BAYESIAN NONPARAMETRIC ESTIMATION OF A BIVARIATE SURVIVAL FUNCTION

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Abstract: We use a bivariate reinforced process derived from a Generalized Pólya Urn scheme to provide an estimator for a bivariate survival function. The estimator may be considered as a Bayesian nonparametric predictive estimator and it can be obtained easily via an implementation of a Gibbs sampler. Consistency of the estimator is studied.

Key words and phrases: Bayesian nonparametric, beta-Stacy process, bivariate survival function, Pólya urn scheme.

1. Introduction

A difficult problem in survival and reliability analysis is the estimation of a bivariate survival function for lifetimes subjected to censoring.

Such problems arise in studies where the experimental unit consists of couples of components (for example, twins, eyes, kidneys) or pairs of lifetimes are observed for the same individual (for example, response times for successive courses of a medical treatment).


Most of the proposed estimators have drawbacks; some are not proper while others have no explicit form or are quite complicated to obtain in practice. Furthermore, efficiency results often hold only under restrictive conditions.
In this paper, using a reinforcement scheme, a model for coupled survival times is proposed. We work exclusively with discrete observations, and so with observation space $\mathbb{N}^2 = \{0, 1, \ldots\} \times \{0, 1, \ldots\}$, but in many applications this does not seem to represent a severe limitation.

Our approach can be considered as Bayesian predictive in that the main concern is to provide a sensible procedure to predict the future behaviour of a bivariate lifetimes when data having the same form were collected in the past. Moreover in the model, observations are exchangeable and, hence, define via de Finetti’s Representation Theorem, a prior on the space of bivariate distributions. Although the prior has a structure which makes the posterior intractable, it is possible to study its support and obtain some consistency results. Inference will be done using sampling based methods.

Here we describe the layout of the paper. Section 2 recalls the definition and some features of Generalized Pólya Urn scheme. In Section 3 the construction of a bivariate reinforced process is carried out, a prior on the space of distribution functions on $\mathbb{N}^2$ is derived, and some properties are pointed out, with particular attention to its support and consistency. Section 4 shows how to use this prior to make inference about a bivariate survival function with data eventually subjected to censorship. An example is given in Section 5.

2. Preliminaries

The basic building block of the model is the Generalized Pólya Urn (GPU) scheme. Here we recall the definition of [Walker and Muliere (1997)].

**Definition 1.** Consider a sequence of random variables $\{T_n; n \geq 1\}$ with values on the non-negative integers $\mathbb{N}_0 = \{0, 1, 2, \ldots\}$, and let $\{\alpha_j, \beta_j, j \in \mathbb{N}_0\}$ satisfy

1. $\alpha_j, \beta_j \geq 0 \forall j$;
2. $\alpha_j + \beta_j > 0 \forall j$;
3. $\lim_{n \to \infty} \prod_{j=0}^n \beta_j/\alpha_j = 0$. 

The sequence $\{T_n; n \geq 1\}$ is said to come from a GPU scheme if

$$P[T_1 = t] = \frac{\alpha_t}{\alpha_t + \beta_t} \frac{\prod_{j=0}^{t-1} \beta_j}{\prod_{j=0}^{t-1} \alpha_j + \beta_j}$$

and

$$P[T_{n+1} = t \mid T_n = t_n] = \frac{\alpha_t + m_t(t_n)}{\alpha_t + \beta_t + s_t(t_n)} \frac{\prod_{j=0}^{t-1} \beta_j + r_j(t_n)}{\prod_{j=0}^{t-1} \alpha_j + \beta_j + s_j(t_n)}, \quad (2.1)$$

where $m_j(t_n) = \sum_{k=1}^n 1_{[t_k = j]}$, $r_j(t_n) = \sum_{k=1}^n 1_{[t_k > j]}$ and $s_j(t_n) = m_j(t_n) + r_j(t_n)$. 

Henceforward bold letters indicate vectors, for example \( \mathbf{T}_n = (T_1, \ldots, T_n) \); relations and operations between them are done componentwise.

These predictive distributions arise from a beta process model of Hjort (1990). Briefly, the model puts independent beta prior distributions on hazards at \( t = 1, 2, \ldots \). That is, a random hazard at time \( t \) from the prior is given by \( V_t \prod_{s<t}(1 - V_s) \), with \( V_s \sim \text{beta} (\alpha_s, \beta_s) \). A reason for this name can be found in the following scheme to generate the sequence \( \{T_n\} \).

Consider a Pólya urn \( U_j \) that has \( \alpha_j \) white balls and \( \beta_j \) black balls, \( j = 0, 1, \ldots \). A ball is drawn starting from \( U_0 \); if white put \( T_1 = 0 \), otherwise a ball is drawn from \( U_1 \) and so on, until a white ball is obtained. If the white ball is drawn from \( U_t \), say, then put \( T_1 = t \). All the urns are updated according to the traditional Pólya reinforcement rule - the drawn ball is reintroduced in the corresponding urn along with another of the same color. So, \( T_2, T_3, \ldots \) are generated from continually updated urns.

The GPU scheme translates the idea of Bayesian learning, specifying through (2.1) how to update the knowledge about survival times when data come from follow-up studies on different subjects. Walker and Muliere (1997) and Muliere, Secchi and Walker (2000) show that the sequence \( \{T_n\} \) is exchangeable and, by de Finetti’s Representation Theorem, there exists a random distribution function \( F \), such that, given \( F \), the random variables \( T_n \) are independent and identically distributed with distribution \( F \). Moreover, \( F \) is distributed according to a beta-Stacy process on the integers with parameters \( \{\alpha_j, \beta_j, j \in \mathbb{N}_0\} \). The beta-Stacy process is neutral to the right and, so, conjugate to right censored observations.

Let \( T_1, \ldots, T_n \) be independent and identically distributed and subject to right censoring. Thus, what is observed is \( (T^*_1, \delta_1), \ldots, (T^*_n, \delta_n) \) where

\[
T^*_i = t, \delta_i = 0 \quad \iff \quad \text{a censoring took place: } T_i > t \\
T^*_i = t, \delta_i = 1 \quad \iff \quad \text{a death happened: } T_i = t.
\]

With a quadratic loss function, the predictive distribution of \( T_{n+1} \) given \( (T_n, \delta_n) \) is the Bayes estimator for the random distribution function.

So, analogously for the survival function and under a beta-Stacy prior, we have

\[
\hat{S}(t) = P [T_{n+1} > t | \mathbf{T}_n = \mathbf{t}_n, \mathbf{d}_n = \mathbf{d}_n] \\
= \prod_{j=0}^{t} \left[ 1 - \frac{\alpha_j + m^*_j(\mathbf{t}_n, \mathbf{d}_n)}{\alpha_j + \beta_j + s_j(\mathbf{t}_n)} \right],
\]

where \( \mathbf{d}_n \in \{0, 1\}^n \) and \( m^*_j(\mathbf{t}_n, \mathbf{d}_n) = \sum_{k=1}^n 1_{[t_k=j, d_k=1]} \).

Finally, note the following:
1. without censoring (2.2) reduces to

\[ \hat{S}(t) = P \{ T_{n+1} > t \mid T_n = t_n \} = \prod_{j=0}^{t} \frac{\beta_j + r_j(t_n)}{\alpha_j + \beta_j + s_j(t_n)}; \]

2. the limit of (2.2) for \( \alpha_j, \beta_j \to 0, \forall j \), reduces to classical Kaplan-Meier estimator end extend it when it was not defined.

3. A Bivariate Reinforced Random Process

3.1. Definition

Our aim is to construct a bivariate random process \( \{(X_n, Y_n), n \geq 1\} \) providing a model for coupled lifetimes and incorporating the basic principle of reinforcement similar to the GPU. The idea underlying the GPU scheme is that of reinforcing the path from the origin to the point \( T_n = t \) before generating \( T_{n+1} \), sequentially for \( n \geq 1 \). This is relatively easy because the random variables \( T_n \) can be represented as points on the non-negative line. On the other hand, \( (X_n, Y_n) \) is a point in the non-negative orthant and, unfortunately, there is no unique path from \((0, 0)\) to \((x, y)\). So, the reinforcement procedure must be introduced in an alternative way.

Let \( \{A_n, n \geq 1\}, \{B_n, n \geq 1\} \) and \( \{C_n, n \geq 1\} \) be independent sequences from GPUs with parameters \((\alpha_j^A, \beta_j^A), (\alpha_j^B, \beta_j^B)\) and \((\alpha_j^C, \beta_j^C), j \in \mathbb{N}_0\), respectively. Now, define a bivariate random process \( \{(X_n, Y_n), n \geq 1\} \) by

\[ X_n = A_n + B_n \]
\[ Y_n = A_n + C_n, \quad n \geq 1. \]

(3.1)

The relations above postulate a particular and very easy form of dependence between \( X_n \) and \( Y_n \): for a given couple, each element is supposed to have a common component \( A_n \) and a individual specific one \( B_n \) and \( C_n \). This is a natural way to construct a dependence without forming a parametric model. And, mathematically, it is that the dependence between \( X_n \) and \( Y_n \) is determined by the variance of \( A_n \).

By this construction it turns out, conditionally on \( A_n \), that \( X_n \) and \( Y_n \) are independent. Moreover, \( \sigma(A_n, B_n, C_n) = \sigma(A_n, X_n, Y_n) \).

The structure of the dependence is described by

\[ \text{Cov} (X_1, Y_1) = \text{Var} (A_1) \geq 0, \]
\[ \text{Cov} (X_{n+1}, Y_{n+1} | A_n, B_n, C_n) = \text{Var} (A_{n+1} | A_n), \quad n \geq 1. \]
Hence, we have introduced, correspondingly to each lifetimes couple, an auxiliary variable whose variance describes the covariance between $X_n$ and $Y_n$. Note that even though $A_n$ cannot be directly observed, the predictive distribution of this bivariate process can be easily computed in terms of those of the three GPUs, as is shown in the Appendix A.

The most interesting feature of this bivariate process given in the following proposition.

**Proposition 1.** The sequence of couples $\{(X_n,Y_n), n \geq 1\}$ is exchangeable.

**Proof.** Note that $(X_n,Y_n)$ is a measurable function of $(A_n,B_n,C_n)$. This is an exchangeable sequence and hence so is $\{(X_n,Y_n), n \geq 1\}$.

The de Finetti Representation Theorem assures the existence of a bivariate random distribution function $F_{XY}$, conditionally on which the couples $(X_n,Y_n)$ are independent and identically distributed with distribution $F_{XY}$. The random distribution functions corresponding to GUPs $\{A_n\}$, $\{B_n\}$ and $\{C_n\}$ are $F_A$, $F_B$ and $F_C$; moreover, they are distributed according to beta-Stacy processes with parameters $(\alpha_j^A,\beta_j^A)$, $(\alpha_j^B,\beta_j^B)$ and $(\alpha_j^C,\beta_j^C)$, $j \in \mathbb{N}_0$, respectively. On the other hand, the de Finetti’s measure of $\{(X_n,Y_n)\}$, that is the distribution of the bivariate distribution function $F_{XY}$, is not explicitly known. Nevertheless, it is possible to elicit some of its properties.

First of all, if $F_X$ and $F_Y$ are the marginal distributions of $\{X_n\}$ and $\{Y_n\}$, given $F_A$, $F_B$ and $F_C$, (3.1) implies

$$F_X = F_A * F_B$$
$$F_Y = F_A * F_C.$$ 

Therefore, each of the two marginals is a convolution of two beta-Stacy processes.

In terms of probability functions, we can write

$$P_{XY}(x,y) = \sum_{a=0}^{x\wedge y} P_A(a)P_B(x-a)P_C(y-a) \quad \forall (x,y) \in \mathbb{N}_0^2,$$ 

where $P$ is the probability function corresponding to the distribution $F$. For the marginals we get the usual expression for the convolution.

Moreover, given $F_{XY}, F_A, F_B$ and $F_C$, if $\sigma_A^2 = Var_{F_A}(A)$, the dependence between $X$ and $Y$ is described by

$$Cov_{F_{XY}}(X,Y) = \sigma_A^2.$$ 

Thus, assuming a model for coupled lifetimes data, represented by the bivariate process built on the basis of GPU and equations (3.1) is equivalent, in
a Bayesian point of view, to defining a probability measure on the space of the bivariate distribution functions on $\mathbb{N}_0^2$. Let $\Pi_2$ be such a measure.

### 3.2. The support of $\Pi_2$

Before exploring the properties of the support of $\Pi_2$, it is worth recalling the topology on spaces of probability measures. Given $(\mathcal{X}, \mathcal{B}(\mathcal{X}))$ a measurable space, where $\mathcal{X}$ is a Polish space and $\mathcal{B}(\mathcal{X})$ its Borel $\sigma$-algebra, let $\mathcal{M}$ denote the space of all probability measures on $(\mathcal{X}, \mathcal{B}(\mathcal{X}))$ and $\mathcal{B}(\mathcal{M})$ a suitable Borel $\sigma$-algebra.

If, for a random element $P$ of $(\mathcal{M}, \mathcal{B}(\mathcal{M}))$, $\Pi$ is the prior and $\Pi(\cdot | X_n)$ the posterior, given a vector of observations $X_n = (X_1, \ldots, X_n) \in X^n$ independent and identically distributed according to $P$, the definition of a suitable topology on $(\mathcal{M}, \mathcal{B}(\mathcal{M}))$ allows us to deal with some interesting problems. First of all, we can point out which probability measures belong to the support of $\Pi$ and, secondly, we can describe the asymptotic behaviour of the posterior when the number of observations grows.

**Definition 2.** A subset $U$ of $\mathcal{M}$ is said to be a weak neighborhood of $P_0$ if it contains a set of the form $\{P : |P(A_i) - P_0(A_i)| < \varepsilon_i, i = 1, \ldots, k\}$ where $A_i$ are $P_0$-continuous sets and $\varepsilon_i > 0$. The sequence $\{\Pi(\cdot | X_n), n \geq 1\}$ is said to be weak consistent at $P_0$, if for every weak neighborhood $U$ of $P_0$, $\Pi(U | X_n) \to 1$, $n \to \infty$ a.s. $P_0$.

**Definition 3.** Let $L(\mu)$ the set of all densities with respect to a finite $\sigma$-measure $\mu$. For $f, f_0 \in L(\mu)$ the Kullback-Leibler divergence of $f$ from $f_0$ is

$$K(f, f_0) = \int f \log \frac{f}{f_0} d\mu. \quad (3.5)$$

For $\varepsilon > 0$, $\{f : K(f_0, f) < \varepsilon\}$ is the Kullback-Leibler neighborhood of $f_0$ with radius $\varepsilon$.

It is possible to give a definition of Kullback-Leibler consistency, but we do not deal with it. More important for our purpose is a corollary of a classical and well-known result of Schwartz (1965), providing a sufficient condition for weak consistency.

**Proposition 2.** (Schwartz (1965)) If $\forall \varepsilon > 0$, $\Pi(f : K(f_0, f) < \varepsilon) > 0$, then the posterior is weakly consistent at $f_0$.

Exploiting the properties of the beta-Stacy process, we can obtain some knowledge about the width of the support of $\Pi_2$ with respect to weak topology. We let $P_{XY}(i,j) = p_{ij}, \forall (i,j) \in \mathbb{N}_0^2$. Moreover, for a distribution (or more generally for a measure) $\mu$, let $S_\mu$ indicate its support.
Let $\mathcal{P}_{c2}$ be the set of the probability distributions on $\mathbb{N}_0^2$ such that there exist three probability distributions on $\mathbb{N}_0$ which (3.3) is satisfied.

The above proposition transfers a well-known result for the Dirichlet process, easily proved also for discrete beta-Stacy, to $\mathcal{P}_{c2}$. Proofs of following are in the Appendix B.

**Proposition 3.** If $\Pi_2$ is the prior on the space of the bivariate distributions on $\mathbb{N}_0^2$ determined by the parameters $\alpha_j^A, \beta_j^A, \alpha_j^B, \beta_j^B, \alpha_j^C, \beta_j^C > 0$, $\forall j \in \mathbb{N}_0$, then

$$S_{\Pi_2} \supseteq \mathcal{P}_{c2}. \quad (3.6)$$

**Remark 1.** As will be pointed out in the next section, it is possible to center $\Pi_2$ with respect to three distributions on $\mathbb{N}_0$, $Q_A, Q_B$ and $Q_C$; some of the parameters could be null and, instead of (3.6), we have

$$S_{\Pi_2} \supseteq \{P_{XY} \text{ s.t. } \exists P_A, P_B, P_C \text{ satisfying (3.3) and} \}
S_{P_A} \subseteq S_{Q_A}, S_{P_B} \subseteq S_{Q_B}, S_{P_C} \subseteq S_{Q_C}\} ,$$

where the set on the right-hand side is just a subset of $\mathcal{P}_{c2}$.

A more detailed knowledge of the support of $\Pi_2$ is provided by analysing the behaviour of the prior in the Kullback-Leibler neighborhoods. As in the previous case, the best strategy is to extend to $\mathcal{P}_{c2}$ the properties of the beta-Stacy process on $\mathbb{N}_0$.

**Proposition 4.** Let $\Pi$ the measure induced by a beta-Stacy process with parameters $\alpha_j, \beta_j$, $j \in \mathbb{N}_0$, on the space of distribution functions on $\mathbb{N}_0$ with $p^o = \{p^o_j, j \in \mathbb{N}_0\}$ being one of them. If $\alpha_j, \beta_j$, $j \in \mathbb{N}_0$ are such that

$$\begin{align*}
\sum_{j=0}^{\infty} p^o_j \left[ \frac{\beta_j}{\alpha_j (\alpha_j + \beta_j)} + \beta_j T(\alpha_j, \beta_j) \right] &< +\infty, \quad (3.7) \\
\sum_{j=0}^{\infty} p^o_j \left[ \frac{\alpha_j}{\beta_j (\alpha_j + \beta_j)} + \alpha_j T(\beta_j, \alpha_j) \right] &< +\infty, \quad (3.8)
\end{align*}$$

where $p^o_j = \sum_{k>j} p^o_k$, and

$$T(\alpha, \beta) = \sum_{n=0}^{\infty} \frac{1}{\alpha + n + 1} \frac{1}{\alpha + \beta + n + 1} < +\infty \quad \alpha, \beta > 0,$$

then $\forall \varepsilon > 0$,

$$\Pi \left[ p : \sum_{j=0}^{\infty} p^o_j \log \frac{p^o_j}{p_j} < \varepsilon \right] > 0.$$
The previous proposition gives sufficient conditions for the parameters to produce positive probability in each Kullback-Leibler neighborhood of \( p^o \); straightforwardly, from Schwartz’ result, we get the weak consistency at \( p^o \).

An easy condition for consistency when \( p^o \) is unknown is, for instance,

\[
0 < \alpha \leq \alpha_j \leq \alpha, \forall j \in \mathbb{N}_0, \quad (3.9)
\]

\[
0 < \beta \leq \beta_j \leq \beta, \forall j \in \mathbb{N}_0. \quad (3.10)
\]

For the bivariate prior, the following holds.

**Proposition 5.** Let \( \Pi_2 \) indicate the prior on the space of bivariate distribution function on \( \mathbb{N}_0^2 \) with parameters \( \alpha^A_j, \beta^A_j, \alpha^B_j, \beta^B_j, \alpha^C_j, \beta^C_j > 0, j \in \mathbb{N}_0, \) and \( p^o \in \mathcal{P}_{c^2} \) with marginals \( p^o_X = \{ p^o_i, i \in \mathbb{N}_0 \} \) and \( p^o_Y = \{ p^o_j, j \in \mathbb{N}_0 \} \), where \( p^o_i = \sum_{j=0}^{\infty} p^o_{ij} \) and \( p^o_j = \sum_{i=0}^{\infty} p^o_{ij} \).

If \( \alpha^B_j, \beta^B_j \) for \( j \in \mathbb{N}_0 \) satisfy

\[
\sum_{j=0}^{\infty} p^o_{X,j} \left[ \frac{\beta_j}{\alpha_j (\alpha_j + \beta_j)} + \beta_j T(\alpha_j, \beta_j) \right] < +\infty,
\]

\[
\sum_{j=0}^{\infty} p^o_{Y,j} \left[ \frac{\alpha_j}{\beta_j (\alpha_j + \beta_j)} + \alpha_j T(\beta_j, \alpha_j) \right] < +\infty,
\]

and analogous conditions hold for \( \alpha^C_j, \beta^C_j \) substituting \( p^o_{X,j} \) with \( p^o_{Y,j} \), then \( \forall \varepsilon > 0 \)

\[
\Pi_2 \left[ p : \sum_{i=0}^{\infty} \sum_{j=0}^{\infty} p^o_{ij} \log \frac{p^o_{ij}}{\sum_{a=0}^{\infty} p^o_A p^o_{B,a} p^o_{C,a}} < \varepsilon \right] > 0. \quad (3.11)
\]

Therefore, provided (3.11) holds, the crucial conditions must be satisfied just for \( \alpha^B_j, \beta^B_j \) and \( \alpha^C_j, \beta^C_j \) with respect to the marginals. Taking these parameters as suggested, for instance in (3.9) and (3.10), we obtain that \( \Pi_2 (\cdot | X_n, Y_n) \) is consistent at every \( p^o \in \mathcal{P}_{c^2} \).

The next section shows how to make inference about the bivariate survival function when \( \Pi_2 \) is the prior.

**4. Estimation of a Bivariate Survival Function**

Though the lack of a well-determined form prevents the direct computation of the posterior, it is possible to obtain an estimate of the survival function.

More precisely, let

\[
S(x, y) = P[X > x, Y > y] \quad (4.1)
\]
be a bivariate survival function on \( N^2_0 \) and \((X_n, Y_n)\) be an independent and identically distributed sample from \( S \), where each of the two components is subject to independent right censoring, so that the data take the form \((X^*_n, \delta_n, Y^*_n, \xi_n)\).

With this \( \Pi_2 \) as prior, we are interested in the predictive distribution
\[
\hat{S}(x, y) = P[X_{n+1} > x, Y_{n+1} > y \mid X^*_n, \delta_n, Y^*_n, \xi_n].
\]

(4.2)

**Remark 2.** Note that, if the data are not subjected to censoring, weak consistence of the posterior implies weak consistence of the predictive distribution. Hence the conditions on the parameters of the previous section are sufficient for a consistent predictive distribution as well.

Before any inference, an interpretation of the parameters of the model must be provided. This coincides, in the Bayesian perspective, with specifying the initial distribution centered in accordance with some prior choice.

Recall that if \( F \) is distributed according to a discrete beta-Stacy process, it is possible to center on a given discrete distribution \( G \) (Walker and Muliere (1997)) so that \( E[F(\{j\})] = G(\{j\}) \), putting, \( \forall j, c_j > 0 \) and
\[
\alpha_j = c_j G(\{j\}), \quad \beta_j = c_j \left(1 - \sum_{i=0}^{j} G(\{i\})\right).
\]

Moreover, if \( c_j = c \ \forall j \), then \( \alpha_j + \beta_j = \beta_{j-1} \) and the beta-Stacy reduces to a discrete Dirichlet process. While \( G \) is the distribution corresponding to the initial guess, the parameters \( c_j \) play the role of strength of belief, so that higher values mean higher weight is given to this guess in the posterior distribution.

Hence, to determine the parameters of our model we do not need some complicated idea about the bivariate distribution of the lifetimes, but rather \textit{a priori} guesses on the covariance between \( X \) and \( Y \), \( \text{Cov}(X, Y) \), and on their marginal distributions.

In fact, (3.2) and (3.4) suggest proceeding as follow:
1. choose an initial distribution for \( A, F_0^A \), having variance \( \text{Cov}(X, Y) \), and determine \( \alpha^A_j, \beta^A_j \);
2. given the prior guess \( F^0_X, F^0_Y \) and \( F^0_A \), solve (3.2) to obtain \( F^0_B \) and \( F^0_C \) and then compute \( \alpha^B_j, \beta^B_j, \alpha^C_j, \beta^C_j \).

In the absence of further information about \( F_A \), the choice of the distribution for \( A \) is free, except for the variance; hence, it could be convenient to choose a distribution making the procedure simpler at point 2.

For particular values of the parameters it is possible to abandon the hypothesis of dependence between \( X \) and \( Y \). Indeed, taking \( \alpha^A_0 > 0, \alpha^A_j = 0 \ \forall j \geq 1, \beta^A_0 = 0 \ \forall j \geq 0 \), we obtain \( A_n = 0, X_n = B_n, Y_n = C_n \ \forall n \ a.s. \) and
\[
P[X_{n+1} > x, Y_{n+1} > y \mid X^*_n = x_n, \delta_n = d_n, Y^*_n = y_n, \xi_n = e_n]
\]
This corresponds to assuming as prior for $F_A$ a Dirichlet process centered in a distribution degenerate at 0. If, in addition, $\alpha F^B_j, \beta F^B_j, \alpha F^C_j, \beta F^C_j \rightarrow 0 \forall i$, the result is the product of Kaplan-Meier estimators for $X$ and $Y$.

When the parameters are fixed, the right hand side of (4.2) can be directly expressed in terms of the predictives of $A_n, B_n$ and $C_n$, as in the previous section. The practice computation may yet be cumbersome and laborious.

A Markov Chain Monte Carlo estimation procedure can be achieved without difficulty through the following steps.

1. Given the observations $(X_n^*, \delta_n, Y_n^*, \xi_n), A_n$ is generated via a Gibbs sampler, so the full conditional of $A_n, P_{A_n|A_{n-1}, X_n^*, \delta_n, Y_n^*, \xi_n}$ is

$$P[A_n = a_n | A_{n-1} = a_{n-1}, X_n^* = x_n, \delta_n = d_n, Y_n^* = y_n, \xi_n = e_n]$$

$$\propto P[B_n^* = x_n - a_n, \delta_n = d_n | B_{n-1}^* = x_{n-1} - a_{n-1}, \delta_{n-1} = d_{n-1}]$$

$$P[C_n^* = y_n - a_n, \xi_n = e_n | C_{n-1}^* = y_{n-1} - a_{n-1}, \xi_{n-1} = e_{n-1}]$$

$$P[A_n = a_n | A_{n-1} = a_{n-1}],$$

where

$$P[B_n^* = b, \delta_n = d | B_{n-1}^* = b_{n-1}, \delta_{n-1} = d_{n-1}]$$

$$= \begin{cases} P[B_n \geq b | B_{n-1}^* = b_{n-1}, \delta_{n-1} = d_{n-1}], & d = 0 \\ P[B_n = b | B_{n-1}^* = b_{n-1}, \delta_{n-1} = d_{n-1}], & d = 1 \end{cases}$$

and similarly for $P[C_n^* = y_n - a_n, \xi_n = e_n | C_{n-1}^* = e_{n-1}, \xi_{n-1} = e_{n-1}]$.

For exchangeability of $\{A_i\},$ the other full conditionals $P_{A_i|A_{i-1}, X_i^*, \delta_i, Y_i^*, \xi_i}, i = 1, \ldots, n - 1$ have an analogous form. (Let $A_{i-} = (A_1, \ldots, A_{i-1}, A_{i+1}, \ldots, A_n)$). Then $B_n^* = X_n^* - A_n$ and $C_n^* = Y_n^* - A_n$ are computed.

2. $A_{n+1}, B_{n+1}$ and $C_{n+1}$ are sampled according to the predictive distributions $P_{A_{n+1}|A_n}, P_{B_{n+1}|B_n^*, \delta_n}$ and $P_{C_{n+1}|C_n^*, \xi_n}$.

3. Take $X_{n+1} = A_{n+1} + B_{n+1}$ and $Y_{n+1} = A_{n+1} + C_{n+1}$.

This is straightforward to implement in practice.

5. An Example

We give an example involving a dataset. The following table reports the data (Woolson and Lachenbruch (1981) and Lin and Ying (1993)) consisting of survival times of two kinds of skin grafts on the same burn patient; more precisely, $X$ is referred to as closely matched grafts, $Y$ as poorly matched ones in relation to the HL-A antigen system.
Table 1. Days of survival of skin grafts on burn patients.

<table>
<thead>
<tr>
<th>Patient</th>
<th>1</th>
<th>2</th>
<th>3</th>
<th>4</th>
<th>5</th>
<th>6</th>
<th>7</th>
<th>8</th>
<th>9</th>
<th>10</th>
<th>11</th>
</tr>
</thead>
<tbody>
<tr>
<td>Close match (X)</td>
<td>37</td>
<td>19</td>
<td>57†</td>
<td>93</td>
<td>16</td>
<td>22</td>
<td>20</td>
<td>18</td>
<td>63</td>
<td>29</td>
<td>60†</td>
</tr>
<tr>
<td>Poor match (Y)</td>
<td>29</td>
<td>13</td>
<td>15</td>
<td>26</td>
<td>11</td>
<td>17</td>
<td>26</td>
<td>21</td>
<td>43</td>
<td>15</td>
<td>40</td>
</tr>
</tbody>
</table>

First, we try to reproduce the Kaplan-Meier ("empirical") estimator. Using well-understood ideas connecting Bayes nonparametric estimators, and empirical estimators, we allow $F_A$ to be the distribution degenerate at 0. We take $\alpha_0^A = 1,000$, $\alpha_j^A = 0 \forall j \geq 1$, $\beta_j^A = 0 \forall j \geq 0$, while $\alpha_j^B, \beta_j^B, \alpha_j^C, \beta_j^C$ are all taken close to 0. The marginal estimators are represented by black circles in Figures 1 and 2, and compare very well with the Kaplan-Meier estimates, provided with their standard associated confidence bounds.

Figure 1. Marginal estimate for $X$.  
Figure 2. Marginal estimate for $Y$.

Figure 3 shows the joint estimator. As we know, according to theoretical issues about the meaning of the parameters, in this case the estimators are constructed as if the $X$ and $Y$ data are different (independent) data sets; that is we have lost any dependence between the pairs in order to obtain the empirical marginal estimates.

Here we also give a "smooth" estimate when the prior choice embodies some knowledge about the dependence between $X$ and $Y$. This will carry through, and be updated, into the posterior. We choose to center the priors on Poisson (Po) distributions to exploit some of their closure properties under convolution. For illustrative purposes, we center $F_A$ on the Po(10) distribution, which corresponds to Cov($X, Y$) = 10, and center $F_X$ and $F_Y$ on the Po(40) and Po(25)
distributions, respectively. Solving the equations in (3.2), we obtain a Po(40) distribution for $F_B$ and a Po(15) distribution for $F_C$. Finally, we put all the parameters related to the degree of belief $c_A^j$, $c_B^j$ and $c_C^j$ equal to 1, $\forall j \in \mathbb{N}_0$.

The estimates are represented by white circles in Figures 1 and 2. As can be seen, the marginal estimators are smoothed version of Kaplan-Meier estimators. Similarly, the joint survival function of Figure 4 is a smoothed version of Figure 3.

![Figure 3. Empirical independent case, estimate of the bivariate survival function.](image1)

![Figure 4. Smooth case, estimate of the bivariate survival function.](image2)

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**Appendix A. Predictive Distribution**

The predictive distribution $P[X_{n+1} > x, Y_{n+1} > y|X_n = x_n, Y_n = y_n]$ is nothing but

$$P[X_{n+1} > x, Y_{n+1} > y|X_n = x_n, Y_n = y_n] = \frac{P[X_{n+1} > x, Y_{n+1} > y, X_n = x_n, Y_n = y_n]}{P[X_n = x_n, Y_n = y_n]},$$

where

$$P[X_{n+1} > x, Y_{n+1} > y, X_n = x_n, Y_n = y_n] = \sum_{a_{n+1} = 0}^{x_n} \sum_{a_n = 0}^{y_n} \cdots \sum_{a_1 = 0}^{x_1} \frac{\alpha_{a_{n+1}}^A + m_{a_{n+1}}(a_n)}{\alpha_{a_{n+1}}^A + \beta_{a_{n+1}}^A + s_{a_{n+1}}(a_n)} \prod_{j=0}^{a_{n+1} - 1} \frac{\beta_j^A + r_j(a_n)}{\alpha_j^A + \beta_j^A + s_j(a_n)}$$
Proof of Proposition 3. As $\mathbb{N}_0^d$ is discrete we need only show $\Pi_2[p_{x_iy_i} - p_{x_iy_i}^{0}] < \epsilon$, $i = 1, \ldots, k > 0$ for each $p^0 \in \mathcal{P}_2$, $\forall \epsilon > 0$, $k \geq 1$, $\forall (x_i, y_i), \ldots (x_k, y_k)$

Appendix B: Proofs of Propositions and Lemmas
Now, \( \forall i (m_i = x_i \wedge y_i) \)

\[
|p_{x_i y_i} - p_{x_i y_i}^o| = \sum_{a=0}^{m_i} \left( p_a^A p_{x_i-a}^B p_{y_i-a}^C - p_a^A p_{x_i-a}^B p_{y_i-a}^C \right) \\
- p_a^A p_{x_i-a}^B p_{y_i-a}^C + p_a^A p_{x_i-a}^B p_{y_i-a}^C - p_a^A p_{x_i-a}^B p_{y_i-a}^C \\
\leq \sum_{a=0}^{m_i} |p_a^A - p_a^A| + \sum_{a=0}^{m_i} |p_{x_i-a}^B - p_{x_i-a}^B| + \sum_{a=0}^{m_i} |p_{y_i-a}^C - p_{y_i-a}^C| \\
= \sum_{a=0}^{m_i} |p_a^A - p_a^A| + \sum_{j=x_i-m_i}^{x_i} |p_j^B - p_j^B| + \sum_{j=y_i-m_i}^{y_i} |p_j^C - p_j^C| \text{ a.s. } \Pi_2,
\]

as \( p_i^A, p_i^B, p_i^C \in [0,1] \) and \( p_i^A, p_i^B, p_i^C \in [0,1] \) a.s. \( \Pi_2, \forall i \).

By construction, the sequences \( \{p_i^A, i \in \mathbb{N}_0\} \), \( \{p_i^B, i \in \mathbb{N}_0\} \), and \( \{p_i^C, i \in \mathbb{N}_0\} \) are independent beta-Stacy processed on \( \mathbb{N}_0 \), so

\[
\Pi_2 \left[ |p_{x_i y_i} - p_{x_i y_i}^o| < \varepsilon, i = 1, \ldots, k \right] \geq \Pi_2 \left[ \sum_{j=0}^{m_i} |p_j^A - p_j^A| < \frac{\varepsilon}{3}, i = 1, \ldots, k \right] \\
\Pi_2 \left[ \sum_{j=0}^{x_i} |p_j^B - p_j^B| < \frac{\varepsilon}{3}, i = 1, \ldots, k \right] \\
\Pi_2 \left[ \sum_{j=0}^{y_i} |p_j^C - p_j^C| < \frac{\varepsilon}{3}, i = 1, \ldots, k \right].
\]

Consider, for instance, the first element of the product.

Let \( M = \bigwedge_{i=1}^k m_i \). If

\[
|p_j^A - p_j^A| < \frac{\varepsilon}{3(M+1)} = \varepsilon_M, \quad j = 0, \ldots, M,
\]

then

\[
\sum_{j=0}^{m_i} |p_j^A - p_j^A| < \frac{\varepsilon}{3}, i = 1, \ldots, k,
\]

so that

\[
\Pi_2 \left[ \sum_{j=0}^{m_i} |p_j^A - p_j^A| < \frac{\varepsilon}{3}, i = 1, \ldots, k \right] \geq \Pi_2 \left[ |p_j^A - p_j^A| < \varepsilon_M, j = 0, \ldots, M \right].
\]

(B.1)

Since \( (p_0^A, \ldots, p_M^A) \) has a Generalized Dirichlet distribution with parameters \( \alpha_j^A, \beta_j^A > 0, j = 0, 1, \ldots, M \) (see Walker and Muliere (1997)), for the full support of this distribution, the result in Proposition 3 of Ferguson (1973) can be
generalized to the discrete beta-Stacy process and the last probability in (B.1) is strictly positive.

Lemma 6. If \( X \sim \text{Beta}(\alpha, \beta) \), \( \alpha > 0, \beta > 0 \), then

\[
E[-\log X] = \frac{\beta}{\alpha} \left[ \frac{1}{\alpha + \beta} + \alpha \sum_{n=0}^{\infty} \frac{1}{\alpha + n + 1} \frac{1}{\alpha + \beta + n + 1} \right] < +\infty.
\]

Proof. We write \( B(x; \alpha, \beta) \) for the incomplete beta function and note that \( B(\alpha, \beta) = B(1; \alpha, \beta) = (\Gamma(\alpha)\Gamma(\beta))/\Gamma(\alpha + \beta) \) and \( I(x; \alpha, \beta) = B(x; \alpha, \beta)/B(\alpha, \beta) \).

Now

\[
E[-\log X] = \int_0^1 -\log x \frac{x^{\alpha-1}(1-x)^{\beta-1}}{B(\alpha, \beta)} \, dx = |-\log x I(x; \alpha, \beta)|_0^1 + \int_0^1 \frac{1}{x} I(x; \alpha, \beta) \, dx. \tag{B.2}
\]

The first term is 0 as

\[
\lim_{x \to 0} \log x B(x; \alpha, \beta) = \lim_{x \to 0} \frac{\log x}{B(x; \alpha, \beta)^{-1}}
= \lim_{x \to 0} \frac{1}{x} - B(x; \alpha, \beta)^{-2}x^{\alpha-1}(1-x)^{\beta-1}
= \lim_{x \to 0} - \frac{B(x; \alpha, \beta)^2}{x^\alpha}
= \lim_{x \to 0} - \frac{2B(x; \alpha, \beta)x^{\alpha-1}(1-x)^{\beta-1}}{\alpha x^{\alpha-1}} = 0, \tag{B.3}
\]

where (B.3) and (B.4) apply De l’Hôpital’s rule.

According to Abramowitz and Stegun (1964),

\[
I(x; \alpha, \beta) = \frac{x^\alpha(1-x)^\beta}{\alpha B(\alpha, \beta)} \left[ 1 + \sum_{n=0}^{\infty} \frac{B(\alpha+1,n+1)}{B(\alpha+\beta,n+1)} x^{n+1} \right],
\]

So (B.2) reduces to

\[
\int_0^1 \frac{x^{\alpha-1}(1-x)^\beta}{\alpha B(\alpha, \beta)} \left[ 1 + \sum_{n=0}^{\infty} \frac{B(\alpha+1,n+1)}{B(\alpha+\beta,n+1)} x^{n+1} \right] \, dx
= \frac{1}{\alpha} \left[ \frac{B(\alpha, \beta + 1)}{B(\alpha, \beta)} + \sum_{n=0}^{\infty} \frac{B(\alpha+1,n+1)}{B(\alpha+\beta,n+1)B(\alpha, \beta)} \int_0^1 x^{\alpha+n}(1-x)^{\beta} \, dx \right]
= \frac{1}{\alpha} \left[ \frac{\beta}{\alpha + \beta} + \sum_{n=0}^{\infty} \frac{B(\alpha+1,n+1)B(\alpha+\beta,n+1, \beta + 1)}{B(\alpha+\beta,n+1)B(\alpha, \beta)} \right]\]
\[ = \frac{1}{\alpha} \left[ \frac{\beta}{\alpha + \beta} + \sum_{n=0}^{\infty} \frac{\alpha}{\alpha + n + 1} \frac{\beta}{\alpha + \beta + n + 1} \right]. \]

Since \( \sum_{n=0}^{\infty} (\alpha + n + 1)^{-1} (\alpha + \beta + n + 1)^{-1} < +\infty \), we are finished.

Recall that \( T(\alpha, \beta) = \sum_{n=0}^{\infty} (\alpha + n + 1)^{-1} (\alpha + \beta + n + 1)^{-1} \), \( \alpha, \beta > 0 \), is a well defined function.

**Proof of Proposition 4.** Under \( \Pi \), for \( j \in \mathbb{N}_0 \), \( p_j = u_j \prod_{k=0}^{j-1} (1 - u_k) \), where \( u_k \sim \text{Beta}(\alpha_k, \beta_k) \) and independent. Thus

\[
E \left[ -\sum_{j=0}^{\infty} p_j^0 \log p_j \right] = \sum_{j=0}^{\infty} p_j^0 E \left[ -\log p_j \right]
\]

\[
= \sum_{j=0}^{\infty} p_j^0 E \left[ -\log u_j \right] + \sum_{j=0}^{\infty} \sum_{k=0}^{j-1} p_k^0 E \left[ -\log (1 - u_k) \right]
\]

\[
= \sum_{j=0}^{\infty} p_j^0 \left[ \frac{\beta_j}{\alpha_j (\alpha_j + \beta_j)} + \beta_j T(\alpha_j, \beta_j) \right]
\]

\[
+ \sum_{j=0}^{\infty} p_j^0 \left[ \frac{\alpha_j}{\beta_j (\alpha_j + \beta_j)} + \alpha_j T(\beta_j, \alpha_j) \right],
\]

by Lemma 6.

Conditions (B.7) and (B.8) imply the finiteness of the expected value and

\[-\sum_{j=0}^{\infty} p_j^0 \log p_j < +\infty \quad \text{a.s. } \Pi.\]

Since \( \sum_{j=0}^{\infty} p_j^0 \log(p_j^0/p_j) = \sum_{j=0}^{\infty} p_j^0 \log p_j^0 - \sum_{j=0}^{\infty} p_j^0 \log p_j < \varepsilon \), it is sufficient to require

\[
\sum_{j=0}^{M} p_j^0 \log p_j^0 - \sum_{j=0}^{M} p_j^0 \log p_j < \frac{\varepsilon}{2}. \tag{B.5}
\]

But \( (p_0, \ldots, p_M) \), under \( \Pi \), has a generalized Dirichlet distribution with parameters \( \alpha_j, \beta_j, j = 0, \ldots, M \). Since this distribution has full support on the \( M + 1 \)-dimensional sub-simplex, and the event above is implied by \( \{ p_j > p_j^0/\exp(\varepsilon/2), j = 0, \ldots, M \} \), (B.5) has strictly positive probability.
Proof of Proposition 5. Compute

\[
E \left[ \sum_{i=0}^{\infty} \sum_{j=0}^{\infty} -p^{0}_{ij} \log \sum_{a=0}^{i} p^{A}_{a_i} p^{B}_{i-a} p^{C}_{j-a} \right] = \sum_{i=0}^{\infty} \sum_{j=0}^{\infty} p^{0}_{ij} E \left[ -\log \sum_{a=0}^{i} p^{A}_{a_i} p^{B}_{i-a} p^{C}_{j-a} \right]
\]

\[
\leq \sum_{i=0}^{\infty} \sum_{j=0}^{\infty} p^{0}_{ij} E \left[ -\log p^{A}_{i} p^{B}_{j} p^{C}_{j-a} \right]
\]

\[
= \sum_{i=0}^{\infty} \sum_{j=0}^{\infty} p^{0}_{ij} E \left[ -\log p^{A}_{i} \right] + \sum_{i=0}^{\infty} \sum_{j=0}^{\infty} p^{0}_{ij} E \left[ -\log p^{B}_{j} \right] + \sum_{i=0}^{\infty} \sum_{j=0}^{\infty} p^{0}_{ij} E \left[ -\log p^{C}_{j} \right]
\]

\[
= E \left[ -\log p^{A}_{i} \right] + \sum_{i=0}^{\infty} p^{0}_{i} E \left[ -\log p^{B}_{i} \right] + \sum_{j=0}^{\infty} p^{0}_{j} E \left[ -\log p^{C}_{j} \right].
\]

Hence if \( \alpha_j^B, \beta_j^B \) and \( \alpha_j^C, \beta_j^C \) satisfy the above hypotheses, the expected value is finite.

Now

\[
-\sum_{i=0}^{\infty} \sum_{j=0}^{\infty} p^{0}_{ij} \log \sum_{a=0}^{i} p^{A}_{a_i} p^{B}_{i-a} p^{C}_{j-a} < +\infty \quad \text{a.s. } \Pi_2.
\]

To complete the proof, we can just show

\[
\sum_{i=0}^{M} \sum_{j=0}^{M} p^{0}_{ij} \log p^{0}_{ij} - \sum_{i=0}^{M} \sum_{j=0}^{M} p^{0}_{ij} \log \sum_{a=0}^{i} p^{A}_{a_i} p^{B}_{i-a} p^{C}_{j-a} < \frac{\epsilon}{2} = \epsilon'
\]

has positive probability.

Now, as \( p^{0}_{ij} = \sum_{a=0}^{i} p^{A}_{a_i} p^{B}_{i-a} p^{C}_{j-a} \), \( \forall i, j \in \mathbb{N}_0^2 \), the event above is implied by

\[
p^{A}_{i} > \frac{p^{0}_{i}}{\delta} \quad i = 0, \ldots, M, \tag{B.7}
\]

\[
p^{B}_{i} > \frac{p^{0}_{i}}{\delta} \quad i = 0, \ldots, M, \tag{B.8}
\]

\[
p^{C}_{i} > \frac{p^{0}_{i}}{\delta} \quad i = 0, \ldots, M, \tag{B.9}
\]

where \( \delta = \exp(\epsilon'/3) > 1 \). But, under \( \Pi_2 \), \( (p^{A}_{0}, \ldots, p^{A}_{M}), (p^{B}_{0}, \ldots, p^{B}_{M}) \) and \( (p^{C}, \ldots, p^{C}_{M}) \) have independent generalized Dirichlet distribution with parameters \( \alpha_j^A, \beta_j^A \), \( \alpha_j^B, \beta_j^B \), \( \alpha_j^C, \beta_j^C \) > 0, \( j = 0, \ldots, M \), respectively. The independent events in (B.7), (B.8) and (B.9) define subsets of the \( M + 1 \)-dimensional sub-simplex (the support of the above distribution), so that they have positive probability under \( \Pi_2 \) as well as does (B.6).
References


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