

# Versatile Parametric Classes of Covariance Functions that Interlace Anisotropies and Hole Effects

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## Supplementary Material

### S1 Literature Review on Spatial Hole Effects

Spatial covariances with hole effects have been reported in different scientific and engineering disciplines, including

- atmospheric science (Bleck, 1975; Thiébaux, 1976, 1985);
- soil science (Webster, 1977; Pierson and Wight, 1991; Ciollaro and Romano, 1995; Guillobez and Arnaud, 1998; Sharifi et al., 2020);
- agronomy (San Martín et al., 2018; Bosaz et al., 2019);
- ecology (Curran, 1988; Cohen et al., 1990; Pastor et al., 1998);

- physics (Price and Kozłowski, 2021);
- manufacturing and materials science (Bonetto et al., 2002; Yang and Shao, 2018; Everett et al., 2020);
- biology (Mary-Huard et al., 2004; Dong et al., 2015);
- image analysis (Balaguer et al., 2010; Balaguer-Beser et al., 2013);
- geotechnical engineering (Chang et al., 2021; Ching et al., 2023);
- geomorphology (Jordan, 2003);
- geodesy (Varbla and Ellmann, 2023);
- glaciology (Irvine-Fynn et al., 2022);
- hydrology (Fiori et al., 2003; Chen, 2005; Salamon et al., 2007);
- outcrop-based geology (Jennings et al., 2000; Budd et al., 2006; Matonti et al., 2015);
- subsurface geology (Journel and Froidevaux, 1982; Jones and Ma, 2001; Lefranc et al., 2008; Parra and Emery, 2013; Emery and Parra, 2013; Le Blévec et al., 2018).

Many of the above references have pointed out the importance of accounting for hole effects for improved spatial predictions, uncertainty modeling and decision-making.

## S2 Visual Illustrations

### S2.1 Basic Models

Figure S1 shows the following basic constructions in dimension  $d = 2$ :

**I.**  $2 \exp(-0.8 \mathbf{h}^\top \mathbf{A} \mathbf{h}) - \exp(-0.4 \mathbf{h}^\top \mathbf{A} \mathbf{h})$ , with  $\mathbf{A} = \begin{pmatrix} 1 & -0.5 \\ -0.5 & 1 \end{pmatrix}$ .

**II.**  $\exp(-0.2 \|\mathbf{h}\|^2) [3.41 \exp(-0.8 h_2^2) - 2.41 \exp(-0.4 h_2^2)]$ .

**III.**  $\exp(-0.5 \|\mathbf{h}\|) \mathcal{W}(5|h_2|)$ , with  $\mathcal{W}$  being the wave model.

The positive semidefiniteness of the first two models, where differences of covariance functions are involved, is a consequence of Theorem 1(i) in Ma (2005).

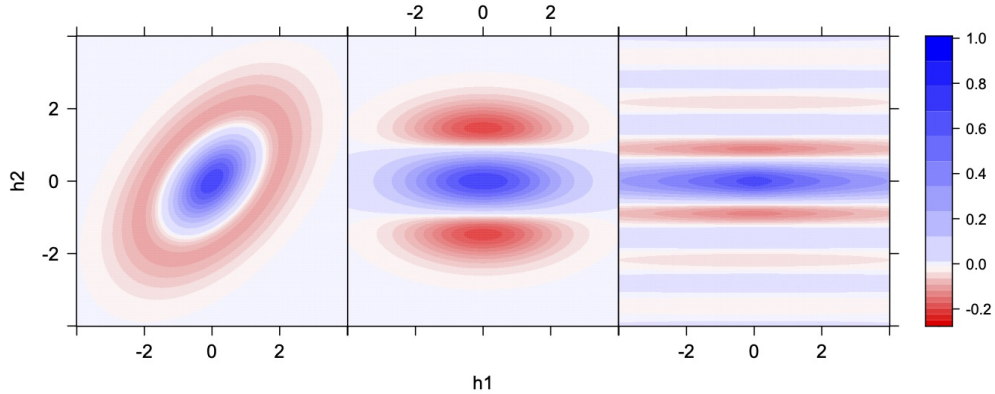


Figure S1: Basic models **I-III** (from left to right).

## S2.2 Proposed Models

We now illustrate the various shapes that can be achieved with the proposed models in dimension  $d = 2$ . We consider the following scenarios:

**I.** The models in Corollary 3 with  $\mathbf{A}_1 = \mathbf{I}_2$  and  $\mathbf{A}_2 = \mathbf{P} \text{diag}(\mu_1, \mu_2) \mathbf{P}^\top$ ,

with  $\mu_1, \mu_2 > 0$  and

$$\mathbf{P} = \begin{bmatrix} \cos(\pi/4) & -\sin(\pi/4) \\ \sin(\pi/4) & \cos(\pi/4) \end{bmatrix}$$

being a rotation matrix. The conditions of Corollary 3 are satisfied if,

and only if,  $\max(\mu_1, \mu_2) \leq 1$  and  $b_1 \sqrt{\mu_1 \mu_2} \geq b_2$ . Thus, we fix  $b_1 = 2.5$ ,

$b_2 = 1$ ,  $\mu_1 = 0.2$  and  $\mu_2 = 0.8$ .

**II.** The models in Corollary 4, with  $b_1 = 2$ ,  $b_2 = 1$ ,  $a_1 = 0.8$  and  $a_2 = 0.4$ ,

with a shift vector given by  $\boldsymbol{\eta} = [1, 1]^\top$ .

**III.** The models in Corollary 5, with  $b_1 = 1$ ,  $b_2 = 2$ ,  $a_1 = 1$  and  $a_2 = 0.5$ ,

and the unit vector  $\mathbf{u} = [1/\sqrt{2}, 1/\sqrt{2}]^\top$ .

Figure S2 shows the contour plots of the Matérn model with  $\nu = 1.5$ , the Cauchy model with  $\delta = 1$  and the Gauss hypergeometric model with  $\alpha = 3, \beta = 7/2$  and  $\gamma = 6$ , after the application of the transformations described in Corollaries 3-5 under scenarios **I-III**, respectively, together with a normalization in order to obtain correlation functions. To improve

the visualization of each individual model, we have chosen specific ranges for plotting. We consider  $\mathbf{h} = [h_1, h_2]^\top \in [-10, 10]^2$  for the first two models, and  $\mathbf{h} = [h_1, h_2]^\top \in [-2, 2]^2$  for the last model. All the covariance functions have been designed to present a hole effect around the northeast direction.

Figure S3 shows  $\mathcal{T}_{a_1, a_2, b_1, b_2, \mathbf{u}}^{(3)}[\mathcal{W}]$  and  $\mathcal{T}_{a_1, a_2, b_1, b_2, \mathbf{u}}^{(3)}[\mathcal{M}_{1/2}, \mathcal{W}]$  in dimension  $d = 2$ , with parameters  $a_1 = a_2 = b_1 = 1$ ,  $b_2 = 2$  and  $\mathbf{u} = [1/\sqrt{2}, 1/\sqrt{2}]^\top$ . While certain structural oscillations from the cardinal sine model persist, the proposed models exhibit a notably amplified hole effect in the  $\mathbf{u}$  direction. Observe that  $\mathcal{T}_{a_1, a_2, b_1, b_2, \mathbf{u}}^{(3)}[\mathcal{W}]$  exceeds the lower bound required for isotropic models in  $\mathbb{R}^2$ .

### S3 Simulation Study

We use simulated data to compare covariance models with or without hole effect and anisotropy. Specifically, we consider  $d = 2$  and the following covariance structures, where  $\mathcal{H}_{\alpha, \beta, \gamma}$  stands for the radial part of the Gauss hypergeometric model defined in (4.21):

- **Model 1.**  $\sigma^2 \mathcal{H}_{\alpha, \beta, \gamma}(\sqrt{a} \|\mathbf{h}\|)$
- **Model 2.**  $b_1 \mathcal{H}_{\alpha, \beta, \gamma}(\sqrt{a_1} \|\mathbf{h}\|) - b_2 \mathcal{H}_{\alpha, \beta, \gamma}(\sqrt{a_2} \|\mathbf{h}\|)$

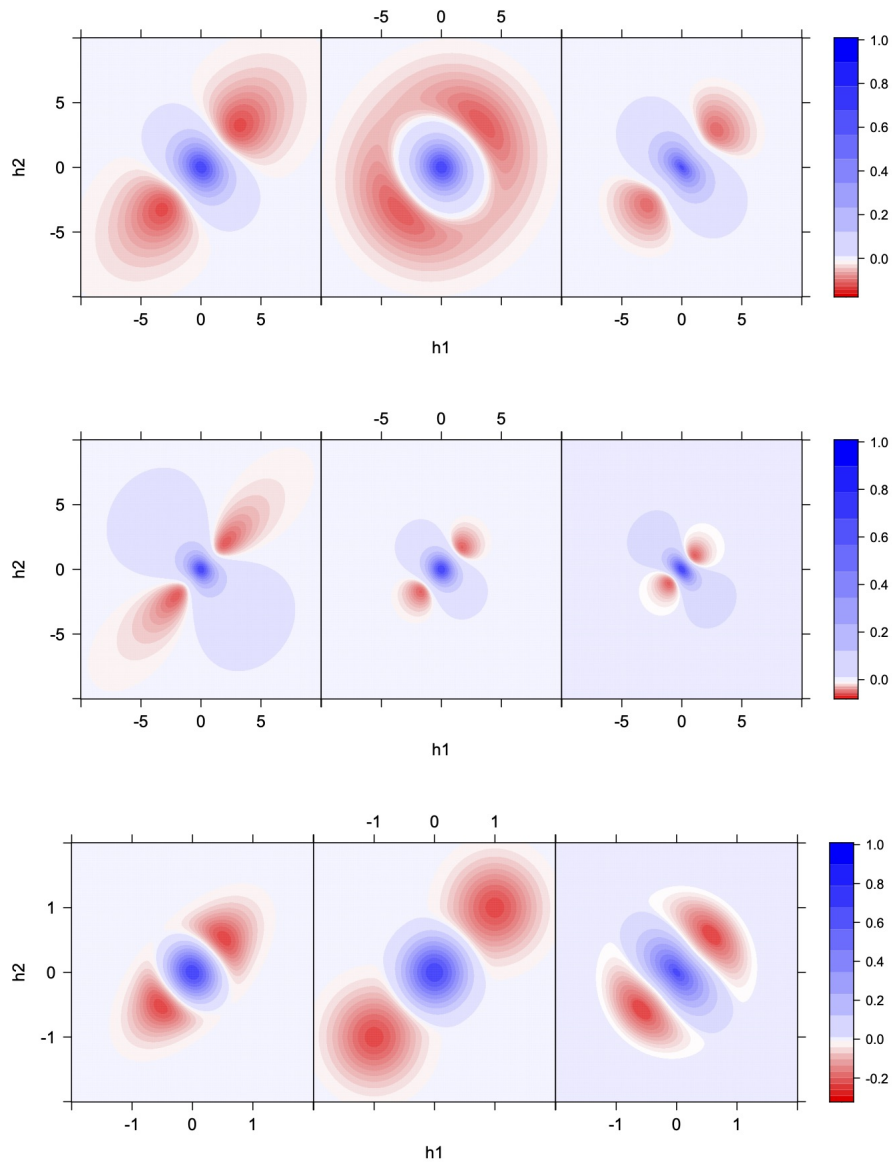


Figure S2: Different combinations of anisotropies and hole-effects for the transformed Matérn (top), the transformed Cauchy (middle) and the transformed Gauss hypergeometric (bottom) models. From left to right we consider the transformations introduced in Corollaries 3-5, respectively. The values of the parameters have been described in scenarios **I-III**.

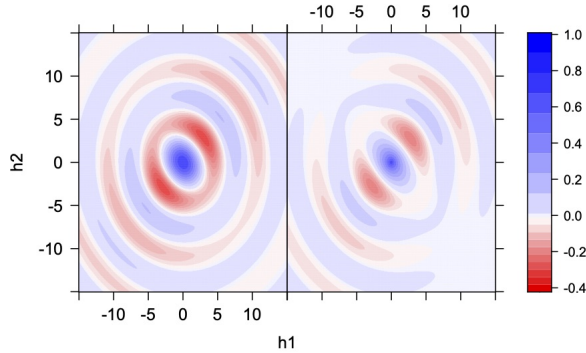


Figure S3: Models  $\mathcal{T}_{a_1, a_2, b_1, b_2, \mathbf{u}}^{(3)}[\mathcal{W}]$  (Left) and  $\mathcal{T}_{a_1, a_2, b_1, b_2, \mathbf{u}}^{(3)}[\mathcal{M}_{1/2}, \mathcal{W}]$  (Right).

- **Model 3.**  $b_1 \mathcal{H}_{\alpha, \beta, \gamma}(\sqrt{a_1} \|\mathbf{h}\|) - \frac{b_2}{2} (\mathcal{H}_{\alpha, \beta, \gamma}(\sqrt{a_2} \|\mathbf{h} - \boldsymbol{\eta}\|) + \mathcal{H}_{\alpha, \beta, \gamma}(\sqrt{a_2} \|\mathbf{h} + \boldsymbol{\eta}\|))$ .

As in Section S2.2, we fix  $\alpha = 3$ ,  $\beta = 7/2$  and  $\gamma = 6$ , which corresponds to the well-known cubic model (see Emery and Alegría, 2022). Unlike Model 1, Models 2 and 3 can exhibit a hole effect. The hole effect in Model 2 appears in all directions, whereas Model 3 is the only anisotropic model and exhibits the hole effect in specific directions (it is a special case of construction (3.15)). These models offer a range of increasing complexity to make statistical comparisons, and further contribute to the ongoing discussion in this manuscript regarding the model versatility.

Figure S4 displays realizations of Gaussian random fields with these covariance models over a regular grid with  $80 \times 80$  nodes in the square  $[0, 4]^2$ .

The simulation was performed by means of the Cholesky factorization of the covariance matrix; the same seed for random number generation was considered for each realization. The values of the parameters were  $\sigma^2 = 1$  and  $a = 1/2$  for Model 1, and  $b_1 = 2$ ,  $b_2 = 1$ ,  $a_1 = 1$ ,  $a_2 = 1/2$  for Models 2 and 3. In addition, for Model 3, we used  $\boldsymbol{\eta} = [1/\sqrt{2}, 1/\sqrt{2}]^\top$ . Note that these values satisfy the admissibility condition (3.14). Although some distinction emerges among these realizations, the presence or absence of hole effect or anisotropy may be difficult to perceive with a naked eye. To explore this aspect, we simulate 100 independent samples from each model, over a grid with  $20 \times 20$  nodes in  $[0, 4]^2$ , with the parametric setting explained above, and calculate sample variograms across the northeast direction (parallel to  $\boldsymbol{\eta}$ ) and the southeast direction (orthogonal to  $\boldsymbol{\eta}$ ). The results are reported in Figure S5, together with the average sample variograms and the theoretical underlying models. For the first model, there is no hole effect in either direction. In the second model, a hole effect is observed along both directions. In the third model, a hole effect is observed in one direction but not in the other. These observations align closely with the expected properties of the underlying theoretical models, and serve as a reinforcement of their main features.

Now, we conduct a study to quantify the difference in terms of good-



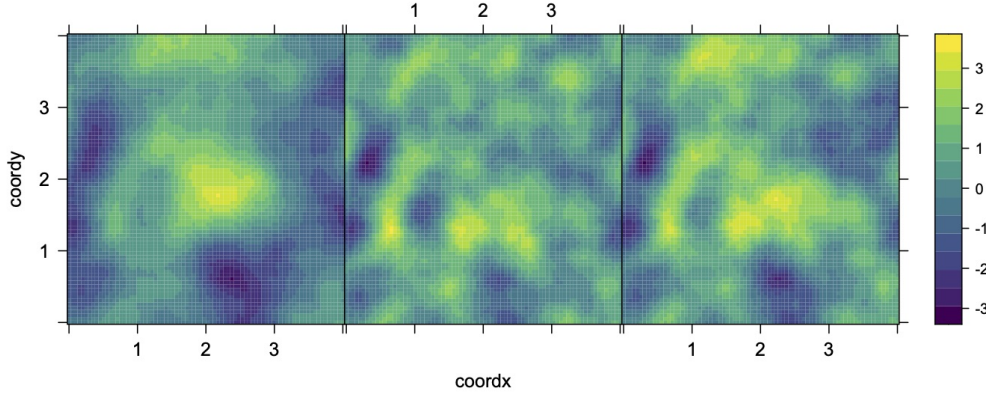


Figure S4: Realizations of Gaussian random fields from Models 1, 2 and 3 (from left to right), over a regular grid with  $80 \times 80$  nodes in the square  $[0, 4]^2$ .

ness of fit of Model 3 with respect to the other models, when the inherent correlation structure presents a hole effect in a specific direction.

Let us first establish an adequate parameterization. Note that the intensity of the hole effect in Models 2 and 3 depends on the ratios  $b_1/b_2$  and  $a_1/a_2$  (see condition (3.14)). For instance, when  $b_1/b_2$  decreases, not exceeding its minimum admissible value  $a_1/a_2$ , the significance of the negative term in the covariance structure amplifies and the hole effect emerges. Since only the ratios matter, allowing the parameters to vary freely could give rise to identifiability issues. To circumvent this problem, we parameterize Model 2 in the following way:

$$\sigma^2 (b \mathcal{H}_{\alpha,\beta,\gamma}(\|\mathbf{h}\|) - \mathcal{H}_{\alpha,\beta,\gamma}(\sqrt{a}\|\mathbf{h}\|)) ,$$

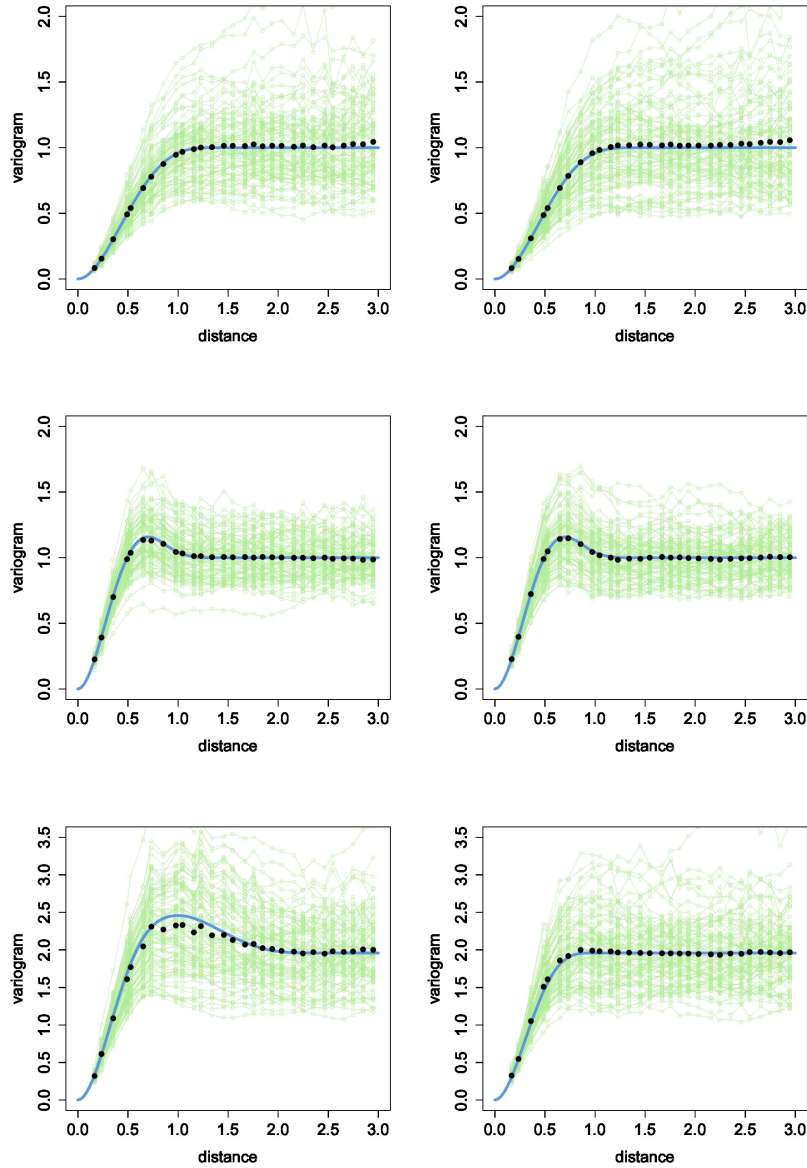


Figure S5: Sample directional variograms for 100 realizations (green lines), average of sample directional variograms (black dots) and theoretical directional variograms (blue solid lines). From the top, each row refers to Models 1, 2 and 3, respectively. Left panels are associated to northeast direction, whereas right panels correspond to southeast direction.

and the validity condition (3.14) simplifies into  $b \geq 1/a$ . A similar parameterization is used for Model 3. In addition,  $\boldsymbol{\eta}$  is taken as a unit vector, parameterized through an angle  $\theta \in [0, 2\pi)$ , i.e.,  $\boldsymbol{\eta} = (\cos \theta, \sin \theta)^\top$ . To sum up, Model 1 is parameterized by  $(a, \sigma^2)$ , Model 2 by  $(b, a, \sigma^2)$  and Model 3 by  $(b, a, \theta, \sigma^2)$ . The parameters in Model 3 allow us to control the hole effect, the correlation range, the predominant direction of the hole effect, and the variance of the random field.

We simulate independent samples from Model 3, considering the following scenarios: **1.**  $(a, \theta) = (1/2, \pi/4)$ , **2.**  $(a, \theta) = (3/4, \pi/4)$ , **3.**  $(a, \theta) = (1/2, 3\pi/4)$  and **4.**  $(a, \theta) = (3/4, 3\pi/4)$ . For each scenario,  $b = 1/a$ , i.e., we use its minimum admissible value, and  $\sigma^2 = 1$ . To understand the scenarios covered, let us analyze Model 2, as Model 3 inherits similar characteristics from it. Normalizing Model 2 to obtain a correlation structure, we find numerically that, for scenarios 2 and 4, its minimum value is  $-0.170$  at a distance of  $0.64$ . In contrast, for scenarios 1 and 3, the minimum value is  $-0.158$  at a distance of  $0.70$ . These scenarios also encompass two distinct directions regarding the presence of the hole effect.

For each scenario, we simulate 100 independent realizations from Model 3, fit each model through maximum likelihood and assess their performance through the Akaike Information Criterion (AIC), which inherently penalizes

the number of parameters. The results are summarized in Table S1. Model 3 consistently shows smaller AIC averages in each of the scenarios, as expected. This improvement is more pronounced in scenarios 2 and 4, where the hole effect is more marked and the correlation range is smaller. Model 2 exhibits slightly better performance than Model 1 in all scenarios, yet both models demonstrate suboptimal results due to the misspecification. Figure S6 displays a more comprehensive panorama of the AIC values for Model 1 in comparison to those of Model 3, depicted through their ratios across 100 realizations. As AIC values are negative, a ratio less than one indicates superior performance of Model 3. While most values fall below one; it is worth noting that many of them are considerably smaller than one (it is common to observe improvements of 10% to 20%), providing further support for the superiority of Model 3. For completeness, Figure S7 displays centered boxplots for the maximum likelihood estimates of Model 3 involved in this experiment. These plots reveal unbiased estimates, emphasizing that the selected parameterization yields models with statistically meaningful and identifiable parameters.

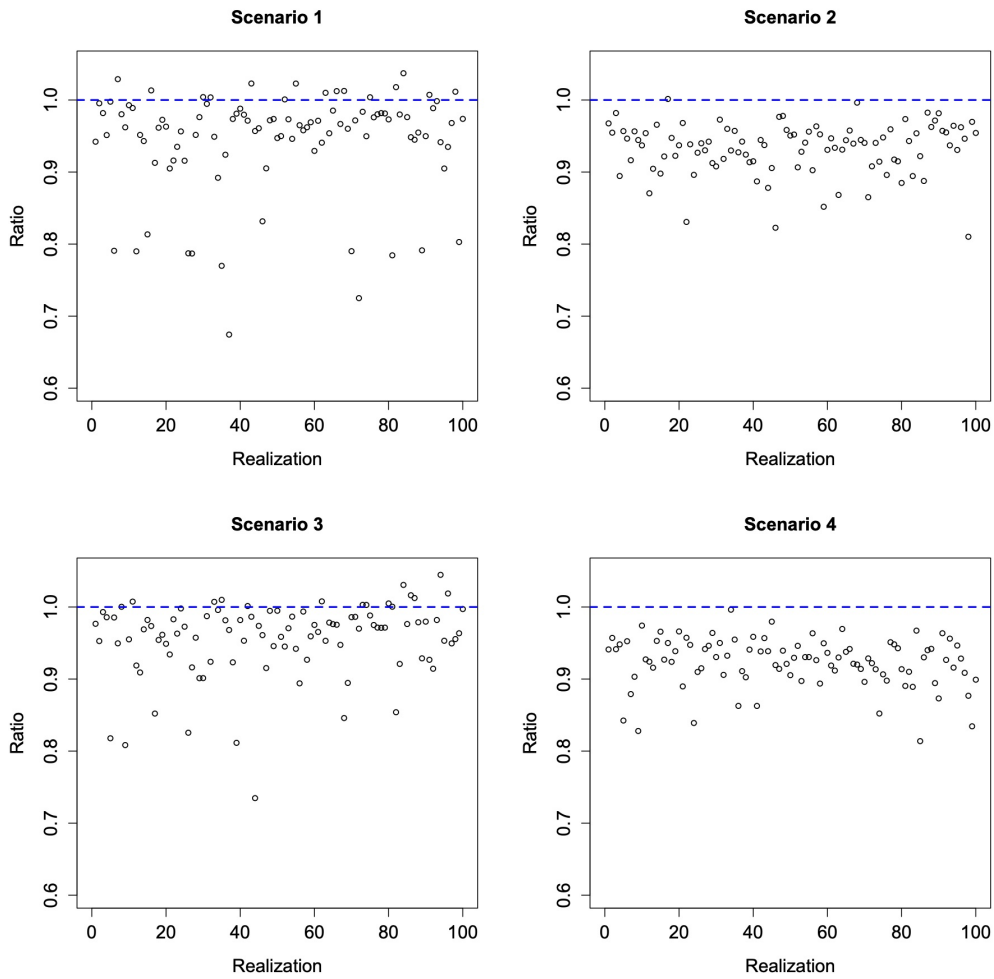


Figure S6: Ratios between AIC values for Models 1 and 3 across 100 realizations, for each scenario.

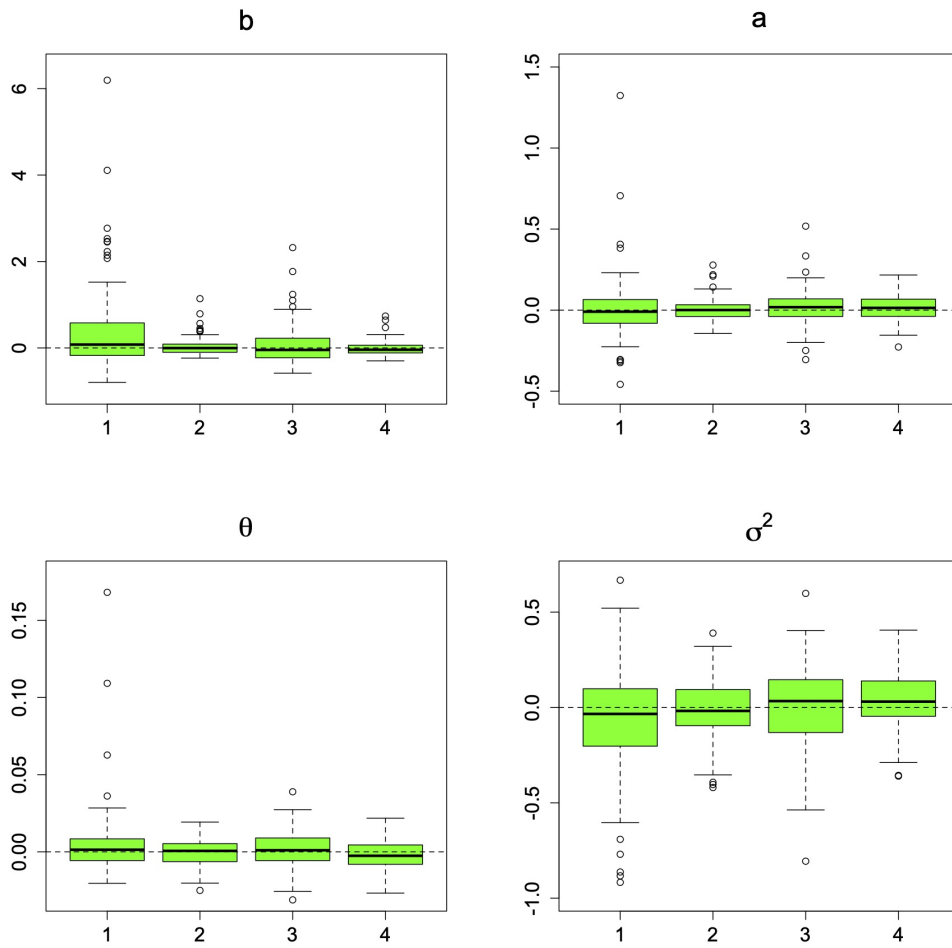


Figure S7: Centered boxplots of the maximum likelihood estimates of Model 3 for scenarios 1 to 4.

Table S1: Summary statistics of AIC values from fitting each model on 100 independent realizations.

		$a = 0.50$				$a = 0.75$			
		Q <sub>1</sub>	Median	Q <sub>3</sub>	Mean	Q <sub>1</sub>	Median	Q <sub>3</sub>	Mean
$\theta = \pi/4$	Model 1	-165.4	-147.8	-126.0	-146.5	-330.0	-313.1	-296.2	-313.4
	Model 2	-167.0	-151.5	-129.3	-148.9	-334.2	-313.6	-296.1	-314.8
	Model 3	-173.6	-157.0	-136.9	-155.1	-349.4	-336.1	-316.9	-336.0
$\theta = 3\pi/4$	Model 1	-166.8	-146.1	-125.8	-147.4	-331.7	-310.4	-294.3	-311.2
	Model 2	-165.5	-146.8	-126.3	-147.7	-332.9	-313.1	-293.6	-312.1
	Model 3	-172.2	-150.2	-132.4	-154.5	-356.6	-336.8	-314.2	-337.3

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