

# Statistics and Machine Learning

## Homework1

Due on October 7, 2005

Exercise 1: (a) Solve

$$\min_{x \in \mathbb{R}^2} \frac{1}{2} x^T \begin{bmatrix} 1 & 0 \\ 0 & 900 \end{bmatrix} x$$

using the *steep descent with exact line search*. You are welcome to copy the MATLAB code from my slides. Start your code with the initial point  $x_0 = [1000 \ 1]^T$ . Stop until  $\|x_{n+1} - x_n\|_2 < 10^{-8}$ . Report your solution and the number of iteration.

**Ans:** We consider solving a unconstrained quadratic programming problem. That is,

$$\min_{x \in \mathbb{R}^n} f(x) = \frac{1}{2} x' Q x + p' x.$$

Let  $g_n$  be the gradient of  $f(x)$  at  $x_n$  and

$$h(\lambda) = f(x_n + \lambda(-g_n)) = \frac{1}{2} (x_n - \lambda g_n)' Q (x_n - \lambda g_n) + p' (x_n - \lambda g_n).$$

Find  $\lambda^*$  such that  $\frac{dh(\lambda)}{d\lambda} = 0$ . We have  $\lambda^* = \frac{g_n' g_n}{g_n' Q g_n}$ .

```
function [x, f_value, iter] = grdlines(Q,p, x0, esp)
%
% min 0.5*x'Q*x+p*x
% Solving unconstrained minimization via
% steep descent with exact line search
%
%The stopping criterion:
% Either the ||gradient||_2^2 ,10^-12
```

```

%
%or    ||x_n+1 -x_n||_2<esp
flag =1; iter = 0; while flag > esp
    grad = Q*x0+p;
    temp1 = grad'*grad;
    if temp1 < 10^-12
        flag = esp
    else
        stepsize = temp1/(grad'*Q*grad);
        x1 = x0 - stepsize*grad;
        flag = norm(x1-x0);
        x0=x1;
    end;
    iter = iter+1;
end;
x = x0;
f_value = 0.5*x'*Q*x+p'*x;

```

- (b) Implement the Newton's method for minimizing a quadratic function  $f(x) = \frac{1}{2}x^T Qx + p^T x$  in MATLAB code. Apply your code to solve the minimization problem in (a).

**Ans:** function [x, f\_value, iter] = newtonqp(Q,p, x0, esp)

```

%
% min 0.5*x'*Q*x+p'*x
% Solving unconstrained QP via
% Newton's method
%
%The stopping criterion:
% Either the ||gradient||_2^2 ,10^-12
%
%or    ||x_n+1 -x_n||_2<esp
flag =1; iter = 0; while flag > esp
    grad = Q*x0+p;
    temp1 = grad'*grad;
    if temp1 < 10^-12
        flag = esp
    else
        %d=inv(Q)*grad;

```

```

        d=x0+inv(Q)*p;
        x1 = x0 - d;
        flag = norm(x1-x0);
        x0=x1;
    end;
    iter = iter+1;
end;
x = x0;
f_value = 0.5*x'*Q*x+p'*x;

```

Exercise 2: Find an approximate solution using MATLAB to the following system by minimizing  $\|Ax - b\|_p$  for  $p = 1, 2, \infty$ . Write down both the approximate solution, and the value of the  $\|Ax - b\|_p$ . Draw the solution points in  $R^2$  and the four equations being solved.

$$\begin{aligned}
 x_1 + 2x_2 &= 2 \\
 2x_1 - x_2 &= -2 \\
 x_1 + x_2 &= 3 \\
 4x_1 - x_2 &= -4
 \end{aligned}$$

Ans: (a)  $\|Ax - b\|_1$ :

```

function [x, residual, one_error]=oneapprox(A,b)
%
%Input A: mXn matrix
%      b: m-vector
%
%Solve the problem by LP
%Output: the approximate solution of Ax=b
%      one_error = ||Ax-b||_1
%
[m,n]=size(A); obj_p=[zeros(n,1); ones(m,1)];
H=[A -eye(m);-A -eye(m)]; h=[b;-b];
[sol, one_error]=linprog(obj_p,H,h);
x=sol(1:n); residual=sol((n+1):(m+n));

```

We have  $x^* = [-0.6667, 1.333]'$  and  $\|Ax^* - b\|_1 = 3$ .

(b)  $\|Ax - b\|_2$ : This problem is equivalent to

$$\min_{x \in \mathbb{R}^2} \frac{1}{2} \|Ax - b\|_2^2 \Leftrightarrow \min_{x \in \mathbb{R}^2} \frac{1}{2} x' A' A x - b' A x.$$

Hence, can use the code given in Exercise 1 (b). Please note that the objective function value returned by the code is *not*  $\|Ax - b\|_2$ . We have  $x^* = [-0.4552, 1.6621]'$  and  $\|Ax^* - b\|_2 = 2.1367$ . Of course, you can solve the *normal equation*,  $x^* = (A'A)^{-1}A'b$  directly.

(c)  $\|Ax - b\|_\infty$ :

```
function [x, inf_error,residual ]=infapprox(A,b)
%
%Input A: mXn matrix
%      b: m-vector
%
%Solve the problem by LP
%Output: the approximate solution of Ax=b
%      inf_error =||Ax-b||_inf
%
[m,n]=size(A); obj_p=[zeros(n,1); 1];
H=[A -ones(m,1);-A -ones(m,1)]; h=[b;-b];
[sol, one_error]=linprog(obj_p,H,h); x=sol(1:n);
inf_error=sol((n+1)); residual=A*x-b;
```

We have  $x^* = [-0.2, 1.8]'$  and  $\|Ax^* - b\|_\infty = 1.4$ .