation setup. Let $X_{1}, \ldots, X_{n}$ be independent identically distributed random variables. The interest is to estimate the common density $f(x)$ and its derivatives on an interval $[a, b]$. Partition the interval $[a, b]$ into $N$ subintervals $\left\{I_{k}, k=1, \ldots, N\right\}$. Let $x_{k}$ be the center of $I_{k}$ and $y_{k}$ be the proportion of data $\left\{X_{i}, i=1, \ldots, n\right\}$, falling in the partition $I_{k}$, divided by the bin length. Then, we use a local polynomial of order $p$ to fit the data $\left\{\left(x_{k}, y_{k}\right), k=1, \ldots, N\right\}$. Let $\hat{\beta}_{0}, \ldots, \hat{\beta}_{p}$ be the solution of the local polynomial regression problem:

$$
\sum_{k=1}^{N}\left(y_{k}-\sum_{j=0}^{p} \beta_{j}\left(x_{k}-x\right)^{j}\right)^{2} K\left(\frac{x_{k}-x}{h}\right) .
$$

Then, the estimator for the $\nu$ th derivative is $\hat{f}^{(\nu)}(x)=\nu!\hat{\beta}_{\nu}$.
In order to have the same asymptotic properties for $\hat{f}^{(\nu)}(x)$ as those available for the kernel density estimator, we require that $N h \longrightarrow \infty$ (see Cheng, Fan, and Marron (1993)). Now, the bandwidth selection procedure discussed in the previous section can also be applied to this setting. We would expect the resulting bandwidth selector to have the following property (compare with (2.8)):

$$
\begin{aligned}
& \sqrt{n h_{*}^{2 p+3}}\left(\frac{\hat{h}_{\nu}-h_{\nu, o p t}}{h_{\nu, o p t}}+\frac{2 \alpha(p+1)!f^{(r+1)}(x)}{(2 p+3)(r+1)!f^{(p+1)}(x)} h_{*}^{r-p}\right) \\
& \xrightarrow{D} N\left(0, \frac{4 \gamma}{(2 p+3)^{2}\left(f^{(p+1)}(x) /(p+1)!\right)^{2}}\right) .
\end{aligned}
$$

We now illustrate the data-driven density estimation procedure via four simulated examples. These four densities were chosen from the 15 normal mixture densities discussed in Marron and Wand (1992). They were recommended by J.S. Marron in a private conversation, on the grounds that they range from densities easy to estimate to densities very hard to estimate. In the implementation, we took $N=n / 4$ and used Anscombe's (1948) variance-stabilizing transformation to the bin count $c_{k}=n y_{k} \times \operatorname{length}\left(I_{k}\right): y_{k}^{*}=2\left(c_{k}+3 / 8\right)^{1 / 2}$.

Let $\hat{\beta}_{0}^{*}$ be the local linear regression smoother for the transformed data. Then the density estimator is obtained by considering the inverse of Anscombe's transformation:

$$
\hat{f}(x)=C\left(\frac{\left(\hat{\beta}_{0}^{*}(x)\right)^{2}}{4}-\frac{3}{8}\right)_{+}
$$

where the constant $C$ is a normalization constant such that $\hat{f}(x)$ has area 1 . This transformation step stabilized our simulation results somewhat, but did not result in a significant improvement. The variable bandwidth is, as described above, selected by using the techniques developed in Fan and Gijbels (1995) for the regression setup. Another possible, but more complicated, way of converting the density estimation problem into a regression problem is given in Wei and Chu (1994). We have no intention to recommend that the scientific community use regression techniques for density estimation. Here, we only point out the inner connection between nonparametric regression and density estimation. This connection indicates that nonparametric regression techniques such as data-driven bandwidth selection are also available for density estimation.

The four simulated examples concern a Gaussian density, a Strongly Skewed density, a Separated Bimodal density and a Smooth Comb density. These correspond with Densities \#1, \#3, \#7 and \#14 respectively in Marron and Wand (1992). For each of the simulated examples we used the Epanechnikov kernel and estimated the density using a local linear regression, based on samples of size 200 and 800 . The number of simulations was 400 . For each estimated curve we calculated the Average Squared Error over all grid points in which the curve was evaluated. We then ranked the 400 estimated curves according to this global measure. As representatives of all estimated curves we took the curves corresponding to the 10 th $\%$, the 50 th\% and the 90 th\% among those rank-observations. Each of the presented pictures contains the true density function (the solid line) and three typical estimated curves (other line types).


Figure 1.1. Ex 1: Estimated curves, $n=200$


Figure 2.1. Ex 2: Estimated curves, $n=200$


Figure 3.1. Ex 3: Estimated curves, $n=200$


Figure 1.2. Ex 1: Estimated curves, $n=800$


Figure 2.2. Ex 2: Estimated curves, $n=800$


Figure 3.2. Ex 3: Estimated curves, $n=800$


Figures 1-4: True densities (solid curve) and three typical estimated curves (dashed lines), based on $n=200, n=800$ respectively.

The Gaussian density in Example 1 and the Separated Bimodal density in Example 3 are easiest to estimate, and hence estimates based on samples of size 200 show a good performance. The densities in Examples 2 and 4 (i.e. the Strongly Skewed density and the Smooth Comb density) form a more difficult task. Estimates based on samples of size 200 do not succeed in capturing the sharp peaks appearing in the densities. Samples of size 800 result in better estimated curves.

## 4. Proofs

Proof of Theorem 1. Recall the notation after equation (2.5). We first remark that

$$
\begin{equation*}
s_{n, j}=n h^{j+1}\left(f_{X}\left(x_{0}\right) \mu_{j}+h f_{X}^{\prime}\left(x_{0}\right) \mu_{j+1}+O_{P}\left(a_{n}\right)\right) \tag{4.1}
\end{equation*}
$$

where $a_{n}=h^{2}+1 / \sqrt{n h}$. Thus

$$
\begin{equation*}
S_{n}=n h H\left(f_{X}\left(x_{0}\right) S_{p}+h f_{X}^{\prime}\left(x_{0}\right) \tilde{S}_{p}+O_{P}\left(a_{n}\right)\right) H \tag{4.2}
\end{equation*}
$$

It follows from equation (2.1) and Taylor's expansion that

$$
\begin{equation*}
\operatorname{Bias}(\hat{\beta} \mid \underset{\sim}{X})=S_{n}^{-1}\left(\beta_{p+1} c_{n}+\beta_{p+2} \tilde{c}_{n}+O_{P}\left(n h^{p+4}\right)\right) \tag{4.3}
\end{equation*}
$$

where $c_{n}=\left(s_{n, p+1}, \ldots, s_{n, 2 p+1}\right)^{T}$ and $\tilde{c}_{n}=\left(s_{n, p+2}, \ldots, s_{n, 2 p+2}\right)^{T}$. Combining Equations (4.2) and (4.3) and using the fact that

$$
\begin{equation*}
(A+h B)^{-1}=A^{-1}-h A^{-1} B A^{-1}+O\left(h^{2}\right) \tag{4.4}
\end{equation*}
$$

we obtain the bias expression (2.2) via some simple algebra.
For the variance matrix note from (2.1) that

$$
\begin{equation*}
\operatorname{Var}(\hat{\beta} \mid X \underset{\sim}{X})=S_{n}^{-1} S_{n}^{*} S_{n}^{-1}, \tag{4.5}
\end{equation*}
$$

where $S_{n}^{*}=\left(s_{n, i+j-2}^{*}\right)_{1 \leq i, j \leq(p+1)}$, with $s_{n, j}^{*}=\sum_{i=1}^{n}\left(X_{i}-x_{0}\right)^{j} K^{2}\left(\frac{X_{i-x_{0}}}{h}\right) \sigma^{2}\left(X_{i}\right)$. Following similar arguments as in (4.1) we find that,

$$
\begin{equation*}
s_{n, j}^{*}=n h^{j+1}\left(g\left(x_{0}\right) \nu_{j}+h g^{\prime}\left(x_{0}\right) \nu_{j+1}+O_{P}\left(a_{n}\right)\right), \tag{4.6}
\end{equation*}
$$

where $g\left(x_{0}\right)=f_{X}\left(x_{0}\right) \sigma^{2}\left(x_{0}\right)$. From (4.5), (4.6) and (4.2) we obtain

$$
\begin{aligned}
\operatorname{Var}(\hat{\beta} \mid \underset{\sim}{X})= & \frac{n h g\left(x_{0}\right)}{\left(f_{X}\left(x_{0}\right) n h\right)^{2}} H^{-1}\left(S_{p}+\frac{h f_{X}^{\prime}\left(x_{0}\right)}{f_{X}\left(x_{0}\right)} \tilde{S}_{p}+O_{P}\left(a_{n}\right)\right)^{-1} \\
& \times\left(S_{p}^{*}+h \frac{g^{\prime}\left(x_{0}\right)}{g\left(x_{0}\right)} \tilde{S}_{p}^{*}+O_{P}\left(a_{n}\right)\right)\left(S_{p}+\frac{h f_{X}^{\prime}\left(x_{0}\right)}{f_{X}\left(x_{0}\right)} \tilde{S}_{p}+O_{P}\left(a_{n}\right)\right)^{-1} H^{-1}
\end{aligned}
$$

The conclusion in (2.3) now follows from equation (4.4) and some simple algebra.
Proof of Theorem 2. Since the kernel $K$ is symmetric, $\mu_{2 j+1}=0$, for $j=$ $0,1, \ldots,(p+1)$. Thus, the matrix $S_{p}=\left(\mu_{i+j-2}\right)_{1 \leq i, j \leq(p+1)}$ has the following structure:

$$
S_{p}=\left(\begin{array}{ccccc}
\times & 0 & \times & 0 & \ldots \\
0 & \times & 0 & \times & \ldots \\
\times & 0 & \times & 0 & \ldots \\
\vdots & \vdots & \vdots & \vdots & \ddots
\end{array}\right)
$$

where " $\times$ " denotes any number. It can be shown that $S_{p}^{-1}$ will have exactly the same structure as $S_{p}$, by examining the determinant of the accompanying submatrix: this submatrix contains $[(p+1) / 2]$ rows which each have at most $[(p+1) / 2]-1$ nonzero elements. Thus, these rows are linearly dependent and the determinant of the accompanying submatrix must be zero. Therefore, each odd-position (e.g. (3,4))-element is zero. Similar arguments hold for the matrix

$$
\tilde{S}_{p}=\left(\mu_{i+j-1}\right)_{1 \leq i, j \leq(p+1)}=\left(\begin{array}{ccccc}
0 & \times & 0 & \times & \ldots \\
\times & 0 & \times & 0 & \ldots \\
0 & \times & 0 & \times & \ldots \\
\vdots & \vdots & \vdots & \vdots & \ddots
\end{array}\right)
$$

Using the sparsity structure of the matrices $S_{p}$ and $\tilde{S}_{p}$, and of $c_{p}$ and $\tilde{c}_{p}$, we can see that the $(\nu+1)$ th-element of $S_{p}^{-1} \tilde{c}_{p}$ and of $S_{p}^{-1} \tilde{S}_{p} S_{p}^{-1} c_{p}$ are zero. Thus by Theorem 1 and the remarks after it,

$$
\begin{equation*}
b_{p, \nu}\left(x_{0}\right)=\beta_{p+1} h^{p+1-\nu} e_{\nu+1}^{T} S_{p}^{-1} c_{p}\left(1+O_{P}\left(h^{2}+\frac{\log n}{\sqrt{n h}}\right)\right), \tag{4.7}
\end{equation*}
$$

uniformly in $h \in\left[n^{-a}, n^{-b}\right]$. A similar argument shows that the $(\nu+1)$ th-diagonal element of $V^{*}\left(x_{0}\right)$ in Theorem 1 is zero. Therefore, by Theorem 1 ,

$$
\begin{equation*}
V_{p, \nu}\left(x_{0}\right)=\frac{\sigma^{2}\left(x_{0}\right)}{f_{X}\left(x_{0}\right) n h} h^{-2 \nu} e_{\nu+1}^{T} S_{p}^{-1} S_{p}^{*} S_{p}^{-1} e_{\nu+1}\left(1+O_{P}\left(h^{2}+\frac{\log n}{\sqrt{n h}}\right)\right) . \tag{4.8}
\end{equation*}
$$

Combining equations (4.7) and (4.8) and using Lemma 1 , we obtain the result.
Proof of Theorem 3. By Theorem 1 of Fan and Gijbels (1995a),

$$
E\left(\hat{\sigma}^{2}\left(x_{0}\right) \mid \underset{\sim}{X}\right)=\sigma^{2}\left(x_{0}\right)+O_{P}\left(h_{*}^{2(r+1)}\right),
$$

and it can be shown that

$$
\operatorname{Var}\left(\hat{\sigma}^{2}\left(x_{0}\right) \mid \underset{\sim}{X}\right)=O_{P}\left(\frac{1}{n h_{*}}\right) .
$$

Thus, using Assumption (vii), we obtain

$$
\hat{\sigma}^{2}\left(x_{0}\right)=\sigma^{2}\left(x_{0}\right)+O_{P}\left(h_{*}^{2(r+1)}+\frac{1}{\sqrt{n h_{*}}}\right)=\sigma^{2}\left(x_{0}\right)+o_{P}\left(\left(n h_{*}^{2 p+3}\right)^{-\frac{1}{2}}\right),
$$

and hence

$$
\left(\frac{\hat{\sigma}^{2}\left(x_{0}\right)}{\sigma^{2}\left(x_{0}\right)}\right)^{\frac{1}{2 p+3}}=1+o_{P}\left(\left(n h_{*}^{2 p+3}\right)^{-\frac{1}{2}}\right) .
$$

Now, by Theorem 1 of Fan, Heckman and Wand (1995),

$$
\begin{equation*}
\left\{\frac{n h_{*}^{2 p+3}}{\gamma \sigma^{2}\left(x_{0}\right) / f_{X}\left(x_{0}\right)}\right\}^{1 / 2}\left(\hat{\beta}_{p+1}-\beta_{p+1}-\alpha \beta_{r+1} h_{*}^{r-p}\right) \xrightarrow{D} N(0,1) . \tag{4.9}
\end{equation*}
$$

Note that equation (4.9) can also be proved directly by checking Lindeberg's condition. Evidently,

$$
\left(\frac{\hat{\beta}_{p+1}}{\beta_{p+1}}\right)^{\frac{2}{2 p+3}}=1+\frac{2\left(\hat{\beta}_{p+1}-\beta_{p+1}\right)}{(2 p+3) \beta_{p+1}}+O_{P}\left(\left(\hat{\beta}_{p+1}-\beta_{p+1}\right)^{2}\right) .
$$

Therefore,

$$
\begin{array}{r}
\left\{\frac{n h_{*}^{2 p+3}}{\gamma \sigma^{2}\left(x_{0}\right) / f_{X}\left(x_{0}\right)}\right\}^{1 / 2}\left(\left(\frac{\hat{\beta}_{p+1}}{\beta_{p+1}}\right)^{\frac{2}{2 p+3}}-1-\frac{2 \alpha \beta_{r+1}}{(2 p+3) \beta_{p+1}} h_{*}^{r-p}\right) \\
\xrightarrow{D} N\left(0,\left(\frac{2}{(2 p+3) \beta_{p+1}}\right)^{2}\right)
\end{array}
$$

Hence, it follows from (2.7) that

$$
\begin{array}{r}
\left\{\frac{n h_{*}^{2 p+3}}{\gamma \sigma^{2}\left(x_{0}\right) / f_{X}\left(x_{0}\right)}\right\}^{1 / 2}\left(\frac{\hat{h}_{\nu}-h_{\nu, o p t}}{h_{\nu, o p t}}+\frac{2 \alpha \beta_{r+1}}{(2 p+3) \beta_{p+1}} h_{*}^{r-p}\right) \\
\xrightarrow{D} N\left(0,\left(\frac{2}{(2 p+3) \beta_{p+1}}\right)^{2}\right),
\end{array}
$$

which completes the proof.

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