RESAMPLING-BASED ESTIMATOR IN NONLINEAR REGRESSION

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Abstract: In this paper we suggest a resampling-based estimator (RSE) of nonlinear regression by using Wu's (1986) resampling idea. The RSE is bias-reducing without increasing the variance. Some examples are given using the data of Ratkowsky (1983), and several simulations are also presented.

Key words and phrases: Absolute relative bias, bias reduction, Jackknife-based estimator, nonlinear regression, resampling-based estimator.

1. Introduction

Nonlinear regression models have wide application in a variety of contexts, and much of the theory is established. The usual model has the form

$$y_i = f(x_i, \theta) + \epsilon_i \quad (i = 1, \dots, n), \tag{1}$$

where f is a nonlinear function of the p-dimensional parameter θ and assumed twice continuously differentiable in θ , and the errors ϵ_i are assumed to be independent and identically distributed random variables with mean 0 and unknown variance σ^2 . For this model, the least square estimator (LSE) $\hat{\theta}$ of θ can be obtained by minimizing the objective function

$$J(\theta) = \sum_{i=1}^{n} \{y_i - f(x_i, \theta)\}^2$$
 (2)

or

$$\sum_{i=1}^{n} \frac{\partial f_i}{\partial \theta} (y_i - f(x_i, \theta)) \|_{\theta = \hat{\theta}} = 0.$$
 (3)

The estimator of σ^2 is $\hat{\sigma}^2 = J(\hat{\theta})/(n-p)$. Let $f_i = f(x_i, \theta)$ (i = 1, ..., n), V denote the $n \times p$ matrix with elements

$$f_i^r = \frac{\partial f_i}{\partial \theta_r}$$
 $(i = 1, \dots, n, r = 1, \dots, p).$

W denote the $n \times p \times p$ array with elements

$$f_i^{rs} = \frac{\partial^2 f_i}{\partial \theta_r \partial \theta_s}$$
 $(i = 1, \dots, n, r, s = 1, \dots, p)$

and e denote the residual vector with elements

$$e_i = y_i - f(x_i, \hat{\theta}).$$

Then, Equation (3) can be written as

$$V^T(\hat{\theta})e = 0. (4)$$

2. Bias of $\hat{\theta}$ and Jackknife-Based Estimators

The LSE of the parameters in the model (1) are generally biased estimators of the true parameter values. The bias $Bias(\hat{\theta}) = E(\hat{\theta} - \theta)$ can be expressed as

$$\operatorname{Bias}(\hat{\theta}) \approx -\frac{\sigma^2}{2} (V^T V)^{-1} V^T \operatorname{tr}\{(V^T V)^{-1} W\}$$
 (5)

where $\operatorname{tr}\{(V^TV)^{-1}W\}$ is an $n \times 1$ vector with elements $\operatorname{tr}\{(V^TV)^{-1}W_i\}(i=1,\ldots,n)$ and W_i , is the *i*th face of W, a $p \times p$ matrix with elements

$$f_i^{rs} = \frac{\partial^2 f_i}{\partial \theta_r \partial \theta_s} \quad (r, s = 1, \dots, p).$$

Bates and Watts (1980) pointed out that the bias of the LSE (5) is only a function of the parameter-effects curvature array and thus could be reduced or eliminated by reparameterization. For the single-parameter case, Hougaard (1982) showed that there is a transformation which eliminates bias, but the appropriate transformation does not exist in general for the multiparameter case (Hougaard (1984)).

Many Jackknife-based estimators are supposed to construct confidence regions in nonlinear regression, but, these estimators are not valid in bias-reduction as shown in Simonoff and Tsai (1986).

The linear Jackknife was developed by Fox et al. (1980). With pseudo-values defined as

$$LP_i = \hat{\theta} + (n(\hat{V}^T\hat{V})^{-1}\hat{V}_i e_i)/(1 - \hat{h}_{ii})$$
(6)

where \hat{V} is the values of V evaluated at $\hat{\theta}, \hat{V}_i$ is the ith row of \hat{V} , and \hat{h}_{ii} is the ith diagonal element of the matrix $\hat{V}(\hat{V}^T\hat{V})^{-1}\hat{V}^T$, the linear Jackknife estimator $\hat{\theta}_{LP}$ is defined as the average of the pseudo-values

$$\hat{\theta}_{LP} = \frac{1}{n} \sum_{i=1}^{n} LP_i. \tag{7}$$

By extending the work of Hinkley (1977) to nonlinear regression, Fox et al. (1980) proposed a weighted linear Jackknife estimator to improve the bias reduction. Weighted pseudo-values are given by

$$LQ_i = \hat{\theta} + n(\hat{V}^T \hat{V})^{-1} \hat{V}_i e_i \tag{8}$$

and replacing LP_i by LQ_i in (7) yields the weighted linear Jackknife estimator. The linear Jackknife estimator and the weighted linear Jackknife estimator do not have the first-order bias term eliminated; this is due to using a linear approximation and to lack of design balance.

Simonoff and Tsai (1986) proposed three new Jackknife-based estimators. The pseudo-values are given by

$$MLP_i = \hat{\theta} + nT_i^{-1}\hat{V}_i e_i / (1 - h_{ii}^*)$$
 (9)

$$MLQ_i = \hat{\theta} + nT_i^{-1}\hat{V}_i e_i \tag{10}$$

$$RLQ_{i} = \hat{\theta} + n(\hat{V}^{T}\hat{V})^{-1}\hat{V}_{i}e_{i}(1 - \hat{h}_{ii})$$
(11)

where $T_i = \{\hat{V}^T\hat{V} - [e_{(i)}][\hat{W}_{(i)}]\}$, $h_{ii}^* = \hat{V}_i^T T_i \hat{V}_i$, \hat{V} , \hat{W} are all evaluated at $\hat{\theta}$, $e_{(i)}$ and $W_{(i)}$ are respectively the $(n-1) \times 1$ vector and $(n-1) \times P \times P$ array with the *i*th component removed from the $n \times 1$ vector e and the $n \times p \times p$ array \hat{W} . If the term $[e_{(i)}][W_{(i)}]$ is ignored, then (9) and (10) are identical to (6) and (8), respectively. These Jackknife-based estimators do not reduce the bias of the LSE because of the linear approximation in producing the pseudo-values.

In this article we suggest an alternative weighted scheme and quadratic approximation whereby the bias reduction properties hold, and the first-order bias term of the LSE is eliminated. Some examples are presented to illustrate this property.

3. Resampling-Based Estimator (RSE)

Let $s = \{i_1, \ldots, i_r\}$ be a subset of $\{1, \ldots, n\}$, and $\hat{\theta}_s$ be the LSE of Model (1) based on the (x_i, y_i) in s, i.e. $\hat{\theta}_s$ can be obtained by minimizing the objective function,

$$J_s(\theta) = \sum_{i \in s} \{y_i - f(x_i, \theta)\}^2.$$

For a linear model, $\hat{\theta}_s$ can be expressed as

$$\hat{\theta}_s = (V_s^T V_s)^{-1} V_s^T y_s \tag{12}$$

where $y_s = (y_{i_1}, \ldots, y_{i_r})^T$ and $V_s = (V_{i_1}, \ldots, V_{i_r})$, V_{i_j} is the i_j th row of V. The following results are based on Wu (1986).

Result. For any $r \geq p$, we have

$$\binom{n-p}{r-p}|V^TV| = \sum_r |V_s^T V_s| \tag{13}$$

where \sum_r denotes the summation over all the subsets of size r, and when the model (1) is linear, the LSE can be expressed as

$$\hat{\theta} = (V^T V)^{-1} V^T y = \sum_r \omega_s \hat{\theta}_s, \tag{14}$$

where ω_s is a weight defined as

$$\omega_s \propto |V_s^T V_s| \qquad \sum_r \omega_s = 1.$$

For the nonlinear model (1), we suggest a resampling-based estimator (RSE). The RSE is given by

$$\hat{\theta}_{rs} = \hat{\theta} + \frac{r - p + 1}{n - r} \sum_{r} \hat{\omega}_{s} (\hat{\theta} - \hat{\theta}_{s}), \tag{15}$$

where $\hat{\omega}_s$ are evaluated at $\hat{\theta}$ to reduce the computation of RSE. We construct a Taylor series approximation to $\hat{\theta}_s$, yielding

$$\hat{\theta}_s = \hat{\theta} + (\hat{V}_s^T \hat{V}_s)^{-1} \hat{V}_s^T e_s - \frac{1}{2} (\hat{V}_s^T \hat{V}_s)^{-1} \hat{V}_s^T [\Delta \theta_{1s}^T \hat{W}_s \Delta \theta_{1s}]$$
 (16)

where $\hat{W}_s = (\hat{W}_{i_1}, \dots, \hat{W}_{i_r})^T$ and \hat{V}_s are evaluated at $\hat{\theta}$, and $\Delta \theta_{1s} = (\hat{V}_s^T \hat{V}_s)^{-1} \hat{V}_s^T e_s$. Substituting $\hat{\theta}_s$ into (15), and utilizing (12) and (14), yields

$$\hat{\theta}_{rs} = \hat{\theta} - \frac{r - p + 1}{n - r} (\hat{V}^T \hat{V})^{-1} \hat{V}^T e + \frac{r - p + 1}{2(n - r)} \sum_{r} \hat{\omega}_s (\hat{V}_s^T V_s)^{-1} \hat{V}_s^T [\Delta \theta_{1s}^T \hat{W}_s \Delta \theta_{1s}];$$
(17)

and from (4), we have

$$\hat{\theta}_{rs} = \hat{\theta} + \frac{r - p + 1}{2(n - r)} \sum_{r} \hat{\omega}_{s} (\hat{V}_{s}^{T} \hat{V}_{s})^{-1} \hat{V}_{s}^{T} [\Delta \theta_{1s}^{T} \hat{W}_{s} \Delta \theta_{1s}].$$
 (18)

In the remainder of this paper, the RSE is defined as (18).

Theorem. For r = n - 1, and under some appropriate regularity conditions (Mong (1988))

(i)
$$\operatorname{Bias}(\hat{\theta}_{rs}) = (n-p+1)\operatorname{Bias}(\hat{\theta})$$

 $+ \frac{\sigma^2}{2} \sum_{r} \frac{|V_s^T V_s|(V_s^T V_s)^{-1} V_s^T \operatorname{tr}[(V_s^T V_s)^{-1} W_s]}{|V^T V|} + O(n^{-3/2})$ (19)
 $= O(n^{-3/2})$

(ii)
$$\operatorname{Var}(\hat{\theta}_{rs}) = \operatorname{Var}(\hat{\theta}) + O(n^{-3/2})$$
 (21)

i.e. the RSE eliminates the first-order bias term of the LSE, and the variance of the RSE and LSE have the same first-order term.

Proof.

(i)

$$\operatorname{Bias}(\hat{\theta}_{\tau s}) = \operatorname{Bias}(\hat{\theta}) + E \frac{n-p}{2} \sum_{r} \hat{\omega}_{s} (\hat{V}_{s}^{T} \hat{V}_{s})^{-1} \hat{V}_{s}^{T} [\Delta \theta_{1s}^{T} \hat{W}_{s} \Delta \theta_{1s}]. \tag{22}$$

Let

$$\Delta = E \frac{n-p}{2} \sum_{r} \hat{\omega}_{s} (\hat{V}_{s}^{T} \hat{V}_{s})^{-1} V_{s}^{T} [\Delta \theta_{1s}^{T} \hat{W}_{s} \Delta \theta_{1s}]. \tag{23}$$

Since $\hat{\theta} = \theta + O_p(n^{-1/2})$, substituting into (23) yields

$$\Delta = \frac{n-p}{2} \sum_{r} \omega_s (V_s^T V_s)^{-1} V_s^T \text{tr} \Big[W_s (V_s^T V_s)^{-1} V_s^T E e_s e_s^T V_s (V_s^T V_s)^{-1} \Big] + O(n^{-3/2}).$$
(24)

Note that

$$e_s = y_s - f(x_s, \theta)$$

= $\epsilon_s - V_s^T (V^T V)^{-1} V^T \epsilon + O_p(n^{-1}).$

We have

$$\Delta = \frac{\sigma^2}{2} (n-p) \sum_r \omega_s (V_s^T V_s)^{-1} V_s^T \operatorname{tr} \left[W_s ((V_s^T V_s)^{-1} - (V^T V)^{-1}) \right] + O(n^{-3/2}). \tag{25}$$

From (14), Δ can be described as

$$\Delta = \frac{\sigma^2(n-p)}{2} \sum_r \omega_s (V_s^T V_s)^{-1} V_s^T \text{tr}[W_s (V_s^T V_s)^{-1}] + (n-p) \text{Bias}(\hat{\theta}) + O(n^{-3/2}).$$
(26)

Now, Equation (19) follows from (26) and (22). Using (25), another expression can be obtained:

$$\Delta = \frac{\sigma^2}{2} \sum_{r} (V_s^T V_s)^{-1} V_s^T \operatorname{tr} \left[W_s (V^T V)^{-1} V_i V_i^T (V^T V)^{-1} \right] + O(n^{-3/2})$$
 (27)

since $|V_s^T V_s| = |V^T V| (1 - h_{ii})$ and $(V_s^T V_s)^{-1} - (V^T V)^{-1} = \frac{(V^T V)^{-1} V_i V_i^T (V^T V)^{-1}}{1 - h_{ii}}$. Replacing $(V_s^T V_s)^{-1}$ by $(V^T V)^{-1}$ in (27), the difference can be ignored. Thus,

$$\Delta = \frac{\sigma^2}{2} \sum_{r} (V^T V)^{-1} V_s^T \operatorname{tr} \left[W_s (V^T V)^{-1} V_i V_i^T (V^T V)^{-1} \right] + O(n^{-3/2})$$

$$= \frac{\sigma^2}{2} (V^T V)^{-1} V^T \operatorname{tr} \left[W (V^T V)^{-1} \right]$$

$$- \frac{\sigma^2}{2} \sum_{r} (V^T V)^{-1} V_i \operatorname{tr} \left[W_i (V^T V)^{-1} V_i V_i^T (V^T V)^{-1} \right] + O(n^{-3/2})$$

$$= -\operatorname{Bias}(\hat{\theta}) + O(n^{-3/2}). \tag{28}$$

From (28), (22) and (2) Equation (20) is obtained immediately.

(ii) Under some regularity conditions, the RSE can be written as

$$\hat{\theta}_{rs} = \hat{\theta} + O_p(n^{-1})$$

and it can be proved that

$$\operatorname{Var}(\hat{\theta}_{rs}) = \operatorname{Var}(\hat{\theta}) + O(n^{-3/2}).$$

The details can be found in Mong (1988).

The theorem can be established when n-r is bounded. More information is available in Mong (1988).

4. Examples

In this section several examples are presented to illustrate the result of Section 3. The biases, given in following Tables are defined as

$$\% \operatorname{Bias}(\hat{\theta}) = \frac{\operatorname{Bias}(\hat{\theta})}{\hat{\theta}} \times 100\% \tag{29}$$

$$\% \operatorname{Bias}(\hat{\theta}_{rs}) = \frac{\operatorname{Bias}(\hat{\theta}_{rs})}{\hat{\theta}_{rs}} \times 100\%.$$
 (30)

These examples were all analyzed by Ratkowsky (1983). The first example is the Gompertz model, with the form

$$y = \alpha \exp\{-\exp(\beta - rX)\}. \tag{31}$$

The example involves two sets of data, based on data sets 2 and 4 in Table 4 of Ratkowsky (1983). The parameter estimators, with associated bias and parameter-effects curvature, appear in Table 1. For data set 1, the LSE's biases of the two parameters β and γ are serious, but for RSE the biases of parameters β and γ are reduced. Data set 2 also shows that the bias reduction property holds, and in the two data sets, the parameter-effects curvature for LSE and RSE are quite close.

Table 1. LSE and RSE (Model (31)), with associated estimated biases and parameter-effects curvature (PE)

| | | Data | . 1 | Data 2 | | | | |
|-------|---------|--------|----------|--------|--------|-------|----------|-------|
| | α | β | γ | PE | α | β | γ | PE |
| LSE | 723.1 | 2.5 | 0.45 | 0.70 | 22.51 | 2.106 | 0.388 | 0.880 |
| %Bias | 0.185 | 1.088 | 1.007 | | 0.271 | 1.066 | 0.976 | |
| RSE | 721.539 | 2.4881 | 0.446 | 0.71 | 22.441 | 2.086 | 0.384 | 0.896 |
| %Bias | -0.077 | 0.027 | 0.0116 | | -0.112 | 0.066 | 0.0177 | |

The second example is based on the model

$$y = \theta_1 + \theta_2(x - \theta_4) + \theta_3 \left\{ (x - \theta_4)^2 + \theta_5 \right\}^{1/2}$$
 (32)

and data set 3 in Table 6.18 of Ratkowsky (1983). Ratkowsky (1983) showed that the most effective method to reduce the bias of the LSE is reparameterization. However, it is difficult to find an appropriate transformation. We propose a transformation for Model (32). Let $\theta_5' = \theta_5^{1/2}$,

$$y = \theta_1 + \theta_2(x - \theta_4) + \theta_3 \left\{ (x - \theta_4)^2 + {\theta_5'}^2 \right\}^{1/2}.$$
 (33)

The results for models (32) and (33) are presented in Table 2. The calculations indicate that the transformation has reduced the bias of LSE, but it is still serious. The bias of RSE is the only one that can be ignored.

Table 2. LSE and RSE (Models (32) and (33)), with associated estimated biases and parameter-effects curvature (PE)

| | LSE | $\% \mathrm{Bias}(heta)$ | RSE | $\% \mathrm{Bias}(\theta_{rs})$ | LSE* | $\% \mathrm{Bias}(\theta)$ |
|-----------------------|---------|---------------------------|---------|---------------------------------|---------|----------------------------|
| $\overline{\theta_1}$ | 136.822 | 0.124 | 136.501 | 0.060 | 136.822 | 0.124 |
| $\overline{\theta_2}$ | 0.696 | -0.996 | 0.713 | .016 | 0.696 | -0.996 |
| $\overline{\theta_3}$ | -0.587 | 1.761 | -0.566 | .007 | -0.587 | 1.761 |
| $\overline{\theta_4}$ | 18.752 | 0.330 | 18.609 | .004 | 18.752 | 0.330 |
| θ_5 | 6.727 | 20.521 | 4.627 | .750 | 2.594 | 1.609 |
| PE | 1.812 | | 1.893 | | 4.497 | |
| | | | | | | · · |

*Note: The LSE and biases of parameters in Model (30)

For the third example, we consider the Morgan-Mercer-Flodin model (Ratkow-sky (1983)),

 $y = \frac{\beta \gamma + \alpha x^{\delta}}{\gamma + x^{\delta}}. (34)$

Two data sets are used to fit this model; the results are shown in Table 3. This example also shows that RSE is an effective bias-reducing estimator.

| _ | | Dat | a 1 | | Data 2 | | | |
|--------------|---------|--------|----------|-------|--------|--------|---------|-------|
| | α | β | γ | δ | α | β | γ | δ |
| LSE | 723.9 | 33.35 | 6266 | 4.641 | 22.08 | 1.653 | 5586 | 4.56 |
| %Bias | 0.313 | -2.468 | 86.600 | 1.424 | 0.237 | -0.794 | 55.327 | 0.942 |
| RSE | 722.218 | 33.546 | 3714.59 | 4.592 | 22.006 | 1.663 | 2238.86 | 4.510 |
| %Bias | -0.02 | 0.836 | 0.432 | 0.053 | -0.034 | 0.771 | -0.078 | 0.005 |

Table 3. LSE and RSE (Model (34)), with associated estimated biases

5. Simulation

In this section, several simulations are provided to examine the properties of RSE, LSE and other Jackknife-based estimators.

Suppose that $\hat{\theta}$ and $\hat{\sigma}^2$ are treated as the true values of θ , σ^2 and M sets of size-n samples are simulated from

$$Y_i = f(x_i, \hat{\theta}) + \epsilon_i \quad (i = 1, \dots, n)$$

where ϵ_i are i.i.d. $N(0, \hat{\sigma}^2)$. For each set we obtain an estimator $\tilde{\theta}^{(m)}$ $(m = 1, \ldots, M)$. We consider the estimation characteristics in regard to bias, variance, skewness and kurtosis. They are defined as follows:

$$\tilde{\theta}_{i}^{(\cdot)} = \sum_{m=1}^{M} \tilde{\theta}_{i}^{(m)} / M,$$

$$\text{Bias}_{i} = \tilde{\theta}_{i}^{(\cdot)} - \hat{\theta}_{i},$$

$$\text{Var}_{i} = \frac{1}{M} \sum_{m=1}^{M} (\tilde{\theta}_{i}^{(m)} - \tilde{\theta}_{i}^{(\cdot)})^{2},$$

$$g_{1i} = \frac{M^{1/2} \sum_{m=1}^{M} (\tilde{\theta}_{i}^{(m)} - \tilde{\theta}_{i}^{(\cdot)})^{3}}{\left(\sum_{m=1}^{M} (\tilde{\theta}_{i}^{(m)} - \tilde{\theta}_{i}^{(\cdot)})^{2}\right)^{3/2}},$$

$$g_{2i} = \frac{M \sum_{m=1}^{M} (\tilde{\theta}_{i}^{(m)} - \tilde{\theta}_{i}^{(\cdot)})^{4}}{\left(\sum_{m=1}^{M} (\tilde{\theta}_{i}^{(m)} - \tilde{\theta}_{i}^{(\cdot)})^{4}\right)^{2}} - 3.$$

The absolute relative biases (ARB) of LSE and RSE are also presented, they are computed as:

$$ARB_i = ||Bias_i||/S.E._i$$

where $S.E._i = \sqrt{v_i/M}$, v_i is a linear approximation variance of LSE and RSE. Let $C = \hat{\sigma}^2(V^TV)^{-1}$; then $v_i = C_{ii}$.

The first simulation set is based on the Gompertz model (Section 4, Model (31)). The simulation results (Table 4) show that simulation biases and variance of LSE are very close to the theory values, and the results also quantify the bias-reduction property of RSE. The simulation variances of RSE are close to the variances of LSE. This supports the theory of theorem part (ii); RSE is less biased without increasing variance and has lower ARB.

The second simulation is based on Duncan's (1978) example. The model is

$$Y = \frac{\theta_1}{\theta_1 - \theta_2} (e^{-\theta_2 x} - e^{-\theta_1 x}). \tag{35}$$

All of the estimators are quite close as regards bias, variance, ARB, skewness and kurtosis, and RSE is still a good estimator, with lower bias, variance and ARB. (Table 5)

The final simulation is based on a chemical-reaction rate model from Meyer and Roth (1972, Example 1) previously analyzed by Rotkowsky (1983, Sec. 6.3) and Simonoff and Tsai (1986). The model is:

$$Y = \frac{\theta_1 \theta_3 x_1}{1 + \theta_1 x_1 + \theta_2 x_2}. (36)$$

The results of simulation are presented in Table 6. There are some differences in this example; Only $\hat{\theta}$, $\hat{\theta}_{RLQ}$ and $\hat{\theta}_{rs}$ perform well. Although the biases of $\hat{\theta}_{LP}$ are close to those of LSE, the variances of $\hat{\theta}_{LP}$ are much bigger than the variances of LSE. Both the biases and variances of $\hat{\theta}_{MLP}$ and $\hat{\theta}_{MLQ}$ are much larger than those of LSE. The RSE is still good at bias-reducing and yielding lower variance.

In conclusion, RSE is effective as a bias-reducing estimator without increasing the variance. In addition, RSE could be applied to construct confidence regions.

Table 4. Simulation results for the Gompertz Model

| | | LSE | RSE | LP | RLQ | MLQ | MLP |
|----------|-----------------------|----------|-----------|----------|----------|----------|-----------|
| Data set | 1. | | | | | | |
| Bias | θ_1 | 2.3211 | 0.9883 | 2.4441 | 2.2495 | 0.1231 | -0.6779 |
| (% Bias) | | (0.3210) | (0.1367) | (0.3380) | (0.3111) | (0.0170) | (-0.0937) |
| | $	heta_2$ | 0.0275 | 0.0010 | 0.0236 | 0.0294 | 0.0603 | 0.0885 |
| | | (1.0983) | (0.0396) | (0.9435) | (1.1855) | (2.4126) | (3.5390) |
| | $	heta_3$ | 0.0041 | -0.0003 | 0.0034 | 0.0044 | 0.0102 | 0.0150 |
| | | (0.8998) | (-0.0733) | (0.7598) | (0.9798) | (2.2662) | (3.3418) |
| ARB | θ_1 | 3.3271 | 1.4167 | | | | |
| | $	heta_2$ | 3.0502 | 0.1100 | | | | |
| | $	heta_3$ | 2.4739 | 0.2016 | | | | |
| Var | $\overline{	heta_1}$ | 500.8908 | 493.9358 | 505.5539 | 501.9933 | 507.8207 | 548.6551 |
| | $	heta_2$ | 0.0866 | 0.0839 | 0.0884 | 0.0873 | 0.0926 | 0.1128 |
| | $	heta_3$ | 0.0029 | 0.0028 | 0.0029 | 0.0029 | 0.0031 | 0.0037 |
| Ske. | $\overline{	heta_1}$ | 0.5193 | 0.5266 | 0.5313 | 0.5130 | 0.5225 | 0.4847 |
| | $	heta_2$ | 0.4669 | 0.4660 | 0.5843 | 0.4277 | 0.5033 | 0.8462 |
| | $	heta_3$ | 0.3583 | 0.3550 | 0.4370 | 0.3376 | 0.3786 | 0.6463 |
| Kur. | $\overline{	heta_1}$ | 0.6589 | 0.6841 | 0.6802 | 0.6419 | 0.6649 | 0.7686 |
| | $	heta_2$ | 0.7583 | 0.7715 | 1.1560 | 2.5605 | 2.5887 | 2.5012 |
| | $	heta_3$ | 0.5082 | 0.5153 | 0.7781 | 0.4094 | 0.5308 | 1.3310 |
| Data set | 2. | | | | | | |
| Bias | θ_1 | 0.0934 | 0.0313 | 0.0979 | 0.0905 | 0.0111 | 0.0162 |
| (%Bias) | | (0.4150) | (0.1393) | (0.4349) | (0.4023) | (0.0491) | (0.0719) |
| | $	heta_2$ | 0.0247 | 0.0030 | 0.0221 | 0.0262 | 0.0498 | 0.0643 |
| | | (1.1703) | (0.1405) | (1.0502) | (1.2415) | (2.3620) | (3.0528) |
| | θ_3 | 0.0037 | 0.0001 | 0.0033 | 0.0040 | 0.0088 | 0.0111 |
| | | (0.9533) | (0.0180) | (0.8399) | (1.0203) | (2.2545) | (2.8548) |
| ARB | θ_1 | 3.5281 | 1.1837 | | | | |
| | $	heta_2$ | 3.3154 | 0.3981 | | | | |
| | $	heta_3$ | 2.5472 | 0.0482 | | | | |
| Var | θ_1 | 0.7520 | 0.7333 | 0.7610 | 0.7558 | 0.7707 | 0.9054 |
| | $	heta_2$ | 0.0590 | 0.0574 | 0.0598 | 0.0593 | 0.0635 | 0.0762 |
| | θ_3 | 0.0023 | 0.0022 | 0.0023 | 0.0023 | 0.0024 | 0.0029 |
| Ske. | $\overline{\theta_1}$ | 0.5934 | 0.5998 | 0.6058 | 0.5907 | 0.6171 | 0.7189 |
| | $	heta_2$ | 0.4696 | 0.4711 | 0.5690 | 0.4299 | 0.5054 | 0.7560 |
| | θ_3 | 0.3530 | 0.3525 | 0.4150 | 0.3296 | 0.3606 | 0.4797 |
| Kur. | $\frac{1}{\theta_1}$ | 0.6613 | 0.6940 | 0.6709 | 0.6571 | 0.7305 | 1.1844 |
| | $	heta_2$ | 0.6832 | 0.6956 | 1.0212 | 0.5500 | 2.1706 | 2.1092 |
| | θ_3 | 0.5166 | 0.5282 | 0.7601 | 0.4159 | 0.5385 | 1.1274 |
| | - 3 | | | | | | |

Table 5. Simulation results for Duncan's Model

| | | LSE | RSE | LP | RLQ | MLQ | MLP |
|---------------|------------|----------|-----------|----------|----------|----------|----------|
| Bias | θ_1 | 0.0017 | -0.0001 | 0.0016 | 0.0017 | 0.0051 | 0.0051 |
| (%Bias) | - | (0.7798) | (-0.0567) | (0.7656) | (0.7940) | (2.4103) | (2.4103) |
| (,,, | $	heta_2$ | 0.0024 | -0.0002 | 0.0023 | 0.0025 | 0.0141 | 0.0167 |
| | _ | (0.5335) | (-0.0448) | (0.5089) | (0.5515) | (3.1585) | (3.7436) |
| ARB | θ_1 | 2.0871 | 0.1518 | | | | |
| | $	heta_2$ | 1.4598 | 0.1227 | | | | |
| Var | θ_1 | 6.2285 | 6.1741 | 6.2660 | 6.2158 | 6.3399 | 6.4061 |
| $\times 10^4$ | $	heta_2$ | 29.7200 | 29.2228 | 29.7699 | 29.7606 | 32.7239 | 33.5404 |
| Ske. | θ_1 | 0.2478 | 0.2502 | 0.2457 | 0.2497 | 0.2452 | 0.2437 |
| | $	heta_2$ | 0.4529 | 0.4566 | 0.4546 | 0.4501 | 0.4605 | 0.4613 |
| Kur. | θ_1 | 0.0551 | 0.0615 | 0.0284 | 0.0749 | 0.0386 | 0.0033 |
| | $	heta_2$ | 0.1951 | 0.2089 | 0.1939 | 0.1936 | 0.1925 | 0.1955 |

Table 6. Simulation results for Model (36)

| | | LSE | RSE | LP | RLQ | MLQ | MLP |
|----------|------------|----------|-----------|----------|----------|------------|------------|
| Bias | θ_1 | 0.0171 | -0.0167 | 0.1565 | 0.0186 | -2.8677 | -0.2644 |
| (%Bias) | - | (0.5451) | (-0.5333) | (4.9960) | (0.5927) | (-91.5756) | (-8.4426) |
| (, •===) | $	heta_2$ | 0.0373 | 0.0102 | 0.8352 | 0.0379 | -0.5020 | -10.6552 |
| | - 2 | (0.2461) | (0.0670) | (5.5097) | (0.2501) | (-3.3114) | (-70.2881) |
| | θ_3 | 0.0401 | 0.0009 | 0.0489 | 0.0397 | 0.6719 | -0.6768 |
| | • 0 | (5.1342) | (0.1141) | (6.2700) | (5.0932) | (86.1280) | (-86.7651) |
| ARB | θ_1 | 0.6678 | 0.6533 | | | | |
| | $	heta_2$ | 1.8673 | 0.5086 | | | | |
| | $	heta_3$ | 8.3329 | 0.1852 | | | | |
| Var | θ_1 | 0.6344 | 0.6204 | 60.7894 | 0.6425 | 4710.9600 | 7916.0800 |
| | $	heta_2$ | 0.3630 | 0.3601 | 958.1200 | 0.3660 | 163.9922 | 4884.8700 |
| | $	heta_3$ | 0.0336 | 0.0274 | 0.6649 | 0.0338 | 204.4682 | 843.0529 |
| Ske. | θ_1 | 0.2984 | 0.2994 | 0.0684 | 0.3197 | -30.2997 | 29.0962 |
| | $	heta_2$ | 0.1650 | 0.1668 | -0.0857 | 0.1839 | -29.8790 | -22.4977 |
| | θ_3 | 1.5195 | 1.3416 | 1.5660 | 1.5162 | 28.6021 | -31.1751 |
| Kur. | θ_1 | 0.1830 | 0.1992 | 0.8167 | 0.2638 | 938.9550 | 899.5855 |
| | $	heta_2$ | -0.0073 | -0.0348 | -0.0857 | 0.0556 | 920.8717 | 593.3932 |
| | θ_3 | 3.7300 | 3.2149 | 8.3050 | 3.7577 | 852.1255 | 978.6693 |
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(Received March 1992; accepted August 1993)