# ORTHOGONAL-MAXIMIN LATIN HYPERCUBE DESIGNS 

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#### Abstract

A randomly generated Latin hypercube design (LHD) can be quite structured: the variables may be highly correlated or the design may not have good space-filling properties. There are procedures for finding good LHDs by minimizing the pairwise correlations or by maximizing the inter-site distances. In this article we show that these two criteria need not be in close agreement. We propose a multi-objective optimization approach to find good LHDs by combining correlation and distance performance measures. We also propose a new exchange algorithm for efficiently generating such designs. Several examples are presented to show that the new algorithm is fast, and that the optimal designs are good in terms of both the correlation and distance criteria.


Key words and phrases: Computer experiments, Kriging, multi-objective optimization, simulated annealing.

## 1. Introduction

Computer experiments are widely used for the design and development of products (for examples, see Fang. Li and Sudiianto (2006)). In computer experiments, instead of physically doing an experiment on the product, mathematical models describing the performance of the product are developed using engineering/physics laws and solved on computers through numerical methods such as the finite element method. Because deterministic models are used for experiments, the output of a computer experiment is not subject to random variations, which makes the design of computer experiments different from that of physical experiments (see Sacks et al. (1989)). For example, replication is not required. In fact, it is desirable to avoid replicates when projecting the design onto a subset of factors. This is because relatively few factors in the system usually dominate the performance of the product (this is known as effect sparsity). Thus a good model can be fitted using only these few important factors, and when we project the design onto these factors, replication is not required. This is acknowledged by Latin Hypercube Designs (LHD) (McKay. Beckman and Conover (1979)). Since a LHD has the property that by projecting an $n$-point design onto any factor, one gets $n$ different levels for that factor.

Suppose the $n$ levels of a factor are denoted by $1, \ldots, n$. Figure 1a shows a LHD with two factors in six points. In general, a $n$-run LHD can be generated
using a random permutation of $\{1, \ldots, n\}$ for each factor. Each permutation leads to a different LHD. For $k$ factors, we can thus obtain $(n!)^{k}$ LHDs. Figure 1 b shows a LHD that is clearly not a good design. It is poor for two reasons. First, the two factors are perfectly correlated; we are not able to distinguish between the effects of the two factors based on this experiment. Second, there is a large area in the experimental region that is not explored; if we use such a design to develop a prediction model, then the prediction cannot be expected to do well in these areas.


Figure 1. LHDs.
There has been some work in the literature to avoid the above problems and obtain a "good" LHD. The idea is to find the "best" design by optimizing a criterion that describes a "desirable" property. Iman and Conover (1982), Owen (1994) and Tang (1998) proposed to find designs minimizing the correlations among factors. Figure 1c shows the optimal LHD found by the procedure in Tang (1998), one that is clearly much better than those in Figure 1a and 1b. As discussed before, apart from the correlations we are also interested in spreading the points out across the experimental region. This is the idea behind spacefilling designs. Morris and Mitchell (1995) proposed to find the best LHD by maximizing the minimum distance between the points. The optimal LHD under this criterion is shown in Figure 1d. Other approaches to find good LHDs are given by Owen (1994), Tang (1993), Park (1994), Ye (1998), Ye. Li and Sudjianto (2000) and Jin. Chen and Sudiianto (2005).

The minimum pairwise correlation between the factors and the maximum distance between the points are both good criteria for finding optimal LHDs. Intuitively, minimizing correlation should spread out the points and maximizing


Figure 2. Maximin rank vs correlation in $n=6, k=2$ case.


Figure 3. LHDs with $n=6$ and $k=2$. (a) correlation $=0.714$, maximin rank $=11$. (b) correlation $=0.086$, maximin rank $=80$.
the distance between the points should reduce the correlation. But in reality, there is no one-to-one relationship between the two, and designs obtained by these two criteria can be quite different. To illustrate this, consider again a LHD with six points and two factors. There are a total of $(6!)^{2}=518,400$ LHDs. The designs can be ranked based on the maximin distance criterion (Morris and Mitchell (1995)), where rank 1 is assigned to the best design. These are plotted in Figure 2 against absolute values of correlations (there are a total of 113 different combinations of correlations and maximin ranks in this example). We can see that the points are highly scattered showing that the minimization of one criterion may not lead to the minimization of the other criterion (see Figure 3 for an example.) The problem becomes more serious as the number of points or the number of factors is increased. This motivates us to develop a multiobjective criterion that minimizes the pairwise correlations as well as maximizes the inter-site distances.

Because of the huge combinatorial nature of the problem, finding the optimal LHD is a very difficult task. Several algorithms such as simulated anneal-
ing Morris and Mitchell (1995)), columnwise-pairwise algorithms Ye, Li, and Sudjianto (2000)), enhanced stochastic evolutionary algorithms (Jin, Chen, and Sudjianto (2005)), etc., are proposed in the literature for finding the optimal LHD. Most of the algorithms use an exchange method for searching in the design space. For example, in the algorithm proposed by Morris and Mitchell, a column in the design is randomly selected and two randomly chosen elements within that column are exchanged to find a new design. We note that the columns in the design matrix correspond to the experimental factors and thus we can choose them deterministically to reduce the pairwise correlations. Similarly, the rows in the design matrix correspond to the points in the experimental region and thus the elements can be chosen to maximize the inter-site distances. These observations lead to a new algorithm, which is highly suitable for finding the optimum based on our multi-objective criterion.

The article is organized as follows. In Section 2, performance measures for evaluating the goodness of an LHD with respect to pairwise correlations and inter-site distances are described. In Section 3, we propose a multi-objective criterion combining the two performance measures. In Section 4, we propose a new algorithm for generating optimal designs. Several examples are presented in Section 5, and a statistical justification for the new criterion is given in Section 6.

## 2. Performance Measures

Iman and Conover (1982), Owen (1994) and Tang (1998) proposed to choose designs by minimizing correlations among factors within the class of LHDs. We use the performance measure proposed by Owen for evaluating the goodness of the LHD with respect to pairwise correlations. It is defined as

$$
\begin{equation*}
\rho^{2}=\frac{\sum_{i=2}^{k} \sum_{j=1}^{i-1} \rho_{i j}^{2}}{k(k-1) 2^{-1}} \tag{1}
\end{equation*}
$$

where $\rho_{i j}$ is the linear correlation between columns $i$ and $j$.
Now we discuss a performance measure based on the inter-site distances. Let $\boldsymbol{X}$ be the design, which is an $n \times k$ matrix. Let $\boldsymbol{s}$ and $\boldsymbol{t}$ be any two design points (or sites). Consider the distance measure $d(\boldsymbol{s}, \boldsymbol{t})=\left\{\sum_{j=1}^{k}\left|s_{j}-t_{j}\right|^{p}\right\}^{1 / p}$, in which $p=$ 1 and $p=2$ correspond to the rectangular and Euclidean distances respectively. Johnson. Moore and Ylvisaker (1990) proposed the maximin distance criterion, which maximizes the minimum inter-site distance. Morris and Mitchell (1995) applied this criterion to the class of LHDs to find the optimal LHD. Because there are many designs that maximize the minimum inter-site distance, they proposed an extended definition of the maximin criterion. For a given LHD, define a distance list $\left(D_{1}, \ldots, D_{m}\right)$ in which the elements are the distinct values of intersite distances, sorted from the smallest to the largest. Hence $m \leq\binom{ n}{2}$. Let $J_{i}$ be
the number of pairs of sites in the design separated by $D_{i}$. Then a design $\boldsymbol{X}$ is called a maximin design if it sequentially maximizes $D_{i}$ 's and minimizes $J_{i}$ 's in the following order: $D_{1}, J_{1}, D_{2}, J_{2}, \ldots, D_{m}, J_{m}$. Morris and Mitchell (1995) then proposed a scalar-valued function which can be used to rank competing designs in such a way that the maximin design received the highest ranking. The family of functions indexed by $p$ is given by

$$
\begin{equation*}
\phi_{p}=\left(\sum_{i=1}^{m} J_{i} D_{i}^{-p}\right)^{\frac{1}{p}} \tag{2}
\end{equation*}
$$

where $p$ is a positive integer. Then for large enough $p$, the design that minimizes $\phi_{p}$ will be a maximin design. In the next section we propose a new criterion which combines the performance measures in (11) and (2).

## 3. Multi-Objective Criterion

Our objective is to find an LHD that minimizes both $\rho^{2}$ and $\phi_{p}$. A common approach in multi-objective optimization is to optimize a weighted average of all the objective functions. Therefore consider the objective function

$$
w_{1} \rho^{2}+w_{2} \phi_{p}
$$

where $w_{1}$ and $w_{2}$ are some pre-specified positive weights. Because the two objectives are very different, it is not easy to choose appropriate weights. Moreover, the two objectives have different scales. The objective function $\rho^{2} \in[0,1]$, whereas the objective function $\phi_{p}$ can be larger than 1 . If we scale $\phi_{p}$ to $[0,1]$, then we might be able to assign some reasonable weights. In order to do this, we need to find an upper and lower bound for $\phi_{p}$.

Consider a LHD with $n$ points and $k$ factors, denoted by $\operatorname{LHD}(n, k)$. Suppose each factor takes values in $\{1, \ldots, n\}$. Let $d_{1}, d_{2}, \ldots, d_{\left(\frac{n}{2}\right)}$ be the intersite distances among the $n$ points based on the rectangular distance measure $d(\boldsymbol{s}, \boldsymbol{t})=\sum_{j=1}^{k}\left|s_{j}-t_{j}\right|$. We use the following two results for deriving bounds for $\phi_{p}$. All proofs are given in the Appendix.
Lemma 1. For a $\operatorname{LHD}(n, k)$, the average inter-site distance (rectangular measure) is $\bar{d}=(n+1) k / 3$.
Lemma 2. Consider a set of positive values $\left\{d_{j 1}, d_{j 2}, \ldots, d_{j m}\right\}$ and write $d_{j(1)} \leq$ $d_{j(2)} \leq \cdots \leq d_{j(m)}$ for $j=1, \ldots, k$. Then

$$
\sum_{i=1}^{m} \frac{1}{\sum_{j=1}^{k} d_{j i}} \leq \sum_{i=1}^{m} \frac{1}{\sum_{j=1}^{k} d_{j(i)}}
$$

As an interesting consequence of Lemma 1, note that the last step in the definition of maximin criterion cannot be applied to a LHD, because $D_{m}$ is determined by $D_{1}, \ldots, D_{m-1}$. Therefore, one could define the objective function for the distances as $\left(\sum_{i=1}^{m-1} J_{i} D_{i}^{-p}\right)^{1 / p}$. We choose to use (2) because it has a computationally simpler form (Jin. Chen and Sudiianto (2005)). In particular,

$$
\phi_{p}=\left(\sum_{i=1}^{\left(\frac{n}{2}\right)} \frac{1}{d_{i}^{p}}\right)^{\frac{1}{p}},
$$

which can be easily calculated without ordering the $d_{i}$ 's.
Let

$$
\left.\phi_{p, L}=\left\{\begin{array}{c}
n \\
2
\end{array}\right)\left(\frac{\lceil\bar{d}\rceil-\bar{d}}{\lfloor\bar{d}\rfloor^{p}}+\frac{\bar{d}-\lfloor\bar{d}\rfloor}{\lceil\bar{d}\rceil^{p}}\right)\right\}^{\frac{1}{p}} \text { and } \phi_{p, U}=\left\{\sum_{i=1}^{n-1} \frac{(n-i)}{(i k)^{p}}\right\}^{\frac{1}{p}},
$$

where $\lfloor x\rfloor$ is the largest integer $\leq x$ and $\lceil x\rceil$ is the smallest integer $>x$.
Proposition 1. For a $\operatorname{LHD}(n, k), \phi_{p, L} \leq \phi_{p} \leq \phi_{p, U}$.
It is easy to see that the upper bound is achieved when all of the factors are equal. Thus the worst design in terms of $\phi_{p}$ is the same as the worst design in terms of $\rho$. However, there may not exist a design that achieves the lower bound.

Adjusting for range, our new criterion is to minimize

$$
\psi_{p}=w \rho^{2}+(1-w) \frac{\phi_{p}-\phi_{p, L}}{\phi_{p, U}-\phi_{p, L}},
$$

where $w \in(0,1)$. We call a design that minimizes $\psi_{p}$ as an orthogonal-maximin Latin hypercube design (OMLHD). In the next section we propose a new algorithm for finding an OMLHD.

## 4. A New Algorithm

Morris and Mitchell (1995) proposed a version of the simulated annealing algorithm for optimizing $\phi_{p}$. We call their algorithm MMA. In MMA, the search begins with a randomly chosen LHD, and proceeds through the examination of a sequence of designs, each generated as a perturbation of the preceding one. A perturbation $\boldsymbol{X}_{\text {try }}$ of a design $\boldsymbol{X}$ is generated by interchanging two randomly chosen elements within a randomly chosen column in $\boldsymbol{X}$. The perturbation $\boldsymbol{X}_{\text {try }}$ replaces $\boldsymbol{X}$ if it leads to an improvement. Otherwise, it will replace $\boldsymbol{X}$ with probability $\pi=\exp \left\{-\left[\phi_{p}\left(\boldsymbol{X}_{\text {try }}\right)-\phi_{p}(\boldsymbol{X})\right] / t\right\}$, where $t$ is a preset parameter known as "temperature".

We propose a modification of the above algorithm. Instead of randomly choosing a column and two elements within that column, we choose them judiciously in order to achieve improvement in our multi-objective function. Suppose at some stage of the iterations, a column is almost orthogonal to the other columns. Then clearly, we will not gain much in perturbing this column and it is better to choose a column that is highly correlated with the other columns, because a perturbation here may reduce the correlation, thereby improving our objective function. Similarly, if a point is far from the other points, there is no need to perturb the elements in that row. Instead, we can choose a point that is close to the other points and perturb the elements in the chosen column. This may increase the distance of the point from the others, thereby improving our objective function. For doing this, at each step, compute measures of correlation and distance as

$$
\begin{equation*}
\rho_{l}^{2}=\frac{1}{k-1} \sum_{j \neq l} \rho_{l j}^{2} \tag{3}
\end{equation*}
$$

for each column $l=1, \ldots, k$ and

$$
\begin{equation*}
\phi_{p i}=\left(\sum_{j \neq i} \frac{1}{i_{i j}^{p}}\right)^{\frac{1}{p}} \tag{4}
\end{equation*}
$$

for each row $i=1, \ldots, n$, where $\rho_{l j}$ is the correlation between columns $l$ and $j$; and $d_{i j}$ is the distance between the rows $i$ and $j$. For exchanging the elements, we choose a column with high probability that is highly correlated with the other columns. Similarly, we choose a row with high probability that is closest to the other rows. Specifically, choose column

$$
l^{*}=l \text { with probability } P(l)=\frac{\rho_{l}^{\alpha}}{\sum_{l=1}^{k} \rho_{l}^{\alpha}},
$$

and row

$$
i^{*}=i \text { with probability } P(i)=\frac{\phi_{p i}^{\alpha}}{\sum_{i=1}^{n} \phi_{p i}^{\alpha}},
$$

with $\alpha \in[1, \infty)$. Now exchange $x_{i^{*} l^{*}}$ with a randomly chosen element $x_{i^{\prime} l^{*}}$. This gives us the new design $\boldsymbol{X}_{\text {try }}$. If $\psi_{p}\left(\boldsymbol{X}_{t r y}\right)<\psi_{p}(\boldsymbol{X})$, then we replace $\boldsymbol{X}$ by $\boldsymbol{X}_{t r y}$, otherwise we replace it with probability $\pi=\exp \left\{-\left[\psi_{p}\left(\boldsymbol{X}_{t r y}\right)-\psi_{p}(\boldsymbol{X})\right] / t\right\}$.

All the parameters in the new algorithm are set the same as that used in a standard simulated annealing algorithm for which the convergence is already established (Lundy and Mees (1986)). Therefore the new algorithm will also converge to the global optimum. A limiting case of the algorithm is interesting. When $\alpha \rightarrow \infty$, the exchange rule becomes deterministic, given by
$l^{*}=\arg \max _{l} \rho_{l}^{2}$ and $i^{*}=\arg \max _{i} \phi_{p i}$. Under this rule, the transition probability matrix for moving from one design to another design can be reducible, violating one of the conditions required for convergence. But our simulations, given in the next section, show that the convergence is faster with the above modification. Therefore, we recommend it for use in practice.

Because the objective function is evaluated at each iteration of the algorithm, it is important to have a computationally efficient implementation of the objective function (see Jin. Chen and Sudiianto (2005)). Instead of calculating $\rho_{l}^{2}$ and $\phi_{p i}$ using (3) and (4), we can use the following iterative formulas. Let $\left(\rho_{l}^{2}\right)^{(s)}$ and $\phi_{p}^{(s)}$ denote the values of $\rho_{l}^{2}$ and $\phi_{p}$ at the iteration step $s$. Then at step $(s+1)$

$$
\phi_{p i}^{(s+1)}= \begin{cases}\left(\sum_{j \neq i} \frac{1}{\left(d_{i j}^{(s+1)}\right)^{p}}\right)^{\frac{1}{p}}, & i=i^{\prime}, i^{*} \\ \left(\left(\phi_{p i}^{(s)}\right)^{p}-\left(d_{i^{*} i}^{(s)}\right)^{-p}-\left(d_{i^{\prime} i}^{(s)}\right)^{-p}+\left(d_{i^{*} i}^{(s+1)}\right)^{-p}+\left(d_{i^{\prime} i}^{(s+1)}\right)^{-p}\right)^{\frac{1}{p}}, & i \neq i^{\prime}, i^{*}\end{cases}
$$

For all $j \neq i^{*}, i^{\prime}$ we have $d_{i^{*} j}^{(s+1)}=d_{i^{*} j}^{(s)}-t\left(i^{*}, i^{\prime}, j, l^{*}\right)$, and $d_{i^{\prime} j}^{(s+1)}=d_{i^{\prime} j}^{(s)}+$ $t\left(i^{*}, i^{\prime}, j, l^{*}\right)$, where $t\left(i_{1}, i_{2}, u, v\right)=\left|x_{i_{1} v}-x_{u v}\right|-\left|x_{i_{2} v}-x_{u v}\right|$. Also note that the distance matrix $\left(d_{i j}\right)$ is symmetric. For $\rho_{l}^{2}$ at step $(s+1)$, we obtain

$$
\left(\rho_{l}^{2}\right)^{(s+1)}= \begin{cases}\frac{1}{k-1} \sum_{j \neq l}\left(\rho_{j l}^{2}\right)^{(s+1)}, & l=l^{*} \\ \left(\rho_{l}^{2}\right)^{(s)}+\frac{\left(\rho_{l l^{*}}^{2}\right)^{(s+1)}-\left(\rho_{l l^{*}}^{2}\right)^{(s)}}{k-1}, & l \neq l^{*}\end{cases}
$$

Thus

$$
\phi_{p}^{(s+1)}=\left(\frac{1}{2} \sum_{i=1}^{n}\left(\phi_{p i}^{(s+1)}\right)^{p}\right)^{\frac{1}{p}} \text { and }\left(\rho^{2}\right)^{(s+1)}=\left(\rho^{2}\right)^{(s)}+\frac{2\left(\rho_{l^{*}}^{2}\right)^{(s+1)}-2\left(\rho_{l^{*}}^{2}\right)^{(s)}}{k}
$$

We should point out that the proposed exchange procedure can also be implemented with any of the other stochastic optimization algorithms such as the columnwise-pairwise algorithm ( Li and Wu (1997)), and $\mathrm{Ye}, \mathrm{Li}$ and Sudianto (2000), the threshold accepting heuristic (Winker and Fang (1998)), and the stochastic evolutionary algorithm (Jin. Chen and Sudiianto (2005)).

## 5. Examples

In this section, we compare our proposed method with some of the existing methods. For a fair comparison, we choose all the parameters in the simulated annealing algorithm equal to the recommended values in Morris and Mitchell (1995). In the following examples, we let $p=15$ and $w=0.5$. In all examples, we started the iteration by using a randomly generated symmetric LHD (Ye. Li and Sudjianto (2000)).

Example 1 ( $O M L H D$ vs $M L H D$ ). Consider an $\operatorname{LHD}(5,3)$. In this case it is feasible to enumerate all the LHDs. We found that there are 142 different designs according to the maximin criterion (Morris and Mitchell (1995)). The maximin Latin hypercube design (MLHD) and the proposed OMLHD are given in Table 1. We see that for OMLHD, the maximum pairwise correlation is only 0.1 compared to the 0.4 of MLHD. The minimum inter-site distances of the two designs are the same ( $D_{1}=5$ ), although the number of sites separated by this distance is one less in MLHD.

Table 1. Example 1, MLHD vs OMLHD for $n=5$ and $k=3$.

|  | MLHD | OMLHD |
| :---: | :---: | :---: |
|  | 112 | 123 |
| optimal | 253 | 245 |
| design | 325 | 351 |
| matrix | 431 | 412 |
|  | 544 | 534 |
| $\phi_{p}$ | 0.2170 | 0.2201 |
| $D_{1}\left(J_{1}\right)$ | $5(3)$ | $5(4)$ |
| $\rho$ | 0.265 | 0.081 |
| pairwise correlations | $(0.4,0.2,0.1)$ | $(-0.1,-0.1,0)$ |

Example 2 (OMLHD vs OLHD). Ye (1998) proposed the orthogonal Latin hypercube designs (OLHD), in which all the columns are orthogonal (correlation $=0)$ to each other. Table 2 compares the OLHD with the proposed OMLHD for the case of $n=9$ and $k=4$. For comparison, the MLHD is also given in the table. We can see that the OMLHD is a compromise between the MLHD and OLHD. OLHD exists only for certain $n$ and $k$, whereas MLHD and OMLHD exist for all $n$ and $k$. In this sense MLHD and OMLHD are more general.
Example 3 (OMLHD vs OA-based LHD). Owen (1994) and Tang (1993) proposed using orthogonal arrays for constructing good LHDs. Tang called such designs OA-based LHDs. Figure 4 shows an OA-based LHD and the OMLHD for the case of $n=9$ and $k=2$. Clearly the OMLHD is superior to this particular OA-based LHD. Interestingly, in this case, the OMLHD is also an OA-based LHD, but a good one in terms of both correlation and space-filling. However, in general, an OMLHD need not be an OA-based LHD.
Example 4 (OMLHD vs ULHD). Another popular space-filling design is the unform design. It can be obtained by minimizing the centered $L_{2}$-discrepancy criterion $\left(C L_{2}\right)$ (see Fang. Ma and Winker (2002)). Denote the optimal LHD under this criterion by ULHD. The ULHD for $n=9$ and $k=4$ is given in Table 2. We can see that the OMLHD is slightly worse than the ULHD under this
criterion, but is better in terms of both $\phi_{p}$ and $\rho$. Interestingly, the OMLHD performs much better than MLHD and OLHD in terms of $C L_{2}$.

Table 2. Examples 2 and 4, OMLHD vs OLHD, MLHD and ULHD for $n=9$ and $k=4$.

|  | MLLHD | OMLHD | OLHD | ULHD |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :--- | :--- | :---: | :--- | :---: | :---: | :---: |
|  | 1 | 3 | 3 | 4 | 1 | 5 | 3 | 3 | 1 | 2 | 6 | 3

(a)

(b)


Figure 4. Example 3, (a) OA-based LHD ( $\phi_{p}=0.5380, D_{1}\left(J_{1}\right)=2(3)$, $\rho=-0.067$ ) (b)OMLHD ( $\left.\phi_{p}=0.2879, D_{1}\left(J_{1}\right)=4(8), \rho=0\right)$.

We have also studied the performance of the proposed exchange algorithm. Figure 5 shows how $\phi_{p}$ and $\rho^{2}$ are reduced with each iteration for the case of $L H D(25,4)$. The same starting design is used for both MMA and the new algorithm. We can see that the new algorithm converges more quickly than the MMA. We repeated this 200 times. The values of $\psi_{p}$ at the $50^{\text {th }}$ iteration are plotted in Figure 6. We can see that they are much smaller for the new algorithm compared to the MMA. Thus, for a fixed number of iterations, the new algorithm produces LHDs with smaller pairwise correlations and larger inter-site distances. The simulations are repeated for $\operatorname{LHD}(50,4), L H D(10,10)$, and $L H D(100,10)$. The number of iterations for each of these cases was fixed at 100,200 , and 500
respectively. The results are shown in Figure 6. We can see that remarkable improvements are obtained by using the new algorithm compared to the MMA.



Figure 5. Performance of the new algorithm (solid) and MMA (dashed) against the number of iterations.


Figure 6. Plot of $\psi_{p}$ values from the new algorithm against that of the MMA.

## 6. A Statistical Justification

Because of the absence of random errors, interpolating methods such as kriging are widely used for modeling and analysis in computer experiments. Consider a function $y(\boldsymbol{x})$, where $\boldsymbol{x}=\left(x_{1}, \ldots, x_{k}\right)^{\prime}$. The ordinary kriging model is given by

$$
\begin{equation*}
Y(\boldsymbol{x})=\mu+Z(\boldsymbol{x}) \tag{5}
\end{equation*}
$$

where $Z(\boldsymbol{x})$ is a weakly stationary stochastic process with mean 0 and covariance function $\sigma^{2} R$. A popular choice for the correlation function is the exponential:

$$
\begin{equation*}
R(\boldsymbol{h})=e^{-\theta \sum_{i=1}^{k}\left|h_{i}\right|^{\gamma}} \tag{6}
\end{equation*}
$$

with $\theta \in(0, \infty)$ and $\gamma \in(0,2]$. Suppose we evaluated the function at $n$ points $\left\{\boldsymbol{x}_{1}, \ldots, \boldsymbol{x}_{n}\right\}$ and let $\boldsymbol{y}=\left(y_{1}, \ldots, y_{n}\right)^{\prime}$ be the corresponding function values. Then, the best linear unbiased predictor (BLUP) is given by $\hat{y}(\boldsymbol{x})=\hat{\mu}+\boldsymbol{r}(\boldsymbol{x})^{\prime} \boldsymbol{R}^{-1}(\boldsymbol{y}-$ $\hat{\mu} \mathbf{1})$, where $\mathbf{1}$ is a column of 1's having length $n, \boldsymbol{r}(\boldsymbol{x})^{\prime}=\left(R\left(\boldsymbol{x}-\boldsymbol{x}_{1}\right), \ldots, R(\boldsymbol{x}-\right.$ $\left.\boldsymbol{x}_{n}\right)$ ), $\boldsymbol{R}$ is an $n \times n$ matrix with elements $R\left(\boldsymbol{x}_{i}-\boldsymbol{x}_{j}\right)$, and $\hat{\mu}=\mathbf{1}^{\prime} \boldsymbol{R}^{-1} \boldsymbol{y} / \mathbf{1}^{\prime} \boldsymbol{R}^{-1} \mathbf{1}$. Note that the model in (5) assumes a constant mean, and the predictor does not perform well when there are some trends (see Joseph (2006)). If the trends are known, then universal kriging can be used instead of ordinary kriging. The universal kriging model with linear trends is given by

$$
\begin{equation*}
Y(\boldsymbol{x})=\beta_{0}+\sum_{i=1}^{k} \beta_{i} x_{i}+Z(\boldsymbol{x}) \tag{7}
\end{equation*}
$$

where $\beta_{0}, \beta_{1}, \ldots, \beta_{k}$ are some unknown constants. Simulations carried out by Martin and Simpson (2005) show that universal kriging can improve the prediction over ordinary kriging. See Qian et al. (2006) for an application of universal kriging with linear trends.

Johnson. Moore and Ylvisaker (1990) have shown that the maximin design with minimum $J_{1}$ is asymptotically D-optimum under the ordinary kriging model (as correlation becomes weak). Thus the objective of a maximin design can be thought of as finding a design to improve prediction through the stochastic part $Z(\boldsymbol{x})$, whereas minimizing the correlation among the variables will help in estimating the deterministic mean part $\beta_{0}+\sum_{i=1}^{k} \beta_{i} x_{i}$ efficiently. For the universal kriging predictor to perform well, both parts need to be estimated precisely. Thus the orthogonal-maximin LHD can be considered suitable for the efficient estimation of the universal kriging model with linear trends.

More specifically, consider the following hierarchical Bayesian model:

$$
\boldsymbol{y} \mid \boldsymbol{\beta} \sim N\left(\boldsymbol{F} \boldsymbol{\beta}, \sigma^{2} \boldsymbol{R}\right), \quad \boldsymbol{\beta} \sim N\left(\boldsymbol{\mu}, \tau^{2} \boldsymbol{I}\right)
$$

where $\boldsymbol{F}=[\mathbf{1}, \boldsymbol{X}]$ is the model matrix corresponding to $\boldsymbol{\beta}=\left(\beta_{0}, \ldots, \beta_{k}\right)^{\prime}$ and $\boldsymbol{I}$ is an identity matrix. The maximum entropy design (Shewry and Wynn (1987))) is obtained by maximizing the determinant of the variance-covariance matrix of $\boldsymbol{y}$. Thus we need to maximize $\operatorname{det}\left(\sigma^{2} \boldsymbol{R}+\tau^{2} \boldsymbol{F} \boldsymbol{F}^{\prime}\right)$, which is equal to (see Santner. Williams and Notz (2003, p.167))

$$
\operatorname{det}\left(\sigma^{2} \boldsymbol{R}\right) \operatorname{det}\left(\tau^{2} / \sigma^{2} \boldsymbol{F}^{\prime} \boldsymbol{R}^{-1} \boldsymbol{F}+\boldsymbol{I}\right)
$$

Johnson. Moore and Ylvisaker (1990) have shown that as $\theta \rightarrow \infty$ in (6), a maximin design maximizes the first term $\operatorname{det}\left(\sigma^{2} \boldsymbol{R}\right)$. As $\theta \rightarrow \infty, \tau^{2} / \sigma^{2} \boldsymbol{F}^{\prime} \boldsymbol{R}^{-1} \boldsymbol{F}+\boldsymbol{I} \rightarrow$ $\tau^{2} / \sigma^{2} \boldsymbol{F}^{\prime} \boldsymbol{F}+\boldsymbol{I}$, whose determinant is maximized when $\boldsymbol{F}$ is orthogonal. Thus an orthogonal design maximizes the second term. A design will be asymptotically $(\theta \rightarrow \infty)$ optimum with respect to the maximum entropy criterion if both terms are maximized. Therefore, an OMLHD, which possesses good maximin and orthogonality properties, can be expected to perform well in terms of the maximum entropy criterion for the model in (7) among all LHDs.

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## Appendix. Proofs

Proof of Lemma 1. Since each column in the $L H D(n, k)$ is a permutation of $\{1, \ldots, n\}$, we have

$$
\sum_{i=1}^{\substack{n \\ 2\\)}} d_{i}=\sum_{i=2}^{n} \sum_{j=1}^{i-1} d\left(s_{i}, \boldsymbol{s}_{j}\right)=\sum_{l=1}^{k} \sum_{i=2}^{n} \sum_{j=1}^{i-1}\left|s_{i l}-s_{j l}\right|=k \sum_{i=2}^{n} \sum_{j=1}^{i-1}\left|s_{i 1}-s_{j 1}\right|
$$

Without loss of generality, take the first column as $(1, \ldots, n)^{\prime}$. Therefore,

$$
\begin{aligned}
& \sum_{i=1}^{\binom{n}{2}} d_{i}=k \sum_{i=2}^{n} \sum_{j=1}^{i-1}|i-j|=k \sum_{i=2}^{n} \frac{i(i-1)}{2}=\frac{k n\left(n^{2}-1\right)}{6} \\
& \bar{d}=\frac{k n\left(n^{2}-1\right) 6^{-1}}{\binom{n}{2}}=\frac{(n+1) k}{3}
\end{aligned}
$$

Proof of Lemma 2. For $m=2$,

$$
\frac{1}{\sum_{j=1}^{k} d_{j 1}}+\frac{1}{\sum_{j=1}^{k}\left(c_{j}-d_{j 1}\right)}=\frac{\sum_{j=1}^{k} c_{j}}{\sum_{j=1}^{k} d_{j 1} \times \sum_{j=1}^{k}\left(c_{j}-d_{j 1}\right)}
$$

where $c_{j}=d_{j 1}+d_{j 2}$, for all $j=1, \ldots, k$. Since $\sum_{j=1}^{k} c_{j}$ is a constant, it is easy to see that the right side is a maximum when $\sum_{j=1}^{k} d_{j 1}=\sum_{j=1}^{k} d_{j(1)}$. Therefore,

$$
\sum_{i=1}^{2} \frac{1}{\sum_{j=1}^{k} d_{j i}} \leq \sum_{i=1}^{2} \frac{1}{\sum_{j=1}^{k} d_{j(i)}}
$$

Thus, the result holds for $m=2$. Assume the upper bound is achieved by the ordered sequence for $m=M$. When $m=M+1$, suppose the upper bound is achieved by some unordered sequence $\left\{d_{j 1^{*}}, \ldots, d_{j M+1^{*}}\right\}$, so the upper bound is $\sum_{i=1}^{M+1}\left(\sum_{j=1}^{k} d_{j i^{*}}\right)^{-1}$. Without loss of generality, assume that at least the first sequence does not follow the order. Because of this, there always exists an $M$ element subset $\left\{d_{11^{*}}, \ldots, \widehat{d_{1 t^{*}}} \ldots, d_{1 M+1^{*}}\right\}$ that does not follow the order, where the notation $\widehat{d_{1 t^{*}}}$ means that the sequence is without $d_{1 t^{*}}$. But since the upper bound holds for $m=M$, we have

$$
\begin{aligned}
& \frac{1}{\sum_{j=1}^{k} d_{j 1^{*}}}+\cdots+\frac{\widehat{1}}{\sum_{j=1}^{k} d_{j t^{*}}} \cdots+\frac{1}{\sum_{j=1}^{k} d_{j M+1^{*}}} \\
& \quad \leq \frac{1}{\sum_{j=1}^{k} d_{j(1)}}+\cdots+\frac{1}{\sum_{j=1}^{k} d_{j t^{*}}} \cdots+\frac{1}{\sum_{j=1}^{k} d_{j(M+1)}}
\end{aligned}
$$

This is a contradiction, because by adding $1 / \sum_{j=1}^{k} d_{j t^{*}}$ to both sides we obtain

$$
\sum_{i=1}^{M+1} \frac{1}{\sum_{j=1}^{k} d_{j i^{*}}} \leq \frac{1}{\sum_{j=1}^{k} d_{j(1)}}+\cdots+\frac{1}{\sum_{j=1}^{k} d_{j t^{*}}} \cdots+\frac{1}{\sum_{j=1}^{k} d_{j(M+1)}}
$$

which is a better upper bound. By mathematical induction, we can prove that the function achieves the upper bound when all $k$ sequences are in increasing order.

Proof of Proposition 1. To find a lower bound for $\phi_{p}$, consider the following minimization problem with respect to $d_{1}, \ldots, d_{\binom{n}{2}}$.

$$
\min \phi_{p}=\left(\sum_{i=1}^{\substack{n \\ 2\\)}} \frac{1}{d_{i}^{p}}\right)^{\frac{1}{p}} \text { subject to } \sum_{i=1}^{\substack{n \\ 2\\)}} d_{i}=\binom{n}{2} \bar{d}
$$

where $\bar{d}=(n+1) k / 3$. Using Lagrange multipliers, it is easy to show that the optimal solution is given by $d_{1}=d_{2}=\cdots=d_{\binom{n}{2}}=\bar{d}$. Therefore, $\binom{n}{2}^{1 / p} / \bar{d}$ is a lower bound for $\phi_{p}$. But since we know the $d_{i}$ 's in a LHD are integers, a better lower bound can be obtained by adding this constraint to the above optimization problem. To find the optimal solution under the integer restriction, consider the
following two groups: $I=\left\{i: d_{i} \leq \bar{d}\right\}$ and $I I=\left\{i: d_{i}>\bar{d}\right\}$. Since the sum of the $d_{i}$ 's is a constant, if we increase a $d_{i}$ for an $i \in I$, then we should decrease a $d_{i}, i \in I I$, by the same amount. It is easy to show that such a change will decrease $\phi_{p}$. Therefore, the minimum of $\phi_{p}$ can be achieved by

$$
d_{1}=\cdots=d_{N}=\lfloor\bar{d}\rfloor ; d_{N+1}=\cdots=d_{\binom{n}{2}}=\lceil\bar{d}\rceil
$$

provided such an $N$ exists. We must have $N\lfloor\bar{d}\rfloor+\left\{\binom{n}{2}-N\right\}\lceil\bar{d}\rceil=\binom{n}{2} \bar{d}$, which gives $N=\binom{n}{2}(\lceil\bar{d}\rceil-\bar{d})$. This is a feasible solution, because $\binom{n}{2} \bar{d}=(n+1) k$ is an integer. Thus

$$
\phi_{p} \geq\left(\frac{N}{\lfloor\bar{d}\rfloor^{p}}+\frac{\binom{n}{2}-N}{\lceil\bar{d}\rceil^{p}}\right)^{\frac{1}{p}}=\phi_{p, L}
$$

Now consider the upper bound. All the $k$ factors have the same inter-site distances $\left\{d_{j, 1}, \ldots, d_{j,\binom{n}{2}}\right\}$, where $j=1, \ldots, k$. For example, if $n=5$, the intersite distances for each factor is $\{1,1,1,1,2,2,2,3,3,4\}$. In general, $(n-1)$ of the $d_{j, i}$ 's are $1,(n-2)$ of the $d_{j, i}$ 's are $2, \cdots$, and one is $(n-1)$. Different LHDs have different combinations of the inter-site distances of each factor. Therefore $d_{i}=\sum_{j=1}^{k} d_{j, i}$, where $i=1, \ldots,\binom{n}{2}$. By Lemma 2 ,

$$
\phi_{p}=\left(\sum_{i=1}^{\binom{n}{2}} \frac{1}{d_{i}^{p}}\right)^{\frac{1}{p}} \leq\left(\sum_{i=1}^{\binom{n}{2}} \frac{1}{\sum_{j=1}^{k} d_{j, i}^{p}}\right)^{\frac{1}{p}} \leq\left(\sum_{i=1}^{\binom{n}{2}} \frac{1}{\sum_{j=1}^{k} d_{j,(i)}^{p}}\right)^{\frac{1}{p}}
$$

Note that the inter-site distances of each of the $k$ factors is ordered in the same way. Therefore, $(n-1)$ of the $d_{i}$ 's are $k,(n-2)$ of the $d_{i}$ 's are $2 k, \cdots$, and one is $(n-1) k$, and

$$
\phi_{p} \leq\left(\sum_{i=1}^{\binom{n}{2}} \frac{1}{\sum_{j=1}^{k} d_{j, i}^{p}}\right)^{\frac{1}{p}}=\left\{\sum_{i=1}^{n-1} \frac{(n-i)}{(i k)^{p}}\right\}^{\frac{1}{p}}=\phi_{p, U}
$$

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