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Empirical Likelihood Estimation Using Auxiliary Summary Information with Different Covariate Distributions

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Abstract: The potential use of auxiliary summary information to improve the efficiency of estimation has attracted significant interest. Most existing methods assume that the data distribution is the same for the sample data and for the population that generates the auxiliary information. However, recent works have relaxed this assumption by allowing heterogeneity between the two covariate distributions. We consider an empirical likelihood approach that guarantees that using auxiliary information will increase the efficiency of estimation when the variability associated with this information is sufficiently small. We also investigate the effects of this variability on the efficiency. Furthermore, we implement the proposed approach using a Newton–Raphson-type algorithm. Lastly, we discuss our simulation results, which demonstrate the efficiency gains and confirm the large sample approximations.

Key words and phrases: Auxiliary information; Data integration; Empirical likelihood; Estimation efficiency; Information uncertainty; Summary information.

1. Introduction

In many settings the main statistical objective is to fit models for a response variable conditional on certain covariates. With the increasing availability of large databases, there is much interest in the possibility of using auxiliary information to enhance modeling, prediction and inference for a current study. Such methodology has been used for many years in survey sampling, where summary population-level data (e.g., from a census) are used to provide calibration factors that increase the efficiency of an estimation based on the survey data (e.g., Deville and Särndal 1992; Chen and Qin 1993; Chaudhuri et al. 2008; Chen and Kim 2014). Similar problems have also been considered in economics. For example, Imbens and Lancaster (1994) considered a longitudinal employment study involving covariates, with auxiliary data provided by longitudinal unemployment rates. More recently, studies in medicine and public health have received attention (e.g., Qin et al. 2015; Chatterjee et al. 2016; Huang et al. 2016). The auxiliary data typically have much less detailed covariate information than the study data, and are often in summary or aggregate form. For

example, Huang et al. (2016) consider detailed models for the time to some event, such as the recurrence of cancer in a group of treated patients, along with auxiliary data that summarize the recurrence rates by a specific time, available from a population cancer registry. Another example is the use of large cohorts or populations as the basis for two-phase studies (e.g., Breslow et al. 2009; Lumley et al. 2011), where a subset of the cohort is selected to measure detailed information on certain covariates. See also Kim and Rao (2012) in the context of survey sampling.

Several methods for using auxiliary data have been proposed, including weight calibration (e.g., Lumley et al. 2011), generalized regression (e.g., Chen and Chen 2000; Lawless and Kalbfleisch 2011), the constrained maximum likelihood method (Handcock et al. 2000; Chatterjee et al. 2016), the generalized method of moments (e.g., Imbens and Lancaster 1994), and the empirical likelihood method (e.g., Chen and Qin 1993; Qin 2000; Chaudhuri et al. 2008; Chen and Kim 2014; Qin et al. 2015; Huang et al. 2016). Most of these methods assume that (a) the conditional distribution of the response variable, given the covariates of interest, is the same in the populations that provide the study data and the auxiliary data, and (b) the covariate distributions in the two populations are also the same. These assumptions are reasonable when a study is based on a sample of individuals

from the population that provides the auxiliary data. However, researchers are increasingly using large databases that are external to their studies (e.g., Qin et al. 2015; Chatterjee et al. 2016; Huang et al. 2016). In many such contexts, assumption (a) may be plausible but assumption (b) is more likely to be violated. For example, Keiding and Louis (2016) noted that conditional features or distributions are more likely to be “transportable” from one population to another than marginal distributions. In this case, methods that assume both (a) and (b) can lead to biased estimation and incorrect conclusions. Our objective in this paper is to provide an empirical likelihood-based method for the case where assumption (b) does not hold.

In order to use auxiliary summary information when the covariate distributions are different, we require a supplementary sample from the auxiliary data population, for which measurements on the covariates of interest are collected. This supplementary sample can be of small size, and it can be independent of or a subset of the original units on which the auxiliary information is based. It is sometimes relatively easy to obtain such a supplementary sample, for example when the covariates of interest represent demographic characteristics in a large data base with accessible micro-data on individuals. However, there will often be significant incremental costs to obtaining a supplementary sample, which need to be weighed against

potential efficiency gains.

We study here an empirical likelihood-based method which treats the covariate distributions as nuisance parameters and leaves them unspecified. The only model we specify is for the conditional distribution of the response given the covariates of interest. The approach was proposed by Han and Lawless (2016) in a discussion of Chatterjee et al. (2016), but was not developed or studied there. When the variability associated with the auxiliary summary information is negligible compared with that in the study data, we show that the proposed estimators are more efficient than the maximum likelihood estimator based on the study data alone. When the variability in the auxiliary summary information is non-negligible, we show explicitly how it affects the efficiency of the proposed estimators. Furthermore, we discuss how to implement the proposed method and provide numerical results on the efficiency for binary logistic and normal linear regression models. In the final section we discuss our assumptions and related issues, including potential uses of the proposed approach when employing large data sets.

2. Setup and review of some existing methods

The setting we consider is as follows. Let $(Y_i, X_i^T, Z_i^T)^T$, $i = 1, \dots, n$, denote the random sample collected in the current study, where Y is the re-

sponse and X and Z are vectors of covariates. Our interest is in $f(Y|X, Z)$, the distribution of Y given X and Z . We consider a family of models $f(Y | X, Z; \beta)$ that is parametrized by parameter β and assume that $f(Y|X, Z) = f(Y | X, Z; \beta_0)$ for some β_0 . In addition to the study data, auxiliary summary information is available in the form of an estimate $\hat{\theta}$ and its variance estimate, based on a known set of estimating functions $h(Y, X; \theta)$ that are applied to the auxiliary data set. The summary data reflect measurements on Y and X , but not on Z . This is relatively common because the current study is typically tailored to particular scientific questions and measures numerous relevant covariates, whereas the auxiliary data summarize a few features only. Examples can be found in Imbens and Lancaster (1994), Chaudhuri et al. (2008), Qin et al. (2015), and Huang et al. (2016). We assume that the populations represented by the study data and by the auxiliary data share the same conditional distribution $f(Y|X, Z)$. The goal is to make inference about β_0 using both the study data and the auxiliary summary information, in the hope this improves efficiency over inference based solely on the study data.

Most existing methods assume that the two populations share the same covariate distribution $f(X, Z)$. To describe the situation, assume for now that there is no variability or uncertainty associated with the estimate

$\hat{\theta}$. In other words, the auxiliary data summary consists of the vector θ^* that satisfies $E\{h(Y, X; \theta^*)\} = 0$, where the expectation $E(\cdot)$ is taken under the joint distribution $f(Y | X, Z)f(X, Z)$. Let $s(Y, X, Z; \beta) = \partial \log f(Y | X, Z; \beta) / \partial \beta$ be the score function of model $f(Y | X, Z; \beta)$. Estimation based on the current study data alone solves the estimating equation $\sum_{i=1}^n s(Y_i, X_i, Z_i; \beta) = 0$. The simplest way to use the auxiliary information is to treat $\{s(Y, X, Z; \beta)^T, h(Y, X; \theta^*)^T\}^T$ as a set of estimating functions and then to apply the generalized method of moments (Hansen 1982) or the empirical likelihood method (Qin and Lawless 1994; Owen 2001) to the current study data. However, this approach does not yield a fully efficient estimator because it does not make full use of the fact that $f(Y | X, Z; \beta)$ is a likelihood function (Imbens and Lancaster 1994).

Because $E\{h(Y, X; \theta^*)\} = E[E\{h(Y, X; \theta^*) | X, Z\}]$, it follows that $E\{u(X, Z; \beta_0, \theta^*)\} = 0$, where

$$u(X, Z; \beta, \theta^*) = \int h(Y, X; \theta^*) f(Y | X, Z; \beta) dY.$$

This moment equality provides a constraint on $f(X, Z)$. Applying the semi-empirical likelihood method (Qin 2000; Chatterjee et al. 2016) leads to an

estimator of β_0 defined through

$$\begin{aligned} & \max_{\beta, p_1, \dots, p_n} \prod_{i=1}^n f(Y_i | X_i, Z_i; \beta) p_i \quad \text{subject to} \\ & p_i \geq 0, \quad \sum_{i=1}^n p_i = 1, \quad \sum_{i=1}^n p_i u(X_i, Z_i; \beta, \theta^*) = 0, \end{aligned}$$

where the p_i denote an empirical distribution for (X, Z) supported on the study data. This estimator has been shown to be more efficient than $\hat{\beta}_{\text{MLE}}$, the maximum likelihood estimator based on current study data alone (Qin 2000; Chatterjee et al. 2016). Asymptotically equivalent estimators can be derived by treating $\{s(Y, X, Z; \beta)^T, u(X, Z; \beta, \theta^*)^T\}^T$ as a set of estimating functions and then straightforwardly applying the generalized method of moments or the empirical likelihood method (Imbens and Lancaster 1994; Han and Lawless 2016).

As noted, the assumption of the same $f(X, Z)$ is often implausible (e.g., Keiding and Louis 2016), and when it is violated, the aforementioned estimators, other than $\hat{\beta}_{\text{MLE}}$, are biased. To relax this assumption, denote $f(X, Z)$ and $f^*(X, Z)$ as the covariate distributions for the study data and the auxiliary data populations, respectively. The auxiliary summary information θ^* then satisfies $E^*\{h(Y, X; \theta^*)\} = 0$, where the expectation $E^*(\cdot)$ is taken under the joint distribution $f(Y | X, Z)f^*(X, Z)$. As before, we have that $E^*\{u(X, Z; \beta_0, \theta^*)\} = 0$. However, with the study data alone

the auxiliary estimating function $u(X, Z; \beta, \theta^*)$ cannot be used because $E^*(\cdot)$ is taken under the auxiliary data covariate distribution $f^*(X, Z)$. To use the auxiliary information, Chatterjee et al. (2016) assumed that a small random sample $(X_j^{*\text{T}}, Z_j^{*\text{T}})^{\text{T}}, j = 1, \dots, n^*$, is available from the auxiliary data population, referred to here as the supplementary sample. They proposed a constrained maximum likelihood estimator by maximizing $\prod_{i=1}^n f(Y_i | X_i, Z_i; \beta)$ under the constraint $n^{*-1} \sum_{j=1}^{n^*} u(X_j^*, Z_j^*; \beta, \theta^*) = 0$. However, this estimator can be less efficient than $\hat{\beta}_{\text{MLE}}$, especially when n^*/n is not large. Han and Lawless (2016) observed that an empirical likelihood approach could be applied. We develop this idea in the following sections.

3. The proposed empirical likelihood-based method

3.1 The proposed estimators

With the auxiliary summary information and the supplementary sample $(X_j^{*\text{T}}, Z_j^{*\text{T}})^{\text{T}}, j = 1, \dots, n^*$, we can construct estimators that are guaranteed to be more efficient than $\hat{\beta}_{\text{MLE}}$. Han and Lawless (2016) noted that the approach of Qin (2000), also considered by Chen et al. (2003), could be applied. This involves $p_j^*, j = 1, \dots, n^*$, an empirical distribution for the

3.1 The proposed estimators

supplementary sample, and defines an estimator $\hat{\beta}_{\text{EL1}}$ through

$$\begin{aligned} & \max_{\beta, p_1^*, \dots, p_{n^*}^*} \prod_{i=1}^n f(Y_i | X_i, Z_i; \beta) \prod_{j=1}^{n^*} p_j^* \quad \text{subject to} \\ & p_j^* \geq 0, \quad \sum_{j=1}^{n^*} p_j^* = 1, \quad \sum_{j=1}^{n^*} p_j^* u(X_j^*, Z_j^*; \beta, \theta^*) = 0. \end{aligned} \quad (3.1)$$

For convenience, we write $f(\beta) = f(Y | X, Z; \beta)$, $s(\beta) = \partial \log f(\beta) / \partial \beta$ and $u^*(\beta) = u(X^*, Z^*; \beta, \theta^*)$. In the Appendix we show that $\hat{\beta}_{\text{EL1}}$ is the component of $(\hat{\beta}_{\text{EL1}}^T, \hat{\lambda}^T)^T$ that satisfies

$$\sum_{i=1}^n s_i(\hat{\beta}_{\text{EL1}}) + \sum_{j=1}^{n^*} \frac{\partial u_j^*(\hat{\beta}_{\text{EL1}}) / \partial \beta^T}{1 - \hat{\lambda}^T u_j^*(\hat{\beta}_{\text{EL1}})} \hat{\lambda} = 0, \quad (3.2)$$

$$\sum_{j=1}^{n^*} \frac{u_j^*(\hat{\beta}_{\text{EL1}})}{1 - \hat{\lambda}^T u_j^*(\hat{\beta}_{\text{EL1}})} = 0, \quad (3.3)$$

where λ is a vector of Lagrange multipliers, and $\hat{p}_j^* = 1/[n^* \{1 - \hat{\lambda}^T u_j^*(\hat{\beta}_{\text{EL1}})\}]$ with

$$1 - \hat{\lambda}^T u_j^*(\hat{\beta}_{\text{EL1}}) > 1/n^*, \quad j = 1, \dots, n^*. \quad (3.4)$$

Based on the Z-estimator theory (e.g., van der Vaart 1998), it is easy to see that $(\hat{\beta}_{\text{EL1}}^T, \hat{\lambda}^T)^T \xrightarrow{p} (\beta_0^T, 0^T)^T$, and thus $\hat{\beta}_{\text{EL1}}$ is a consistent estimator of β_0 . To introduce the asymptotic distribution of $\hat{\beta}_{\text{EL1}}$, we write $S = E\{s(\beta_0)s(\beta_0)^T\}$, $G^* = E\{\partial u^*(\beta_0)/\partial \beta\}$, $\Omega^* = E\{u^*(\beta_0)u^*(\beta_0)^T\}$, and $\kappa = \lim_{n \rightarrow \infty} n^*/n$. In the Appendix we show that

$$\sqrt{n}(\hat{\beta}_{\text{EL1}} - \beta_0) \xrightarrow{d} N(0, (S + \kappa G^{*T} \Omega^{*-1} G^*)^{-1}). \quad (3.5)$$

3.1 The proposed estimators

It is clear that $G^{*T}\Omega^{*-1}G^*$ is positive-definite, and thus the above asymptotic variance $V_{\text{EL}} \equiv (S + \kappa G^{*T}\Omega^{*-1}G^*)^{-1}$ is always smaller than $V_{\text{MLE}} \equiv S^{-1}$, the asymptotic variance of $\hat{\beta}_{\text{MLE}}$. Therefore, $\hat{\beta}_{\text{EL1}}$ is guaranteed to be more efficient than $\hat{\beta}_{\text{MLE}}$, and the efficiency improvement increases with κ .

The formulation (3.1), following Qin (2000), uses a parametric likelihood multiplied by a nonparametric likelihood. A full empirical likelihood formulation as in Qin and Lawless (1994) can be given by letting p_i , $i = 1, \dots, n$, denote an empirical distribution supported on the study data sample. Then we define an estimator $\hat{\beta}_{\text{EL2}}$ through

$$\begin{aligned} & \max_{\beta, p_i, s, p_j^*, s} \prod_{i=1}^n p_i \prod_{j=1}^{n^*} p_j^* \quad \text{subject to} \\ & p_i \geq 0, \quad \sum_{i=1}^n p_i = 1, \quad \sum_{i=1}^n p_i s(Y_i, X_i, Z_i; \beta) = 0, \\ & p_j^* \geq 0, \quad \sum_{j=1}^{n^*} p_j^* = 1, \quad \sum_{j=1}^{n^*} p_j^* u(X_j^*, Z_j^*; \beta, \theta^*) = 0. \end{aligned}$$

Arguments similar to those in the Appendix leading to (3.2)-(3.3) show that

$\hat{\beta}_{\text{EL2}}$ is the component of $(\hat{\beta}_{\text{EL2}}^T, \hat{\lambda}^T, \hat{\rho}^T)^T$ that satisfies

$$\sum_{i=1}^n \frac{\partial s_i(\hat{\beta}_{\text{EL2}})/\partial \beta}{1 - \hat{\lambda}^T s_i(\hat{\beta}_{\text{EL2}})} \hat{\lambda} + \sum_{j=1}^{n^*} \frac{\partial u_j^*(\hat{\beta}_{\text{EL2}})/\partial \beta^T}{1 - \hat{\rho}^T u_j^*(\hat{\beta}_{\text{EL2}})} \hat{\rho} = 0, \quad (3.6)$$

$$\sum_{i=1}^n \frac{s_i(\hat{\beta}_{\text{EL2}})}{1 - \hat{\lambda}^T s_i(\hat{\beta}_{\text{EL2}})} = 0, \quad (3.7)$$

$$\sum_{j=1}^{n^*} \frac{u_j^*(\hat{\beta}_{\text{EL2}})}{1 - \hat{\rho}^T u_j^*(\hat{\beta}_{\text{EL2}})} = 0, \quad (3.8)$$

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and $\hat{p}_i = 1/[n\{1 - \hat{\lambda}^T s_i(\hat{\beta}_{\text{EL2}})\}]$ and $\hat{p}_j^* = 1/[n^*\{1 - \hat{\rho}^T u_j^*(\hat{\beta}_{\text{EL2}})\}]$ with

$$1 - \hat{\lambda}^T s_i(\hat{\beta}_{\text{EL2}}) > 1/n, \quad i = 1, \dots, n; \quad 1 - \hat{\rho}^T u_j^*(\hat{\beta}_{\text{EL2}}) > 1/n^*, \quad j = 1, \dots, n^*. \quad (3.9)$$

Based on the Z-estimator theory, it is easy to see that $(\hat{\beta}_{\text{EL2}}^T, \hat{\lambda}^T, \hat{\rho}^T)^T \xrightarrow{p} (\beta_0^T, 0^T, 0^T)^T$, showing the consistency of $\hat{\beta}_{\text{EL2}}$. In the Appendix, we show that $\sqrt{n}(\hat{\beta}_{\text{EL2}} - \beta_0)$ has the same asymptotic distribution as that in (3.5). In other words, $\hat{\beta}_{\text{EL2}}$ is asymptotically equivalent to $\hat{\beta}_{\text{EL1}}$, and thus is guaranteed to be more efficient than $\hat{\beta}_{\text{MLE}}$.

3.2 Numerical implementation

Reliable procedures for obtaining empirical or constrained maximum likelihood estimates can be difficult to find (e.g., Chaudhuri et al. 2008). A simple way to compute $\hat{\beta}_{\text{EL1}}$ and $\hat{\beta}_{\text{EL2}}$ seems to be to solve (3.2)–(3.3) for $(\beta^T, \lambda^T)^T$ and (3.6)–(3.8) for $(\beta^T, \lambda^T, \rho^T)^T$, respectively. However, this way is not recommended owing to its unstable behavior: equations (3.3) and (3.7)–(3.8), viewed as equations for λ and $(\lambda^T, \rho^T)^T$, respectively, for a fixed β , typically have many roots (Han and Wang 2013). Here we need $\hat{\lambda}$ and $(\hat{\lambda}^T, \hat{\rho}^T)^T$ that satisfy (3.4) and (3.9), respectively. Solving those equations directly can lead to an unwanted root.

A more reliable implementation is to consider the saddle-point repre-

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resentation of $\hat{\beta}_{\text{EL1}}$ and $\hat{\beta}_{\text{EL2}}$, as recommended in the empirical likelihood literature (e.g., Owen 2001; Imbens 2002; Kitamura 2007). As such, we outline a Newton–Raphson-type algorithm, which we show demonstrates good performance. The following discussion focuses on $\hat{\beta}_{\text{EL1}}$ for simplicity. From the derivation of (3.2)-(3.3) in the Appendix, we have that, for a fixed β , the solution $\hat{p}_j^*(\beta)$ to (3.1) is given by $\hat{p}_j^*(\beta) = 1/[n^*\{1 - \hat{\lambda}(\beta)^\text{T}u_j^*(\beta)\}]$, where $\hat{\lambda}(\beta)$ solves $\sum_{j=1}^{n^*} u_j^*(\beta)/\{1 - \lambda^\text{T}u_j^*(\beta)\} = 0$. It is then easy to see that $\hat{\lambda}(\beta)$ minimizes

$$L^*(\lambda, \beta) \equiv - \sum_{j=1}^{n^*} \log\{1 - \lambda^\text{T}u_j^*(\beta)\}, \quad (3.10)$$

and $\sum_{j=1}^{n^*} \log \hat{p}_j^*(\beta) = L^*\{\hat{\lambda}(\beta), \beta\} - n^* \log n^*$. Therefore, $\hat{\beta}_{\text{EL1}}$ defined in (3.1) can be equivalently defined as

$$\hat{\beta}_{\text{EL1}} = \arg \max_{\beta} \left\{ \sum_{i=1}^n \log f_i(\beta) + \min_{\lambda} L^*(\lambda, \beta) \right\} \equiv \arg \max_{\beta} M(\beta).$$

This is the so-called saddle-point representation, so named because of its nested optimizations.

An implementation based on the Newton–Raphson algorithm requires the Jacobian $M_{\beta}(\beta) = \partial M(\beta)/\partial \beta$ and the Hessian $M_{\beta\beta}(\beta) = \partial^2 M(\beta)/\partial \beta \partial \beta^\text{T}$ of $M(\beta)$, the expressions of which, together with some simplifications, are given in the Appendix. Both $M_{\beta}(\beta)$ and $M_{\beta\beta}(\beta)$ involve $\hat{\lambda}(\beta)$, the value of which at the current β in each iteration can be calculated by minimiz-

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ing $L^*(\lambda, \beta)$ in (3.10) with respect to λ . This minimization requires the Jacobian $L_\lambda^*(\lambda, \beta)$ and Hessian $L_{\lambda\lambda}^*(\lambda, \beta)$:

$$L_\lambda^*(\lambda, \beta) = \sum_{j=1}^{n^*} \frac{u_j^*(\beta)}{1 - \lambda^T u_j^*(\beta)}, \quad L_{\lambda\lambda}^*(\lambda, \beta) = \sum_{j=1}^{n^*} \frac{u_j^*(\beta) u_j^{*T}(\beta)}{\{1 - \lambda^T u_j^*(\beta)\}^2}.$$

The implementation consists of two loops: the outer loop updates β using $M_\beta(\beta)$ and $M_{\beta\beta}(\beta)$, where the needed $\hat{\lambda}(\beta)$ at the current β is calculated by the inner loop. The algorithm is described below.

Outer loop:

Step 0: Set $l = 0$ (iteration count), $\sigma = 5$ (maximum number of attempts within each iteration to find a step-length that increases $M(\beta)$), and $\epsilon = 10^{-4}$ (algorithm convergence criterion). Let $\hat{\beta}^{(0)} = \hat{\beta}_{\text{MLE}}$ (initial value of β) and $M^{(0)} = M(\hat{\beta}^{(0)})$ (here the calculation invokes the inner loop).

Step 1: Calculate $\Delta^{(l)} = M_{\beta\beta}(\hat{\beta}^{(l)})^{-1} M_\beta(\hat{\beta}^{(l)})$ (direction for updating $\hat{\beta}^{(l)}$; the calculation invokes the inner loop). Set $\tau = 1$ (the initial step-length taken along the direction $\Delta^{(l)}$) and $t = 0$ (number of attempts to find a step-length that increases $M(\beta)$).

Step 2: Calculate $\hat{\beta}^{\text{temp}} = \hat{\beta}^{(l)} - \tau \Delta^{(l)}$ and $M^{\text{temp}} = M(\hat{\beta}^{\text{temp}})$ (the calculation invokes the inner loop). If $M^{\text{temp}} > M^{(l)}$ or $t = \sigma$, then go to Step 3;

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otherwise, let $t = t + 1$ and $\tau = \tau/2$ and repeat Step 2.

Step 3: Let $\hat{\beta}^{(l+1)} = \hat{\beta}^{\text{temp}}$ and $M^{(l+1)} = M^{\text{temp}}$. If $\|\hat{\beta}^{(l+1)} - \hat{\beta}^{(l)}\|_1 < \epsilon$, let $\hat{\beta}_{\text{EL1}} = \hat{\beta}^{(l+1)}$ and stop the algorithm; otherwise, set $l = l + 1$ and go back to Step 1.

Inner loop:

Step 0: Set $l = 0$ (iteration count) and $\epsilon = 10^{-4}$ (algorithm convergence criterion). Let $\hat{\lambda}^{(0)} = 0$ (initial value of λ) and $L^{*(0)} = 0$.

Step 1: Calculate $\Delta^{(l)} = L_{\lambda\lambda}^*(\hat{\lambda}^{(l)}, \beta)^{-1} L_{\lambda}^*(\hat{\lambda}^{(l)}, \beta)$ (direction for updating $\hat{\lambda}^{(l)}$). Set $\tau = 1$ (the initial step-length taken along the direction $\Delta^{(l)}$).

Step 2: Calculate $\hat{\lambda}^{\text{temp}} = \hat{\lambda}^{(l)} - \tau \Delta^{(l)}$. If $\hat{\lambda}^{\text{temp}}$ satisfies $1 - (\hat{\lambda}^{\text{temp}})^T u_j^*(\beta) > 1/n^*$ for $j = 1, \dots, n^*$ and $L^{*\text{temp}} \equiv L^*(\hat{\lambda}^{\text{temp}}, \beta) < L^{*(l)}$, then go to Step 3; otherwise, let $\tau = \tau/2$ and repeat Step 2.

Step 3: Let $\hat{\lambda}^{(l+1)} = \hat{\lambda}^{\text{temp}}$ and $L^{*(l+1)} = L^{*\text{temp}}$. If $\|\hat{\lambda}^{(l+1)} - \hat{\lambda}^{(l)}\|_1 < \epsilon$, let $\hat{\lambda} = \hat{\lambda}^{(l+1)}$ and stop the algorithm; otherwise, set $l = l + 1$ and go back to Step 1.

In the outer loop, Step 2 sequentially tries step-lengths $1, 2^{-1}, \dots, 2^{-5}$ along the direction for updating β , and accepts the first length that makes $M(\beta)$

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increase. If no step-length is identified, we update β by taking the step-length as 2^{-5} . This is because the current β might be a local rather than a global maximizer, and continuing to update β could take the iterations out of this region. In the inner loop, with β fixed, Step 2 sequentially tries step-lengths $1, 2^{-1}, \dots$, along the direction for updating λ , accepting the first length that satisfies $1 - \lambda^T u_j^*(\beta) > 1/n^*$ for $j = 1, \dots, n^*$ and makes $L^*(\lambda, \beta)$ decrease. Such a step-length always exists because $\hat{\lambda}^{(0)} = 0$ and $L^*(\lambda, \beta)$ is a strictly convex function of λ . The inner loop almost always converges (Chen et al. 2002; Han 2014). The initial value for the outer loop, $\hat{\beta}^{(0)} = \hat{\beta}_{\text{MLE}}$, is a consistent estimator of β_0 , and the initial value for the inner loop, $\hat{\lambda}^{(0)} = 0$, is the probability limit of $\hat{\lambda}$. Therefore, the convergence of the above algorithm is usually fast.

For $\hat{\beta}_{\text{EL2}}$, we have the following saddle-point representation:

$$\hat{\beta}_{\text{EL2}} = \arg \max_{\beta} \left\{ \min_{\lambda} \left[- \sum_{i=1}^n \log\{1 - \lambda^T s_i(\beta)\} \right] + \min_{\rho} \left[- \sum_{j=1}^{n^*} \log\{1 - \rho^T u_j^*(\beta)\} \right] \right\}.$$

The determination of $\hat{\beta}_{\text{EL2}}$ is similar to that of $\hat{\beta}_{\text{EL1}}$. Thus we omit the details here.

3.3 Uncertainty of the auxiliary summary information

3.3 Uncertainty of the auxiliary summary information

If the auxiliary data set is not sufficiently large, the variability associated with the auxiliary summary information may be non-negligible and may affect the properties of $\hat{\beta}_{\text{EL1}}$ and $\hat{\beta}_{\text{EL2}}$. To study this effect, let N^* denote the sample size for the auxiliary data set from which the auxiliary estimate $\hat{\theta}$ is derived based on solving $\sum_{k=1}^{N^*} h(Y_k, X_k; \theta) = 0$, and let V_{θ^*} be the asymptotic variance of $\sqrt{N^*}(\hat{\theta} - \theta^*)$, where now θ^* is the unknown probability limit of $\hat{\theta}$. The auxiliary summary information now includes $\hat{\theta}$ and $\hat{V}_{\hat{\theta}}$, where $\hat{V}_{\hat{\theta}}$ is an estimate of V_{θ^*} .

The estimation procedures are as before, but with $\hat{\theta}$ replacing θ^* . It turns out that in this case the asymptotic distribution of $\hat{\beta}_{\text{EL1}}$ depends on whether the supplementary sample is independent of or a subset of the auxiliary data set. In the former case, as shown in the Appendix, $\sqrt{n}(\hat{\beta}_{\text{EL1}}^{\text{T}} - \beta_0^{\text{T}}, \hat{\lambda}^{\text{T}})^{\text{T}}$ has an asymptotic normal distribution with mean zero and variance

$$\begin{pmatrix} -S, & \kappa G^{*\text{T}} \\ \kappa G^*, & \kappa \Omega^* \end{pmatrix}^{-1} \begin{pmatrix} S, & 0 \\ 0, & \kappa(\Omega^* + \kappa^* Q^* V_{\theta^*} Q^{*\text{T}}) \end{pmatrix} \begin{pmatrix} -S, & \kappa G^{*\text{T}} \\ \kappa G^*, & \kappa \Omega^* \end{pmatrix}^{-1}, \quad (3.11)$$

where $\kappa^* = \lim_{n \rightarrow \infty} n^*/N^*$ and $Q^* = E^*\{\partial u^*(\beta_0, \theta^*)/\partial \theta\}$. An explicit but messy expression for the asymptotic variance of $\sqrt{n}(\hat{\beta}_{\text{EL1}} - \beta_0)$ may then

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be derived, but this is not necessary for the implementation because we can calculate (3.11) and then extract the corresponding sub-matrix for $\hat{\beta}_{\text{EL1}}$.

From the proof of (3.5) in the Appendix, the asymptotic variance of $\sqrt{n}(\hat{\beta}_{\text{EL1}}^{\text{T}} - \beta_0^{\text{T}}, \hat{\lambda}^{\text{T}})^{\text{T}}$, when θ^* is used instead of $\hat{\theta}$, is

$$\begin{pmatrix} -S, & \kappa G^{*\text{T}} \\ \kappa G^*, & \kappa \Omega^* \end{pmatrix}^{-1} \begin{pmatrix} S, & 0 \\ 0, & \kappa \Omega^* \end{pmatrix} \begin{pmatrix} -S, & \kappa G^{*\text{T}} \\ \kappa G^*, & \kappa \Omega^* \end{pmatrix}^{-1}. \quad (3.12)$$

Because $Q^* V_{\theta^*} Q^{*\text{T}}$ is positive-definite, a comparison between (3.11) and (3.12) reveals that the variability of $\hat{\theta}$ always increases the asymptotic variance of $\hat{\beta}_{\text{EL1}}$. Therefore, the confidence intervals for $\hat{\beta}_{\text{EL1}}$ ignoring this uncertainty will have a coverage rate that is smaller than the nominal level.

When the supplementary sample is a subset of the auxiliary data set, it is shown in the Appendix that $\sqrt{n}(\hat{\beta}_{\text{EL1}}^{\text{T}} - \beta_0^{\text{T}}, \hat{\lambda}^{\text{T}})^{\text{T}}$ has an asymptotic normal distribution with mean zero and variance

$$\begin{pmatrix} -S, & \kappa G^{*\text{T}} \\ \kappa G^*, & \kappa \Omega^* \end{pmatrix}^{-1} \begin{pmatrix} S, & 0 \\ 0, & \kappa \{(1 - 2\kappa^*)\Omega^* + \kappa^* Q^* V_{\theta^*} Q^{*\text{T}}\} \end{pmatrix} \begin{pmatrix} -S, & \kappa G^{*\text{T}} \\ \kappa G^*, & \kappa \Omega^* \end{pmatrix}^{-1}. \quad (3.13)$$

A comparison between (3.13) and (3.12) leads to a surprising observation: the variability of $\hat{\theta}$ increases the asymptotic variance of $\hat{\beta}_{\text{EL1}}$ when $Q^* V_{\theta^*} Q^{*\text{T}} > 2\Omega^*$ and reduces the asymptotic variance when $Q^* V_{\theta^*} Q^{*\text{T}} < 2\Omega^*$. Calculations show that $Q^* V_{\theta^*} Q^{*\text{T}} = \Omega^* + E^*[\text{Var}\{h(\theta^*) \mid X, Z\}]$.

3.3 Uncertainty of the auxiliary summary information

Therefore, the uncertainty of $\hat{\theta}$ reduces the asymptotic variance of $\hat{\beta}_{\text{EL1}}$ when $E^*[\text{Var}\{h(\theta^*) \mid X, Z\}] < \Omega^*$. In other words, the confidence intervals for $\hat{\beta}_{\text{EL1}}$ ignoring this uncertainty have a coverage rate that is smaller than the nominal level when $E^*[\text{Var}\{h(\theta^*) \mid X, Z\}] > \Omega^*$ and larger than the nominal level when $E^*[\text{Var}\{h(\theta^*) \mid X, Z\}] < \Omega^*$.

In general, the asymptotic variance of the proposed estimators is affected by κ and κ^* . Because this effect depends on quantities derived from the data distribution, a quantitative assessment is difficult. For example, consider the case where the supplementary sample is independent of the auxiliary data set. The asymptotic variance is determined by (3.11). When $\kappa = 0$, the asymptotic variance becomes that of $\hat{\beta}_{\text{MLE}}$ based on the current study data alone, and thus the auxiliary information is no longer useful. When $\kappa^* = 0$, (3.11) reduces to (3.12), the asymptotic variance with known θ^* . The case where $\kappa = \infty$ or $\kappa^* = \infty$ is not practically meaningful because n^* is typically small owing to the micro data from the auxiliary data set not being available. When n^*/n and n^*/N^* vary, the asymptotic variance varies between that of $\hat{\beta}_{\text{MLE}}$ and that using a known θ^* , but a quantification is difficult because the quantities in (3.11) depend on the data distribution.

In the special case that the summary information $\hat{\theta}$ is an estimate of $\theta^* = E^*(Y)$ for the auxiliary study population, calculated as the sample av-

erage of the auxiliary data $\{Y_k : k = 1, \dots, N^*\}$, we have $h(Y; \theta) = Y - \theta$. Some calculation shows that $G^* = E^*\{Y s(\beta_0)^T\}$, $\Omega^* = \text{Var}^*\{E(Y | X, Z)\}$, $Q^* = -1$ and $V_{\theta^*} = \text{Var}^*(Y)$ in this case. Therefore, when the supplementary sample is a subset of the auxiliary data set, the uncertainty of $\hat{\theta}$ reduces the asymptotic variance when $E^*\{\text{Var}(Y | X, Z)\} < \text{Var}^*\{E(Y | X, Z)\}$.

The above conclusions all apply to $\hat{\beta}_{\text{EL2}}$ as well because it has the same asymptotic expansion as $\hat{\beta}_{\text{EL1}}$.

4. Simulation and analytical results

4.1 Logistic regression

We first examine the efficiency for logistic regression, as considered by Qin et al. (2015) and Chatterjee et al. (2016) in case-control settings. Two covariates X and Z are assumed to jointly follow a bivariate normal distribution with marginal means of zero and marginal variances of one. The correlation coefficient is taken as $\rho = 0.5$ for the current study population and $\rho^* = 0.1$ for the auxiliary data population. Given X and Z , Y follows a Bernoulli distribution with $\text{logit}\{P(Y = 1 | X, Z)\} = \beta_{0c} + \beta_{0X}X + \beta_{0Z}Z + \beta_{0XZ}XZ$, where $\text{logit}(\pi) = \log\{\pi/(1-\pi)\}$ and $\beta_0^T = (\beta_{0c}, \beta_{0X}, \beta_{0Z}, \beta_{0XZ}) = (0.5, -0.5, -0.5, 0.5)$. For the auxiliary data set, we assume the model $\text{logit}\{P(Y = 1 | X)\} = \theta_c + \theta_X X$ was fitted for $f^*(Y | X)$ using the maxi-

4.1 Logistic regression

mum likelihood score function $h(Y, X; \theta) = (1, X)^T \{Y - \text{expit}(\theta_c + \theta_X X)\}$, where $\text{expit}(\gamma) = e^\gamma / (1 + e^\gamma)$. Note that this is a misspecified model for $f^*(Y | X)$. The value of θ^* can be calculated numerically as the solution to $E^* \{h(Y, X; \theta)\} = 0$. We then have $u(X, Z; \beta, \theta^*) = P(Y = 1 | X, Z; \beta)h(Y = 1, X; \theta^*) + P(Y = 0 | X, Z; \beta)h(Y = 0, X; \theta^*)$.

Table 1 contains the simulation results based on 1000 replications. Scenarios 1–3 correspond to (i) no uncertainty in the auxiliary summary information, (ii) uncertainty in the auxiliary summary information (that is, $\hat{\theta}$ replaces θ^*) and the supplementary sample is independent of the auxiliary data set, and (iii) uncertainty in the auxiliary summary information and the supplementary sample is a subset of the auxiliary data set, respectively. For all scenarios, we take $n = 300$ for the study sample and $n^* = 100$ for the supplementary sample; for scenarios 2 and 3, we take $N^* = 500$ for the auxiliary data set used to calculate $\hat{\theta}$ and $\hat{V}_{\hat{\theta}}$. In all scenarios, $\hat{\beta}_{\text{EL1}}$ and $\hat{\beta}_{\text{EL2}}$ show almost identical performance. Furthermore, both have considerably smaller empirical standard errors than those of $\hat{\beta}_{\text{MLE}}$ for the components β_c and β_X , corresponding to the regressors included in the auxiliary data model. The reduction is much less in scenarios 2 and 3, where the variability in $\hat{\theta}$ is non-negligible. Note that $N^* = 500$ is small for most auxiliary databases and in practice large data sets yield gains close to those in sce-

4.2 Normal linear regression

nario 1. In addition, the efficiency gains are small for β_Z and β_{XZ} , even in scenario 1. These results agree qualitatively with the results of Qin et al. (2015) and Chatterjee et al. (2016), although the former assumes that the covariate distributions are the same. The coverage probabilities of the 95% confidence intervals constructed using the asymptotic distributions, with no uncertainty in scenario 1 and with an adjustment for uncertainty in scenarios 2 and 3, are very close to the nominal levels.

4.2 Normal linear regression

To gain further insight into how the efficiency improvement might be affected by various factors, we next consider a linear regression, where a mathematical calculation is feasible. Let X and Z be generated as before, but with ρ and ρ^* unspecified. We assume that the model $N(\theta_c + \theta_X X, 1)$ was fitted to the auxiliary data, and that the model $N(\beta_c + \beta_X X + \beta_Z Z + \beta_{XZ} XZ, 1)$ holds for $f(Y | X, Z)$. Here the variances of the normal distributions are assumed to be known in order to simplify the calculations. The auxiliary data model leads to $h(Y, X; \theta) = (1, X)^T(Y - \theta_c - \theta_X X)$ and then $u(X, Z; \beta, \theta) = (1, X)^T(\beta_c + \beta_X X + \beta_Z Z + \beta_{XZ} XZ - \theta_c - \theta_X X)$. Solving $E^*\{h(Y, X; \theta^*)\} = 0$ gives $\theta_c^* = \beta_{0c} + \beta_{0XZ}\rho^*$ and $\theta_X^* = \beta_{0X} + \beta_{0Z}\rho^*$. Thus the auxiliary data provide information only on a two-dimensional function

4.2 Normal linear regression

of β_{0c} , β_{0X} , β_{0Z} , and β_{0XZ} . Straightforward calculations show that

$$S = \begin{pmatrix} 1 & 0 & 0 & \rho \\ 0 & 1 & \rho & 0 \\ 0 & \rho & 1 & 0 \\ \rho & 0 & 0 & 1 + 2\rho^2 \end{pmatrix}, \quad G^* = \begin{pmatrix} 1 & 0 & 0 & \rho^* \\ 0 & 1 & \rho^* & 0 \end{pmatrix},$$

$$\text{and } \Omega^* = \begin{pmatrix} \beta_{0Z}^2(1 - \rho^{*2}) + \beta_{0XZ}^2(1 + \rho^{*2}) & 2\beta_{0Z}\beta_{0XZ}(1 - \rho^{*2}) \\ 2\beta_{0Z}\beta_{0XZ}(1 - \rho^{*2}) & \beta_{0Z}^2(1 - \rho^{*2}) + \beta_{0XZ}^2(3 + 7\rho^{*2}) \end{pmatrix}. \quad (4.1)$$

From (3.5), the efficiency improvement becomes more significant when $|\beta_{0Z}|$ and $|\beta_{0XZ}|$ are small. For example, taking $\rho = 0.5$, $\rho^* = 0.1$ and $\kappa = 1/3$, the square root of the ratio of the diagonal elements of V_{EL} to those of V_{MLE} is (0.68, 0.81, 0.97, 0.97) when $\beta_0^T = (0.5, -0.5, -0.5, 0.5)$ and (0.40, 0.52, 0.93, 0.95) when $\beta_0^T = (0.5, -0.5, -0.2, 0.2)$. This observation makes intuitive sense because a weak association between Y and (Z, XZ) means that the fitted auxiliary data model $N(\theta_c + \theta_X X, 1)$ is close to the model of interest $N(\beta_c + \beta_X X + \beta_Z Z + \beta_{XZ} XZ, 1)$, and thus should lead to a greater efficiency improvement. This observation is confirmed by our simulation results for these models. These results are omitted owing to their similarity with those based on the logistic regression. Imbens and Lancaster (1994) found similar behavior for probit binary response models, using generalized

4.2 Normal linear regression

method of moments estimators, when the covariate distributions are the same.

For the above linear regression case, we can further examine the effect of the uncertainty in $\hat{\theta}$ for scenario 3. Here, as shown by our theoretical results, the definiteness of $E^*[\text{Var}\{h(\theta^*) \mid X, Z\}] - \Omega^*$ determines whether using $\hat{\theta}$ increases or reduces the asymptotic variance of $\hat{\beta}_{\text{EL1}}$ and $\hat{\beta}_{\text{EL2}}$, as compared with using θ^* . In this case, Ω^* is given in (4.1), and a simple calculation shows that $E^*[\text{Var}\{h(\theta^*) \mid X, Z\}]$ is the identity matrix. Taking $\beta_0^T = (1, 1, 1, 1)$ as an example, it is easy to see that $E^*[\text{Var}\{h(\theta^*) \mid X, Z\}] - \Omega^*$ is never positive-definite and is negative-definite when $|\rho^*| > 0.27$. In other words, using $\hat{\theta}$ instead of θ^* reduces the asymptotic variance of $\hat{\beta}_{\text{EL1}}$ and $\hat{\beta}_{\text{EL2}}$ when $|\rho^*| > 0.27$. Figure 1 plots, as a function of ρ^* , the ratio of the asymptotic standard deviation of $\sqrt{n}(\hat{\beta}_{\text{EL1}} - \beta_0)$ using $\hat{\theta}$ versus that using θ^* , taking $\rho = 0.5$, $\kappa = 1/3$ and $\kappa^* = 1/5$. Clearly, when $|\rho^*| > 0.27$, the uncertainty of $\hat{\theta}$ reduces the asymptotic variance. When $|\rho^*| < 0.27$, this uncertainty may reduce the asymptotic variance for some regression coefficients but increase it for others. The impact, however, is very small, as can be seen from the scale of the y -axis. Other aspects of efficiency can be examined using (4.1), such as the effects of ρ and ρ^* .

5. Conclusion

The fact that a supplementary sample of $(X^T, Z^T)^T$ from the auxiliary data population is needed when $f(X, Z) \neq f^*(X, Z)$ limits the use of auxiliary summary information, as well as the methodology presented here, to cases where such information can be obtained. This is feasible in settings where individual-level data can be produced from the auxiliary database. However, if micro data are not available or if the covariates Z are not included in such data, then a randomly selected supplementary sample of individuals from the auxiliary data population is needed to measure the covariates. In such cases the cost of doing so needs to be weighted against the potential efficiency gains or, in some cases, the cost of expanding the current study. There is a growing awareness of the need to consider covariate distributions, and for methodologies to deal with situations where these distributions differ across populations. In addition to the analysis of a current study “borrowing strength” from external summary data, this also applies to the comparison or integration of results from different studies. It is essential that information concerning different populations be compared critically in order to assess the usefulness of auxiliary data.

The two proposed estimators are asymptotically equivalent and perform similarly in our simulations. However, further research is needed to compare

their finite-sample behavior in more detail. On computational grounds, we recommend using $\hat{\beta}_{\text{EL1}}$ because its implementation involves only one Lagrange multiplier $\hat{\lambda}$, whereas the implementation of $\hat{\beta}_{\text{EL2}}$ involves both $\hat{\lambda}$ and $\hat{\rho}$. A larger set of Lagrange multipliers may affect the performance of the optimization procedures.

Let $\hat{g}(\beta) = \{n^{-1} \sum_{i=1}^n s_i(\beta)^{\text{T}}, (n^*)^{-1} \sum_{j=1}^{n^*} u_j^*(\beta)^{\text{T}}\}^{\text{T}}$. An alternative to the proposed empirical likelihood estimators is the generalized method of moments estimator that minimizes $\hat{g}(\beta)^{\text{T}} \hat{C}(\beta)^{-1} \hat{g}(\beta)$, where

$$\hat{C}(\beta) = \begin{pmatrix} \frac{1}{n} \sum_{i=1}^n s_i(\beta) s_i(\beta)^{\text{T}} & 0 \\ 0 & \frac{n}{n^*} \frac{1}{n^*} \sum_{j=1}^{n^*} u_j^*(\beta) u_j^*(\beta)^{\text{T}} \end{pmatrix}$$

is the sample version of $C(\beta_0) = \text{diag}(S, \kappa^{-1} \Omega^*)$, the asymptotic variance of $\sqrt{n} \hat{g}(\beta_0)$. Standard results on generalized method of moments (Hansen 1982) show that this estimator is asymptotically equivalent to the ones we have proposed. The well-established comparisons between the generalized method of moments and the empirical likelihood method apply here (e.g., Imbens 2002; Newey and Smith 2004). Imbens and Lancaster (1994) considered auxiliary information and the generalized method of moments when $f(X, Z) = f^*(X, Z)$.

The parametric model $f(Y | X, Z; \beta)$ assumed in the current study can be checked using relevant goodness-of-fit tests. The assumption that

the study population and the auxiliary data population have the same distribution $f(Y | X, Z)$ is more difficult to check in the setting considered here, where only summary information plus a supplementary sample on $(X^T, Z^T)^T$ is available for the latter population. One option is to compare $\hat{\beta}_{\text{MLE}}$ with $\hat{\beta}_{\text{EL1}}$ or $\hat{\beta}_{\text{EL2}}$, with a significant lack of agreement suggesting departures from this assumption (e.g., Imbens and Lancaster 1994; Chatterjee et al. 2016). Another is to evaluate the average of $u(X, Z; \hat{\beta}_{\text{MLE}}, \hat{\theta})$ over the supplementary sample, where a significant difference from zero indicates a violation of this assumption. However, note that such checks cannot detect certain types of differences in the distributions for Y given X and Z (e.g., Newey 1985) and a supplementary sample of $(Y, X^T, Z^T)^T$ or background information is needed to remedy this. These issues will be examined in more detail elsewhere.

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Appendix

Derivation of (3.2) and (3.3)

The Lagrangian corresponding to the constrained optimization problem

(3.1) is

$$\mathcal{L} = \sum_{i=1}^n \log f_i(\beta) + \sum_{j=1}^{n^*} \log p_j^* + n^* \lambda^T \sum_{j=1}^{n^*} p_j^* u_j^*(\beta) - \mu \left(\sum_{j=1}^{n^*} p_j^* - 1 \right),$$

where λ and μ are the Lagrange multipliers. At the solution $\hat{\beta}_{\text{EL1}}$ and \hat{p}_j^* we must have $\partial \mathcal{L} / \partial p_j^* = 0$ and $\partial \mathcal{L} / \partial \beta = 0$. Multiplying both sides of $\partial \mathcal{L} / \partial p_j^* = 1/p_j^* + n^* \lambda^T u_j^*(\beta) - \mu$ by p_j^* and summing over j , the constraints in (3.1) lead to $\hat{\mu} = n^*$, which, combined with $\partial \mathcal{L} / \partial p_j^* = 0$ yields $\hat{p}_j^* = 1/[n^* \{1 - \hat{\lambda}^T u_j^*(\hat{\beta}_{\text{EL1}})\}]$. Then $\partial \mathcal{L} / \partial \beta = 0$ gives (3.2) and the constraint $\sum_{j=1}^{n^*} \hat{p}_j^* u_j^*(\hat{\beta}_{\text{EL1}}) = 0$ gives (3.3).

Proof of (3.5)

Applying the mean-value theorem to (3.2)–(3.3) around $(\beta_0^T, 0^T)^T$ leads to

$$0 = \begin{pmatrix} \frac{1}{n} \sum_{i=1}^n s_i(\beta_0) \\ \frac{\sqrt{n^*}}{n} \frac{1}{\sqrt{n^*}} \sum_{j=1}^{n^*} u_j^*(\beta_0) \end{pmatrix} + \begin{pmatrix} \frac{1}{n} \sum_{i=1}^n \frac{\partial s_i(\bar{\beta})}{\partial \beta}, & \frac{n^*}{n} \frac{1}{n^*} \sum_{j=1}^{n^*} \frac{\partial u_j^*(\hat{\beta}_{\text{EL1}}) / \partial \beta^T}{1 - \hat{\lambda}^T u_j^*(\hat{\beta}_{\text{EL1}})} \\ \frac{n^*}{n} \frac{1}{n^*} \sum_{j=1}^{n^*} \frac{\partial u_j^*(\bar{\beta}) / \partial \beta}{1 - \bar{\lambda}^T u_j^*(\hat{\beta}_{\text{EL1}})}, & \frac{n^*}{n} \frac{1}{n^*} \sum_{j=1}^{n^*} \frac{u_j^*(\bar{\beta}) u_j^*(\hat{\beta}_{\text{EL1}})^T}{\{1 - \bar{\lambda}^T u_j^*(\hat{\beta}_{\text{EL1}})\}^2} \end{pmatrix} \begin{pmatrix} \hat{\beta}_{\text{EL1}} - \beta_0 \\ \hat{\lambda} \end{pmatrix}$$

where $\bar{\beta}$ is some value between $\hat{\beta}_{\text{EL1}}$ and β_0 and $\bar{\lambda}$ is some value between $\hat{\lambda}$

and 0. Then we have

$$\sqrt{n} \begin{pmatrix} \hat{\beta}_{\text{EL1}} - \beta_0 \\ \hat{\lambda} \end{pmatrix} = - \begin{pmatrix} -S, & \kappa G^{*T} \\ \kappa G^*, & \kappa \Omega^* \end{pmatrix}^{-1} \begin{pmatrix} \frac{1}{\sqrt{n}} \sum_{i=1}^n s_i(\beta_0) \\ \frac{\sqrt{n^*}}{\sqrt{n}} \frac{1}{\sqrt{n^*}} \sum_{j=1}^{n^*} u_j^*(\beta_0) \end{pmatrix} + o_p(1). \quad (5.1)$$

From the central limit theorem, $\sqrt{n}(\hat{\beta}_{\text{EL1}}^{\text{T}} - \beta_0^{\text{T}}, \hat{\lambda}^{\text{T}})^{\text{T}}$ has an asymptotic normal distribution with mean zero and variance

$$= \begin{pmatrix} -S, & \kappa G^{*\text{T}} \\ \kappa G^*, & \kappa \Omega^* \end{pmatrix}^{-1} \begin{pmatrix} S, & 0 \\ 0, & \kappa \Omega^* \end{pmatrix} \begin{pmatrix} -S, & \kappa G^{*\text{T}} \\ \kappa G^*, & \kappa \Omega^* \end{pmatrix}^{-1} \\ = \begin{pmatrix} (S + \kappa G^{*\text{T}} \Omega^{*-1} G^*)^{-1}, & 0 \\ 0, & (\kappa \Omega^* + \kappa^2 G^* S^{-1} G^{*\text{T}})^{-1} \end{pmatrix},$$

which shows (3.5).

Derivation of the asymptotic distribution of $\sqrt{n}(\hat{\beta}_{\text{EL2}} - \beta_0)$

Applying the mean-value theorem to (3.6)–(3.8) around $(\beta_0^{\text{T}}, 0^{\text{T}}, 0^{\text{T}})^{\text{T}}$ leads

to

$$0 = \begin{pmatrix} \frac{1}{n} \sum_{i=1}^n s_i(\beta_0) \\ \frac{\sqrt{n^*}}{n} \frac{1}{\sqrt{n^*}} \sum_{j=1}^{n^*} u_j^*(\beta_0) \\ 0 \end{pmatrix} + \begin{pmatrix} \frac{1}{n} \sum_{i=1}^n \frac{\partial s_i(\bar{\beta})/\partial \beta}{1 - \bar{\lambda}^{\text{T}} s_i(\hat{\beta}_{\text{EL2}})}, & \frac{1}{n} \sum_{i=1}^n \frac{s_i(\bar{\beta}) s_i(\hat{\beta}_{\text{EL2}})^{\text{T}}}{\{1 - \bar{\lambda}^{\text{T}} s_i(\hat{\beta}_{\text{EL2}})\}^2}, & 0 \\ \frac{n^*}{n} \frac{1}{n^*} \sum_{j=1}^{n^*} \frac{\partial u_j^*(\bar{\beta})/\partial \beta}{1 - \bar{\rho}^{\text{T}} u_j^*(\hat{\beta}_{\text{EL2}})}, & 0, & \frac{n^*}{n} \frac{1}{n^*} \sum_{j=1}^{n^*} \frac{u_j^*(\bar{\beta}) u_j^*(\hat{\beta}_{\text{EL2}})^{\text{T}}}{\{1 - \bar{\rho}^{\text{T}} u_j^*(\hat{\beta}_{\text{EL2}})\}^2} \\ 0, & \frac{1}{n} \sum_{i=1}^n \frac{\partial s_i(\hat{\beta}_{\text{EL2}})/\partial \beta}{1 - \hat{\lambda}^{\text{T}} s_i(\hat{\beta}_{\text{EL2}})}, & \frac{n^*}{n} \frac{1}{n^*} \sum_{j=1}^{n^*} \frac{\partial u_j^*(\hat{\beta}_{\text{EL2}})/\partial \beta^{\text{T}}}{1 - \hat{\rho}^{\text{T}} u_j^*(\hat{\beta}_{\text{EL2}})} \end{pmatrix} \begin{pmatrix} \hat{\beta}_{\text{EL2}} - \beta_0 \\ \hat{\lambda} \\ \hat{\rho} \end{pmatrix} \\ = \begin{pmatrix} \frac{1}{\sqrt{n}} \sum_{i=1}^n s_i(\beta_0) \\ \frac{\sqrt{n^*}}{\sqrt{n}} \frac{1}{\sqrt{n^*}} \sum_{j=1}^{n^*} u_j^*(\beta_0) \\ 0 \end{pmatrix} + \begin{pmatrix} -S, & S, & 0 \\ \kappa G^*, & 0, & \kappa \Omega^* \\ 0, & -S, & \kappa G^{*\text{T}} \end{pmatrix} \sqrt{n} \begin{pmatrix} \hat{\beta}_{\text{EL2}} - \beta_0 \\ \hat{\lambda} \\ \hat{\rho} \end{pmatrix} + o_p(1),$$

where $\bar{\beta}$ is some value between $\hat{\beta}_{\text{EL2}}$ and β_0 , $\bar{\lambda}$ is some value between $\hat{\lambda}$ and 0, and $\bar{\rho}$ is some value between $\hat{\rho}$ and 0. Then we have $S\hat{\lambda} = \kappa G^{*\text{T}}\hat{\rho} + o_p(1)$, and thus the above equality becomes

$$0 = \begin{pmatrix} \frac{1}{\sqrt{n}} \sum_{i=1}^n s_i(\beta_0) \\ \frac{\sqrt{n^*}}{\sqrt{n}} \frac{1}{\sqrt{n^*}} \sum_{j=1}^{n^*} u_j^*(\beta_0) \end{pmatrix} + \begin{pmatrix} -S, & \kappa G^{*\text{T}} \\ \kappa G^*, & \kappa \Omega^* \end{pmatrix} \sqrt{n} \begin{pmatrix} \hat{\beta}_{\text{EL2}} - \beta_0 \\ \hat{\rho} \end{pmatrix} + o_p(1),$$

which has the same structure as (5.1). Therefore, $\sqrt{n}(\hat{\beta}_{\text{EL2}} - \beta_0)$ and $\sqrt{n}(\hat{\beta}_{\text{EL1}} - \beta_0)$ have the same asymptotic distribution.

Expressions for $M_\beta(\beta)$ and $M_{\beta\beta}(\beta)$

Bearing in mind the implicit dependence of $\hat{\lambda}(\beta)$ on β , routine calculation leads to

$$\begin{aligned} M_\beta(\beta) &= \sum_{i=1}^n s_i(\beta) + \sum_{j=1}^{n^*} \frac{u_{\beta j}^*(\beta)^\text{T}}{1 - \hat{\lambda}(\beta)^\text{T} u_j^*(\beta)} \hat{\lambda}(\beta), \\ M_{\beta\beta}(\beta) &= \sum_{i=1}^n s_{\beta i}(\beta) + \sum_{j=1}^{n^*} \frac{u_{\beta j}^*(\beta)^\text{T} \hat{\lambda}(\beta) \hat{\lambda}(\beta)^\text{T} u_{\beta j}^*(\beta)}{\{1 - \hat{\lambda}(\beta)^\text{T} u_j^*(\beta)\}^2} + \sum_{j=1}^{n^*} \frac{\sum_{k=1}^m u_{\beta\beta j}^{*[k]}(\beta) \hat{\lambda}^{[k]}(\beta)}{1 - \hat{\lambda}(\beta)^\text{T} u_j^*(\beta)} \\ &\quad - \left(\sum_{j=1}^{n^*} \frac{u_{\beta j}^*(\beta)^\text{T} \hat{\lambda}(\beta) u_j^*(\beta)^\text{T}}{\{1 - \hat{\lambda}(\beta)^\text{T} u_j^*(\beta)\}^2} + \sum_{j=1}^{n^*} \frac{u_{\beta j}^*(\beta)^\text{T}}{1 - \hat{\lambda}(\beta)^\text{T} u_j^*(\beta)} \right) \left(\sum_{j=1}^{n^*} \frac{u_j^*(\beta) u_j^*(\beta)^\text{T}}{\{1 - \hat{\lambda}(\beta)^\text{T} u_j^*(\beta)\}^2} \right)^{-1} \\ &\quad \times \left(\sum_{j=1}^{n^*} \frac{u_j^*(\beta) \hat{\lambda}(\beta)^\text{T} u_{\beta j}^*(\beta)}{\{1 - \hat{\lambda}(\beta)^\text{T} u_j^*(\beta)\}^2} + \sum_{j=1}^{n^*} \frac{u_{\beta j}^*(\beta)}{1 - \hat{\lambda}(\beta)^\text{T} u_j^*(\beta)} \right), \end{aligned}$$

where $u^{*[k]}(\beta)$ and $\hat{\lambda}^{[k]}(\beta)$ are the k -th components of $u^*(\beta)$ and $\hat{\lambda}(\beta)$, respectively.

When $\hat{\lambda}(\beta)$ is close to 0, as is the case for our implementation in Section 3.2 because $\hat{\lambda} \xrightarrow{p} 0$ and $\hat{\lambda}^{(0)} = 0$, we have the approximation

$$M_{\beta\beta}(\beta) \approx \sum_{i=1}^n s_{\beta i}(\beta) - \left(\sum_{j=1}^{n^*} \frac{u_{\beta j}^*(\beta)^T}{1 - \hat{\lambda}(\beta)^T u_j^*(\beta)} \right) \left(\sum_{j=1}^{n^*} \frac{u_j^*(\beta) u_j^*(\beta)^T}{\{1 - \hat{\lambda}(\beta)^T u_j^*(\beta)\}^2} \right)^{-1} \left(\sum_{j=1}^{n^*} \frac{u_{\beta j}^*(\beta)}{1 - \hat{\lambda}(\beta)^T u_j^*(\beta)} \right),$$

which is used in our implementation.

Proof of (3.11)

Similarly to the derivation of (5.1), we have

$$\sqrt{n} \begin{pmatrix} \hat{\beta}_{\text{EL1}} - \beta_0 \\ \hat{\lambda} \end{pmatrix} = - \begin{pmatrix} -S, & \kappa G^{*\text{T}} \\ \kappa G^*, & \kappa \Omega^* \end{pmatrix}^{-1} \begin{pmatrix} \frac{1}{\sqrt{n}} \sum_{i=1}^n s_i(\beta_0) \\ \frac{\sqrt{N^*}}{\sqrt{n}} \frac{1}{\sqrt{N^*}} \sum_{j=1}^{n^*} u_j^*(\beta_0, \hat{\theta}) \end{pmatrix} + o_p(1). \quad (5.2)$$

Then the mean-value theorem and the law of large numbers yield to

$$\frac{1}{\sqrt{N^*}} \sum_{j=1}^{n^*} u_j^*(\beta_0, \hat{\theta}) = \frac{1}{\sqrt{N^*}} \sum_{j=1}^{n^*} u_j^*(\beta_0, \theta^*) + \kappa^* Q^* \sqrt{N^*} (\hat{\theta} - \theta^*) + o_p(1), \quad (5.3)$$

leading to (3.11).

Proof of (3.13)

Let $\{(Y_k^*, X_k^{*\text{T}})^T : k = 1, \dots, N^*\}$ denote the auxiliary data. From (5.3) we

have

$$\frac{1}{\sqrt{N^*}} \sum_{j=1}^{n^*} u_j^*(\beta_0, \hat{\theta}) = \frac{1}{\sqrt{N^*}} \sum_{k=1}^{N^*} \{R_k u_k^*(\beta_0, \theta^*) - \kappa^* Q^* H^{*-1} h(Y_k^*, X_k^*; \theta^*)\} + o_p(1), \quad (5.4)$$

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where R_k indicates whether the k -th subject in the sample $\{k : k = 1, \dots, N^*\}$ is also in the supplementary sample $\{j : j = 1, \dots, n^*\}$, and $H^* = E^*\{\partial h(Y, X; \theta^*)/\partial \theta\}$. Without loss of generality, we assume that the underlying mechanism that generates R_k samples n^* subjects from a finite population of N^* subjects without replacement. Let $W^* = Ru^*(\beta_0, \theta^*) - \kappa^* Q^* H^{*-1} h(Y^*, X^*; \theta^*)$. It is easy to verify that W^* has mean zero and that the covariance of $W_{k_1}^*$ and $W_{k_2}^*$ is zero when $k_1 \neq k_2$. In addition, from $H^* = Q^*$, calculations show that the variance of W^* is equal to $(\kappa^* - 2\kappa^{*2})\Omega^* + \kappa^{*2}Q^*V_{\theta^*}Q^{*\top}$. Therefore, from (5.2) and (5.4), (3.13) follows from the central limit theorem for dependent random variables (e.g., Billingsley 1995).

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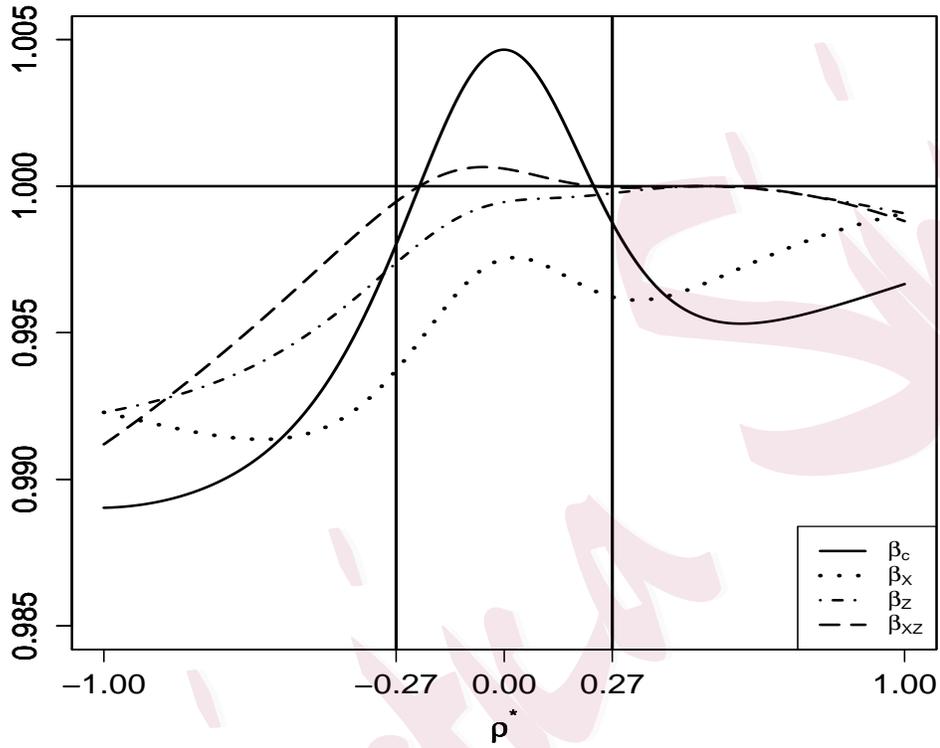


Figure 1: Plot of the ratio of the asymptotic standard deviation of $\sqrt{n}(\hat{\beta}_{ELI} - \beta_0)$ using $\hat{\theta}$ versus that using θ^* when the supplementary sample is a subset of the auxiliary data set, taking $\beta_0^T = (1, 1, 1, 1)$, $\rho = 0.5$, $\kappa = 1/3$, and $\kappa^* = 1/5$.

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Table 1: Simulation results for logistic regression models based on 1000 replications. All numbers other than the percentages have been multiplied by 1000. Scenarios 1-3 correspond to no uncertainty in the auxiliary summary information, uncertainty in the auxiliary summary information and the supplementary sample is independent of the auxiliary data set, and uncertainty in the auxiliary summary information and the supplementary sample is a subset of the auxiliary data set, respectively. For all scenarios, $n = 300$ and $n^* = 100$. For scenarios 2 and 3, $N^* = 500$.

	Scenario 1				Scenario 2				Scenario 3			
	β_c	β_X	β_Z	β_{XZ}	β_c	β_X	β_Z	β_{XZ}	β_c	β_X	β_Z	β_{XZ}
current study sample only												
bias	11	-14	-25	30	7	-9	-24	32	8	-12	-23	31
SE-EMP	139	168	167	173	144	169	179	166	139	166	181	168
empirical likelihood 1												
bias	-13	-9	-24	35	13	-13	-22	30	9	-12	-23	31
SE-EMP	66	86	159	163	106	127	172	169	101	120	172	167
SE-NAIVE	65	87	159	160	65	86	158	159	65	86	159	159
CP-95%	93.7	95.3	95.4	95.5	76.1	80.3	94.1	93.6	79.3	83.1	92.8	93.7
SE-EST	-	-	-	-	105	124	162	164	101	118	161	163
CP-95%-ADJ	-	-	-	-	94.6	95.1	94.3	94.3	94.6	95.7	93.3	94.2
empirical likelihood 2												
bias	-13	-9	-25	35	13	-12	-23	30	9	-13	-23	32
SE-EMP	67	86	159	164	106	127	172	169	101	120	172	167
SE-NAIVE	65	87	159	160	65	86	159	159	65	86	159	159
CP-95%	93.8	95.5	95.4	95.5	75.9	80.7	93.9	93.7	79.4	83.2	92.5	93.3
SE-EST	-	-	-	-	105	124	162	164	101	118	161	163
CP-95%-ADJ	-	-	-	-	94.5	94.7	94.1	94.2	94.6	95.6	93.1	93.9

SE-EMP: empirical standard error; SE-NAIVE: mean of the estimated standard error based on the asymptotic variance without accounting for the uncertainty in $\hat{\theta}$; CP-95%: coverage probability of the 95% confidence interval based on the asymptotic distribution without accounting for the uncertainty in $\hat{\theta}$; SE-EST: mean of the estimated standard error based on the asymptotic variance adjusting for the uncertainty in $\hat{\theta}$; CP-95%-ADJ: coverage probability of the 95% confidence interval based on the asymptotic distribution adjusting for the uncertainty in $\hat{\theta}$.