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DETERMINING THE SIGNAL DIMENSION IN SOS

for $\mathbf{x}_t \in \mathbb{R}^p$ is through the additive noise model,

$$\mathbf{x}_t = \mathbf{\Omega}\mathbf{z}_t + \boldsymbol{\epsilon}_t, \quad t = 1, \dots, T, \quad (6.4)$$

where $\mathbf{\Omega} \in \mathbb{R}^{p \times q}$ is a non-square mixing matrix, $\mathbf{z}_t \in \mathbb{R}^q$ consists of $q < p$ signal components and $\boldsymbol{\epsilon}_t \in \mathbb{R}^p$ is a noise process. This problem is considered in the case of i.i.d. data in Virta and Nordhausen (2018) where the authors use the PCA-transformation to estimate the $p - k$ principal components with smallest variances. Hypothesis testing can be used to pin-point the correct dimension $k = q$ for which these components consist of pure noise. It seems likely to us that a modification of this idea could be utilized also in the context of the series data and model (6.4), and this will be considered in future work. Note, however, that in such a model only the signal dimension and the mixing matrix can be consistently estimated but not the signals itself, contrary to the model proposed in the current work.

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