

Statistica Sinica Preprint No: SS-2021-0120

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| Title | Testing for Threshold Effects in the TARMA Framework |
| Manuscript ID | SS-2021-0120 |
| URL | http://www.stat.sinica.edu.tw/statistica/ |
| DOI | 10.5705/ss.202021.0120 |
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Testing for threshold effects in the TARMA framework

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Abstract: We present supremum Lagrange multiplier tests for comparing a linear ARMA specification against its threshold ARMA extension. We derive the asymptotic distribution of the test statistics under both the null hypothesis and contiguous local alternatives, and prove the consistency of the tests. A Monte Carlo study shows that the tests enjoy good finite-sample properties and are robust against various forms of model mis-specification. Furthermore, the performance of the tests is not affected by the unknown order of the model. The tests have a low computational burden and do not suffer from some of the drawbacks that affect the quasi-likelihood ratio setting. Lastly, we present an application to a time series of standardized tree-ring growth indices. Our results can lead to new research in climate studies.

Key words and phrases: Threshold ARMA models, Lagrange multiplier test,

Linearity testing, Marked empirical processes, tree-rings.

1. Introduction

Threshold AR (TAR) models are very popular and widely applied in ecology, economics, epidemiology, finance and many other fields (Tong, 1990; Chan, 2009; Tong, 2011; Hansen, 2011). Three special issues have been devoted to such tests: *Statistica Sinica* in 2007 (Chan and Li, 2007), *Statistics and Its Interface* in 2011 (Chan et al., 2011), and the *Journal of Business and Economic Statistics* in 2017 (Chan et al., 2017). In particular, threshold autoregressive-moving average (TARMA) models, introduced by Tong (see Tong, 1990), are nonlinear models with a regime-switching mechanism specifying an autoregressive moving-average (ARMA) sub-model in each regime. They include two particular models of independent interest, namely, the TAR model and the threshold MA (TMA) model. The combination of the two yields the TARMA model, which is a parsimonious, but rich model for nonlinear time series analysis; see, for example, Goracci (2020, 2021)). Least squares estimation of the parameters of a general TARMA model typically assumes stationarity and ergodicity (e.g., Li et al., 2011), although few studies have examined these assumptions. An exception is the work of Ling (1999), albeit his conditions are quite restrictive. In fact, a full characterization of the long-run probabilistic behavior of TARMA models was only recently made available. To the best of our knowledge, Chan and

[Goracci \(2019\)](#) is the only study to provide the necessary and sufficient conditions for the ergodicity of the first-order TARMA model. Moreover, they provide a complete parametric classification of the first-order TARMA into regions of (geometric) ergodicity, null recurrence, and transience.

Many works have developed tests for a linear model versus its threshold extension, although most focus on autoregressive (AR)-type models. For instance, [Petrucci and Davies \(1986\)](#) developed a portmanteau test based on cumulative sums of standardized residuals from an AR fit, and [Tsay \(1998\)](#) studied a variation of this test. [Luukkonen et al. \(1988\)](#) proposed a Lagrange multiplier test for linearity against nonlinear models, including TAR models. A Lagrange multiplier test was also developed by [Wong and Li \(1997, 2000\)](#) for TAR models with conditional heteroscedasticity. Quasi-likelihood ratio tests were studied in [Chan \(1990\)](#), [Chan and Tong \(1990\)](#), [Chan \(1991\)](#), and [Su and Chan \(2017\)](#) for threshold diffusion. For a review, see [Tong \(2011\)](#).

Threshold models that include moving-average (MA) components have been under-developed, probably due to the mathematical difficulties that arise when MA components are included. However, since data are almost always affected by measurement errors, a TARMA model is more appropriate than a TAR model. Indeed, it is known that an AR model with

measurement errors becomes an ARMA model. Similarly, it can be proved that a TAR model with measurement errors can be approximated by a TARMA model (see, e.g., [Chan et al., 2020](#)). Note that the adoption of a TARMA model is significant because, in the presence of measurement errors, a high-order AR model is necessary if tests are conducted only with respect to TAR models, and a loss of power occurs.

For MA-type models, [Ling and Tong \(2005\)](#) investigated a quasi-likelihood ratio test for the MA model against its threshold extension. They proved that, under the null hypothesis, the test statistic converges weakly to a functional of the centered Gaussian process. Their results were extended by [Li and Li \(2008\)](#) to the case with GARCH errors. For a comprehensive development, see [Chan et al. \(2014\)](#). [Li and Li \(2011\)](#) developed a quasi-likelihood ratio statistic to test the presence of thresholds in an ARMA model setting. They used a stochastic permutation device to build the distribution of the statistic under the null hypothesis.

In this study we extend the work of [Chan \(1990\)](#) and [Ling and Tong \(2005\)](#) and propose supremum Lagrange multiplier test statistics (supLM) for determining whether a TARMA model fits a stationary time series significantly better than an ARMA model does. One of the main advantages of using a Lagrange multiplier test over the likelihood-ratio test is that the

former avoids estimation under the alternative hypothesis. We prove that under both the null hypothesis and contiguous local alternatives, the asymptotic distributions of the test statistics reduce to functionals of Gaussian processes that are centered under the null and noncentered under the alternative. Our results extend the work of [Ling and Tong \(2005\)](#) on the weak convergence of linear marked empirical processes with infinitely many markers to the case where the underlying process is an ARMA model. Moreover, we prove the consistency of our tests and show that they have nontrivial power against local alternatives.

In order to test the null hypothesis of an ARMA model against the alternative hypothesis of a TARMA model, we propose two supLM statistics. In the first, denoted by sLM, only the AR part is tested for threshold nonlinearity. In the second statistic, denoted by sLM*, both the AR and MA parts are tested. Note that the sLM* statistic does not reduce to the sLM when the MA part is either absent or regime independent. This is reflected in the different finite-sample behavior of the tests.

We explore systematically the performance of our supLM tests and compare them with the quasi-likelihood ratio (qLR) test of [Li and Li \(2011\)](#). An extensive simulation study shows clearly that our tests have better size and power, while incurring a much lower computational burden. Further-

more, the two supLM tests are robust against model mis-specification, and their performance is not adversely affected if the order of the ARMA model is unknown and selected using the Hannan–Rissanen procedure. Lastly, we apply our tests to time series of standardized tree-ring growth indices. We show that a TARMA model provides a better fit than the ARMA models commonly adopted in the literature. We suggest that a TARMA model can lead to a deeper understanding of the tree-ring dynamics, possibly leading to novel directions of research in climate studies, which incorporate nonlinear dynamics.

The rest of the paper is organized as follows. In Section 2, we present our setting and the two tests. In Section 3, we derive the asymptotic distributions of the supLM test statistics under the null hypothesis. In Section 4, we derive the asymptotic distributions of the statistics under local contiguous alternatives and prove the consistency of the tests. Section 5 contains a Monte Carlo study to assess the finite-sample performance of our proposed tests. We also investigate the behavior of the tests under model mis-specification and when the order of the tested model is unknown. In Section 6, we apply our tests to a tree-ring time series. We conclude the paper in Section 7. All proofs and the tabulated quantiles of the null distribution are provided in the online Supplementary Material, which also

contains additional results from both the simulation study and the tree-ring data analysis.

2. Notation and preliminaries

Let the time series $\{X_t : t = 1, \dots, n\}$ follow the TARMA(p, q) model defined by the difference equation

$$X_t = \phi_0 + \sum_{i=1}^p \phi_i X_{t-i} - \sum_{j=1}^q \theta_j \varepsilon_{t-j} + \varepsilon_t + \left(\varphi_0 + \sum_{i=1}^p \varphi_i X_{t-i} - \sum_{j=1}^q \vartheta_j \varepsilon_{t-j} \right) I(X_{t-d} \leq r). \quad (2.1)$$

When the MA parameters are regime independent, the rightmost summation involving ϑ_j , for $j = 1, \dots, q$, is absent. The innovation process $\{\varepsilon_t\}$ is assumed to be independent and identically distributed (i.i.d.) with zero mean and $E[\varepsilon_t^2] = \sigma^2 < \infty$. The positive integers p and q are the AR and MA orders, respectively, and d is the delay parameter, which takes positive integer values. We assume p, q , and d are known. Moreover, $I(\cdot)$ is the indicator function and $r \in \mathbb{R}$ is the threshold parameter. For notational convenience, we abbreviate $I(X_t \leq r)$ as $I_r(X_t)$. Let $\boldsymbol{\eta}$ be the vector of all

the parameters (excluding the threshold r) in Model (2.1), that is,

$$\boldsymbol{\eta} = (\boldsymbol{\eta}_1^\top, \boldsymbol{\eta}_2^\top, \sigma^2)^\top \in \Theta_\eta = \Theta_\phi \times \Theta_\theta \times \Theta_\varphi \times \Theta_\vartheta \times (0, +\infty),$$

$$\boldsymbol{\eta}_1 = (\boldsymbol{\phi}^\top, \boldsymbol{\theta}^\top)^\top, \quad \boldsymbol{\eta}_2 = (\boldsymbol{\varphi}^\top, \boldsymbol{\vartheta}^\top)^\top,$$

where

$$\boldsymbol{\phi} = (\phi_0, \phi_1, \dots, \phi_p)^\top \in \Theta_\phi; \quad \boldsymbol{\theta} = (\theta_1, \dots, \theta_q)^\top \in \Theta_\theta;$$

$$\boldsymbol{\varphi} = (\varphi_0, \varphi_1, \dots, \varphi_p)^\top \in \Theta_\varphi; \quad \boldsymbol{\vartheta} = (\vartheta_1, \dots, \vartheta_q)^\top \in \Theta_\vartheta, \quad (2.2)$$

with Θ_ϕ and Θ_φ (Θ_θ and Θ_ϑ) being subsets of \mathbb{R}^{p+1} (\mathbb{R}^q). Moreover, let

$\boldsymbol{\Psi}$ be the vector that contains the parameters to be tested, partitioned as

$\boldsymbol{\Psi} = (\boldsymbol{\Psi}_1^\top, \boldsymbol{\Psi}_2^\top)^\top$, where

$$\boldsymbol{\Psi}_1 = \boldsymbol{\phi}, \quad \boldsymbol{\Psi}_2 = \boldsymbol{\varphi} \text{ if only the AR part is tested (sLM), and} \quad (2.3)$$

$\boldsymbol{\Psi}_1 = (\boldsymbol{\phi}^\top, \boldsymbol{\theta}^\top)^\top, \quad \boldsymbol{\Psi}_2 = (\boldsymbol{\varphi}^\top, \boldsymbol{\vartheta}^\top)^\top$ if both the AR and the MA parts are tested (sLM*).

All true parameters have a subscript zero, whereas unknown ones do not.

Specifically, the true parameters are denoted by

$$\boldsymbol{\eta}_0 = (\boldsymbol{\eta}_{0,1}^\top, \boldsymbol{\eta}_{0,2}^\top, \sigma_0^2)^\top; \quad \boldsymbol{\Psi}_0 = (\boldsymbol{\Psi}_{0,1}^\top, \boldsymbol{\Psi}_{0,2}^\top)^\top;$$

$$\boldsymbol{\phi}_0 = (\phi_{0,0}, \phi_{0,1}, \dots, \phi_{0,p})^\top; \quad \boldsymbol{\theta}_0 = (\theta_{0,1}, \dots, \theta_{0,q})^\top;$$

$$\boldsymbol{\varphi}_0 = (\varphi_{0,0}, \varphi_{0,1}, \dots, \varphi_{0,p})^\top; \quad \boldsymbol{\vartheta}_0 = (\vartheta_{0,1}, \dots, \vartheta_{0,q})^\top.$$

In addition, we assume $\boldsymbol{\eta}_0$ is an interior point of the parameter space.

We test whether a TARMA(p, q) model provides a significantly better fit than that of the linear ARMA(p, q) model. To this end, we develop two Lagrange multiplier test statistics for the hypotheses:

$$\begin{cases} H_0 & : \Psi_{0,2} = \mathbf{0}, \\ H_1 & : \Psi_{0,2} \neq \mathbf{0}, \end{cases}$$

where $\mathbf{0}$ is the vector of all zeroes. The statistic for testing the threshold effect in the AR parameters is denoted as sLM, whereas sLM* is the statistic for the general test in which both the AR and the MA parameters change across regimes. Under H_0 , the time series follows the linear ARMA(p, q) model

$$X_t = \phi_{0,0} + \sum_{i=1}^p \phi_{0,i} X_{t-i} - \sum_{j=1}^q \theta_{0,j} \varepsilon_{t-j} + \varepsilon_t. \quad (2.4)$$

To study the asymptotic properties of the tests, we assume the model is ergodic and invertible under both the null hypothesis and the alternative hypothesis. Let the AR and MA polynomials be defined as follows:

$$\phi(z) = 1 - \phi_1 z - \phi_2 z^2 - \dots - \phi_p z^p; \quad \theta(z) = 1 - \theta_1 z - \theta_2 z^2 - \dots - \theta_q z^q.$$

We assume the following.

Assumption A1. $\phi(z) \neq 0$ and $\theta(z) \neq 0$, for all $z \in \mathbb{C}$, such that $|z| \leq 1$ and they do not share common roots. Moreover, $\{X_t\}$ is ergodic and invertible under both H_0 and H_1 .

The ergodicity of TARMA models was investigated in [Ling \(1999\)](#) and [Chan and Goracci \(2019\)](#), and the invertibility of TARMA models was studied in [Chan and Tong \(2010\)](#). A discussion on the invertibility of TMA models can also be found in [Ling and Tong \(2005\)](#) and [Ling et al. \(2007\)](#).

Next, we fully develop the theory for the general statistic sLM*. Unless otherwise stated, the results also hold for the statistic sLM. Suppose we observe X_1, \dots, X_n . The Gaussian log-likelihood, conditional on the initial values X_0, X_{-1}, \dots , is given by

$$\begin{aligned} \ell_n(\boldsymbol{\eta}, r) &= -\frac{n}{2} \ln(\sigma^2 2\pi) - \frac{1}{2\sigma^2} \sum_{t=1}^n \varepsilon_t^2(\boldsymbol{\eta}, r), \quad (2.5) \\ \varepsilon_t(\boldsymbol{\eta}, r) &= X_t - \left\{ \phi_0 + \sum_{i=1}^p \phi_i X_{t-i} - \sum_{j=1}^q \theta_j \varepsilon_{t-j}(\boldsymbol{\eta}, r) \right\} \\ &\quad - \left\{ \varphi_0 + \sum_{i=1}^p \varphi_i X_{t-i} - \sum_{j=1}^q \vartheta_j \varepsilon_{t-j}(\boldsymbol{\eta}, r) \right\} I_r(X_{t-d}), \quad (2.6) \end{aligned}$$

and the q initial values are set to zero. The rightmost summation involving ϑ_j , for $j = 1, \dots, q$, is absent for the sLM test. Furthermore,

$$\varepsilon_t(\boldsymbol{\eta}_1) = \varepsilon_t(\boldsymbol{\eta}, -\infty) = X_t - \left\{ \phi_0 + \sum_{i=1}^p \phi_i X_{t-i} - \sum_{j=1}^q \theta_j \varepsilon_{t-j}(\boldsymbol{\eta}_1) \right\}. \quad (2.7)$$

Consider the partial derivative of $\ell_n(\boldsymbol{\eta}, r)$ with respect to $\boldsymbol{\Psi}$:

$$\frac{\partial \ell_n(\boldsymbol{\eta}, r)}{\partial \boldsymbol{\Psi}} = \left(\left(\frac{\partial \ell_n(\boldsymbol{\eta}, r)}{\partial \boldsymbol{\Psi}_1} \right)^\top, \left(\frac{\partial \ell_n(\boldsymbol{\eta}, r)}{\partial \boldsymbol{\Psi}_2} \right)^\top \right)^\top = -\frac{1}{\sigma^2} \sum_{t=1}^n \varepsilon_t(\boldsymbol{\eta}, r) \frac{\partial \varepsilon_t(\boldsymbol{\eta}, r)}{\partial \boldsymbol{\Psi}},$$

where $\partial \varepsilon_t(\boldsymbol{\eta}, r) / \partial \boldsymbol{\Psi}$ is the partial derivative of $\varepsilon_t(\boldsymbol{\eta}, r)$ with respect to $\boldsymbol{\Psi}$,

namely,

$$\frac{\partial \varepsilon_t(\boldsymbol{\eta}, r)}{\partial \boldsymbol{\Psi}} = \left(\left(\frac{\partial \varepsilon_t(\boldsymbol{\eta}, r)}{\partial \boldsymbol{\Psi}_1} \right)^\top, \left(\frac{\partial \varepsilon_t(\boldsymbol{\eta}, r)}{\partial \boldsymbol{\Psi}_2} \right)^\top \right)^\top. \quad (2.8)$$

Moreover, let $\partial \varepsilon_t(\boldsymbol{\eta}_1)/\partial \boldsymbol{\Psi}_1$ be the derivative of the function $\varepsilon_t(\boldsymbol{\eta}_1)$ defined in Eq. (2.7). Lastly, define the block matrix $\mathcal{I}_n(\boldsymbol{\eta}, r)$ as follows:

$$\mathcal{I}_n(\boldsymbol{\eta}, r) = \begin{pmatrix} \mathcal{I}_{n,11}(\boldsymbol{\eta}) & \mathcal{I}_{n,12}(\boldsymbol{\eta}, r) \\ \mathcal{I}_{n,21}(\boldsymbol{\eta}, r) & \mathcal{I}_{n,22}(\boldsymbol{\eta}, r) \end{pmatrix} = \begin{pmatrix} -\frac{\partial^2 \ell_n(\boldsymbol{\eta}, r)}{\partial \boldsymbol{\Psi}_1 \partial \boldsymbol{\Psi}_1^\top} & -\frac{\partial^2 \ell_n(\boldsymbol{\eta}, r)}{\partial \boldsymbol{\Psi}_1 \partial \boldsymbol{\Psi}_2^\top} \\ -\frac{\partial^2 \ell_n(\boldsymbol{\eta}, r)}{\partial \boldsymbol{\Psi}_2 \partial \boldsymbol{\Psi}_1^\top} & -\frac{\partial^2 \ell_n(\boldsymbol{\eta}, r)}{\partial \boldsymbol{\Psi}_2 \partial \boldsymbol{\Psi}_2^\top} \end{pmatrix}. \quad (2.9)$$

Let $\ell_n(\boldsymbol{\eta}_1) = \ell_n(\boldsymbol{\eta}, -\infty)$. Let $\hat{\boldsymbol{\eta}}_1 = (\hat{\boldsymbol{\phi}}^\top, \hat{\boldsymbol{\theta}}^\top)^\top = \arg \min_{\boldsymbol{\eta}_1} \ell_n(\boldsymbol{\eta}_1)$ be the maximum likelihood estimator (MLE) of the ARMA coefficients in Eq. (2.4), and let $\hat{\sigma}^2 = n^{-1} \sum_{t=1}^n \varepsilon_t(\hat{\boldsymbol{\eta}}_1)$. We define $\hat{\boldsymbol{\eta}} = (\hat{\boldsymbol{\eta}}_1^\top, \mathbf{0}^\top, \hat{\sigma}^2)^\top$ as the so-called *restricted* MLE, that is, under the null hypothesis. We write $\partial \hat{\ell}_n(r)/\partial \boldsymbol{\Psi}_2$ and $\hat{\mathcal{I}}_n(r)$ to refer to $\partial \ell_n(\boldsymbol{\eta}, r)/\partial \boldsymbol{\Psi}$ and $\mathcal{I}_n(\boldsymbol{\eta}, r)$, respectively, evaluated at the restricted MLE, that is,

$$\frac{\partial \hat{\ell}_n(r)}{\partial \boldsymbol{\Psi}_2} = \frac{\partial \ell_n(\hat{\boldsymbol{\eta}}, r)}{\partial \boldsymbol{\Psi}_2}; \quad \hat{\mathcal{I}}_n(r) = \mathcal{I}_n(\hat{\boldsymbol{\eta}}, r) = \begin{pmatrix} \hat{\mathcal{I}}_{n,11} & \hat{\mathcal{I}}_{n,12}(r) \\ \hat{\mathcal{I}}_{n,21}(r) & \hat{\mathcal{I}}_{n,22}(r) \end{pmatrix}.$$

Under the null hypothesis, the threshold parameter r is absent, and so standard asymptotic theory is not applicable. As such, we first develop the Lagrange multiplier test statistic as a function of r ranging over a set \mathcal{R} . Then, we take the overall test statistic as the supremum on \mathcal{R} . We set $\mathcal{R} = [r_L, r_U]$, with r_L and r_U being some percentiles of the sample. This widely used approach in the time series literature for tests involving

threshold models can be dated back to [Chan \(1990\)](#) and was followed by others such as [Ling and Tong \(2005\)](#), [Li and Li \(2011\)](#), and [Chan et al. \(2020\)](#). Our test statistic is

$$T_n = \sup_{r \in [r_L, r_U]} T_n(r), \quad (2.10)$$

where

$$T_n(r) = \left(\frac{\partial \hat{\ell}_n(r)}{\partial \Psi_2} \right)^\top \left(\hat{\mathcal{I}}_{n,22}(r) - \hat{\mathcal{I}}_{n,21}(r) \hat{\mathcal{I}}_{n,11}^{-1} \hat{\mathcal{I}}_{n,12}(r) \right)^{-1} \frac{\partial \hat{\ell}_n(r)}{\partial \Psi_2}. \quad (2.11)$$

3. The null distribution

In this section, we derive the asymptotic distribution of T_n under the null hypothesis that $\{X_t\}$ follows an ARMA(p, q) model of AR order p and MA order q , and the true data-generating process (DGP) is defined in Eq. (2.4). Unless stated otherwise, all expectations are taken with respect to the true probability distribution under H_0 . In addition, $o_p(1)$ denotes the convergence in probability to zero as n increases, and $\|\cdot\|$ is the \mathcal{L}^2 matrix norm (the Frobenius norm, i.e., $\|A\| = \sqrt{\sum_{i=1}^n \sum_{j=1}^m |a_{ij}|^2}$, where A is an $n \times m$ matrix). Moreover, let $\mathcal{D}_{\mathbb{R}}(a, b)$, for $a < b$, be the space of functions from (a, b) to \mathbb{R} that are right continuous with left-hand limits. $\mathcal{D}_{\mathbb{R}}(a, b)$ is equipped with the topology of uniform convergence on compact sets; see [Billingsley \(1968\)](#) for more details.

In Lemma 1 of the Supplementary Material, we rewrite $\partial\varepsilon_t(\boldsymbol{\eta}, r)/\partial\Psi$ as a function of the roots of the MA characteristic polynomial. This is an alternative way of representing the derivatives that simplifies the theoretical derivations. Under the null hypothesis and $\boldsymbol{\eta} = \boldsymbol{\eta}_0$, we obtain the same expansion for the partial derivatives of $\varepsilon_t(\boldsymbol{\eta}_0, r)$ described by Eqs. (6.3) and (6.4) in Ling and Tong (2005). In Lemma 2 of the Supplementary Material, we derive an approximation for the matrix of the second derivatives of the log-likelihood function under H_0 .

Define the vector $\nabla_n(r) = (\nabla_{n,1}^\top, \nabla_{n,2}^\top(r))^\top$, with

$$\nabla_{n,1} = -\frac{1}{\sqrt{n}} \frac{1}{\sigma_0^2} \sum_{t=1}^n \varepsilon_t \frac{\partial\varepsilon_t(\boldsymbol{\eta}_{0,1})}{\partial\Psi_1}, \quad \nabla_{n,2}(r) = -\frac{1}{\sqrt{n}} \frac{1}{\sigma_0^2} \sum_{t=1}^n \varepsilon_t \frac{\partial\varepsilon_t(\boldsymbol{\eta}_0, r)}{\partial\Psi_2}, \quad (3.12)$$

and the matrices

$$\Lambda(\boldsymbol{\eta}, r) = \begin{pmatrix} \Lambda_{11}(\boldsymbol{\eta}) & \Lambda_{12}(\boldsymbol{\eta}, r) \\ \Lambda_{21}(\boldsymbol{\eta}, r) & \Lambda_{22}(\boldsymbol{\eta}, r) \end{pmatrix} = E \left[\frac{1}{\sigma^2} \left(\frac{\partial\varepsilon_t(\boldsymbol{\eta}, r)}{\partial\Psi} \right) \left(\frac{\partial\varepsilon_t(\boldsymbol{\eta}, r)}{\partial\Psi} \right)^\top \right],$$

$$\Lambda(r) = \begin{pmatrix} \Lambda_{11} & \Lambda_{12}(r) \\ \Lambda_{21}(r) & \Lambda_{22}(r) \end{pmatrix} = E \left[\frac{1}{\sigma_0^2} \left(\frac{\partial\varepsilon_t(\boldsymbol{\eta}_0, r)}{\partial\Psi} \right) \left(\frac{\partial\varepsilon_t(\boldsymbol{\eta}_0, r)}{\partial\Psi} \right)^\top \right],$$

where the sub-matrices Λ are $(p+1) \times (p+1)$ matrices in the sLM test, and $(p+q+1) \times (p+q+1)$ matrices in the sLM* test.

In the following proposition, we provide a uniform approximation of the test statistics that enables us to derive the asymptotic null distribution of the test statistic T_n in Theorem 1.

Proposition 1. *Under Assumption A1 and under H_0 , we have the following results:*

(i) *For each $\boldsymbol{\eta}$, the matrix $\Lambda(\boldsymbol{\eta}, r)$ is positive definite.*

(ii)

$$\sup_{r \in [a, b]} \left\| \left(\frac{\hat{\mathcal{I}}_{n,22}(r)}{n} - \frac{\hat{\mathcal{I}}_{n,21}(r)}{n} \left(\frac{\hat{\mathcal{I}}_{n,11}}{n} \right)^{-1} \frac{\hat{\mathcal{I}}_{n,12}(r)}{n} \right)^{-1} - \left(\Lambda_{22}(r) - \Lambda_{21}(r) \Lambda_{11}^{-1} \Lambda_{12}(r) \right)^{-1} \right\| = o_p(1).$$

(iii)

$$\sup_{r \in [a, b]} \left\| \frac{1}{\sqrt{n}} \frac{\partial \hat{\ell}_n(r)}{\partial \boldsymbol{\Psi}_2} - \left(\nabla_{n,2}(r) - \Lambda_{21}(r) \Lambda_{11}^{-1} \nabla_{n,1} \right) \right\| = o_p(1).$$

Note that in the above proposition, $(\nabla_{n,2}(r) - \Lambda_{21}(r) \Lambda_{11}^{-1} \nabla_{n,1})$ is a linear marked empirical process with infinitely many markers. Similarly to [Ling and Tong \(2005\)](#) and [Li and Li \(2011\)](#), we rely on Assumption A2, stated below.

A2. ε_t has a continuous and strictly positive density on the real line and

$$E[\varepsilon_t^4] \text{ is finite.}$$

Theorem 1. *Let $\{\xi(r), r \in \mathbb{R}\}$ be a centered Gaussian process with covariance kernel $\Sigma(r_1, r_2) = \Lambda_{22}(r_1 \wedge r_2) - \Lambda_{21}(r_1)\Lambda_{11}^{-1}\Lambda_{12}(r_2)$. Then, under H_0 and Assumptions A1 and A2, T_n converges weakly to*

$$\sup_{r \in [r_L, r_U]} \xi(r)^\top (\Lambda_{22}(r) - \Lambda_{21}(r)\Lambda_{11}^{-1}\Lambda_{12}(r))^{-1} \xi(r).$$

In Table 1 of the Supplementary Material, we tabulate the empirical quantiles of the null asymptotic distribution of our supLM statistics for AR orders from one to four and MA orders from one to two. The quantiles do not depend on the MA parameters, and are in good agreement with those shown in Table 1 of Andrews (2003), where $\pi_0 = 0.25$, and those in Table 1 of Chan (1991). The asymptotic behavior of the two statistics depends only on the dimension of the parameter vector Ψ , irrespective of whether it has AR or MA components. As shown in Section S1 of the Supplementary Material, the results do not depend on the parameter values of the data-generating process, and are robust with respect to deviations from normality of the innovation process.

4. The distribution under local alternatives and the consistency of the test

In this section, we derive the asymptotic distribution of T_n under a sequence of local alternatives, and prove the consistency of the associated tests. For

each n , the null hypothesis H_0 states that $\{X_t, t = 1, \dots, n\}$ follows the model

$$X_t = \phi_{0,0} + \sum_{i=1}^p \phi_{0,i} X_{t-i} - \sum_{j=1}^q \theta_{0,j} \varepsilon_{t-j} + \varepsilon_t.$$

The sequence of alternative hypotheses $H_{1,n}$ states that $\{X_t, t = 1, \dots, n\}$ follows the model

$$\begin{aligned} X_t = & \phi_{0,0} + \sum_{i=1}^p \phi_{0,i} X_{t-i} - \sum_{j=1}^q \theta_{0,j} \varepsilon_{t-j} + \varepsilon_t \\ & + \left[\frac{h_{10}}{\sqrt{n}} + \sum_{i=1}^p \frac{h_{1i}}{\sqrt{n}} X_{t-i} - \sum_{j=1}^q \frac{h_{2j}}{\sqrt{n}} \varepsilon_{t-j} \right] I_{r_0}(X_{t-d}). \end{aligned} \quad (4.13)$$

Here, $\mathbf{h} = (h_{10}, h_{11}, \dots, h_{1p}, h_{21}, \dots, h_{2q})^\top \in \mathbb{R}^{p+q+1}$ is a vector of constants and r_0 is a fixed scalar. For the sLM statistic, the rightmost summation term within square brackets is absent such that $\mathbf{h} = (h_{10}, h_{11}, \dots, h_{1p})^\top \in \mathbb{R}^{p+1}$.

Let $P_{0,n}$ and $P_{1,n}$ be the probability measure of (X_1, \dots, X_n) under H_0 and $H_{1,n}$, respectively. In the following proposition, we prove the asymptotic normality of the log-likelihood ratio and the contiguity of $P_{1,n}$ to $P_{0,n}$. As in C5 of [Chan \(1990\)](#), 3.1 of [Ling and Tong \(2005\)](#), and A5 of [Li and Li \(2011\)](#), we assume the following.

A3. The density f of ε_t is absolutely continuous with derivative f' almost everywhere and $\int (f'(x)/f(x))^2 f(x) dx < \infty$.

Proposition 2. *Under Assumptions A1–A3, the following assertions hold.*

(i) Let $\nabla_2(r)$ be a Gaussian distributed random vector with zero mean and covariance matrix equal to $\Lambda_{22}(r)$. Under the null hypothesis, the log-likelihood ratio $\log(dP_{1,n}/dP_{0,n})$ converges to the Gaussian random variable $\mathbf{h}^\top \nabla_2(r_0) - 2^{-1} \mathbf{h}^\top \Lambda_{22}(r_0) \mathbf{h}$.

(ii) $\{P_{1,n}\}$ is contiguous to $\{P_{0,n}\}$.

Next, we have the following asymptotic distribution for T_n .

Theorem 2. Assume that A1–A3 hold. Under $H_{1,n}$, the following assertions hold.

(i) T_n converges weakly in $\mathcal{D}(-\infty, \infty)$ to

$$(\xi_r + \gamma_r)^\top (\Lambda_{22}(r) - \Lambda_{2,1}(r) \Lambda_{11}^{-1} \Lambda_{12}(r))^{-1} (\xi_r + \gamma_r),$$

where $\gamma_r = \{\Lambda_{22}(\min\{r, r_0\}) - \Lambda_{21}(r) \Lambda_{11}^{-1} \Lambda_{12}(r_0)\} \mathbf{h}$.

(ii) $\sup_{r \in [r_L, r_U]} T_n$ converges weakly to

$$\sup_{r \in [r_L, r_U]} (\xi_r + \gamma_r)^\top (\Lambda_{22}(r) - \Lambda_{21}(r) \Lambda_{11}^{-1} \Lambda_{12}(r))^{-1} (\xi_r + \gamma_r).$$

Finally, we prove the consistency of our tests.

Theorem 3. Under $H_{1,n}$, as $\|\mathbf{h}\| \rightarrow \infty$, the test statistic T_n has power approaching 100%.

Note that Proposition 2 and Theorem 2 can be proved for the sLM statistic without assumption A3. The two proofs are reported separately in the Supplementary Material.

5. Finite-sample performance

In this section, we investigate the finite-sample performance of our supLM tests (sLM, sLM^{*}) and compare them with the qLR test developed in Li and Li (2011). Hereafter ε_t , for $t = 1, \dots, n$, is generated from a standard Gaussian white noise, the length of the series is $n = 100, 200, 500$, the nominal size is $\alpha = 5\%$, and the number of Monte Carlo replications is 1,000. For our tests, we use the critical values shown in Table 1. For the qLR test, we use $B = 1,000$ resamples. In Section 5.1, we study the size of the tests. Section 5.2 shows the power of the tests in scenarios where *i*) only the AR parameters change across regimes, *ii*) only the MA parameters change across regimes, and *iii*) both the AR and the MA parameters change across regimes. Then, in Section 5.3, we assess the behavior of the tests in presence of model mis-specification and, in Section 5.4, that when the order of the ARMA process tested is treated as unknown and is selected using the Hannan–Rissanen method .

5.1 Size of the tests

We generated time series from 25 different simulation settings of the following ARMA(1, 1) model:

$$X_t = \phi_1 X_{t-1} + \varepsilon_t - \theta_1 \varepsilon_{t-1}, \quad (5.14)$$

where $\phi_1 = 0, \pm 0.3, \pm 0.6$ and $\theta_1 = 0, \pm 0.4, \pm 0.8$. Table 1 shows the rejection percentages for the three sample sizes in use. Note that the case $\theta_1 = 0$ corresponds to testing an AR versus a TAR model. For $n = 100$, the qLR test is biased in almost all settings, and reaches 53% of false rejections for the case $\theta_1 = \phi_1 = 0$. The size of the sLM test is always acceptable, because it is slightly greater than 10% in only three cases, and its maximum value is 15.5%. The size of the sLM* test is slightly more biased than that of the sLM test. When $n = 200$, the bias of the sLM test reduces further, and its size is not far from the nominal 5% in most situations. This also holds for the sLM* test, except for the case $\theta_1 = 0.8$, where the size is still around 10%. This is not the case for the qLR test, with a size close to 40% in three simulation settings. When $n = 500$, both supLM tests achieve a size close to the nominal 5% level, whereas the qLR test is still severely biased for some cases when near cancellation occurs. This may be due to the sensitivity of the quadratic approximation of the qLR test to near invertibility and/or

5.1 Size of the tests

Table 1: Empirical size at nominal level 5% of the supLM tests (sLM, sLM*) and the quasi-likelihood ratio test (qLR). Rejection percentages from the ARMA(1, 1) model of Eq. (5.14). Sample size $n = 100, 200, 500$.

| ϕ_1 | θ_1 | $n = 100$ | | | $n = 200$ | | | $n = 500$ | | |
|----------|------------|-----------|------|------|-----------|------|------|-----------|------|------|
| | | sLM | sLM* | qLR | sLM | sLM* | qLR | sLM | sLM* | qLR |
| -0.6 | -0.8 | 5.8 | 10.0 | 45.0 | 4.6 | 6.2 | 25.2 | 4.4 | 5.7 | 10.2 |
| -0.3 | -0.8 | 3.4 | 8.4 | 29.1 | 3.4 | 7.0 | 14.9 | 4.9 | 5.3 | 7.3 |
| 0.0 | -0.8 | 4.3 | 7.4 | 22.4 | 4.1 | 7.2 | 9.2 | 4.2 | 4.2 | 6.3 |
| 0.3 | -0.8 | 4.2 | 8.7 | 21.0 | 5.0 | 8.0 | 9.8 | 4.9 | 4.6 | 5.6 |
| 0.6 | -0.8 | 4.6 | 8.4 | 19.5 | 5.6 | 7.9 | 8.1 | 4.4 | 5.8 | 4.9 |
| -0.6 | -0.4 | 6.1 | 8.5 | 41.0 | 5.1 | 5.2 | 26.2 | 4.7 | 4.8 | 13.9 |
| -0.3 | -0.4 | 7.5 | 8.3 | 46.1 | 4.9 | 5.0 | 40.7 | 5.9 | 5.8 | 24.0 |
| 0.0 | -0.4 | 4.5 | 4.2 | 20.4 | 4.1 | 5.2 | 8.2 | 5.0 | 4.5 | 5.1 |
| 0.3 | -0.4 | 5.4 | 6.2 | 10.8 | 3.8 | 4.3 | 6.0 | 4.3 | 4.3 | 4.7 |
| 0.6 | -0.4 | 7.1 | 6.5 | 6.7 | 4.4 | 5.6 | 5.8 | 6.1 | 5.2 | 3.2 |
| -0.6 | 0.0 | 4.6 | 4.2 | 10.0 | 4.2 | 4.0 | 5.8 | 4.6 | 4.9 | 3.1 |
| -0.3 | 0.0 | 5.1 | 5.6 | 31.8 | 3.4 | 3.7 | 16.0 | 5.9 | 6.2 | 4.8 |
| 0.0 | 0.0 | 9.4 | 11.4 | 53.5 | 9.2 | 9.4 | 42.0 | 6.7 | 7.1 | 34.0 |
| 0.3 | 0.0 | 7.5 | 6.9 | 22.4 | 5.1 | 4.6 | 7.6 | 3.3 | 4.2 | 4.3 |
| 0.6 | 0.0 | 9.8 | 8.5 | 7.5 | 6.1 | 5.4 | 4.1 | 5.2 | 5.8 | 4.6 |
| -0.6 | 0.4 | 4.2 | 4.8 | 5.9 | 3.3 | 4.3 | 3.7 | 4.6 | 4.4 | 3.1 |
| -0.3 | 0.4 | 4.7 | 5.6 | 9.7 | 4.1 | 5.0 | 5.1 | 3.9 | 4.5 | 3.8 |
| 0.0 | 0.4 | 5.0 | 4.5 | 24.2 | 3.7 | 4.1 | 8.2 | 4.5 | 5.2 | 5.7 |
| 0.3 | 0.4 | 6.4 | 7.7 | 45.6 | 6.0 | 7.1 | 38.1 | 5.1 | 5.4 | 23.4 |
| 0.6 | 0.4 | 15.5 | 14.4 | 27.6 | 8.8 | 9.2 | 8.8 | 6.9 | 7.7 | 3.2 |
| -0.6 | 0.8 | 10.3 | 16.8 | 20.2 | 7.2 | 10.7 | 7.0 | 4.5 | 7.0 | 5.3 |
| -0.3 | 0.8 | 8.3 | 14.8 | 20.2 | 6.3 | 10.4 | 9.7 | 4.2 | 6.6 | 3.3 |
| 0.0 | 0.8 | 8.2 | 16.0 | 20.4 | 6.0 | 11.3 | 8.7 | 4.9 | 7.2 | 5.2 |
| 0.3 | 0.8 | 7.7 | 14.4 | 24.5 | 7.2 | 10.0 | 10.5 | 4.1 | 6.5 | 4.4 |
| 0.6 | 0.8 | 11.9 | 16.0 | 32.0 | 9.3 | 11.2 | 22.2 | 6.3 | 8.1 | 7.6 |

near cancellation. The bias is particularly severe when $\theta_1 = \phi_1 = 0$. One may argue that it is not appropriate to apply these tests to a realization of a white-noise process, and that it would be more sensible to apply other kinds of tests in the first place. Nevertheless, it may occur that a threshold process resembles white noise in terms of its second-order structure. Indeed, some sort of mis-specification is always present. We investigate this aspect in Section 5.3.

5.2 Power of the tests

In this section, we study and compare the power of the supLM tests. Note that the parameter vector Ψ_2 (see Eq. (2.3)) represents the departure from the null hypothesis, and in all the simulations below, we take sequences of increasing distance from H_0 in all of its components. We simulate three different TARMA(1,1) models, where *i*) only the AR parameters change across regimes, *ii*) only the MA parameters change across regimes, and *iii*) both the AR and the MA parameters change across regimes. For the first case, we simulate the following model:

$$X_t = -0.5 - 0.2X_{t-1} - \theta_1\varepsilon_{t-1} + (\varphi_0 + \varphi_1X_{t-1})I(X_{t-1} \leq 0) + \varepsilon_t, \quad (5.15)$$

where $(\varphi_0, \varphi_1) = (0.1, 0.4), (0.3, 0.6), (0.5, 0.8), (0.7, 1.0)$. We combine these with $\theta_1 = 0, \pm 0.4, \pm 0.8$ to obtain 20 different parameter settings. Figure 1

5.3 Size and power in presence of mis-specification

presents the size-corrected power of the tests (in percentage) for different values of θ_1 . Clearly, the supLM tests outperform the qLR test in all cases, except for the single instance $\theta = 0.4$ and $n = 100$. The power depends on the true value of θ_1 , and the case $\theta_1 = 0$ seems to impinge most negatively. In such instances, the qLR test has no power, even for $n = 200$, whereas the supLM tests show power loss due to the size correction only for $n = 100$. Moreover, for $\theta = 0.8$, both supLM tests outperform the qLR test. Indeed, their power for $n = 200(100)$ is greater than that of the qLR test for $n = 500(200)$. Overall, starting from $n = 200$, both supLM tests possess good power in almost every situation. As expected, the sLM test is slightly superior to the sLM* test, because the MA parameter is regime independent. The results for cases *ii*) and *iii*) and for higher-order TARMA models are consistent with the above conclusions and are reported in the Supplementary Material. In particular, they show that when both the AR and the MA parameters change, the sLM* is the most powerful test.

5.3 Size and power in presence of mis-specification

In this section, we assess the impact of model mis-specification on the performance of the tests. The sources of mis-specification can be diverse. As above, we focus on testing the ARMA(1,1) versus the TARMA(1,1) spec-

5.3 Size and power in presence of mis-specification

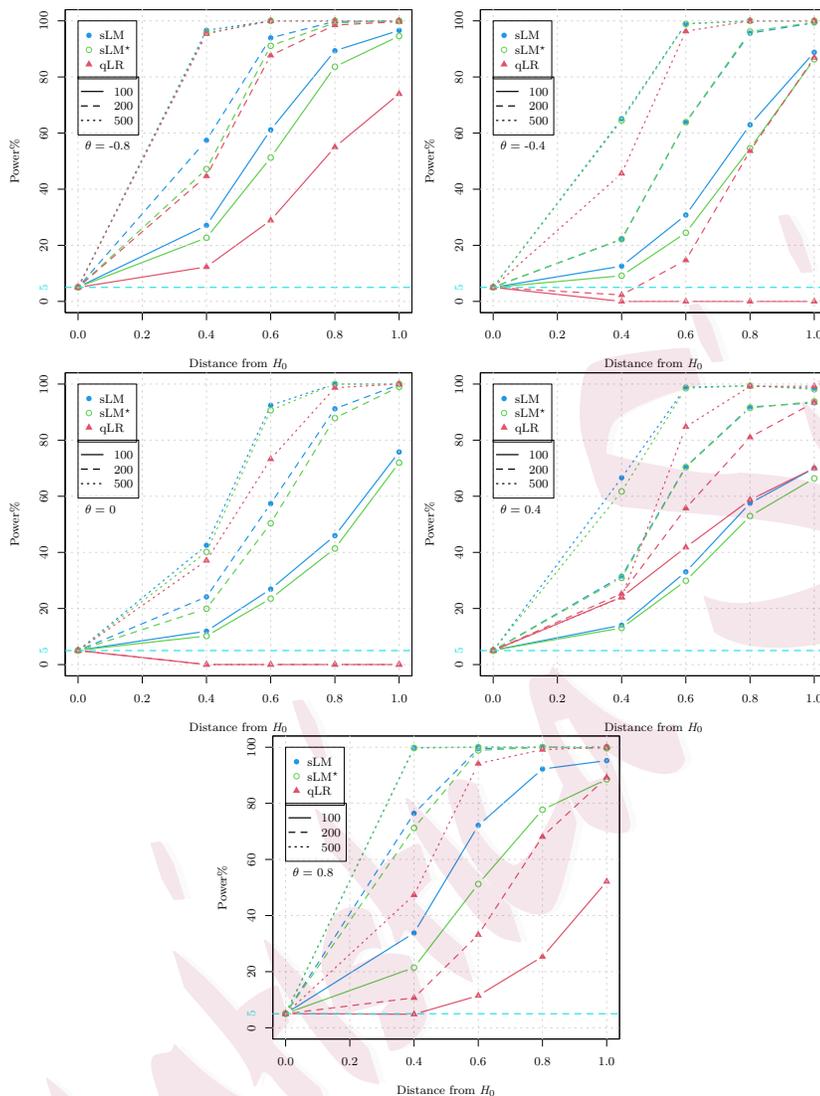


Figure 1: Size-corrected power (percentages) at nominal $\alpha = 5\%$ for the TARMA(1, 1) model of Eq. (5.15), case i): only the AR parameters change across regimes. The sLM, sLM*, and qLR tests are denoted by a blue filled point, an empty green point, and a red triangle, respectively. The line type indicates the sample size: $n = 100$ (continuous), $n = 200$ (dashed), $n = 500$ (dotted).

5.3 Size and power in presence of mis-specification

ification, but the data-generating process is not encompassed within the two models. Loosely speaking, we are investigating the capability of the test to detect general departures from linearity beyond a direct comparison of two specific models. Ideally, if the data-generating process is linear, we would want the test to not reject the null hypothesis. Similarly, if the data-generating process is nonlinear in some of its components, then we expect the test to reject the null hypothesis. The linear and nonlinear data-generating processes used are presented in Table 7 of the Supplementary Material. The seven linear processes are not ARMA(1, 1), because they contain higher-order AR/MA terms. In the second part of the table, we show nonlinear processes that cannot be encompassed within the two-regime TARMA(1, 1) specification. In particular, we simulate from TAR models with both a higher AR order and more than two regimes. Lastly, we generate data from seven nonlinear models that do not belong to the TARMA class. These include the nonlinear MA (NLMA), bilinear (BIL), exponential AR (EXPAR), and deterministic chaos (NLAR) models.

The rejection percentages are reported in Table 2. As discussed above, the first seven rows should reflect the empirical size at nominal level 5% under mis-specification. Consistent with the results of Table 1, the sLM test is well behaved in terms of size, even for $n = 100$, whereas the sLM* test has

5.3 Size and power in presence of mis-specification

Table 2: Rejection percentages under model mis-specification for the processes of Table 7 of the Supplementary Material for the supLM tests (sLM, sLM*) and the quasi-likelihood ratio test (qLR). The upper panel (linear processes) reflects the empirical size at nominal level 5%. The lower panel (nonlinear processes) reflects the empirical power for nonlinear processes that are not representable as a TARMA(1, 1) process.

| | | $n = 100$ | | | $n = 200$ | | | $n = 500$ | | |
|-----------|----------|-----------|-------|------|-----------|-------|------|-----------|-------|------|
| | | sLM | sLM* | qLR | sLM | sLM* | qLR | sLM | sLM* | qLR |
| LINEAR | AR5 | 7.9 | 15.2 | 22.7 | 5.5 | 9.8 | 7.8 | 4.6 | 6.9 | 4.6 |
| | AR2.1 | 6.7 | 7.1 | 6.8 | 4.7 | 5.5 | 4.0 | 5.3 | 5.5 | 4.0 |
| | AR2.2 | 8.7 | 10.1 | 6.6 | 4.1 | 5.8 | 3.2 | 3.4 | 5.0 | 1.6 |
| | ARMA21.1 | 5.9 | 6.8 | 48.0 | 5.5 | 5.2 | 39.7 | 5.5 | 4.8 | 27.8 |
| | ARMA21.2 | 5.8 | 8.9 | 15.8 | 4.5 | 5.7 | 8.3 | 4.0 | 4.9 | 4.1 |
| | ARMA22 | 5.5 | 13.6 | 29.1 | 3.7 | 12.7 | 17.4 | 3.5 | 7.5 | 8.5 |
| | MA2 | 3.5 | 12.1 | 29.9 | 2.3 | 5.8 | 17.0 | 4.4 | 6.2 | 6.5 |
| NONLINEAR | TAR3 | 34.7 | 98.1 | 63.0 | 61.8 | 99.7 | 48.0 | 96.7 | 100.0 | 36.8 |
| | 3TAR1 | 19.2 | 18.4 | 8.8 | 36.1 | 30.4 | 8.5 | 78.5 | 72.4 | 16.5 |
| | NLMA.1 | 85.1 | 84.0 | 78.7 | 97.3 | 97.2 | 92.1 | 99.8 | 99.9 | 99.0 |
| | NLMA.2 | 86.4 | 86.8 | 73.6 | 98.3 | 98.5 | 85.2 | 100.0 | 99.9 | 97.0 |
| | BIL.1 | 12.0 | 62.1 | 53.2 | 13.5 | 84.8 | 58.2 | 14.7 | 95.0 | 77.4 |
| | BIL.2 | 84.0 | 83.1 | 86.8 | 98.7 | 98.9 | 96.0 | 100.0 | 100.0 | 99.9 |
| | EXPAR.1 | 100.0 | 100.0 | 32.5 | 100.0 | 100.0 | 30.5 | 100.0 | 100.0 | 80.1 |
| | EXPAR.2 | 95.8 | 99.1 | 45.0 | 99.6 | 99.9 | 59.3 | 100.0 | 100.0 | 96.2 |
| | NLAR | 100.0 | 100.0 | 63.7 | 100.0 | 100.0 | 47.0 | 100.0 | 100.0 | 27.1 |

5.4 The impact of model selection

acceptable size starting from $n = 200$. The qLR test presents acceptable size for $n = 500$ only, except for the ARMA21.1 case with 27.8% false rejections. The lower panel of Table 2 shows the rejection percentages for the nine nonlinear models that do not belong to the TARMA(1, 1) class. Here, the power of the sLM tests is higher than that of the qLR test in almost every case, even for $n = 100$, and increases consistently with the sample size. The qLR test has good power in several instances, but for the TAR3, the 3TAR1, and NLAR models, the power decreases as the sample size increases. The cause of this phenomenon is not clear and deserves further investigation. One possible intuitive explanation is the following. Consider the case in which we test the null hypothesis of an $AR(p)$ model. In practice, the LM statistics test whether $E[\varepsilon_t X_{t-i} I_r(X_{t-d})] = 0$, for $i = 1, \dots, p$. When the true model is a linear model, the above result most likely holds and, consequently, the sLM tests still have an accurate size. However, when the true model is a nonlinear model, the result most likely does not hold, in which case, the proposed LM tests are still powerful. The above arguments fail for the qLR test, which needs to consider the model under both the null and the alternative hypotheses.

5.4 The impact of model selection

Table 3: Empirical size of the supLM tests at nominal level 5% for six parameterizations of the ARMA(2, 2) process. The subscript “HR” indicates that the order of the ARMA model has been selected using the Hannan–Rissanen procedure.

| ϕ_1 | ϕ_2 | θ_1 | θ_2 | $n = 100$ | | $n = 200$ | | $n = 500$ | |
|----------|----------|------------|------------|-----------|-------------------|-----------|-------------------|-----------|-------------------|
| | | | | sLM | sLM _{HR} | sLM | sLM _{HR} | sLM | sLM _{HR} |
| -0.35 | -0.45 | 0.25 | -0.25 | 5.4 | 4.4 | 3.6 | 3.7 | 4.9 | 4.9 |
| 0.45 | -0.55 | 0.25 | -0.25 | 5.6 | 5.8 | 5.7 | 4.8 | 4.6 | 4.6 |
| -0.90 | -0.25 | 0.25 | -0.25 | 6.1 | 4.6 | 5.8 | 5.9 | 4.4 | 5.6 |
| -0.35 | -0.45 | -0.25 | 0.25 | 2.9 | 3.0 | 4.3 | 4.4 | 5.3 | 5.3 |
| 0.45 | -0.55 | -0.25 | 0.25 | 3.0 | 3.4 | 3.9 | 4.3 | 5.3 | 5.0 |
| -0.90 | -0.25 | -0.25 | 0.25 | 7.1 | 4.7 | 6.8 | 4.6 | 5.7 | 5.2 |

| ϕ_1 | ϕ_2 | θ_1 | θ_2 | $n = 100$ | | $n = 200$ | | $n = 500$ | |
|----------|----------|------------|------------|-----------|--------------------|-----------|--------------------|-----------|--------------------|
| | | | | sLM* | sLM* _{HR} | sLM* | sLM* _{HR} | sLM* | sLM* _{HR} |
| -0.35 | -0.45 | 0.25 | -0.25 | 6.1 | 4.3 | 4.3 | 3.7 | 4.5 | 4.9 |
| 0.45 | -0.55 | 0.25 | -0.25 | 7.2 | 6.4 | 4.8 | 5.3 | 4.5 | 5.1 |
| -0.90 | -0.25 | 0.25 | -0.25 | 6.7 | 5.9 | 4.9 | 5.3 | 4.8 | 5.4 |
| -0.35 | -0.45 | -0.25 | 0.25 | 3.1 | 3.0 | 4.9 | 4.8 | 4.6 | 4.2 |
| 0.45 | -0.55 | -0.25 | 0.25 | 4.4 | 4.8 | 4.1 | 4.7 | 4.9 | 4.8 |
| -0.90 | -0.25 | -0.25 | 0.25 | 11.4 | 6.5 | 6.7 | 4.3 | 5.3 | 5.2 |

5.4 The impact of model selection

In practice, the tests require selecting the model order beforehand. In this section, we show that there is virtually no loss incurred when using our supLM tests without prior information on the order, provided a proper model selection procedure is adopted. Our experience suggests using the order selection proposed in [Hannan and Rissanen \(1982\)](#); see also [Choi \(1992\)](#).

In [Table 3](#), we present the empirical size of the supLM tests at the nominal level 5% for six parameterizations of an ARMA(2, 2) model (the first four columns). The upper panel of the table refers to the sLM test, and the lower panel refers to the sLM* test. In both cases, the subscript HR indicates that the order of the ARMA process has been selected using the Hannan–Rissanen procedure; no subscript is used if the true order has been used. The results indicate that not only does the model selection step not produce a size bias, but it seems to reduce it in some instances.

The impact of model selection on the power of the tests is shown in [Table 4](#), where we simulate twelve parameter settings of the TARMA(1, 1) model of [Eq. \(5.15\)](#). Clearly, the power loss produced by using model selection is minimal, lying within 2% for the sLM test and 3% for the sLM* test. Finally, in the presence of mis-specification, the HR model selection step

poses no problems. The results are shown in the Supplementary Material.

5.5 Discussion

The Monte Carlo study shows that the supLM tests have good finite-sample properties. They are also robust against model mis-specification, and their performance is not affected if the order of the tested process is unknown, provided a consistent order selection procedure is used. In theory, because the asymptotic distribution of the supLM statistics is the same as that of the qLR statistic, the tests should display the same asymptotic behavior. Nevertheless, the Monte Carlo evidence points at clear finite-sample differences, because supLM tests do not suffer from some of the drawbacks that affect the qLR test. The reasons are diverse. First, the supLM statistics require fitting only an ARMA model, whereas the qLR test is bound to estimating a full TARMA model. Recall that there are no theoretical results regarding the sampling properties of the maximum likelihood estimators for the parameters of a TARMA model. Moreover, the qLR test of [Li and Li \(2011\)](#) uses a representation in terms of a quadratic form. However, this is only valid asymptotically, and so impinges on the rate of convergence of the statistic toward its asymptotic distribution. This does not occur in our

Table 4: Empirical power for the TARMA(1, 1) model of Eq. (5.15). Sample size $n = 100, 200, 500$. The subscript “HR” indicates that the order of the ARMA model has been selected using the Hannan–Rissanen procedure.

| φ_0 | φ_1 | θ_1 | $n = 100$ | | $n = 200$ | | $n = 500$ | |
|-------------|-------------|------------|-----------|-------------------|-----------|-------------------|-----------|-------------------|
| | | | sLM | sLM _{HR} | sLM | sLM _{HR} | sLM | sLM _{HR} |
| 0.1 | 0.4 | -0.5 | 13.0 | 12.9 | 30.2 | 29.4 | 71.2 | 69.4 |
| 0.3 | 0.6 | -0.5 | 34.8 | 35.1 | 71.9 | 70.6 | 99.6 | 98.9 |
| 0.5 | 0.8 | -0.5 | 65.5 | 65.2 | 97.1 | 96.3 | 100.0 | 100.0 |
| 0.7 | 1.0 | -0.5 | 90.4 | 89.6 | 99.7 | 99.5 | 100.0 | 100.0 |
| 0.1 | 0.4 | 0.0 | 15.7 | 14.9 | 19.0 | 19.2 | 43.0 | 43.0 |
| 0.3 | 0.6 | 0.0 | 30.7 | 30.4 | 51.8 | 51.0 | 94.0 | 93.6 |
| 0.5 | 0.8 | 0.0 | 54.5 | 54.6 | 87.9 | 87.5 | 100.0 | 99.9 |
| 0.7 | 1.0 | 0.0 | 81.3 | 80.5 | 99.1 | 99.1 | 100.0 | 100.0 |
| 0.1 | 0.4 | 0.5 | 17.4 | 16.0 | 35.9 | 33.8 | 77.9 | 75.8 |
| 0.3 | 0.6 | 0.5 | 41.3 | 38.7 | 78.2 | 73.1 | 99.9 | 99.6 |
| 0.5 | 0.8 | 0.5 | 70.7 | 67.2 | 95.7 | 93.9 | 99.9 | 99.7 |
| 0.7 | 1.0 | 0.5 | 75.5 | 74.6 | 93.7 | 93.1 | 99.5 | 99.5 |

| φ_0 | φ_1 | θ_1 | $n = 100$ | | $n = 200$ | | $n = 500$ | |
|-------------|-------------|------------|-----------|--------------------|-----------|--------------------|-----------|--------------------|
| | | | sLM* | sLM* _{HR} | sLM* | sLM* _{HR} | sLM* | sLM* _{HR} |
| 0.1 | 0.4 | -0.5 | 13.9 | 13.9 | 28.7 | 28.7 | 66.7 | 65.0 |
| 0.3 | 0.6 | -0.5 | 35.5 | 35.7 | 69.5 | 67.0 | 99.0 | 98.6 |
| 0.5 | 0.8 | -0.5 | 65.7 | 65.1 | 96.4 | 95.7 | 100.0 | 100.0 |
| 0.7 | 1.0 | -0.5 | 89.7 | 88.8 | 99.8 | 99.6 | 100.0 | 100.0 |
| 0.1 | 0.4 | 0.0 | 15.0 | 14.4 | 18.7 | 19.1 | 40.3 | 40.6 |
| 0.3 | 0.6 | 0.0 | 27.8 | 28.2 | 48.8 | 48.5 | 91.7 | 91.5 |
| 0.5 | 0.8 | 0.0 | 52.0 | 52.1 | 86.1 | 85.5 | 100.0 | 99.9 |
| 0.7 | 1.0 | 0.0 | 80.1 | 79.7 | 98.9 | 98.7 | 100.0 | 100.0 |
| 0.1 | 0.4 | 0.5 | 16.4 | 16.0 | 32.6 | 31.2 | 75.4 | 73.6 |
| 0.3 | 0.6 | 0.5 | 40.8 | 38.7 | 75.3 | 71.6 | 99.6 | 98.9 |
| 0.5 | 0.8 | 0.5 | 68.3 | 65.8 | 95.9 | 94.5 | 100.0 | 100.0 |
| 0.7 | 1.0 | 0.5 | 74.8 | 74.3 | 93.7 | 93.0 | 99.6 | 99.6 |

case because such a representation is exact for the supLM statistics. The size distortion for the qLR approach is at its greatest when the model is either nearly non-invertible or there is near cancellation in the MA and AR roots, reflecting the sensitivity of the quadratic approximation in these two cases.

The sLM statistic tests the ARMA(p, q) against the TARMA(p, q) model when only the p AR parameters change across regimes. However, the results show that it also has power when only the MA parameters change. This could be ascribed to the duality between the MA and AR processes, and indicates some capabilities in detecting general departures from linearity. The results in Section 5.3 provide additional evidence. The results also show that, as expected, when either only the q MA parameters or all the $p+q$ parameters of the ARMA model change across regimes, then the sLM* test is more powerful. The price to be paid for this superior power is the increased size bias in small samples. In general, we expect the two tests to behave similarly, but in the case of small samples, the sLM statistic is recommended and can be used in conjunction with the sLM* test.

6. A real-data application: tree-ring time series

In this section, we apply our test to the time series of the tree-ring standardized growth index. Tree rings provide a measure of the responses of tree growth to past climatic variation, which is useful in climate studies. Despite the recognition that the climatic factors affecting tree growth form a complex network, according to the literature, the best model to adopt are either the AR(1) or ARMA(1, 1) models; see Table 3 in [Fox et al. \(2001\)](#). Usually, the indices of many trees from the same site are used to cross-date the rings, and are averaged into a single index to obtain a chronology that covers a long time span. Here, we focus on the tree-ring chronology of a *pinus aristata* var. *longaeva* (California, United States) from the year 800 to the year 1979 ($n = 1180$). For more details on the data, see [Graybill \(2018\)](#).

We test the null hypothesis of an ARMA(1, 1) model against the following TARMA(1, 1) model:

$$X_t = \begin{cases} \phi_{10} + \phi_{11}X_{t-1} + \varepsilon_t + \theta_{11}\varepsilon_{t-1}, & \text{if } X_{t-1} \leq r, \\ \phi_{20} + \phi_{21}X_{t-1} + \varepsilon_t + \theta_{11}\varepsilon_{t-1}, & \text{otherwise.} \end{cases} \quad (6.16)$$

With the threshold searched between the 10th and 90th percentiles, the sLM test statistic is 23.45 and the sLM* statistic is 25.21, and both corre-

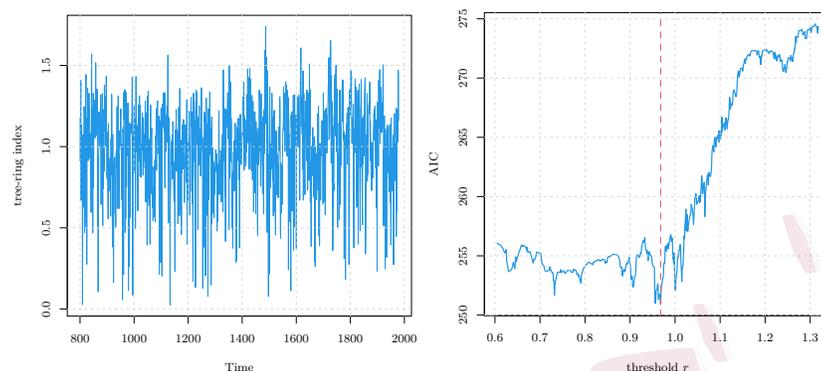


Figure 2: Time series of the yearly standardized tree-ring growth index of *Pinus aristata* var. *longaeva*, California, United States (left). AIC versus the threshold r (right). The value of r that minimizes the AIC is indicated with a dashed vertical line.

respond to a p -value smaller than 0.001, suggesting that tree-ring growth is regulated from below. In Figure 2 (left), we show the time series, and the right panel reports the values of the AIC versus the threshold values. The vertical line indicates the estimated threshold $\hat{r} = 0.97$, the same value of r that maximizes the T_n statistic. Table 5 reports a TARMA(1,1) model parameterized in the form of (6.16), with a common MA parameter, but with unconstrained $\phi_{i,1}$, for $i = 0, 1, 2$, and an ARMA(1,1) model fitted to the data. The estimated AR parameters point to a threshold effect, and the normalized AIC and BIC indicate an improvement with respect to the ARMA(1,1) model. The estimated TARMA(1,1) model is invertible and

Table 5: Parameter estimates for the tree-ring time series

| | θ_{11} | ϕ_{10} | ϕ_{11} | ϕ_{20} | ϕ_{21} | r | d | NAIC | NBIC |
|-------|-----------------|----------------|----------------|----------------|----------------|------|-----|-------|-------|
| ARMA | -0.60 (0.09) | 1.00 (0.01) | 0.76 (0.07) | | | | | 0.232 | 0.251 |
| TARMA | -0.44 (0.09) | 0.54 (0.10) | 0.37 (0.11) | 0.29 (0.09) | 0.71 (0.09) | 0.97 | 1 | 0.213 | 0.240 |

geometrically ergodic. The estimated threshold is $\hat{r} = 0.97$, which is close to one, the mean of the time series. It identifies an upper regime with increased persistence with respect to the lower regime. The entropy-based diagnostics of [Giannerini et al. \(2015\)](#), reported in the Supplementary Material, indicate that the TARMA(1, 1) model provides a good fit to the data, whereas an unaccounted dependence structure is present in the residuals of the ARMA(1, 1) model. Note that tree-ring growth indices are produced by fitting a growth curve that can be derived from a prey–predator-type differential equation describing the growth of a tree in the presence of surrounding trees. Threshold models are discrete-time versions of such equations, and appear as natural candidates to describe this phenomenon. Moreover, the data are likely to be affected by measurement errors, and this is accounted for by the MA parameter.

7. Conclusion

We have presented consistent supremum Lagrange multiplier tests for testing a linear ARMA model against its TARMA extension. Our proposal extends the results of previous studies, such as [Chan \(1990\)](#) and [Ling and Tong \(2005\)](#), and enjoys very good finite-sample properties in terms of size and power. Moreover, being based upon asymptotic theory, it has a low computational burden. Our Monte Carlo study shows that the supLM tests are also robust against various forms of model mis-specification, and their performance is not affected, even if the order of the tested process is unknown, provided a consistent order selection procedure is used. Our supLM tests do not suffer from some of the shortcomings that affect the quasi-likelihood test, and can be used for small samples. In such cases, the sLM statistic has less power than the sLM* statistic, but is better behaved in terms of size, so that it is also recommended. For sample sizes from 200 upwards, the two tests can be used in conjunction. The theoretical framework of our supLM tests does not take into account GARCH-type innovations. A possible solution would be to adopt a wild-bootstrap scheme, similar to that used in [Chan et al. \(2020\)](#). While the implementation is straightforward, to the best of our knowledge, the validity of the bootstrap in a threshold framework has not been proved, even for TAR models, and

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constitutes an interesting challenge for future research. Our analysis of a tree-ring time series shows that TARMA models can provide new insights for all problems that use dendrochronological data. The TARMA(1,1) fit improves considerably over the commonly accepted linear models, because the latter do not take into account nonlinear effects.

Supplementary Material

The online Supplementary Material contains all the proofs, as well as additional results from the simulation study and the tree-ring data analysis.

Acknowledgments

We thank the associate editor and referees for their helpful comments and suggestions, and Guodong Li for kindly making the code available for the qLR test.

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